

Discrete time signals & systems

Classification of DTS :-

- 1) Even & odd DTS.
- 2) periodic & non periodic DTS.
- 3) Deterministic & Random DTS
- 4) Energy & power DTS.

1) Even & odd DTS :-

→ A Discrete time signals satisfy the condition $x(n) = x(-n)$.

Hence Its Even Signal or EVEN DTS.

$$\text{Ex: } \cos(n) = x(n)$$

→ A DTS satisfy the condition

$$x(+n) = -x(n)$$

is called odd DTS Ex: $x(n) = \sin(n)$

To calculate odd & even component of DTS using following equations

$$\text{Even} \Rightarrow x_e(n) = \frac{1}{2} [x(n) + x(-n)]$$

$$\text{odd} \Rightarrow x_o(n) = \frac{1}{2} [x(n) - x(-n)]$$

$$\text{Ex: } x(n) = \cos(n)$$

$$x(1) = \cos(1) = 0.540$$

$$x(-1) = \cos(-1) = 0.540 \quad \text{Even}$$

$$y(n) = \sin(n)$$

$$y(1) = \sin(1) = 0.84$$

$$y(-1) = \sin(-1) = -0.84$$

$$y(n) = -y(-n)$$

$$\text{at } n=1 \quad y(1) = -y(-1)$$

$$0.84 = -(0.84)$$

2) periodic & non-periodic DTs :-

→ If DT signal is periodic, it satisfies $x(n) = x(n+N)$

otherwise It's non periodic DT signals

Here, N should be Integer & its fundamental period of $x(n)$

$$\omega = \frac{2\pi}{N} \quad (\text{radians/sec})$$

3) Deterministic & Random DTs :-

The discrete time signal is predictable, with respect to time (n domain) is called Deterministic.

$$\text{Ex: } x(n) = n^2, \quad 0 < n \leq 10.$$

→ Random DTs : The DT signal is not predictable except value of the signal with respect to particular time (n domain) is called Random signal.

Ex: ECG signal & Tossing a Coin
EMG signal

1) Ever Energy & power signal :-

A Energy of DTS

$$E = \lim_{N \rightarrow \infty} \sum_{n=-N}^N |x(n)|^2$$

$$\textcircled{18} \quad E = \sum_{n=-\infty}^{\infty} |x(n)|^2$$

→ Power of PTS given by

$$P = \lim_{N \rightarrow \infty} \frac{1}{2N+1} \sum_{n=-N}^{N+1} |x(n)|^2$$

$$\textcircled{19} \quad P = \frac{1}{N} \sum_{n=0}^{N-1} x^2(n)$$

Note : 1) The signal is referred to as an energy signal if the total energy 'E' of the signal satisfies the condition is $0 < E < \infty$ [E is finite]

2) where it is referred to as power signal if the average power 'P' of the signal satisfies the condition

$$0 < P < \infty \quad [\text{'P' is finite}]$$

3) All periodic signals are power signals but all power signals are not periodic signals.

4) Generally signals which are both deterministic & non periodic signals are example for energy signals but not for problems :-

1) Find & plot the Even & odd component of following DTS.

$$(a) x(n) = u(n)$$

$$(b) x(n) = 3u(n-2)$$

$$(c) x(n) = 2u(n), 0 \leq n < 1$$

$$(d) x(n) = \alpha^n u(n-3), 0 < \alpha < 1$$

$$(e) x(n) = u(n) - u(n-4)$$

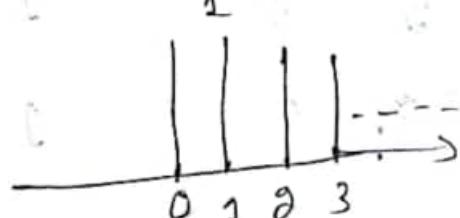
$$(f) x(n) = \cos(\frac{\pi}{2}n) u(n)$$

$$(g) x(n) = [2, 3, 4, 5, 6]$$

$$(a) x(n) = u(n)$$

$$u(n) = \begin{cases} 1 & n \geq 0 \\ 0 & n < 0 \end{cases}$$

$$x(n) = u(n)$$



We need to calculate even & odd component

$$\text{Even} = x_e(n) = \frac{1}{2} [x(n) + x(-n)]$$

$$\text{Odd} = x_o(n) = \frac{1}{2} [x(n) - x(-n)]$$

$$\rightarrow x(-n) = u(-n)$$

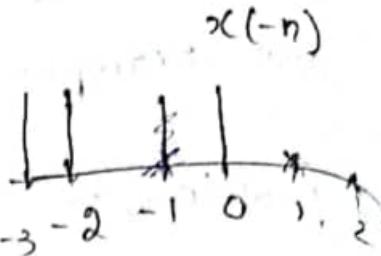
$$n=0; x(-0) = u(-0) = 1$$

$$n=1; x(-1) = u(-1) = 0$$

$$n=-1; x(-(-1)) = u(1) = 1$$

$$n=-2; x(-(-2)) = u(2) = 1$$

$$n=-3; x(-(-3)) = u(3) = 1$$



$$\rightarrow x(n) = u(n)$$

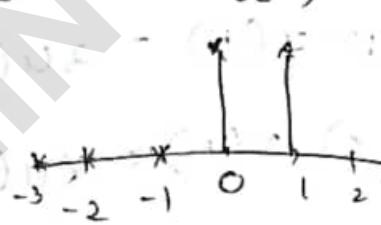
$$n=0; x(+0) = u(0) = 1$$

$$n=1; x(+1) = u(1) = 1$$

$$n=-1; x(-1) = u(-1) = 0$$

$$n=-2; x(-2) = u(-2) = 0$$

$$n=-3; x(-3) = u(-3) = 0$$



n	x(n)	x(-n)	Even	Odd
	x(n) + x(-n)	x(n) - x(-n)		
0	1	1	2	0
1	1	0	1	1
-1	0	1	1	-1
-2	0	1	1	-1
-3	0	1	1	-1

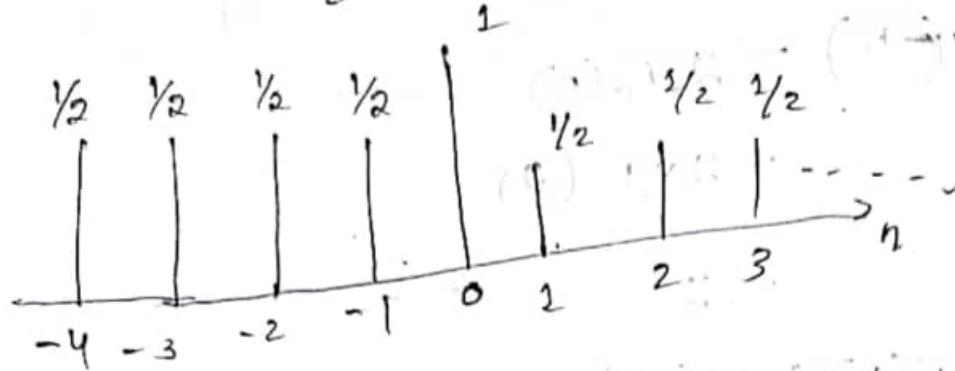
$$\text{Even} = x_e(n) = \frac{1}{2} [x(n) + x(-n)]$$

$$\begin{aligned} x(n) + x(-n) &= 2x_e(n) \\ &= 2 \times \frac{1}{2}(2) \\ &= 2 \end{aligned}$$

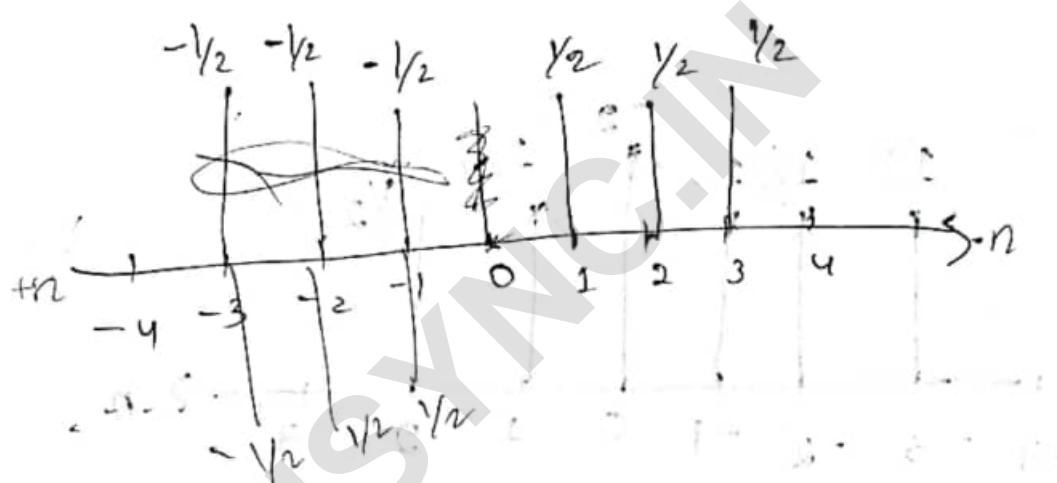
$$n=1; x(n) + x(-n) = 2 \times \frac{1}{2}(1)$$

→ Even sketch

$$x_e(n) = \frac{1}{2} [x(n), x(-n)]$$



$$\rightarrow x_o(n) = \frac{1}{2} [x(n) - x(-n)]$$



b) $x(n) = 3u(n-2)$

$$\begin{aligned} n=0; \quad x(0) &= 3u(0-2) \\ &= 3u(-2) = 3(0) = 0 \end{aligned}$$

$$\begin{aligned} n=1; \quad x(1) &= 3u(1-2) \\ &= 3u(-1) \\ &= 3(0) = 0 \end{aligned}$$

$$\begin{aligned} n=-1; \quad x(-1) &= 3u(-1-2) \\ &= 3u(-3) \\ &= 3(0) \\ &= 0 \end{aligned}$$

$$y(n) = 3u(n-2)$$

Note:- Time shifting:

$$\text{If } y(n) = x(n-n_0)$$

where,

case I : $n_0 > 0$

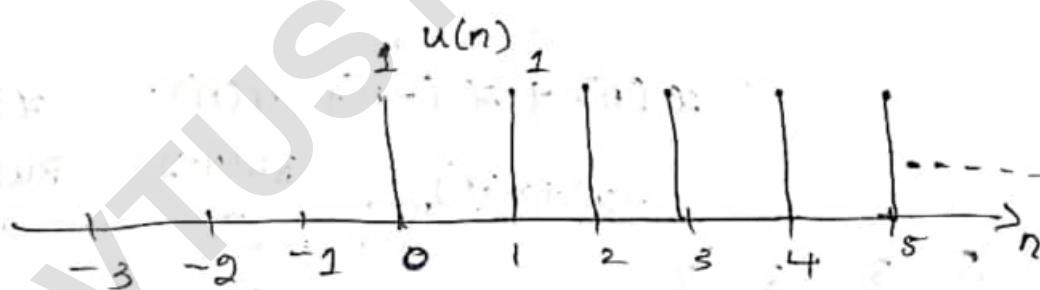
The signal is shifted to the right (n_0 times).

case II : $n_0 < 0$

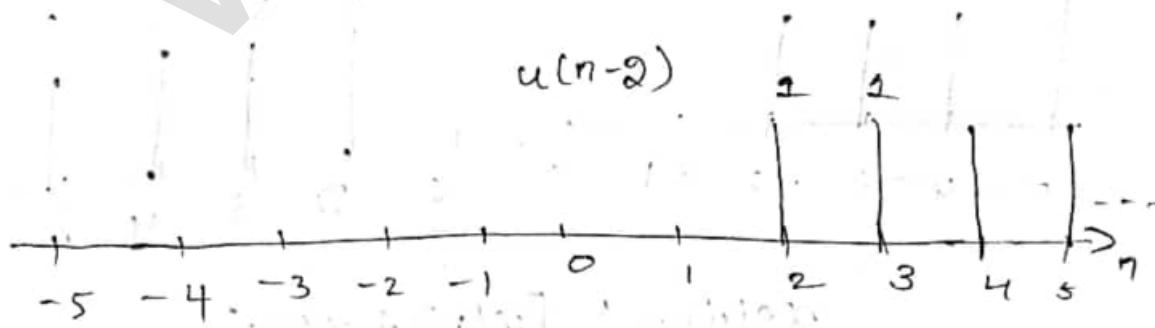
The signal is shifted to the left (n_0 times).

$$x(n) = 3u(n-2)$$

$$u(n) = \begin{cases} 1 & n \geq 0 \\ 0 & n < 0 \end{cases}$$

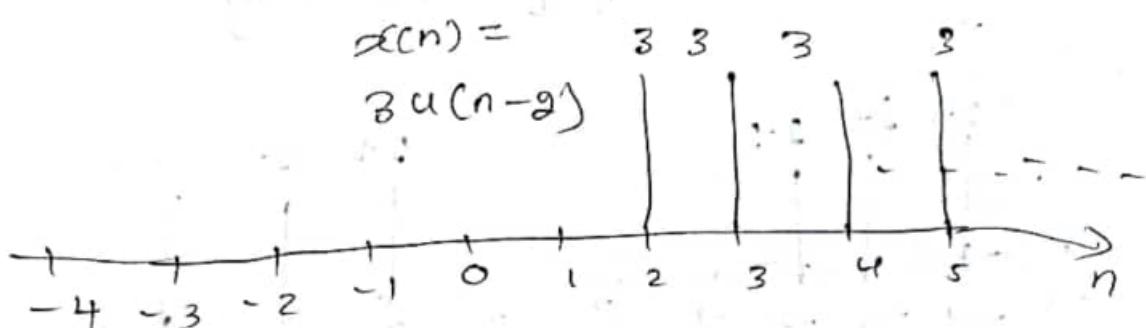


$$u(n-2)$$



$$x(n) =$$

$$3u(n-2)$$



$$x_c(n) = \frac{1}{2} [x(n) + x(-n)]$$

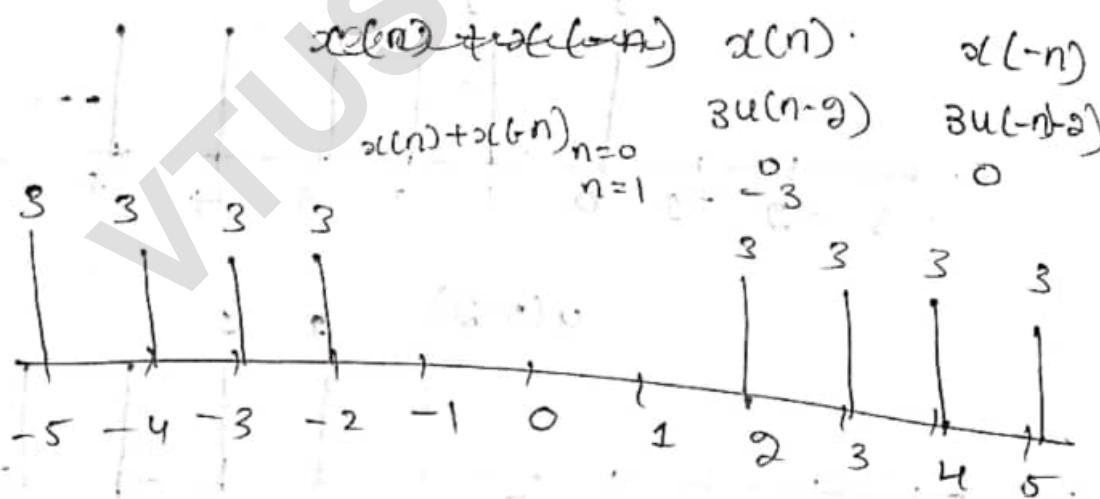
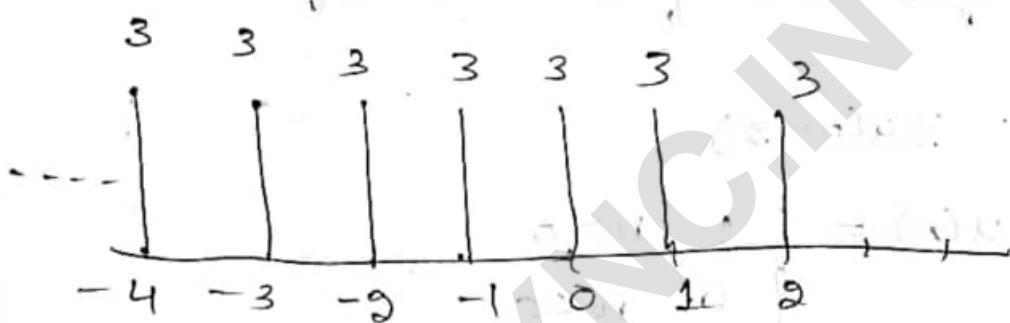
Note :- $x(-n)$

Reflection / Time folding.

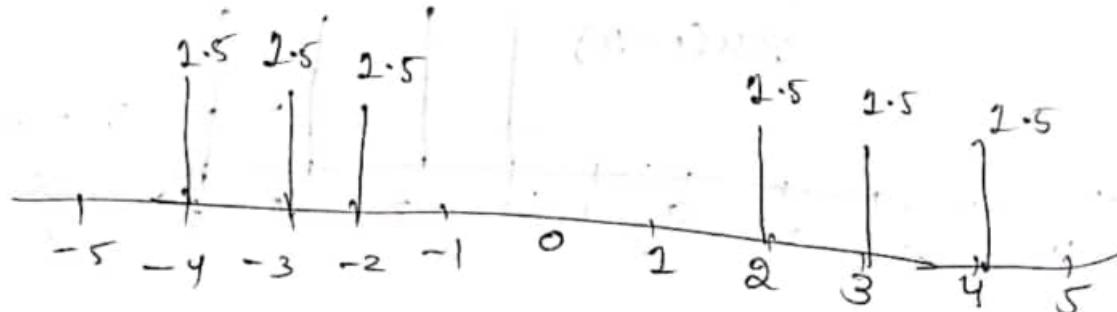
$$y(n) = x(-n)$$

$y(n)$ is reflected version of $x(n)$

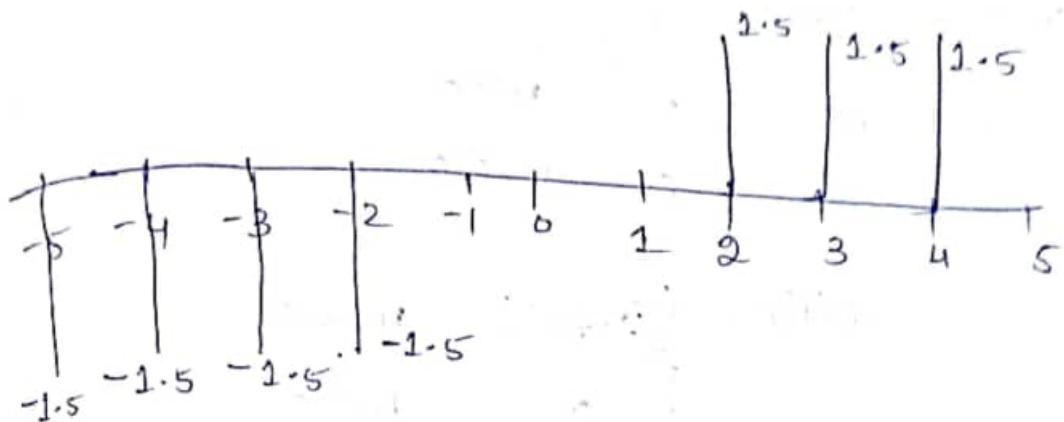
Q9) Time folding.



$$x_c(n) = \frac{1}{2} [x(n) + x(-n)]$$



$$x(n) + x(-n) \quad x_0(n) = \frac{1}{2} [x(n) + x(-n)]$$



* plot and calculate the even & odd for the following

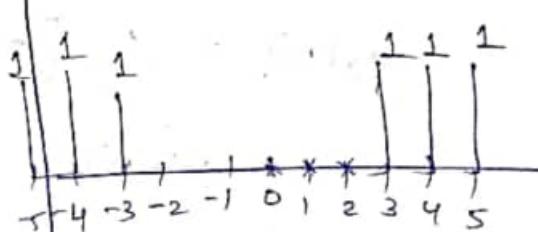
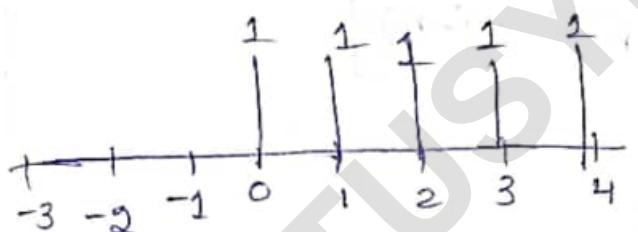
$$1) x(n) = 2u(n-3) \quad 2) x(n) = 4u(n-4)$$

Soln:- Given:-

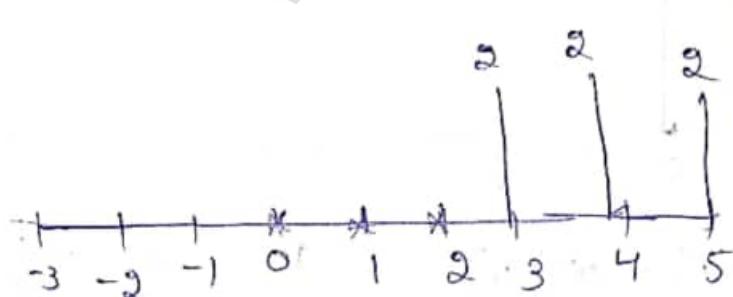
$$x(n) = 2u(n-3)$$

$$\bullet x(n) = u(n)$$

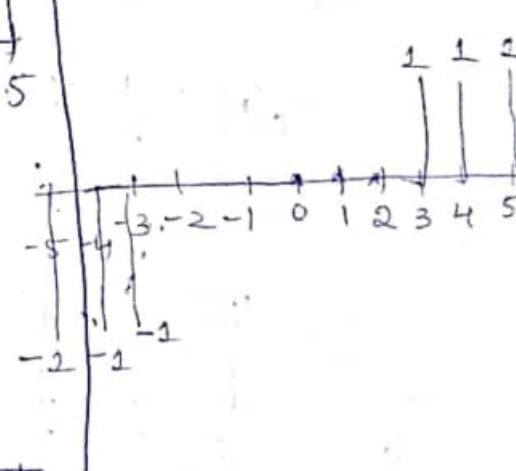
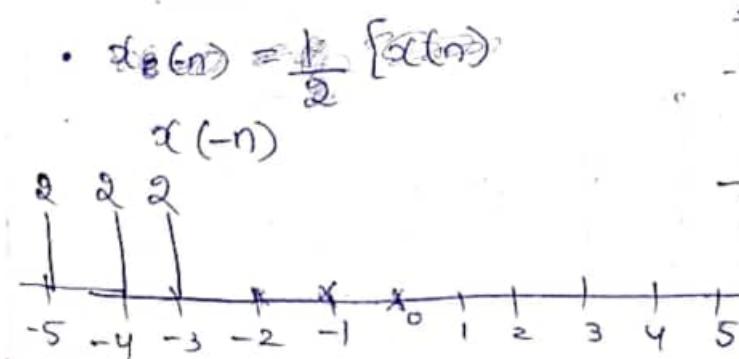
$$\bullet x_e(n) = \frac{1}{2} [x(n) + x(-n)]$$



$$\bullet x(n) = 2u(n-3)$$



$$\bullet x_o(n) = \frac{1}{2} [x(n) - x(-n)]$$

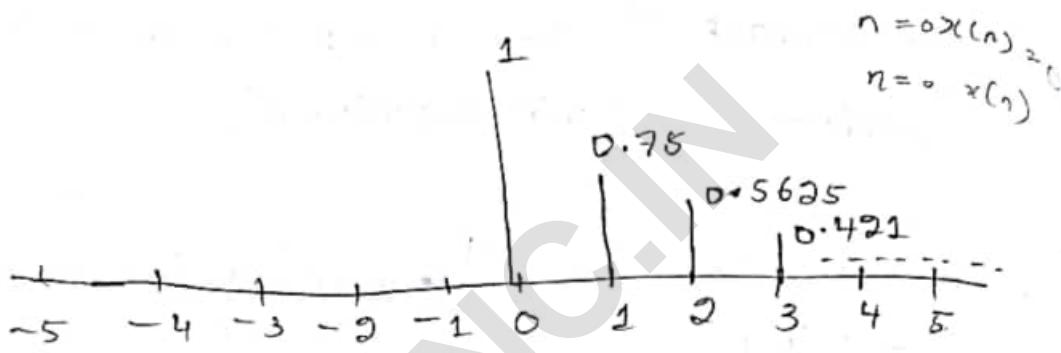


$$(d) x(n) = \alpha^n u(n), 0 < \alpha < 1$$

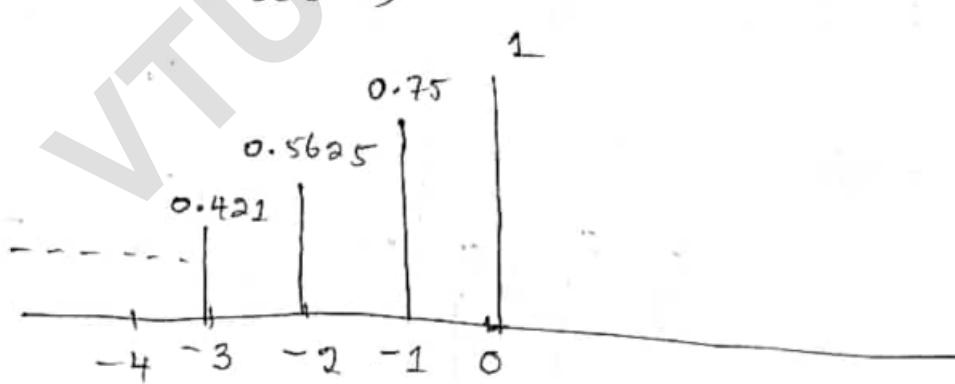
Consider $\alpha = 0.75$

$$u(n) = \begin{cases} 1 & n \geq 0 \\ 0 & n < 0 \end{cases}$$

$$x(n) = \begin{cases} (0.75)^n & n \geq 0 \\ 0 & n < 0 \end{cases}$$



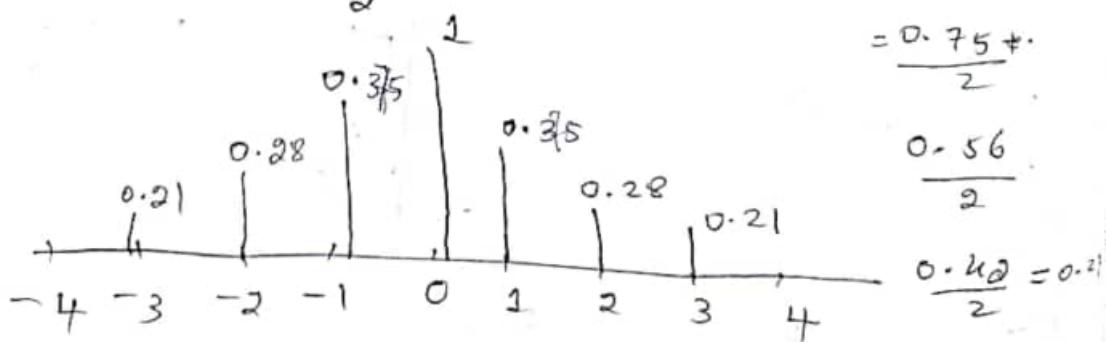
$$x_e(n) = \frac{1}{2} [x(n) + x(-n)]$$



$$x_e(n) = \frac{1}{2} [x(n) + x(-n)]$$

$$1 + 1 = 2 \times \frac{1}{2} = 1$$

$$= \frac{0.75 + 0.75}{2}$$



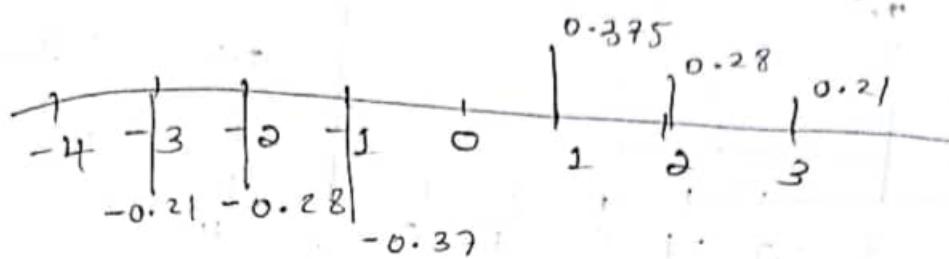
$$\frac{0.56}{2}$$

$$\frac{0.42}{2} = 0.21$$

$$x_0(n) = \frac{1}{2} [x(n) - x(-n)]$$

$$1-1=0$$

$$1-1=0$$



d) $x(n) = \alpha^n u(n-3), \quad 0 < \alpha < 1$

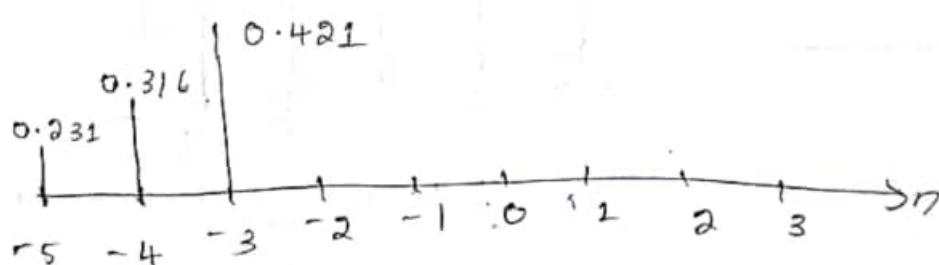
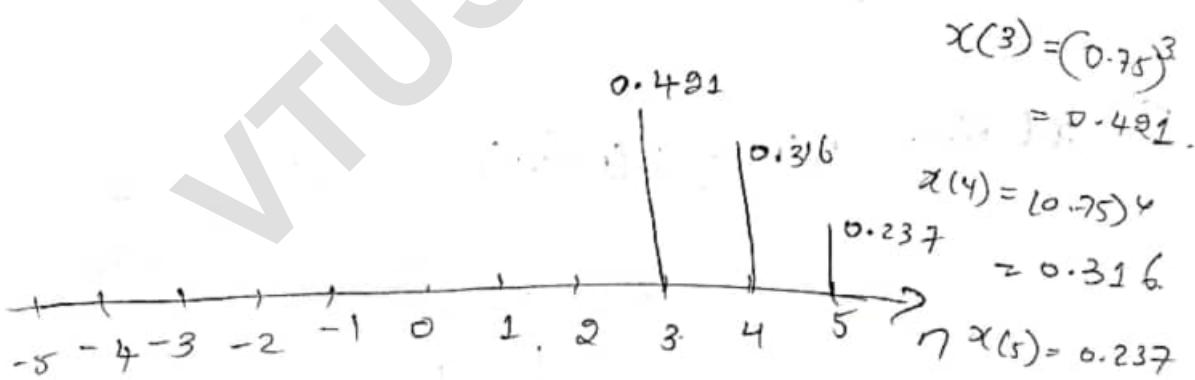
$$\alpha = 0.75$$

$$u(n) = \begin{cases} 1 & n \geq 0 \\ 0 & n < 0 \end{cases}$$

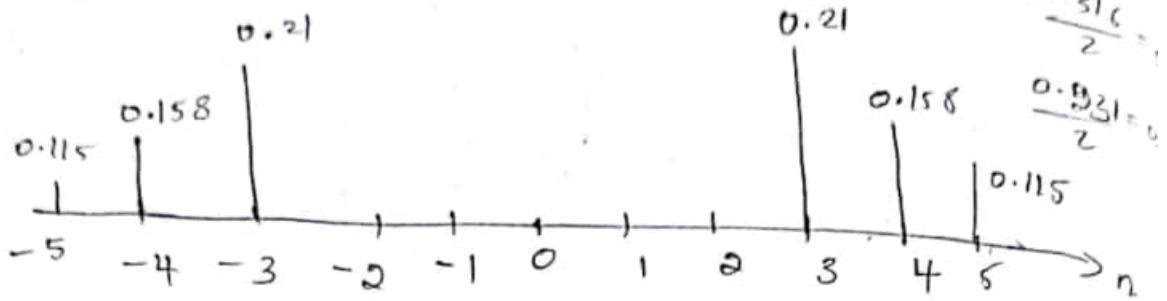
$0.75^3 \rightarrow$

$$x(n) = \begin{cases} (0.75)^n, & n \geq 0 \\ 0, & n < 0 \end{cases}$$

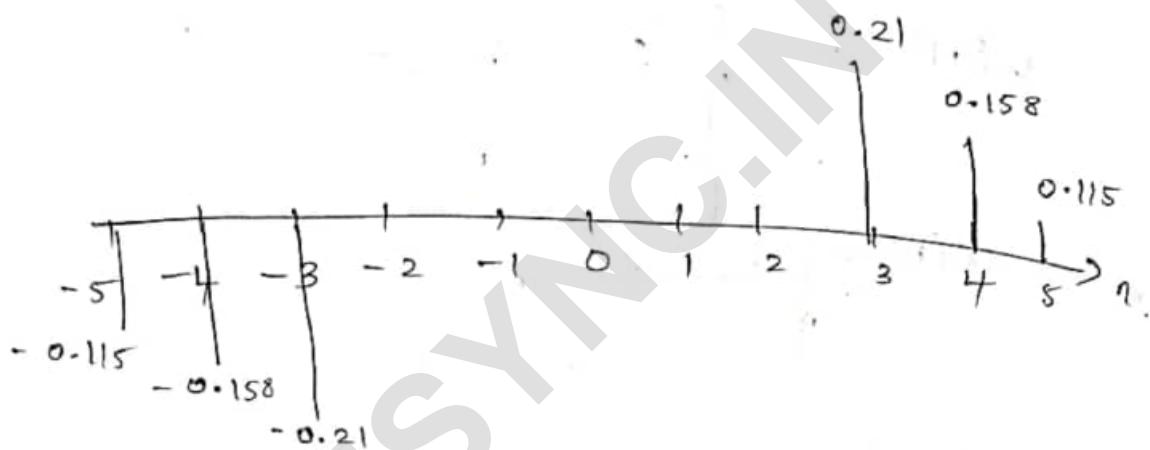
$$3 \times 4$$



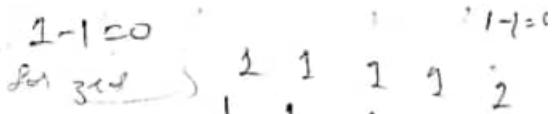
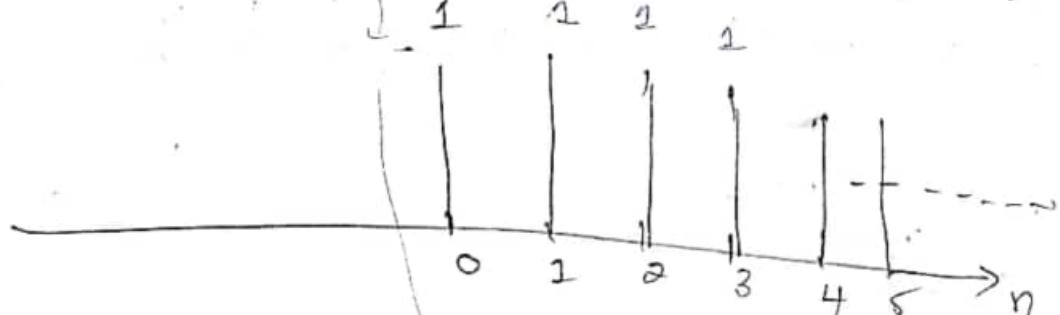
$$x_e(n) = \frac{1}{2} [x(n) + x(-n)]$$



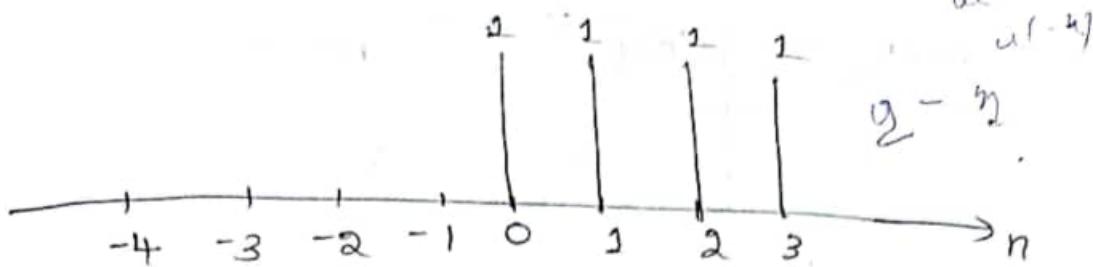
$$x_o(n) = \frac{1}{2} [x(n) - x(-n)]$$



⑦ $x(n) = u(n)(\downarrow_{-1}) u(n-4) \rightarrow \text{delay is 4}$
 So 4 shift

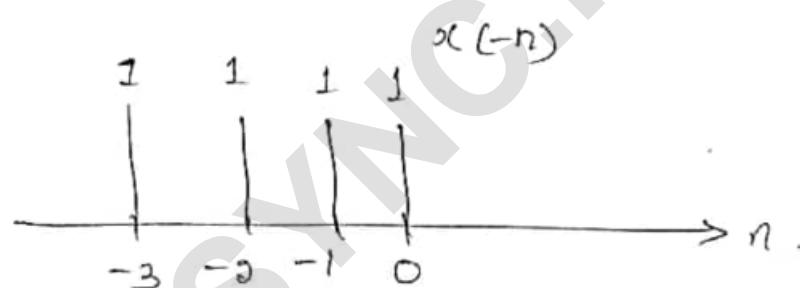
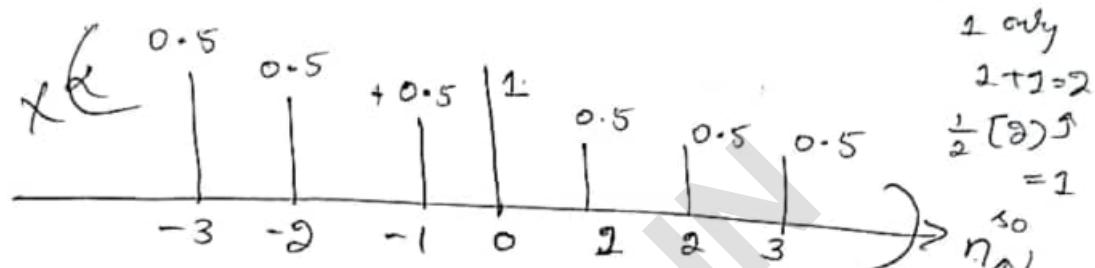


$$x(n) = u(n) - x(n-4)$$

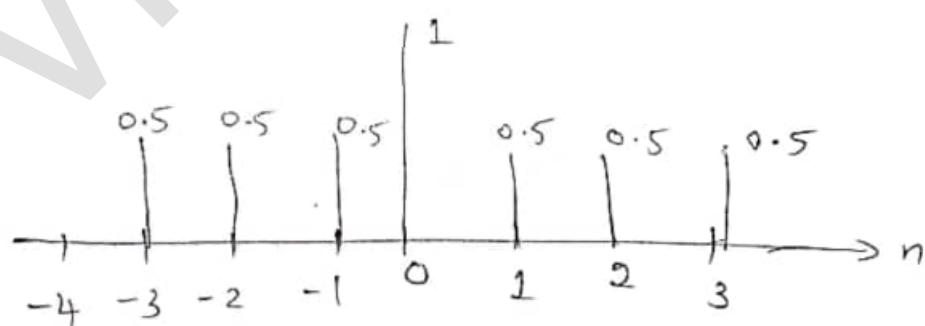


$$x(-n)$$

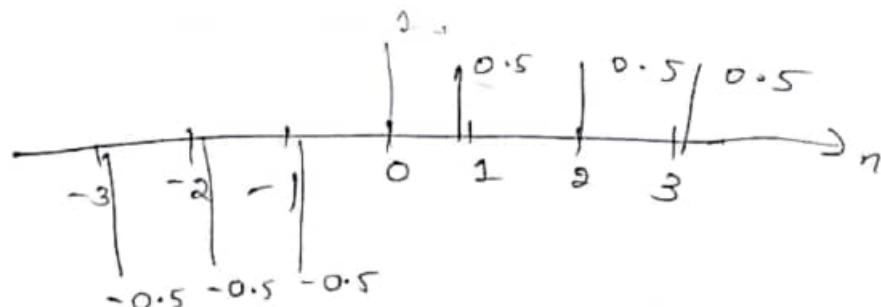
both 0 part



$$x_e(n) = \frac{1}{2} [x(n) + x(-n)]$$



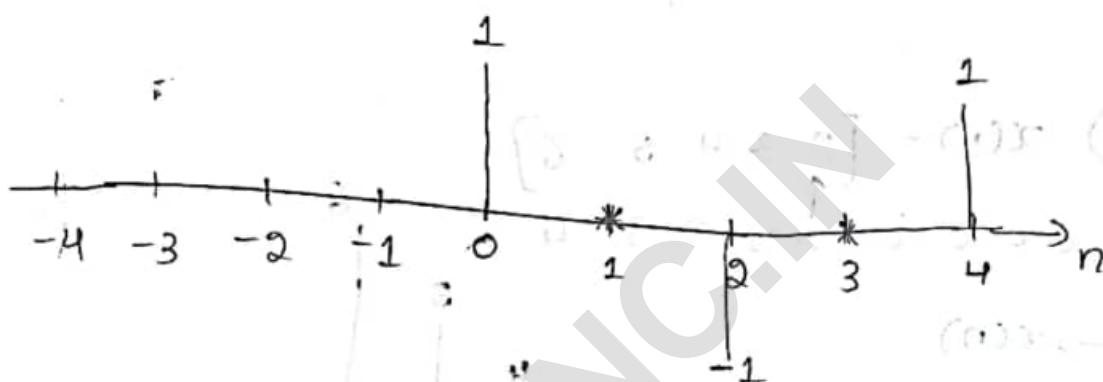
$$x_o(n) = \frac{1}{2} [x(n) - x(-n)]$$



$$f) x(n) = \cos\left(\frac{\pi}{2}n\right) u(n)$$

$$\text{sol: } x(n) = \cos\left(\frac{\pi}{2}n\right) u(n)$$

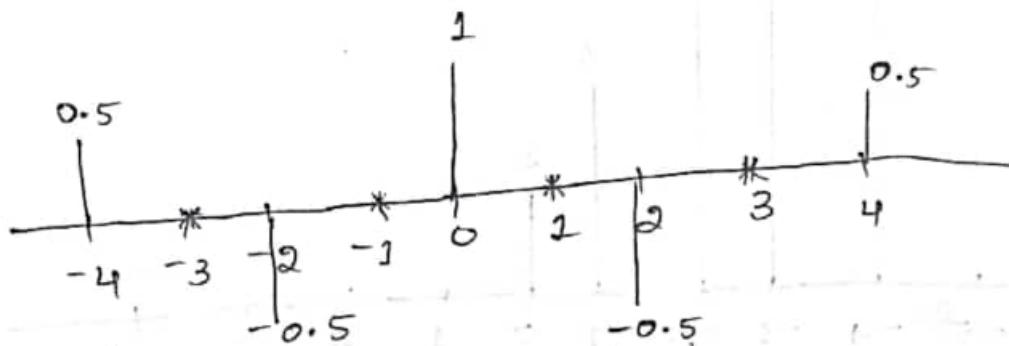
$$\begin{aligned} u(n) &= \begin{cases} 1 & n \geq 0 \\ 0 & n < 0 \end{cases} & \text{when } n = 0, 1, 2, 3, 4 \\ \rightarrow x(n) & \end{aligned}$$



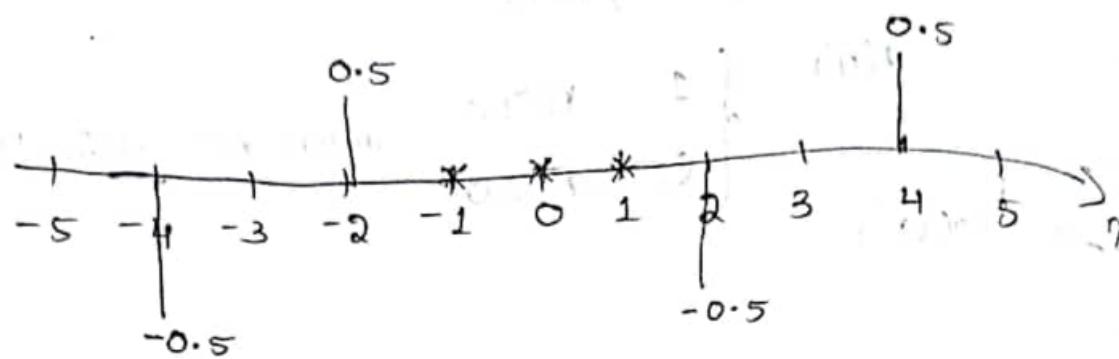
$$\rightarrow x(-n)$$



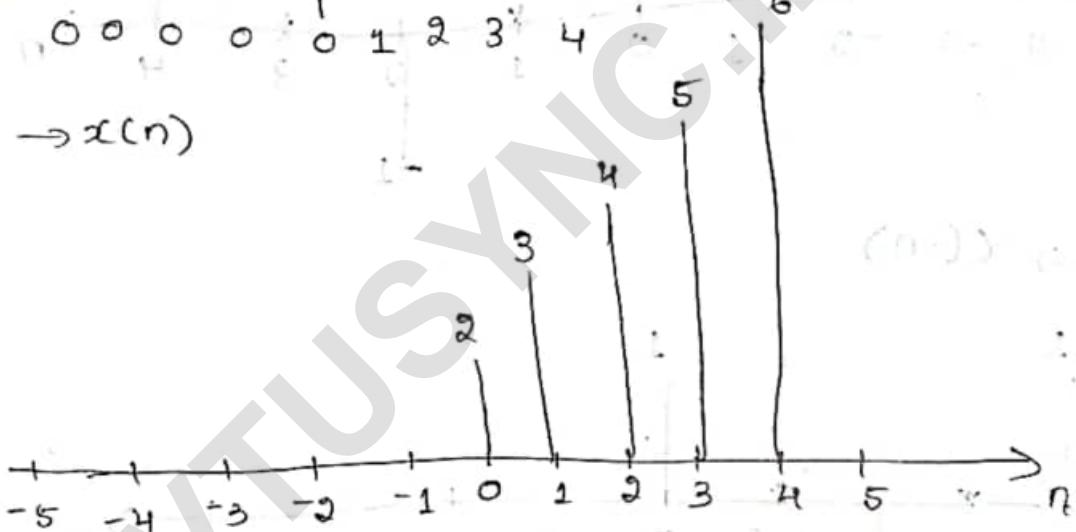
$$\rightarrow x_e(n) = \frac{1}{2} [x(n) + x(-n)]$$



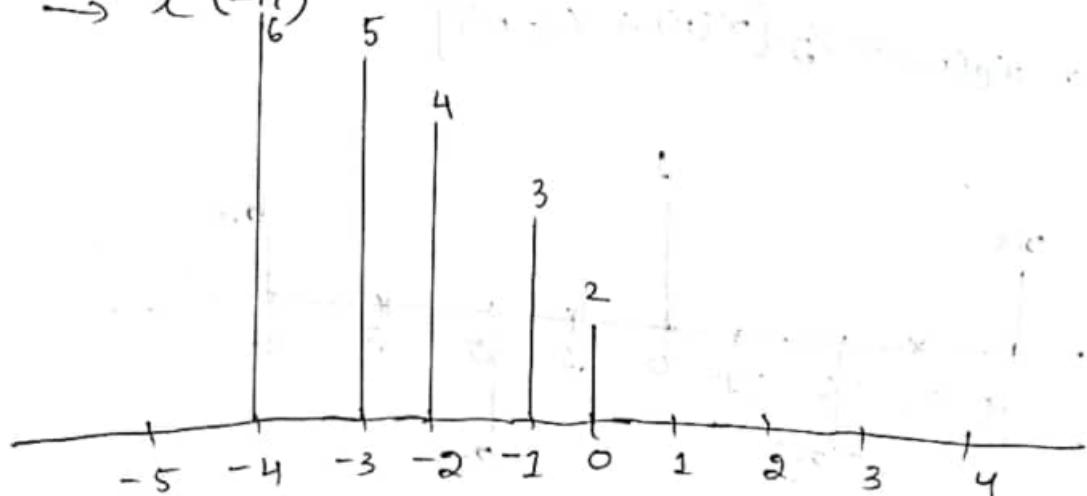
$$\rightarrow x_0(n) = \frac{1}{2} [x(n) - x(-n)]$$



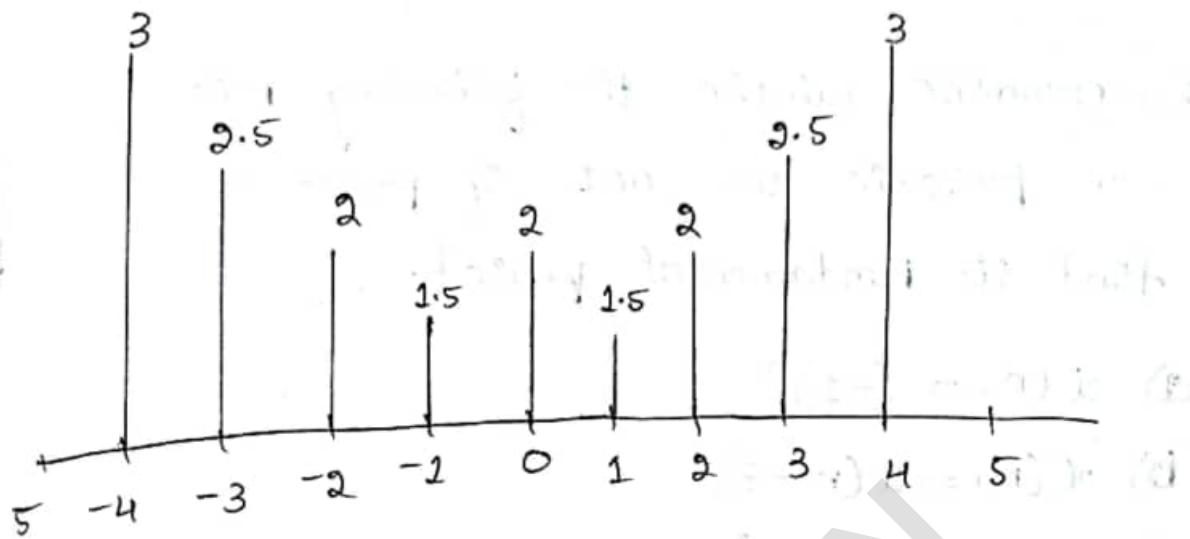
Q) $x(n) = [2 \ 3 \ 4 \ 5 \ 6]$



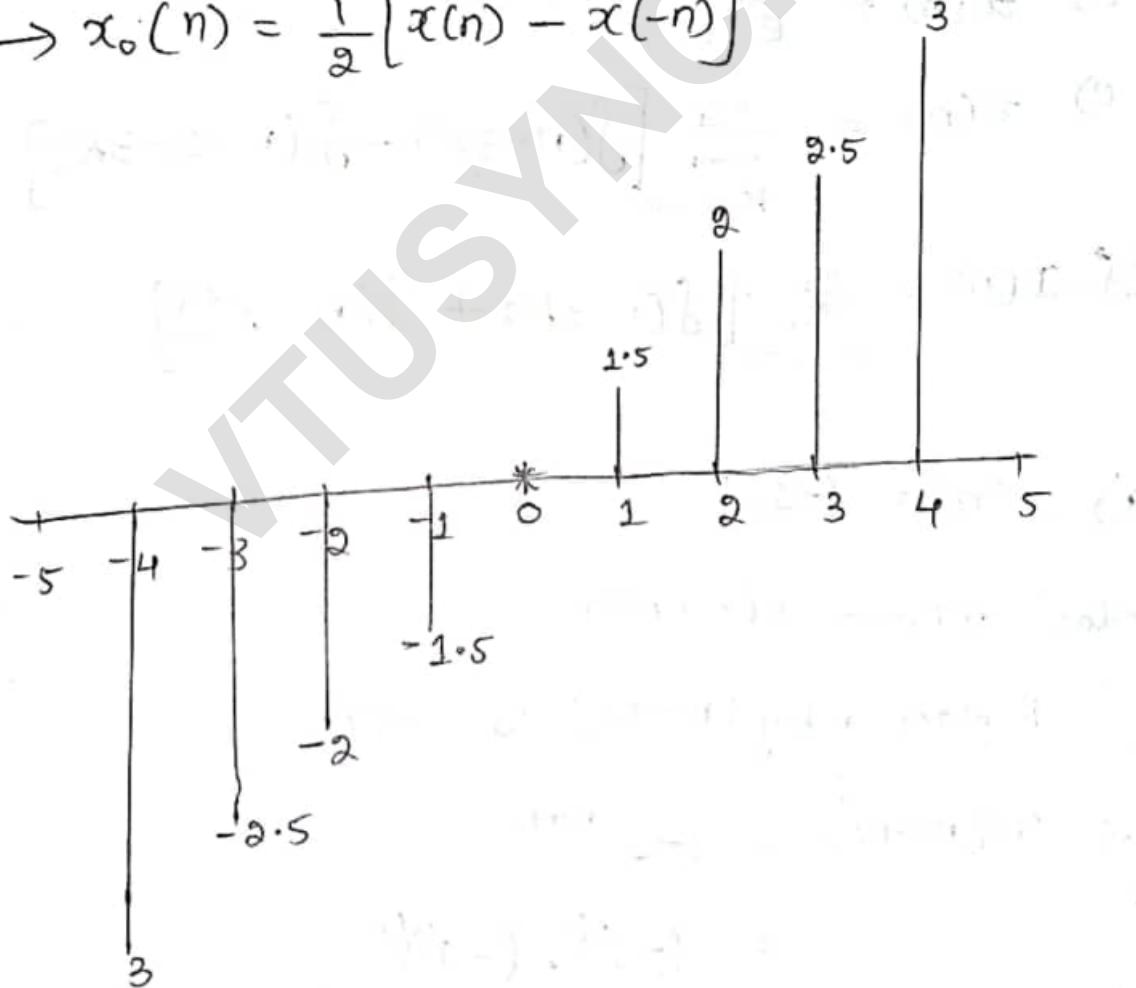
$$\rightarrow x(-n)$$



$$\rightarrow x_e(n) = \frac{1}{2} [x(n) + x(-n)]$$



$$\rightarrow x_o(n) = \frac{1}{2} [x(n) - x(-n)]$$



* Periodic and non-periodic DTs:

→ Problems:

- 1) Determine whether the following DTs
are periodic or not if periodic
find its fundamental period.

a) $x(n) = (-1)^n$

b) $x(n) = u(n-3)$

c) $x(n) = (-1)^{n^2}$

d) $x(n) = e^n$

e) $x(n) = \sum_{k=-\infty}^{\infty} [\delta(n-3k) - \delta(n-1-3k)]$

f) $x(n) = \sum_{k=-\infty}^{\infty} [\delta(n-3k) + \delta(n-k^2)]$

a) $x(n) = (-1)^n$

sln:- $x(n) = x(n+N)$

Replace n by $(n+N)$ in $x(n)$

i.e $x(n+N) = (-1)^{n+N}$

$$= (-1)^n \cdot (-1)^N$$

$$\therefore \text{if } (-1)^N = 1$$

$$\boxed{x(n+N) = x(n)}$$

$$\boxed{N = 2m}$$

$x(n) = (-1)^n$ is periodic when period =
where, $m = 0, 1, 2, 3, \dots, n$

$$b) x(n) = u(n-3)$$

$$\text{soln:- } x(n) = u(n-3)$$

$$x(n) = x(n+n)$$

Replace n by $n+n$

$$x(n+n) = x(u(n+n-3))$$

$$= n=0$$

Then, $x(n) = u(n-3)$

It satisfies when $n=0$ [fundamental period as zero] so, it is non-periodic DTS.

$$c) x(n) = (-1)^{n^2}$$

$$\text{soln:- } x(n) = (-1)^{n^2}$$

$$\Rightarrow x(n) = x(n+n)$$

replace n by $n+n$

$$x(n+n) = (-1)^{(n+n)^2} \Rightarrow (-1)^{n^2+2n+n^2}$$

$$= (-1)^{n^2} \cdot (-1)^{n^2} \cdot (-1)^{2n} \quad \because (-1)^{n^2} = 1$$

$$= (-1)^{n^2} \cdot (1) \quad [n=2m]$$

$$x(n+n) = (-1)^{n^2}$$

$$\boxed{x(n+n) = x(n)}$$

$$x(n) = (-1)^{n^2} \text{ is a periodic}$$

c) $x(n) = (-1)^{n^2}$

Soln: $x(n) = x(n+m)$

Replace n by $n+m$

$$x(n+m) = (-1)^{(n+m)^2}$$

$$= (-1)^{n^2+2mn+m^2}$$

$$= (-1)^{n^2} (-1)^{2mn+m^2}$$

$$= (-1)^{n^2} (-1)^{2mn+m^2} \because (-1)^{2mn+m^2} = 1$$

$$= x(n)$$

$$\boxed{2mn+m^2 = 2m}$$

$x(n) = (-1)^{n^2}$ is periodic when fundamental period $= 2m$

d) $x(n) = e^{an}$

Soln: $x(n) = x(n+m)$

Replace n by $n+m$ in $x(n)$

$$x(n+m) = e^{a(n+m)}$$

$$x(n+m) = e^{an} \cdot e^{am} \quad \text{when } m=0$$

$$x(n) = e^{an}$$

It satisfies when $n=0$, so it is non-periodic

$$\begin{aligned} n &= 3k \\ n &= \frac{n}{3} \\ e^{-n-3k} &= 1 \\ e^{-n} &= 3^k \\ n &= -\ln 3 \\ k &= \frac{n}{\ln 3} \end{aligned}$$

Q) $x(n) = \sum_{k=-\infty}^{\infty} [\delta(n-3k) - \delta(n-1-3k)]$

soln:- $x(n) = x(n+n)$

Replace n by $n+n$.

$$x(n+n) = \sum_{k=-\infty}^{\infty} [\delta(n+n-3k) - \delta(n+n-1-3k)]$$

or if $n=3$. [Take the coefficient of k], value

$$= \sum_{k=-\infty}^{\infty} \delta(n+3-3k) - \delta(n+3-1-3k)$$

$$= \sum_{k=-\infty}^{\infty} \delta(n-3(k-1)) - \delta(n-1-3(k-1))$$

$$\text{put } k-1 = m \Rightarrow k = m+1$$

$$= \sum_{k=-\infty}^{\infty} \delta(n-3m) - \delta(n-1-3m)$$

$$\therefore x(n) = \dots$$

$\therefore x(n)$ is periodic of period or fundamental period as $n=3$.

$$f) x(n) = \sum_{k=-\infty}^{\infty} [\delta(n-3k) + \delta(n-k^2)]$$

$x(n) = x(n+n)$

Soln.

$$x(n+n) = \sum_{k=-\infty}^{\infty} [\delta(n+n-3k) + \delta(n+n-k^2)]$$

if $n=0$

$$x(n) = \sum_{k=-\infty}^{\infty} [\delta(n-3k) + \delta(n-k^2)]$$

$$x(n) = \sum_{k=-\infty}^{\infty} [\delta(n-3k) + \delta(n-k^2)]$$

It satisfies when $n=0$ [fundamental period is zero]

So, It is non-periodic DTS.

* Show that a discrete time complex exponential signal

$x(n) = e^{\pm j\omega_0 n}$ is periodic
if and only if ω_0 is Rational multiple of 2π
(i.e. $\omega_0 = \frac{m}{n} 2\pi$)

Soln:- A DTS is periodic if
 $x(n) = x(n+n)$ for all n

$$\therefore x(n) = e^{\pm j\omega_0 n}$$

$$x(n+n) = e^{\pm j\omega_0 (n+n)}$$

$$= (e^{\pm j\omega_0 n})(e^{\cancel{\pm j\omega_0 n}})$$

$$\therefore e^{\pm j\omega_0 n} = [\cos \omega_0 n \pm j \sin \omega_0 n]$$

[Cos function with even multiple with π as $\pm j$]

Consider $\omega_0 n = m(2\pi)$ where, m is any

$$\boxed{\omega_0 = \frac{m}{n} 2\pi}$$

Integer

* problems :-

- * Determine whether the following DTS are periodic or not if periodic find its fundamental period.

$$1) x(n) = e^{j7\pi n}$$

$$2) x(n) = \cos(3\pi n)$$

$$3) x(n) = \cos(2n)$$

$$4) x(n) = 3e^{j3/5(n+1/2)}$$

$$5) x(n) = 3e^{j3/5\pi(n+1/2)}$$

$$5) x(n) = 3e^{j3/5\pi(n+1/2)}$$

$$1) x(n) = e^{j7\pi n}$$

Soln:- Given: $\omega_0 = 7\pi$

$$\omega_0 = \frac{7}{2}(2\pi)$$

$x(n)$ is periodic. The fundamental period is $n=2$.

$$2) x(n) = \cos(3\pi n) \rightarrow ①$$

Soln: Given:-

$$\omega_0 = 3\pi$$

w.k.t :- sinusoidal signal

$$x(n) = A \cos(\omega_0 n + \phi) \rightarrow ②$$

Compare eq ① and ②

$$\omega_0 = 3\pi$$

$$= \frac{3}{2} 2\pi \Rightarrow$$

$$\left[\omega_0 = \frac{m}{N} 2\pi \right]$$

$x(n)$ is periodic with fundamental period,

$$N = 2$$

$$\frac{3}{2} \cdot 2\pi$$

$$\frac{4}{3} \cdot 2\pi$$

$$3) x(n) = \cos(2n)$$

$$\text{Soln: } x(n) = \cos(2n)$$

w.k.t :-

$$x(n) = A \cos(\omega_0 n + \phi)$$

$\left\{ \begin{array}{l} \text{if } \omega_0 \text{ is} \\ \text{multiple with } \pi \\ \text{Then it is} \\ \text{periodic} \end{array} \right.$

$$\omega_0 = 2$$

$$\frac{2}{2} \cdot 2\pi = 2\pi$$

↓

$x(n)$ is non-periodic because $[\omega_0$ is not multiple with $\pi]$

$$4) x(n) = 3e^{\frac{3}{5}(n + \frac{1}{2})}$$

Soln: Given:-

$$x(n) = 3e^{\frac{3}{5}(n + \frac{1}{2})}$$

$$= 3 \left[e^{\frac{3}{5}n} \quad e^{\frac{3}{5}(\frac{1}{2})} \right]$$

$$\begin{aligned}
 &= 3 \left[e^{j\frac{3}{5}\pi n} \quad 3e^{j\frac{3}{10}\pi n} \right] \\
 &= 3 \left[e^{j\frac{3}{5}\pi n} \left(\cos 0.3 + j \sin 0.3 \right) \right] \\
 &= 3 \left[0.95 + j0.29 \right] e^{j\frac{3}{5}\pi n} \\
 &= [2.85 + j0.87] e^{j\frac{3}{5}\pi n}
 \end{aligned}$$

Here $\omega_0 = \frac{3}{5} \pi$ [ω_0 is not multiple with π]

$\therefore x(n)$ is non periodic.

$$\begin{aligned}
 5) x(n) &= 3e^{j\frac{3}{5}\pi(n+\frac{1}{2})} \\
 \text{Sol: } x(n) &= 3e^{j\frac{3}{5}\pi(n+\frac{1}{2})} \\
 &= 3 \left[e^{j\frac{3}{5}\pi n} \cdot e^{j\frac{3}{5}\pi \frac{1}{2}} \right] \text{ (O)} = 3e^{j\frac{3}{5}\pi n} e^{j\frac{3}{5}\pi \frac{1}{2}} \\
 &= 3 \left[e^{j\frac{3}{5}\pi n} \cdot e^{j\frac{3}{10}\pi} \right]
 \end{aligned}$$

Here $\omega_0 = \frac{3}{5}\pi$

$$\omega_0 = \frac{3}{5 \times 2} 2\pi$$

$\therefore x(n)$ is periodic. The fundamental period is

$$N = 10$$

$$\omega_0 = \frac{3}{10} 2\pi$$

$$\omega_0 = \frac{m}{n} 2\pi$$

$$N = 10$$

* Determine whether the following DTs are periodic or not and find its fundamental period.

$$1) x(n) = 5 \sin\left(\frac{7\pi}{12}n\right) + 8 \cos\left(\frac{14\pi}{8}n\right)$$

$$2) x(n) = \cos\left(\frac{\pi}{2}n\right) - \sin\left(\frac{\pi}{8}n\right) + 3 \cos\left(\frac{\pi}{4}n + \frac{\pi}{2}\right)$$

$$3) x(n) = 1 + e^{\frac{j4\pi}{7}n} - e^{\frac{j2\pi}{5}n}$$

Note: The sum of M periodic signals:

$$x_1(n), x_2(n), x_3(n), \dots, x_M(n)$$

is necessarily periodic, the following steps can be used to determine the period

1) Find the Lcm of fundamental period of M signals that is $n_1, n_2, n_3, \dots, n_m$
Then,

2) Then the period of some signal is given by

$$N = \text{LCM}(n_1, n_2, n_3, \dots, n_m)$$

$$\boxed{N=1}$$

$$1) x(n) = 5 \sin\left(\frac{7\pi}{12}n\right) + 8 \cos\left(\frac{14\pi}{8}n\right)$$

Sol: Given:-

$$x(n) = 5 \sin\left(\frac{7\pi}{12}n\right) + 8 \cos\left(\frac{14\pi}{8}n\right)$$

$$\omega_0 = \frac{7}{12} \pi$$

$$= \frac{7}{12 \times 2} 2\pi$$

$$= \frac{7}{24} 2\pi \Rightarrow \frac{m_1}{N_1} * 2\pi$$

$$\boxed{N_1 = 24}$$

$$\therefore \omega_0 = \frac{14}{8} \pi$$

$$= \frac{14}{16} 2\pi \Rightarrow \frac{m_2}{N_2} 2\pi$$

$$\rightarrow m_2 = \frac{7}{8} 2\pi$$

$$\boxed{N_2 = 8}$$

$$\text{LCM}(N_1, N_2) = l$$

$$\text{LCM}[24, 8] = 24$$

∴ Fundamental period of

$$x(n) = N = 24$$

$$g) x(n) = \cos\left(\frac{\pi}{2} n\right) - 5 \sin\left(\frac{\pi}{8} n\right) +$$

$$3 \cos\left(\frac{\pi}{4} n + \frac{\pi}{3}\right)$$

$$\omega_{01} = \frac{1}{2}\pi$$

$$\omega_{01} = \frac{1}{2 \times 2} 2\pi \Rightarrow \frac{m_1}{n_1} 2\pi$$

$$\omega_{01} = \frac{1}{4} 2\pi$$

$$n_1 = 4 \quad \checkmark$$

$$\omega_{02} = \frac{\pi}{8}$$

$$\omega_{02} = \frac{1}{8}\pi$$

$$= \frac{1}{8 \times 2} 2\pi$$

$$= \frac{1}{16} 2\pi$$

$$n_2 = 16 \quad \checkmark$$

$$n_3 = \omega_{03} = \frac{1}{4}\pi =$$

$$\omega_{03} = \frac{1}{4 \times 2} 2\pi$$

$$= \frac{1}{8} 2\pi \Rightarrow \frac{m_3}{n_3}$$

$$n_3 = 8$$

$$\text{LCM } (n_1, n_2, n_3) = 16$$

$$\text{LCM } (4, 16, 8) = 16 = n$$

\therefore Fundamental Period of $x(n) = n = 16$

$$\begin{array}{r} 2 | 4, 16, 8 \\ 2 | 2, 8, 4 \\ 2 | 1, 4, 2 \\ 2 | 1, 2, 1 \\ \hline & & 1, 1, 1 \end{array}$$

$$3) x(n) = 1 + e^{\frac{j}{7}n} - e^{\frac{j}{5}n}$$

Soln:- Given:-

$$x(n) = 1 + e^{\frac{j}{7}n} - e^{\frac{j}{5}n}$$

$$\omega_0 = \frac{4}{7}$$

$$\omega_0 = \frac{4\pi}{7} \Rightarrow \frac{m_1}{N_1} 2\pi$$

$$\omega_0 = \frac{4}{7} 2\pi$$

$$= \frac{4}{7 \times 9} 2\pi$$

$$= \frac{4}{147} 2\pi$$

$$\omega_0 = \frac{2}{7} 2\pi$$

$$N_1 = 7$$

$$\omega_0 = \frac{2\pi}{5}$$

$$\omega_0 = \frac{2}{5} \pi$$

$$= \frac{2}{5} 2\pi \Rightarrow \frac{m_2}{N_2} 2\pi \quad \text{LCM.}$$

$$= \frac{2}{5 \times 9} 2\pi$$

$$= \frac{2}{45} 2\pi$$

$$\begin{array}{r} 7 \\ 5 \\ \hline 1 \end{array}$$

$$7 \times 5 = 35$$

$$N_2 = 5$$

$$\text{LCM}(N_1, N_2) = l$$

$$\text{LCM}[7, 5] = 35$$

\therefore Fundamental period of $x(n) = N = 35$

* check whether the following discrete time signals are energy or power signals

a) $x(n) = 1 ; |n| \leq 1$

b) $x(n) = n ; 0 \leq n \leq 5$

$$10-n ; 5 < n \leq 10$$

0 ; otherwise.

c) $x(n) = A\delta(n)$

d) $x(n) = A$

e) $x(n) = u(n)$

f) $x(n) = nu(n)$

g) $x(n) = \cos(\pi n) ; -4 \leq n < 4$
0 ; otherwise

a) $x(n) = 1 ; |n| \leq 1$

Soln:- $x(n) = 1 ; |n| \leq 1$

$$x(n) = 1 ; -1 \leq n \leq 1$$

w.k.t:

$$\text{Energy } E = \sum_{n=-\infty}^{\infty} |x(n)|^2$$

$$= \sum_{n=-1}^{1} |x(n)|^2$$

Substitute n value in above

$$\begin{aligned}
 &= |x(-1)|^2 + |x(0)|^2 + |x(1)|^2 \\
 &= 1^2 + 1^2 + 1^2 \\
 &= 3 \text{ It is finite.}
 \end{aligned}$$

$x(n) = 1 ; |n| \leq 1$, is an energy signal.

b) $x(n) = n ; 0 \leq n \leq 5$
 $10-n ; 5 < n \leq 10$.
 $0 ; \text{otherwise.}$

Soln:- $x(n) = n ; 0 \leq n \leq 5$

$$x(n) = \begin{cases} n, & 0 \leq n \leq 5 \\ 10-n, & 5 < n \leq 10 \\ 0, & \text{otherwise.} \end{cases}$$

n	$x(n)$
0	0
1	1
2	2
3	3
4	4
5	5
6	4 (10 - n)
7	3
8	2

$$w.l.o.t:- E = \sum_{n=-\infty}^{\infty} |x(n)|^2$$

$$E = \sum_{n=0}^{10} |x(n)|^2$$

$$E = 0^2 + 1^2 + 2^2 + 3^2 + 4^2 + 5^2 + 4^2 + 3^2 + 2^2 + 1^2 + 0^2$$

$$E = 0 + 1 + 4 + 9 + 16 + 25 + 16 + 9 + 4 + 1$$

$$E = 85 < \infty \rightarrow \text{Finite}$$

Hence $x(n)$ is Energy signal

$$\begin{array}{r} 25 \\ 16 \\ 16 \\ \hline 16 \\ 75 \\ 5 \\ \hline 85 \end{array}$$

$$c) x(n) = A \delta(n)$$

Soln:- Given:-

$$x(n) = A \delta(n), \quad \delta(n) = \begin{cases} 1, & n=0 \\ 0, & \text{otherwise} \end{cases} \rightarrow A$$

$$\delta(n) = \begin{cases} 1, & n=0 \\ 0, & \text{otherwise} \end{cases}$$

$$x(n) = \begin{cases} A & n=0 \\ 0 & \text{otherwise} \end{cases}$$

w.l.o.t:-

$$E = \sum_{n=-\infty}^{\infty} |x(n)|^2 \quad \therefore \text{Finite}$$

$$= \sum_{n=0}^{\infty} |x(n)|^2 \quad \text{Hence } x(n) \text{ is Energy signal}$$

$$\boxed{E = A^2} \Rightarrow E = A^2 < \infty$$

$$d) x(n) = A$$

Sols:- Given :-

$$x(n) = A$$

w.k.t T :-

$$E = \lim_{n \rightarrow \infty} \sum_{n=-\infty}^{\infty} |x(n)|^2$$

$$E = \lim_{N \rightarrow \infty} \sum_{n=-N}^{N} |x(n)|^2$$

$$E = \lim_{N \rightarrow \infty}$$

$$E = \lim_{N \rightarrow \infty} \sum_{n=-N}^{N} A^2$$

$$E = A^2 \lim_{N \rightarrow \infty} \left[\sum_{n=-N}^{N} 1 \right] \cdot \left[\sum_{n=-N}^{N} 1 = 2N+1 \right]$$

$$E = A^2 \lim_{N \rightarrow \infty} (2N+1)$$

$$\boxed{E = \infty} \rightarrow \text{Infinite}$$

$x(n)$ is not Energy signal.

→ Power of DTS is given by

$$P = \lim_{N \rightarrow \infty} \frac{1}{2N+1} \sum_{n=-N}^{N} |x(n)|^2 \quad P = \lim_{N \rightarrow \infty} \frac{1}{2N+1}$$

$$P = \lim_{N \rightarrow \infty} \frac{1}{2N+1} \sum_{n=-N}^{N} A^2$$

$$= A^2 \lim_{N \rightarrow \infty} \frac{1}{2N+1} \sum_{n=-N}^{N} 1 \quad \therefore P = A^2 < \infty$$

$$= A^2 \lim_{N \rightarrow \infty} \frac{1}{2N+1} (2N+1) \quad \text{Hence } x(n) \text{ is power signal}$$

$$= \lim_{N \rightarrow \infty} 1$$

e) $x(n) = u(n)$

$$\left. \begin{array}{l} n \\ 0 \end{array} \right\} \rightarrow N+1$$

soln: $x(n) = u(n)$

$$\left. \begin{array}{l} n \\ -N \end{array} \right\} \rightarrow 2N+1$$

$$u(n) = \begin{cases} 1 & n \geq 0 \\ 0 & n < 0 \text{ or otherwise.} \end{cases}$$

w.k.t:

$$E = \lim_{N \rightarrow \infty} \sum_{n=-\infty}^{\infty} |x(n)|^2$$

$$E = \lim_{N \rightarrow \infty} \sum_{n=0}^{N} |x(n)|^2$$

$$E = \lim_{N \rightarrow \infty} \sum_{n=0}^{N} 1$$

$$\boxed{E = \infty}$$

Hence $x(n)$ is not a Energy signal.

power:

$$= \lim_{N \rightarrow \infty} \frac{1}{2N+1} \sum_{n=-N}^{N} |x(n)|^2$$

$$= \lim_{N \rightarrow \infty} \frac{1}{2N+1} \sum_{n=0}^{\infty} 1$$

$$= \lim_{N \rightarrow \infty} \frac{1}{2N+1} (N+1)$$

$$\boxed{P = \infty}$$

neither En nor power

$$\therefore x(n) = n u(n)$$

Soln:- Given :-

$$x(n) = n u(n)$$

$$u(n) = \begin{cases} 1 & n \geq 0 \\ 0 & n < 0 \end{cases} \Rightarrow x(n) = \begin{cases} n & n \geq 0 \\ 0 & n < 0 \end{cases}$$

$$x(n) = \begin{cases} n & n \geq 0 \\ 0 & n < 0 \end{cases}$$

w.r.t T:-

$$E = \lim_{N \rightarrow \infty} \sum_{n=-\infty}^{\infty} |x(n)|^2$$

$$E = \lim_{N \rightarrow \infty} \sum_{n=0}^{\infty} n^2$$

$$E = \lim_{N \rightarrow \infty} \sum_{n=0}^{\infty} n^2$$

$$E = n^2 \lim_{N \rightarrow \infty} \sum_{n=0}^N 1 \quad : \quad \sum_{k=1}^N k^2 = \frac{n(n+1)(2n+1)}{6}$$

$$E = n^2 \lim_{N \rightarrow \infty} n(n+1) \rightarrow 0^2 + \sum_{n=1}^N n^2$$

$$= \lim_{N \rightarrow \infty} \frac{n(n+1)(2n+1)}{6}$$

$E = \infty$ → Infinite not an energy signal

w.r.t

$$P = \lim_{N \rightarrow \infty} \frac{1}{2N+1} \sum_{n=-N}^{N+1} |x(n)|^2$$

$$= \lim_{N \rightarrow \infty} \frac{1}{2N+1} \sum_{n=0}^{N+1} n^2$$

$$= n \lim_{N \rightarrow \infty} \frac{1}{2n+1} \sum_{n=0}^N 1$$

$$= n^2 \lim_{N \rightarrow \infty} \frac{1}{2n+1} (N+1) = \frac{n(n+1) \times (2n+1)}{6}$$

$\boxed{P = \infty}$ $x(n)$ signal neither Energy nor power

g) $x(n) = \cos(\pi n) ; -4 \leq n \leq 4$
 $0 ; \text{otherwise.}$

soh: Given:-

$$x(n) = \begin{cases} \cos(\pi n) & ; -4 \leq n \leq 4 \\ 0 & ; \text{otherwise.} \end{cases}$$

w.k.t. T:-

$$E = \sum_{n=-\infty}^{\infty} |x(n)|^2$$

$$E = \sum_{n=-4}^{4} |x(n)|^2 \quad n = -4, -3, -2, -1, 0, 1, 2, 3$$

n	x(n)	even = 1	odd = -1
-4	$\cos(-4\pi) = 1$		
-3	$\cos(-3\pi) = -1$		
-2	$\cos(-2\pi) = 1$		
-1	$\cos(-\pi) = -1$		
0	$\cos(0\pi) = 1$		
1	$\cos(\pi) = -1$		
2	$\cos(2\pi) = 1$		
3	$\cos(3\pi) = -1$		
4	$\cos(4\pi) = 1$		

$$= |x(-4)|^2 + |x(-3)|^2 + |x(-2)|^2 + |x(-1)|^2 + \\ |x(0)|^2 + |x(1)|^2 + |x(2)|^2 + |x(3)|^2.$$

$$= 1^2 + (-1)^2 + 1^2 + (-1)^2 + 1^2 + (-1)^2 + \\ 1^2 + (-1)^2 + 1^2$$

$$= 1 + 1 + 1 + 1 + 1 + 1 + 1 + 1 = 8$$

$$E = 9$$

$$E = 9 < \infty \rightarrow \text{Finite}$$

Hence, $x(n)$ is Energy Signal. //

h) Find the energy of the sequence $x(n) =$
 $x(n) = \left(\frac{1}{2}\right)^n; n \geq 0$

h) soln:- Given :-

$$x(n) = \begin{cases} \left(\frac{1}{2}\right)^n & ; n \geq 0 \\ 0 & ; \text{otherwise} \end{cases}$$

w.k.t. T :-

$$E = \sum_{n=-\infty}^{\infty} |x(n)|^2$$

$$= \sum_{n=-\infty}^{\infty} \left| \left(\frac{1}{2}\right)^n \right|^2$$

$$= \sum_{n=0}^{\infty} \left(\frac{1}{4} \right)^n$$

$$= \frac{1}{1 - \frac{1}{4}}$$

$$E = \frac{1}{\frac{4-1}{4}} = \frac{1}{\frac{3}{4}} = \frac{4}{3}.$$

i) Determine whether the given signal

$$x(n) = \begin{cases} 3(-1)^n & ; n \geq 0 \\ 0 & ; \text{otherwise} \end{cases} \quad \text{power } \textcircled{a_2}$$

Soln: - Given:-

$$x(n) = \begin{cases} 3(-1)^n; & n \geq 0 \\ 0, & \text{otherwise} \end{cases}$$

$$E = \lim_{N \rightarrow \infty} \sum_{n=-\infty}^{\infty} |x(n)|^2$$

$$= \lim_{n \rightarrow \infty} \left| \sum_{n=-\infty}^{\infty} 3(-1)^n \right|^2$$

$$= \lim_{n \rightarrow \infty} \sum_{k=1}^n [3(-1)^k]^2$$

$$= \lim_{n \rightarrow \infty} \sum_{n=1}^{\infty} q((-1)^2)^n$$

$$= \lim_{n \rightarrow \infty} \sum_{r=0}^{\infty} q(1)$$

$$= q \lim_{n \rightarrow \infty} \sum_{j=0}^{2^n-1} M^2$$

$$= q \lim_{n \rightarrow \infty} (n+1)$$

$$= 9 (\infty^+)$$

$$t = \infty \quad \text{Infinite}$$

It is not a Energy signal

* power signal

$$P = \lim_{n \rightarrow \infty} \frac{1}{2n+1} \sum_{m=-n}^n x(n)^2.$$

$$= \lim_{n \rightarrow \infty} \frac{1}{2n+1} \sum_{n=0}^N [3(-1)]^2.$$

$$= \lim_{n \rightarrow \infty} \frac{1}{2n+1} \sum_{n=0}^N q(1)$$

$$= \lim_{n \rightarrow \infty} \frac{1}{2n+1} \sum_{n=0}^N q$$

$$= q \lim_{n \rightarrow \infty} \frac{1}{2n+1} \sum_{n=0}^N 1$$

$$= q \lim_{n \rightarrow \infty} \frac{1}{2n+1} (n+1)$$

$$P = q(\infty + 1)$$

$$\boxed{P = \infty}$$

∴ It is neither Energy nor power.

* Discrete Time Systems :-

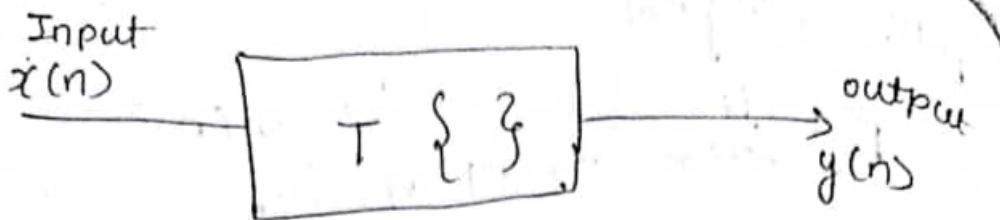
One more discrete time signals as a input

modified according to a desired manner

we will get o/p in the form of

discrete sequence (discrete signal) is called

DT System.



$$y(n) = T \{ x(n) \}$$

$$y(n) = T \{ x_1(n) \} + T \{ x_2(n) \}$$

$$y(n) = y_1(n) + y_2(n)$$

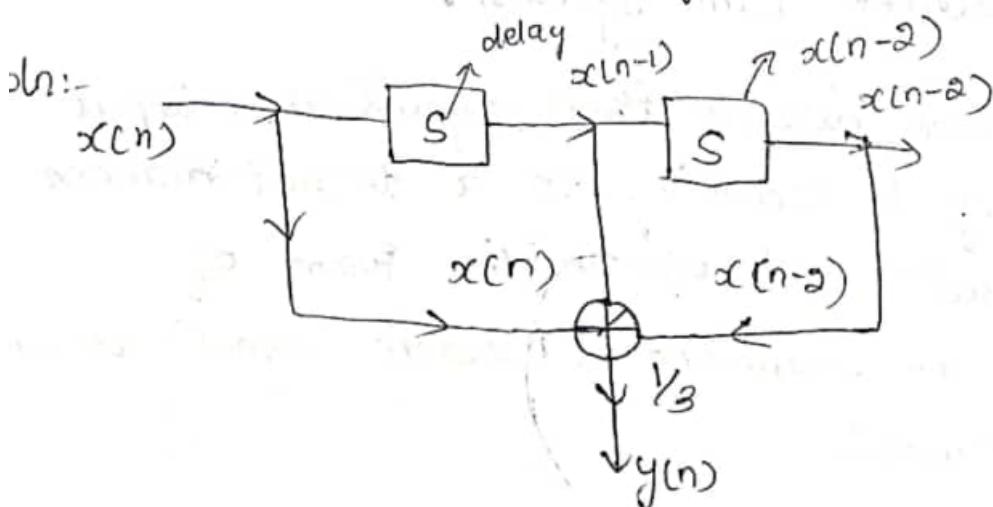
Consider a DT system represented by a operator T . And input signal $x(n)$ applied to discrete time system results in an output signal $y(n)$ described as

$$y(n) = T \{ x(n) \}$$

Example :- i) Find the overall operator of system whose o/p signal $y(n)$ is given by

$$y(n) = \frac{1}{3} [x(n) + x(n-1) + x(n-2)]$$

also draw the block diagram representation.

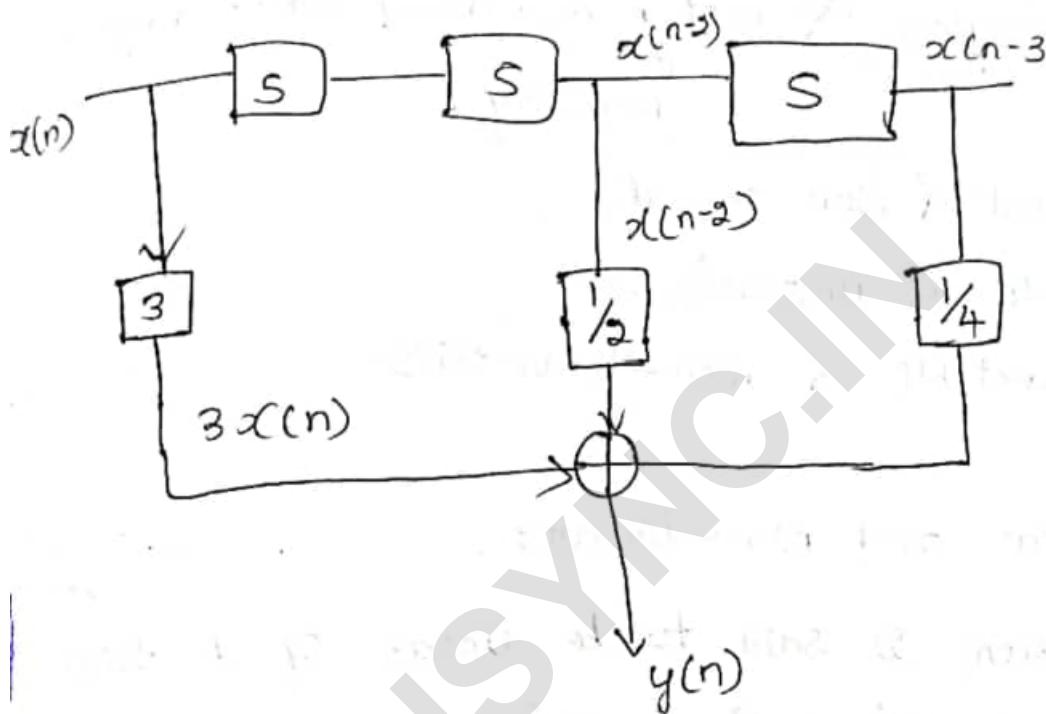


g) Find the general operation of a system whose O/P signal $y(n)$ is given by

$$y(n) = 3x(n) + \frac{1}{2}x(n-1) + \frac{1}{4}x(n-2)$$

Soln:- Given :-

$$y(n) = 3x(n) + \frac{1}{2}x(n-1) + \frac{1}{4}x(n-2)$$



3) A system consist of several sub-system connected as shown in figure below

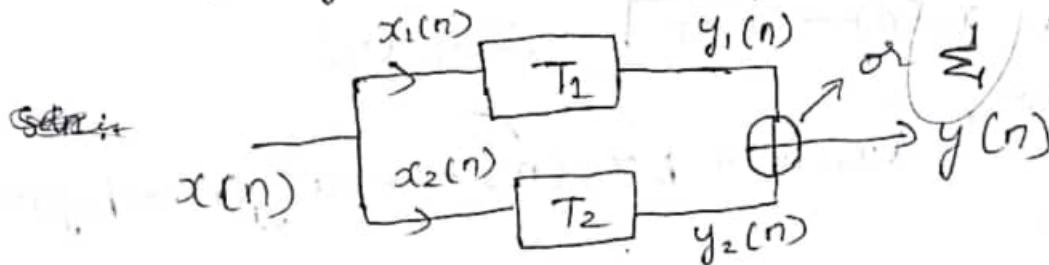
Find the operator T relating $x(n)$ to $y(n)$

for the sub system operators is given by

$$T_1 = y_1(n) = x_1(n)x_1(n-1)$$

$$T_2 = y_2(n) = |x_2(n)|$$

Soln:-



$$\text{soln: } y(n) = x_1(n)x_1(n-1)$$

* properties / classification system :-

- 1) Linear and non-linear
- 2) Time invariant & variant
- 3) Memoryless & not memoryless / static & dynamic
 memory
- 4) Causal & non-causal
- 5) Stable & unstable
- 6) Invertible & non-Invertible

1) Linear and non-linear :-

A system is said to be linear if it satisfies the principle of Superposition.

i.e If an input consist of the weighted sum of several signals then the o/p is weighted sum of the responses of the system, is called principle of Superposition.

$$\text{If } x_1(n) \rightarrow \boxed{T} \rightarrow y_1(n)$$

$$\text{& } x_2(n) \rightarrow \boxed{T} \rightarrow y_2(n)$$

Then, $ax_1(n) + bx_2(n) \rightarrow a y_1(n) + b y_2(n)$

→ Non linear system is said to be non-linear if it's not satisfies the principle of superposition

2) Time Invariant & Variant

→ Time Invariant :- A time invariant system is one in which a time shift of the input signal causes the a corresponding time shift in the output signal.

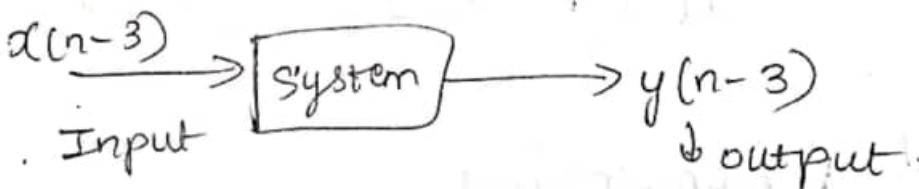
The shift may be advance or delay.

$$\text{If } x(n) \rightarrow y(n)$$

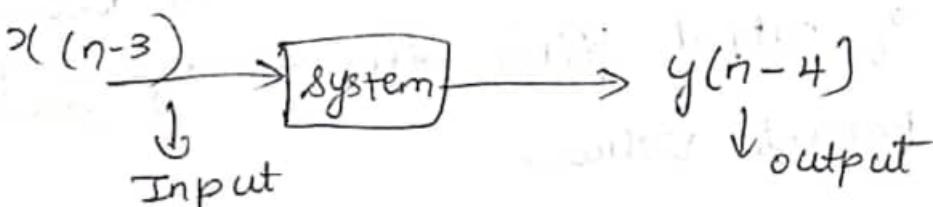
$$\text{Then, } x(n) - x(n-n_0) \rightarrow y(n-n_0)$$

→ Variant :- If it is not satisfies the time invariant condition that type of systems are called time variant

Ex:- For time Invariant

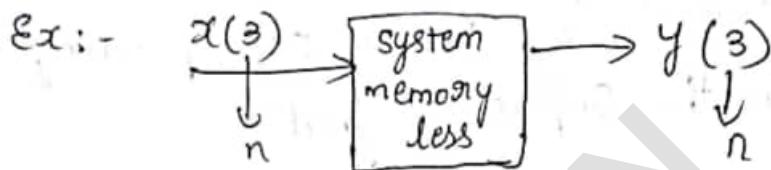


Ex:- for time Variant

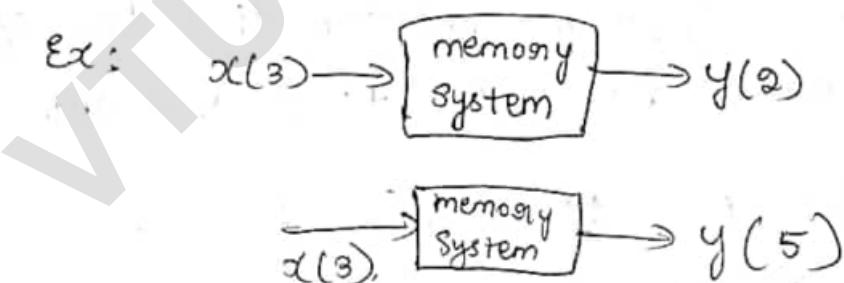


3) Memory less and ~~non~~ dynamic or memory

- Memory less / mem :- A discrete time signal is referred to as if the output $y(n)$ at every value of 'n' depends on the input $x(n)$ at the same value of n .



→ Not memory less :- A system is said to be not memory less (memory/dynamic) memory if its output depends on past and/or future values of input.

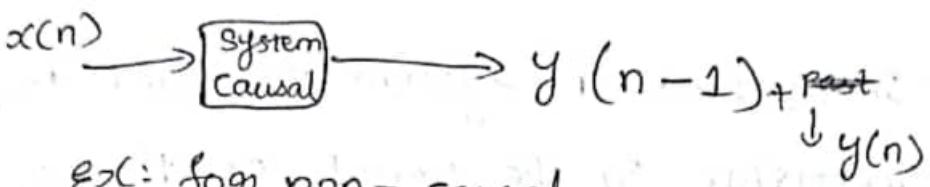


4) causal & Non-causal :- A discrete time signal is said to be causal if present value of output $y(n)$ depends only on past or present values.

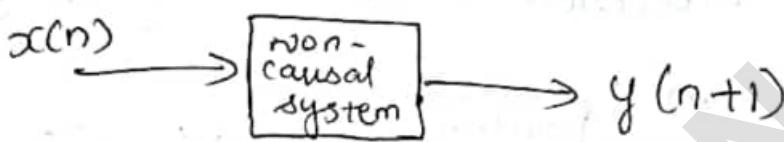
→ If it not satisfies the causal condition the system is called as non-causal

A system is said to be non-causal if present value of output $y(n)$ depends on future value of Input $x(n)$.

Ex: for causal condition



Ex: for non-causal.



5) Stable and unstable:-

→ stable :- A system is said to be stable then bounded input $x(n)$ with respect to output $y(n)$ is finite quantity (bounded).

$$\text{Ex: } -3 < x(n) < 3 \rightarrow -3 < y(n) < 3$$

$\underbrace{2.5}_{\text{2.5}} \rightarrow 1$

→ unstable :- If it is not satisfies the stable condition that is bounded input of bounded output that type of systems are called unstable.

$$\text{Ex: } -3 < x(n) < 3 \rightarrow -3 < y(n) < 3$$

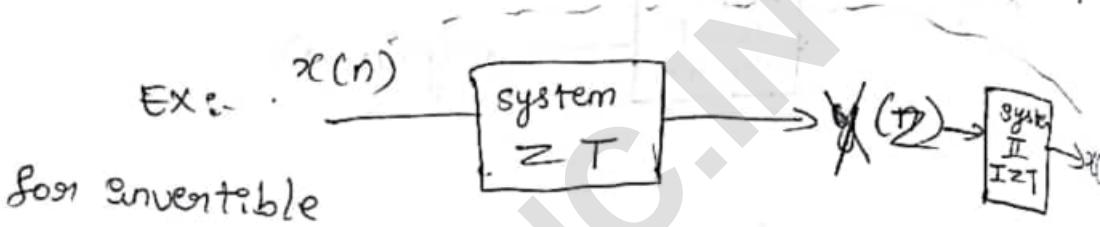
$\underbrace{2.5}_{\text{2.5}} \rightarrow 5$

Amplitude.

6) Invertible & non-invertible

→ Invertible :- A system is said to be invertible if the input of the system can be recovered from the system output.

→ Non-invertible :- A system is said to be non-invertible if the input of the system cannot be recovered from the system output.



* Ex: for non-invertible:-

* Problem : Based on properties of classification DTS

1) For the following DTS whether the system is

i) Linear ii) Time Invariance

iii) memoryless iv) causal v) stable.

a) $y(n) = n x(n)$

b) $y(n) = x(-n)$

c) $y(n) = x(2n)$

d) $y(n) = x^2(n)$

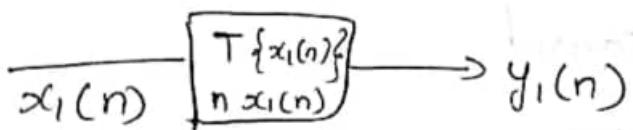
$$a) y(n) = n x(n)$$

soln:-

i) Linear :

$$\text{if } x_1(n) \rightarrow y_1(n)$$

$$\text{if } x_2(n) \rightarrow y_2(n)$$



$$x_2(n) \xrightarrow{T\{x_2(n)\}} y_2(n) = n x_2(n)$$

Then,

$$a x_1(n) + b x_2(n) \rightarrow a y_1(n) + b y_2(n)$$

$$a x_1(n) + b x_2(n) \rightarrow T\{a x_1(n) + b x_2(n)\}$$

$$\rightarrow T\{a x_1(n)\} + T\{b x_2(n)\}$$

$$\rightarrow a T\{x_1(n)\} + b T\{x_2(n)\}$$

$$\rightarrow a n x_1(n) + b n x_2(n)$$

$$a x_1(n) + b x_2(n) \rightarrow a y_1(n) + b y_2(n)$$

∴ Given system is linear.

ii) Time invariant / variant :-

$$\text{if } n \rightarrow n - n_0$$

$$y(n - n_0) = n - n_0 x(n - n_0)$$

$$y(n - n_0) = \tilde{n} x(n - n_0)$$

↪ Variant

Given system is \equiv Time variant

iii) memory less / memory

$$y(n) = n x(n)$$

∴ Given system is memoryless

iv) causal / non-causal

$$y(n) = n x(n)$$

∴ Given system is or A system output depends on present value of Input hence given system is causal.

v) stable / un-stable :-

$$y(n) = n x(n)$$

If n is finite quantity

Then given system is stable.

b) $y(n) = x(-n)$

i) linear :

$$\text{If } y_1(n) = T \{x_1(n)\} = x_1(-n)$$

$$y_2(n) = T \{x_2(n)\} = x_2(-n)$$

$$y(n) = T \{ax_1(n) + bx_2(n)\}$$

$$\begin{aligned}
 &= T \{ax_1(n) + bx_2(n)\} \\
 &= Tax_1(n) + Tb x_2(n) \\
 &= aT\{x_1(n)\} + bT\{x_2(n)\} \\
 &= a x_1(-n) + b x_2(-n). \\
 y(n) &= a y_1(n) + b y_2(n).
 \end{aligned}$$

Hence it is linear.

ii) Time variant/variant

Given :- $y(n) = x(-n)$

$$n \rightarrow n - n_0$$

$$y(n) = x(-(n - n_0))$$

$$y(n - n_0) = x(-n + n_0)$$

$$\text{Ex: } n = 2, \text{ & } n_0 = 3.$$

$$\begin{array}{r}
 2-3 \\
 -1 \\
 +2 \\
 \hline
 3
 \end{array}$$

∴ Given system is variant

iii) Memory less / memory.

$$y(n) = x(-n)$$

∴ It is memory system.

iv) Causal / Non-Causal.

$$y(n) = x(-n) \quad \text{Ex: } n = -3.$$

∴ Non causal.

v) Stable & unstable.

If $n \rightarrow \infty$, $y(n) = x(-n)$

If n is finite quantity

Then given system is stable

c) $y(n) = x(2n)$

i) Linear:

$$y_1(n) = \{T x_1(n)\} = x_1(2n)$$

$$y_2(n) = \{T x_2(n)\} = x_2(2n)$$

$$y(n) = T \{ax_1(n) + bx_2(n)\}$$

$$= T\{ax_1(n)\} + T\{bx_2(n)\}$$

$$= aT\{x_1(n)\} + bT\{x_2(n)\}$$

$$= ax_1(2n) + bx_2(2n)$$

$$y(n) = a y_1(n) + b y_2(n).$$

∴ Hence it is linear

ii) Time invariant / variant

Given: $y(n) = x(2n)$

$$n - n_0 \Rightarrow y(n - n_0) = x(2(n - n_0))$$

$$\underline{y(2-3) = x(2(2-3))} \quad \text{If } p = 2 \\ n_0 = 3$$

iii) memory-less / memory..

$$y(n) = x(2n)$$

$$y(n) = x(2n)$$

∴ It is memory.

iv) causal & non-causal.

$$y(n) = x(2n)$$

$$n = -3 \quad y(-3) = x(2(-3))$$

$$y(-3) = x(-6) \text{ present & future}$$

∴ It is non causal.

v) stable / un-stable.

If n is finite quantity

Then given system is stable.

The given system is linear, time invariant, memory, noncausal & stable.

d) $y(n) = x_1^2(n)$

i) Linear / non linear:-

if $y_1(n) = \{T x_1(n)\} = x_1^2(n)$

~~$y_2(n) = \{T x_2(n)\} = x_2^2(n)$~~

$$\begin{aligned}
 y(n) &= [ay_1(n) + by_2(n)] \\
 &= T[ax_1(n) + bx_2(n)] \Rightarrow x^*(n) \\
 &= [aT x_1(n) + bT x_2(n)] \\
 &= aT y \cdot x [ax_1(n) + bx_2(n)]^2
 \end{aligned}$$

$$ay_1(n) + by_2(n) \neq T\{ax_1(n) + bx_2(n)\}$$

\therefore It is non linear.

ii) Time invariant / variant

$$y(n) = x^2(n) \quad \rightarrow n = n - n_0$$

$$y(3) = x^2(3)$$

i. Time invariant

iii) memory less / memory.

$$\text{if } y(n) = x^2(n)$$

$$\text{ex: } y(3) = x^2(3)$$

\therefore It is memory less

iv) causal / non-causal

$$\text{if } y(n) = x^2(n)$$

$$y(4) = x^2(4)$$

\therefore It is causal

v) stable

$$\text{if } y(n) = x^2(n)$$

n is finite quantity

Then given system

is stable.

H.W
e) $y(n) = m x(n^2)$ linear TV non-causal memory stable

f) $y(n) = n x^2(n) \rightarrow$ non linear : time varying memory causal stable

g) $y(n) = x(1-n)$ linear TV memory non-causal stable

h) $y(n) = p x(n) + q$, where $p \neq q$ are the constant

e) $y(n) = m x(n^2)$

Soln:- i) Linear / non linear

$$y(n) = m x(n^2)$$

$$y_1(n) = \{T x_1(n)\} = m x_1(n^2)$$

Linear Time invariant system :-

A system satisfies linearity property and time invariant property that type of systems are called linear time invariant system.

The output of an LTI system is given by a weighted superposition of time shifted impulse responses.

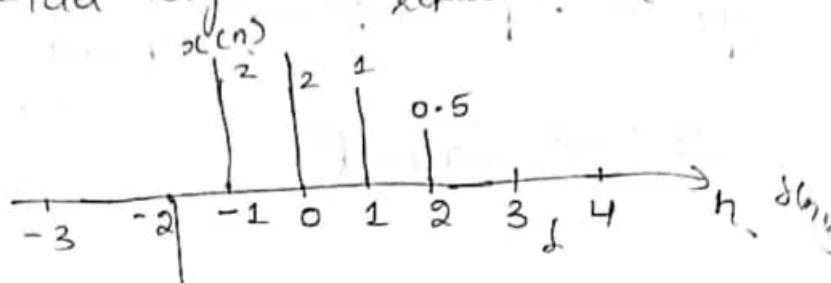
→ This weighted superposition is known as convolution theorem.

→ convolution theorem.

* Impulse Response :- Representation of time LTI system, or graphical representation.

①

⇒ Consider signal:-



$$x_1(n) = x(-2) \delta(n+2)$$

$$n=0; x_1(0) = (-1) \delta(2)$$

$$n=0; x_1(0) = (-1) 0$$

$$\boxed{x_1(0) = 0}$$

$$n=1; x_1(1); x_1(1) = (-1) \delta(1)$$

$$x_1(1) = (-1) 0$$

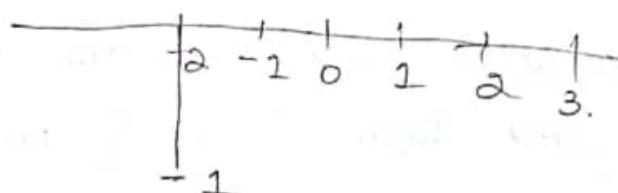
$$\boxed{x_1(1) = 0}$$

$$n=-1; x_1(-1); x_1(-1) = (-1) \delta(-1)$$

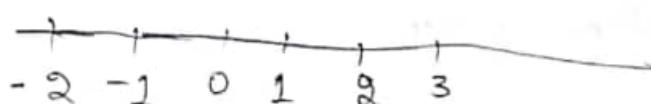
$$\delta_1(-1) = -1 (1)$$

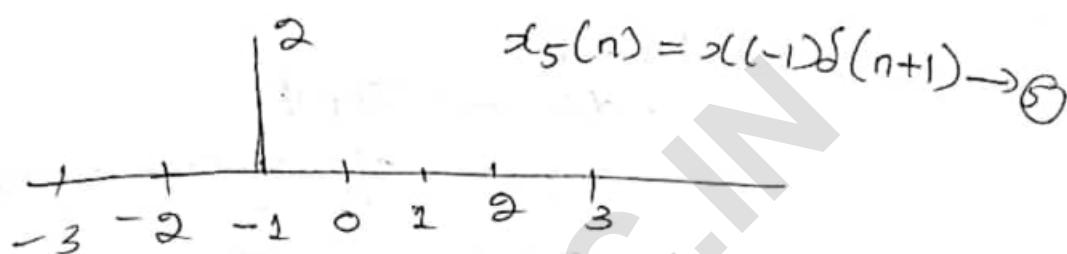
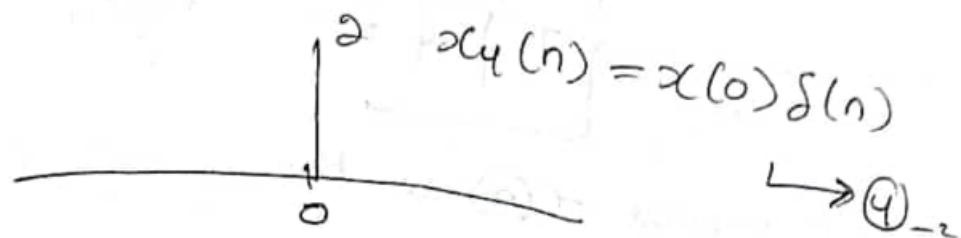
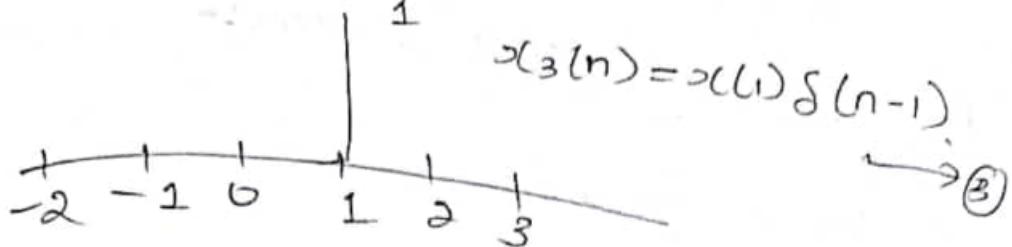
$$\boxed{x_1(-1) = -1}$$

• $x_1(n) = x(-2) \delta(n+2) \rightarrow ①$



• $x_2(n) = 0.5 = x(2) \delta(n-2) \rightarrow ②$





Add eq ①, ②, ③, ④ & ⑤ \rightarrow $x(n)$ signal.

$$x(-2)\delta(n+2) + x(2)\delta(n-2) + x(1)\delta(n-1) +$$

$$x(0)\delta(n) + x(-1)\delta(n+1)$$

$$\Rightarrow x(-2)\delta(n+2) + x(-1)\delta(n+1) +$$

$$x(0)\delta(n) + x(1)\delta(n-1) + x(2)\delta(n-2).$$

$$x(n) = x(-2)\delta(n+2) + x(-1)\delta(n+1) + x(0)\delta(n) +$$

$$x(1)\delta(n-1) + x(2)\delta(n-2).$$

$$x(n) = \sum_{k=-2}^2 x(k)\delta(n-k)$$

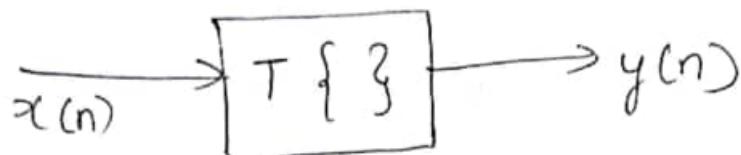
⑥ In general.

$$x(n) = \sum_{k=-\infty}^{\infty} x(k)\delta(n-k)$$

⑦

* Expression for Impulse response for
 Discrete time LTI system:-

Consider a system :



* → we express $x(n)$ as the weighted sum of time shifted impulse.

we have :

$x(n) \rightarrow$ Input

$y(n) \rightarrow$ O/P of the system

we have

$T\{\}$ operator.

$$y(n) = T\{x(n)\} \rightarrow ①$$

$$y(n) = T\left[\sum_{k=-\infty}^{\infty} x(k) \delta(n-k)\right] \rightarrow ②$$

$$y(n) = \sum_{k=-\infty}^{\infty} x(k) T\{\delta(n-k)\}$$

Consider :

$$T\{\delta(n-k)\} = h(n-k)$$

$$y(n) = \sum_{k=-\infty}^{\infty} x(k) h(n-k)$$

③

$$y(n) = x(n) \underset{\downarrow}{\text{*}} h(n)$$

convolution
symbol

1) show that
 3M or total each

- $x(n) * \delta(n) = x(n)$
- $x(n) * \delta(n-n_0) = x(n-n_0)$
- $x(n) * u(n-n_0) = \sum_{k=-\infty}^{n-n_0} x(k)$

get a) $x(n) * \delta(n) = x(n)$

soln: $x(n) * \delta(n) \Rightarrow \sum_{k=-\infty}^{\infty} x(k) \delta(n-k)$

when $k=n$

$$= \sum_{k=n} (x_k) \quad \because \delta(0)=1$$

$$y(n) = x(n) * \delta(n) \Big|_{k=n} = x(n) \delta(0)$$

Hence proved. $= x(n)$

b) $x(n) * \delta(n-n_0) = x(n-n_0)$

soln:- $x(n) * \delta(n-n_0) = \sum_{k=-\infty}^{\infty} x(k) \delta(n-n_0-k)$

when $k = n - n_0$. $\delta(n-n_0-k) = 1$.

$$\boxed{b) x(n) * \delta(n-n_0)} = \sum_{k=-\infty}^{n-n_0} x(n-n_0)$$

$|_{k=(n-n_0)}$

Hence proved.

c) $x(n) * u(n-n_0) = \sum_{k=-\infty}^{n-n_0} x(k)$

soln:- $x(n) * \delta(n) =$

let

→ by definition of unit step signal

$$u(n) = \begin{cases} 1 & n \geq 0 \\ 0 & n < 0 \end{cases} \quad \underline{\delta(0)=1}$$

$$u(n-n_0) = \begin{cases} 1 & n-n_0 \geq 0 \\ 0 & \text{otherwise} \end{cases}$$

$$\begin{aligned} x(n) * u(n-n_0) &= \sum_{k=-\infty}^{\infty} x(k) u(n-n_0-k) u(n-n_0-k) \\ &= \begin{cases} 1 & n-n_0-k \geq 0 \\ 0 & \text{otherwise} \end{cases} \end{aligned}$$

$$x(n) * u(n-n_0) = \sum_{k=-\infty}^{\infty} x(k)$$

2) Find the convolution sum of 2 sequences
 $x_1(n)$ & $x_2(n)$

$$x_1(n) = (1, 2, 3) = x_1(0) = 1, x_1(1) = 2, x_1(2) = 3$$

$$x_2(n) = (2, 1, 4) = x_2(0) = 2, x_2(1) = 1, x_2(2) = 4$$

Soln: $x_1(n) * x_2(n) = y(n)$

$$x_1(n) = 1\delta(n) + 2\delta(n-1) + 3\delta(n-2)$$

$$x_2(n) = 2\delta(n) + 1\delta(n-1) + 4\delta(n-2)$$

$$x_1(n) * x_2(n) = [\delta(n) + 2\delta(n-1) + 3\delta(n-2)] * [\underline{2\delta(n) + 1\delta(n-1) + 4\delta(n-2)}]$$

$$\begin{aligned}
 &= \sum_{k=-\infty}^{\infty} x_1(k) h(n-k) \\
 &= \sum_{k=-\infty}^{\infty} x_1(k) x_2(n-k) \\
 &= \sum_{k=0}^{2} x_1(k) x_2(n-k) \\
 y(n) &= x_1(0) x_2(n-0) + x_1(1) x_2(n-1) + \\
 &\quad x_1(2) x_2(n-2) \\
 y(n) &= x_2(n) + 2x_2(n-1) + 3x_2(n-2) \\
 n=0 \quad y(0) &= x_2(0) + 2x_2(-1) + 3x_2(-2) \\
 \boxed{y(0)} &= 2 \\
 n=1; \quad y(1) &= x_2(1) + 2x_2(0) + 3x_2(-1) \\
 &= 1 + 2x_2 + 0 \\
 \boxed{y(1)} &= 5
 \end{aligned}$$

$$n=2; y(2) = x_2(2) + 2x_2(1)$$

$$= 4 + 2 \times 1 + 3 \times 2 \\ = 4 + 2 + 6$$

$$\boxed{y(2) = 12}$$

$$n=3; y(3) = x_2(3) + 2x_2(2) + 3x_2(1)$$

$$= 2 \times 4 + 3 \times 1 \\ = 8 + 3$$

$$\boxed{y(3) = 11}$$

$$n=4;$$

$$y(4) = x_2(4) + 2x_2(3) + 3x_2(2) \\ = 3 \times 4$$

$$\boxed{y(4) = 12}$$

$$\therefore x_1(n) * x_2(n) = y(n)$$

$$y(n) = [2, 5, 12, 11, 12]$$

3) Determine $y(n) = x(n) * h(n)$

HW

where, $x(n) = \begin{bmatrix} 1 & 3 & 1 \end{bmatrix}$

$$h(n) = \begin{bmatrix} 1 & 4 & 2 \end{bmatrix}$$

HW

4) calculate convolution sum of two sequences

$$x_1(n) = \begin{bmatrix} 2 & 6 & 8 & 4 \end{bmatrix}$$

$$x_2(n) = \begin{bmatrix} 1 & 3 & 4 \end{bmatrix}$$

$$= 32 + 1^2$$

$$\boxed{y(4) = 44}$$

$$\therefore x_1(n) * x_2(n) = y(n)$$

$$y(n) = [1, 9, 30, 52, 44] //$$

Q3) Consider an input $x(n)$ & an unit impulse response $h(n)$ is given by

$$x(n) = \alpha^n u(n); 0 < \alpha < 1$$

$$h(n) = u(n)$$

Evaluate & plot the O/P signal $y(n)$

Soln:- Given :-

$$y(n) = x(n) * h(n)$$

$$= \sum_{k=-\infty}^{\infty} x(k) h(n-k)$$

$$x(k) = \alpha^k u(k)$$

$$h(n) = u(n)$$

Here, $\underline{x(k) = \alpha^k u(k)}$

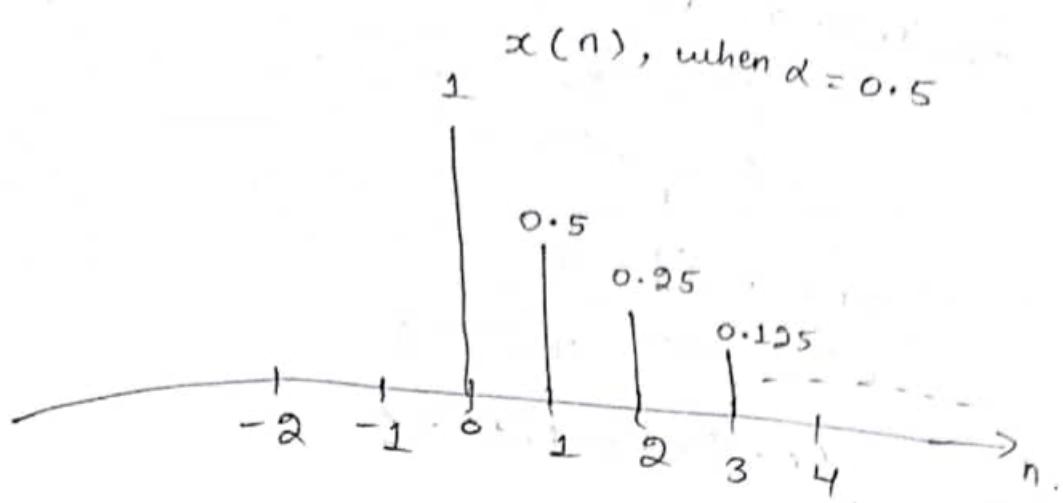
$$n \geq 0 =$$

$$\underline{\Rightarrow h(n) = u(n)}$$

$$\alpha = 0.5, n \geq 0 \quad x(n) = \alpha^n$$

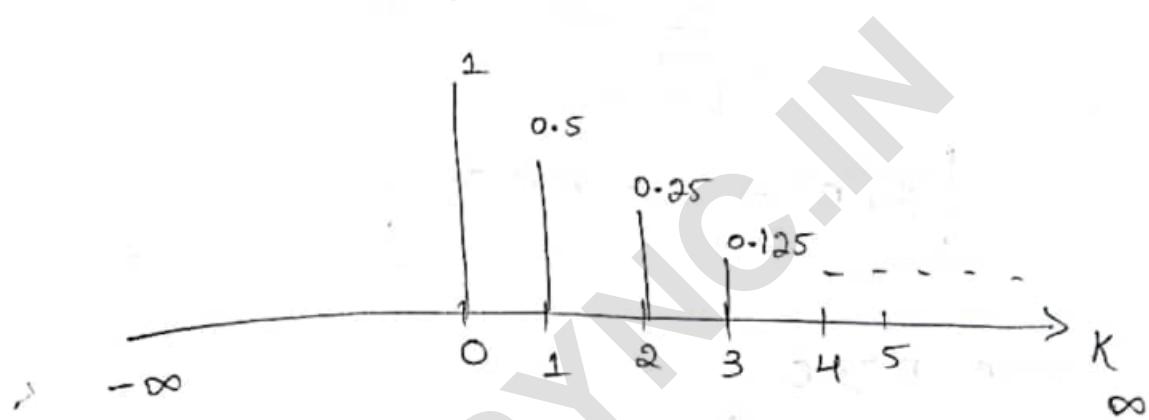
$$n < 0 \quad x(n) = 0.$$

$$n = 0, 1, 2, 3,$$

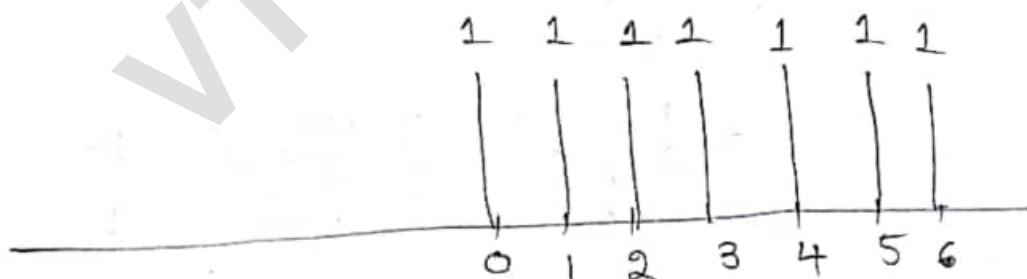


→ when $n = k$

$$x(k) = \alpha^k u(k)$$



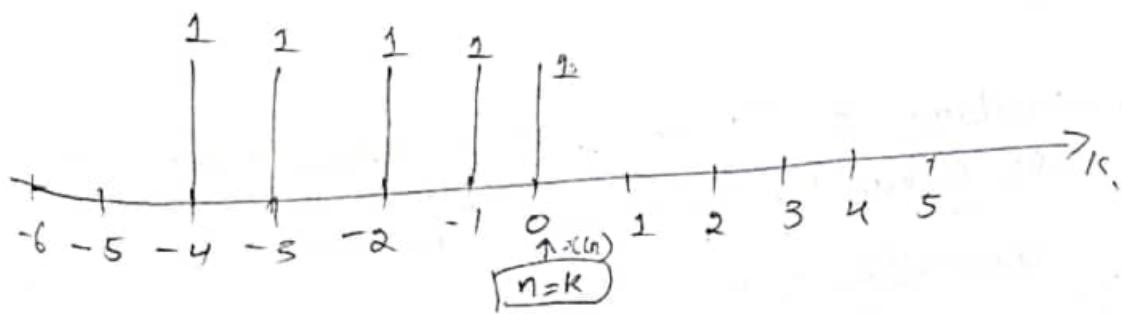
$$\Rightarrow h(n) = u(n)$$



Replace n by $(n-k)$

$$h(n-k) = u(n-k)$$

$$\begin{array}{l} n=0 \\ n=1 \end{array}$$



$$h(n-k) = u(n-k)$$

$$= u(0) = 1$$

$$u(0-1) = u(-1) = 0$$

$$k = -1 \quad u(0-(-1)) = u(1) = 1$$

$$u(0-(-2)) = u(2) = 1$$

$$u(0-(-3)) = u(3) = 1$$

when, $n < 0$

$$y(n) = x(n) * h(n)$$

$$= \sum_{k=-\infty}^{\infty} x(k) h(n-k)$$

$$\boxed{y(n) = 0, n < 0}$$

→ when $n \geq 0$

$$y(n) = \sum_{k=0}^n x(k) h(n-k)$$

$$= \sum_{k=0}^n \alpha^k \cdot 1$$

$$= \sum_{k=0}^n \alpha^k \quad \left[\because \sum_{n=0}^{n-1} \alpha^n = \frac{1-\alpha^n}{1-\alpha} \right]$$

$$y(n) = \begin{cases} \frac{1-\alpha^{n+1}}{1-\alpha} & n \geq 0 \\ 0 & n < 0 \end{cases}$$

Q) Evaluate a discrete time convolution sum

as given by $y(n) = \left(\frac{1}{2}\right)^n u(n-2) * u(n)$

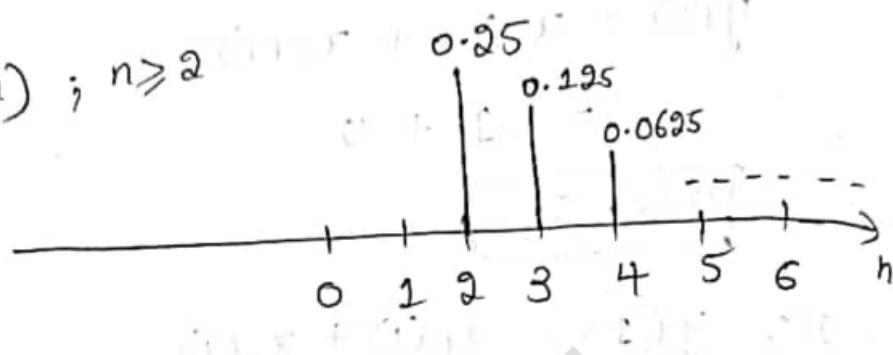
Convolution with $u(n)$

6)

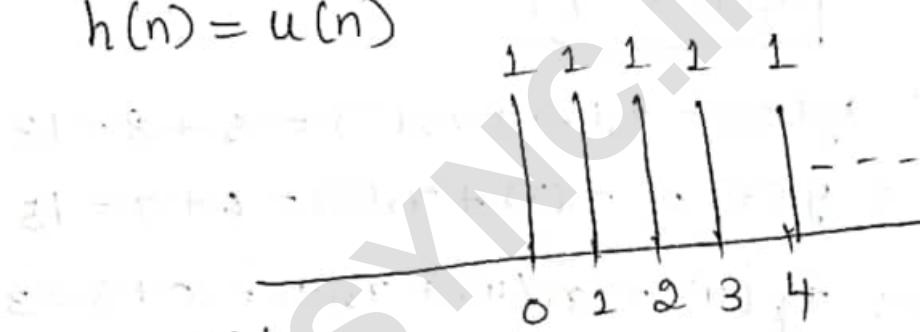
Given:-

$$y(n) = \left(\frac{1}{2}\right)^n u(n-2) * u(n)$$

$$\left(\frac{1}{2}\right)^n u(n-2) ; n \geq 2$$

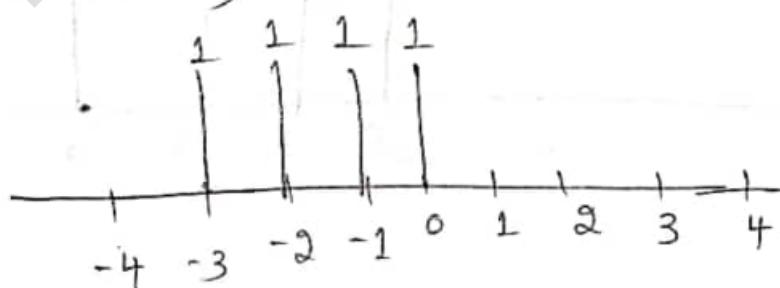


$$h(n) = u(n)$$



Replace n by n-k

$$h(n-k) = u(n-k) \quad \text{for } k \leq n$$

when $n < 0$

$$y(n) = x(n) * h(n)$$

$$= \sum_{k=-\infty}^{\infty} x(k) h(n-k)$$

$$x(k) = \left(\frac{1}{2}\right)^k \cdot h(n-k)$$

$$y(n) = 0 \quad n \leq 0$$

when $n \geq$

$$y(n) = \sum_{k=0}^n x(k) h(n-k)$$

$$= \sum_{k=0}^n \left(\frac{1}{2}\right)^k 1$$

$$= \sum_{k=0}^n \left(\frac{1}{2}\right)^k 1 \quad \left[\because \sum_{n=0}^{\infty} \left(\frac{1}{2}\right)^n = \frac{1-2^n}{1-\alpha} \right]$$

$$= \sum_{k=0}^n \left(\frac{1}{2}\right)^k 1$$

$$\left[\because \sum_{n=0}^{\infty} \alpha^n = \begin{cases} 1-\alpha^n; & \alpha \neq 1 \\ \frac{1-\alpha^n}{1-\alpha}; & \alpha = 1 \end{cases} \right]$$

$$= \frac{1 - \left(\frac{1}{2}\right)^{n+1}}{1 - \frac{1}{2}}$$

$$S = a \frac{1-\alpha^n}{1-\alpha}$$

$$= 2 \left(1 - \left(\frac{1}{2}\right)^{n+1}\right)$$

$$= \sum_{k=0}^n \left(\frac{1}{2}\right)^k 1 \quad \begin{matrix} k=2 \text{ to } n \\ n-2+1=n-1 \end{matrix}$$

$$= \frac{1}{4} \frac{1 - \left(\frac{1}{2}\right)^{n-1}}{1 - \frac{1}{2}} = \frac{1}{4} 2 \left(1 - \left(\frac{1}{2}\right)^{n-1}\right)$$

$$\therefore y(n) = \begin{cases} \frac{1}{2} \left(1 - \left(\frac{1}{2}\right)^{n-1}\right); & n \geq 2 \\ 0; & n < 2 \end{cases}$$

* The unit step Response [S(n)] of an LTI system

The output of DTLTI system characterised by an impulse response $h(n)$ with $x(n)$

$$\begin{aligned} & \xrightarrow{x(n) \quad h(n)} \\ & u(n) \quad y(n) = x(n) * u(n) \\ & S(n) = u(n) * h(n) \end{aligned}$$

$$y(n) = x(n) * h(n)$$

If the input is unit step :

$x(n) = u(n)$ then step response is given by

$$S(n) = h(n) * u(n)$$

$$= \sum_{k=-\infty}^{\infty} h(k) u(n-k)$$

by defn

$$u(n-k) = \begin{cases} 1 & n-k \geq 0 \text{ or } n \geq k \\ 0 & n-k < 0 \end{cases}$$

$$S(n) = \sum_{k=0}^n h(k)$$

$$S(n) = \sum_{k=-\infty}^n h(k)$$

is the required unit step response of an LTI system.

Imp:

- Determine the step response of the following LTI system.

$$\text{i)} h(n) = u(n)$$

$$\text{ii)} h(n) = (-1)^n [u(n+2) - u(n-3)]$$

$$\text{iii)} h(n) = \alpha^n u(n)$$

$$\text{iv)} h(n) = (\frac{1}{2})^n u(n)$$

$$\text{i)} h(n) = u(n)$$

soln:- Given:-

$$h(n) = u(n)$$

w.k.t :-

$$s(n) = \sum_{k=0}^n h(k)$$

$$u(n) = \begin{cases} 1, & n \geq 0 \\ 0, & n < 0 \end{cases}$$

$$u(k) = \begin{cases} 1 & k \geq 0 \\ 0 & k < 0 \end{cases}$$

$$s(n) = \sum_{k=-\infty}^{-1} h(k) + \sum_{k=0}^n h(k)$$

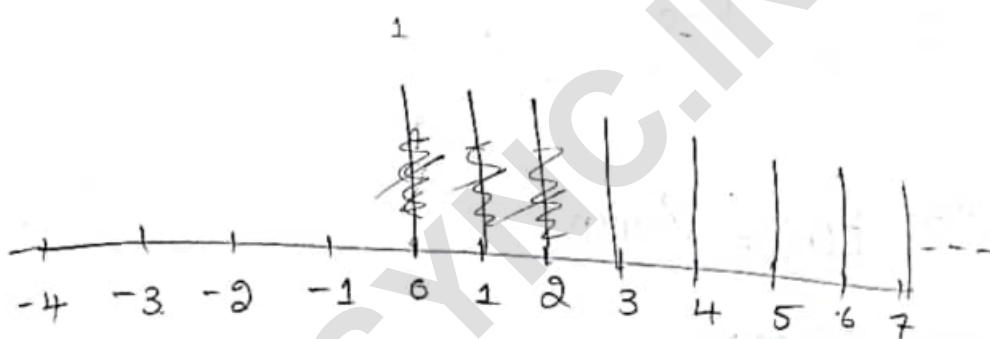
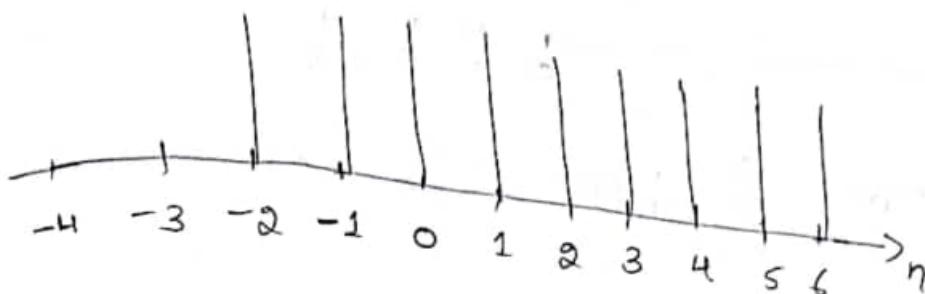
$$= \sum_{k=0}^n h(k)$$

$$= \sum_{k=0}^n 1 \quad \left[\because \sum_{n=0}^{n-1} \alpha^n = \begin{cases} \frac{1-\alpha^n}{1-\alpha} & \alpha \neq 1 \\ n & \alpha = 1 \end{cases} \right]$$

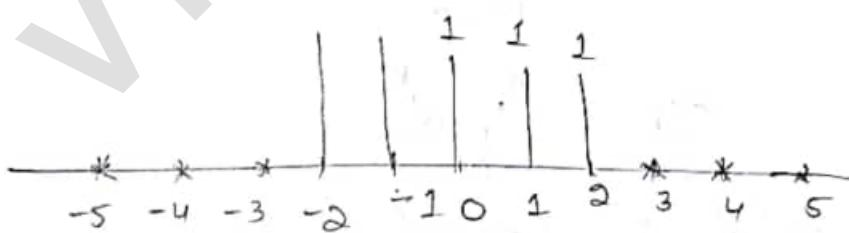
$$\boxed{s(n) = n+1}$$

$$h(n) = (-1)^n [u(n+2) - u(n-3)]$$

$\therefore u(n+2)$



$$u(n+2) - u(n-3)$$



$$h(n) = (-1)^n [u(n+2) - u(n-3)]$$



$$s(n) = \sum_{k=-2}^2 h(k) = \sum_{k=-2}^2 (-1)^k$$

$$\boxed{s(n) = \sum_{k=2}^2 (-1)^k}$$

Q3) $q(n) = \alpha^n u(n)$.

Soln:- Given :-

$$h(n) = \alpha^n u(n) \Rightarrow h(k) = \alpha^k u(k)$$

$$s(n) = \sum_{k=-\infty}^n h(k)$$

$$s(n) = \sum_{k=0}^n \alpha^k$$

$$\therefore \sum_{n=0}^{n-1} \alpha^n = \begin{cases} \frac{1-\alpha^n}{1-\alpha}; & \alpha \neq 1 \\ n; & \alpha = 1 \end{cases}$$

$$s(n) = \begin{cases} \frac{1-\alpha^{n+1}}{1-\alpha}; & \alpha \neq 1 \\ n+1; & \alpha = 1 \end{cases}$$

$$q) h(n) = \left(\frac{1}{2}\right)^n u(n)$$

Soln:- Given:-

$$h(n) = \left(\frac{1}{2}\right)^n u(n)$$

$$s(n) = \sum_{k=-\infty}^{\infty} h(k)$$

$$s(n) = \sum_{k=0}^{n} \left(\frac{1}{2}\right)^k$$

(or)

^{start}
_{from}

$$s(n) = h(n) * u(n)$$

$$s(n) = \sum_{k=-\infty}^{\infty} h(k) u(n-k)$$

$$s(n) = \sum_{k=0}^{n} h(k)$$

$$= \sum_{k=0}^{n} \left(\frac{1}{2}\right)^k$$

$$s(n) = \frac{1 - \left(\frac{1}{2}\right)^{n+1}}{1 - \frac{1}{2}}$$

$\left[\because \sum_{n=0}^{N-1} \alpha^n = \begin{cases} \frac{1-\alpha^N}{1-\alpha} & ; \alpha \neq 1 \\ N & ; \alpha = 1 \end{cases} \right]$

$$s(n) = 2 \left(1 - \left(\frac{1}{2}\right)^{n+1}\right)$$

v) Determine step response for the system

$$i) h(n) = (-1)^2 [u(n+3) - u(n-6)]$$

Soln:- Given:-

$$h(n) = (-1)^2 [u(n+3) - u(n-6)]$$

HW

v) Determine step response for the system

i) $h(n) = (-1)^2 [u(n+3) - u(n-6)]$

ii) $h(n) = (-1)^n u(n)$

iii) $h(n) = \delta(n)$