

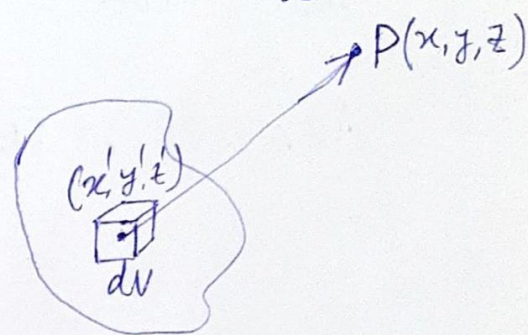
Divergence of Magnetic field

The Biot-Savart law for the general case of volume current reads

$$\vec{B} = \frac{\mu_0}{4\pi} \int \frac{\vec{J} \times \hat{r}}{r^2} dv$$

$$\vec{J} = \frac{I}{d\vec{a}}$$

The above formula gives the magnetic field at a point $P(x, y, z)$ in terms of an integral over the current density $J(x', y', z')$



Applying the divergence to \vec{B} we obtain

$$\nabla \cdot \vec{B} = \frac{\mu_0}{4\pi} \int \nabla \cdot \left(\vec{J} \times \frac{\hat{r}}{r^2} \right) dv$$

We know the product rule

$$\nabla \cdot \left(\vec{J} \times \frac{\hat{r}}{r^2} \right) = \frac{\hat{r}}{r^2} \cdot (\nabla \times \vec{J}) - \vec{J} \cdot \left(\nabla \times \frac{\hat{r}}{r^2} \right)$$

$\nabla \times \vec{J} = 0$, because \vec{J} does not depend on (x, y, z)

$$\text{Also } \nabla \times \left(\frac{\hat{r}}{r^2} \right) = 0$$

Therefore, we get

$$\boxed{\nabla \cdot \vec{B} = 0}$$

Which is known as differential form of Gauss' law. It tells that the magnetic field is solenoidal. Comparing it with Gauss' law in electrostatics $\nabla \cdot \vec{E} = \rho/\epsilon_0$, we can conclude that magnetic monopole does not exist.

(36)

The curl of \vec{B} Applying curl to \vec{B} we get

$$\nabla \times \vec{B} = \frac{\mu_0}{4\pi} \int \nabla \times \left(\vec{J} \times \frac{\hat{r}}{r^2} \right) dv$$

Also, we have from product rule

$$\nabla \times \left(\vec{J} \times \frac{\hat{r}}{r^2} \right) = \vec{J} \left(\nabla \cdot \frac{\hat{r}}{r^2} \right) - (\vec{J} \cdot \nabla) \frac{\hat{r}}{r^2}$$

The second term is zero as $\nabla \cdot \vec{J}$ is zero.Here $\nabla \cdot \left(\frac{\hat{r}}{r^2} \right) = 4\pi \delta^3(r)$, where $\delta^3(r)$ is 3-D

Dirac-Delta function,

where $\int \delta^3(r) dv = 1$.

$$\begin{aligned} \therefore \nabla \times \vec{B} &= \frac{\mu_0}{4\pi} \int \vec{J} \left(\nabla \cdot \frac{\hat{r}}{r^2} \right) dv = \frac{\mu_0}{4\pi} \times 4\pi \int \delta^3(r) dv \\ &= \frac{\mu_0 \vec{J}}{4\pi} \times 4\pi \end{aligned}$$

Hence, $\boxed{\nabla \times \vec{B} = \mu_0 \vec{J}}$ which is known as Ampere's lawAmpere's law in differential form $\nabla \times \vec{B} = \mu_0 \vec{J}$ we can convert it into integral form. By applying Stokes's theorem we get

$$\oint (\nabla \times \vec{B}) \cdot d\vec{s} = \oint \vec{B} \cdot d\vec{l} = \mu_0 \int \vec{J} \cdot d\vec{s} = \mu_0 I_{enc}$$

Here $\int \vec{J} \cdot d\vec{s}$ is the total current passing the surface, which we call I_{enc} . Thus

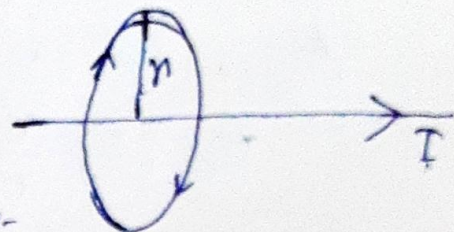
$$\boxed{\oint \vec{B} \cdot d\vec{l} = \mu_0 I_{enc}}$$

This is the integral version of Ampere's law

Application of Ampere's law

Find the magnetic field at distant point r from a long straight wire, carrying a steady current I .

Here the direction of \vec{B} is circumferential, circling around the wire.



By symmetry, the magnitude of $|\vec{B}|$ is constant around an "amperian loop" of radius r centered on the wire, so, Ampere's law gives

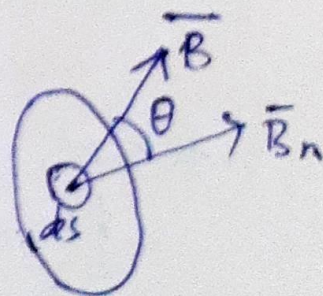
$$\oint \vec{B} \cdot d\vec{l} = B \oint dl = B \times 2\pi r = \mu_0 I$$

$$\therefore \vec{B} = \frac{\mu_0 I}{2\pi r}$$

Magnetic Flux

Magnetic flux through a surface is defined as the number of magnetic field lines crossing the surface normally.

Therefore, magnetic flux through a surface ds , when in a magnetic field \vec{B} is given by



$d\phi = B_n ds$, where B_n is the normal component of the magnetic field B

$$\therefore B_n = B \cos \theta$$

$$\text{Hence } d\phi = B \cos \theta ds = \vec{B} \cdot d\vec{s}$$