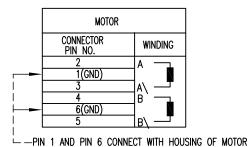


CONNECTION	BIP	OLAR							
SPECIFICATION SERIES			PERMISSIBLE RADIAL+AXIAL FORCE						
VOLTAGE (VDC)	3.1	5		ROTOR SPRING- SPRIN					
AMPS/PHASE	1.8	1		MOUNTED IN WASHER 7					
RESISTANCE/PHASE (Ohms)@25°C	1.75±15%			BEARING					
INDUCTANCE/PHASE (mH) @1KHz	3.3	±20%		Fa Fr					
HOLDING TORQUE (Nm) [lb-in]	0.5	[4.425]							
DETENT TORQUE (Nm) [lb-in]	1.3	7x10 ⁻² [C	.1212]		寸-		⋽		
STEP ANGLE (*)	STEP ANGLE (*)]					
ACCURACY (NON-ACCUM) ±5%			-						
ROTOR INERTIA $(Kg-m^2)$ $[Ib-in^2]$ 8.2x10 ⁻⁶ $[2.8x10^{-2}]$									
WEIGHT (Kg) [lb] 0.34 [0.75]									
TEMPERATURE RISE: MAX.80°C (MOTOR STANDSTILL; FOR 2 PHASE ENERGIZED)				AXIAL-FORCE Fa (N) Fa=7					
AMBIENT TEMPERATURE −10°~ 50°C	[14°F ~ 122°F]			DISTANCE a (mm)	5	10	15	20	
INSULATION RESISTANCE 100 MOhm (UNDER NORMAL TE	MPERATU	RE AND HUMIDITY)	RADIAL-FORCE Fr (N)	58	36	26	20	
INSULATION CLASS B 130° [266°F]	AXIAL			RAI	DIAL				
DIELECTRIC STRENGTH 500VAC FOR 1 MIN.	SHAFT PLAY (mm) 0.08			0.02					
AMBIENT HUMIDITY MAX. 85% (NO CONDENSATION)				AT LOAD MAX: (N)	4.5	4.5 4.5			
			, 	= -	®			A DV/D	



ENCODER PIN ASSIGNMENT JST SM10B-GHS-TB							
PIN NO.	FUNCTION						
PIN 1	GND						
PIN 2	Α						
PIN 3	A\						
PIN 4	B∖						
PIN 5	В						
PIN 6	I\						
PIN 7	I						
PIN 8	0V						
PIN 9	+5V						
PIN 10	GND						

FULL STEP 2 PHASE-Ex.,									
WHEN	FACI	NG M	OUNT	ING E	ND	(X)			
STEP	Α	В	A\	Β\		CCV			
1	+	+	1	ı		A			
2	ı	+	+	ı					
3	ı	ı	+	+	ŧ				
4	+	-	_	+	CW				

	WIRING DIAGRAM	
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02	4-M3 DEPTH TOLERANCE	27.10.16	GYQ		PLUG & D		CHKD	L B	24.10.12	SIEIIIIVO MOTOR
01	NEW MOTOR LENGTH	25.08.14	GYQ	Surface	General	Work piece	DRN	GYQ	24.10.12	DWG.NO
REV	DESCRIPTION	DATE	APVD	specification DIN ISO 1302	tolerances DIN ISO 2768- cH	edge DIN ISO 13715	SIGN	ATURE	DATE	SC4118L1804-EN005K