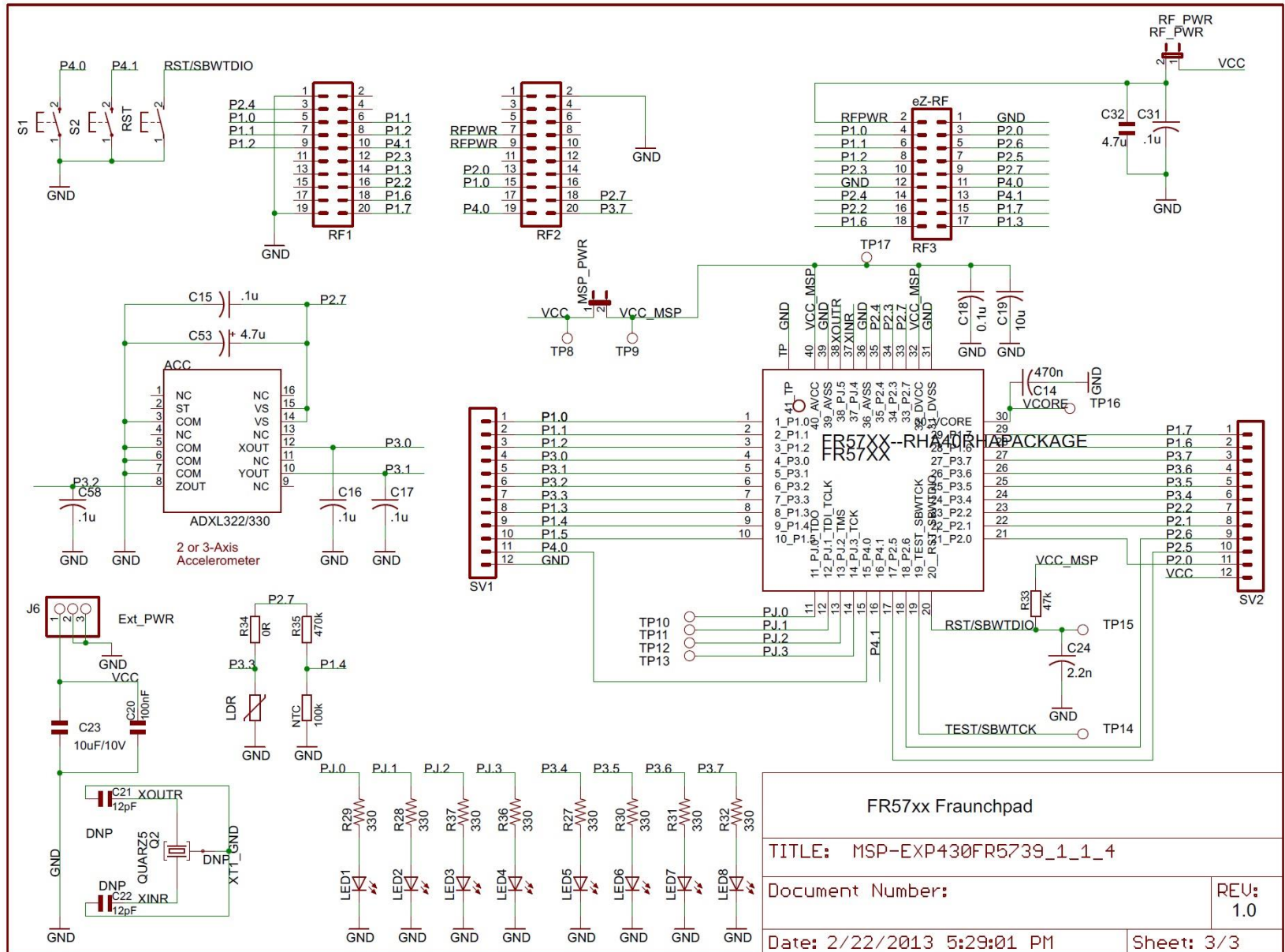
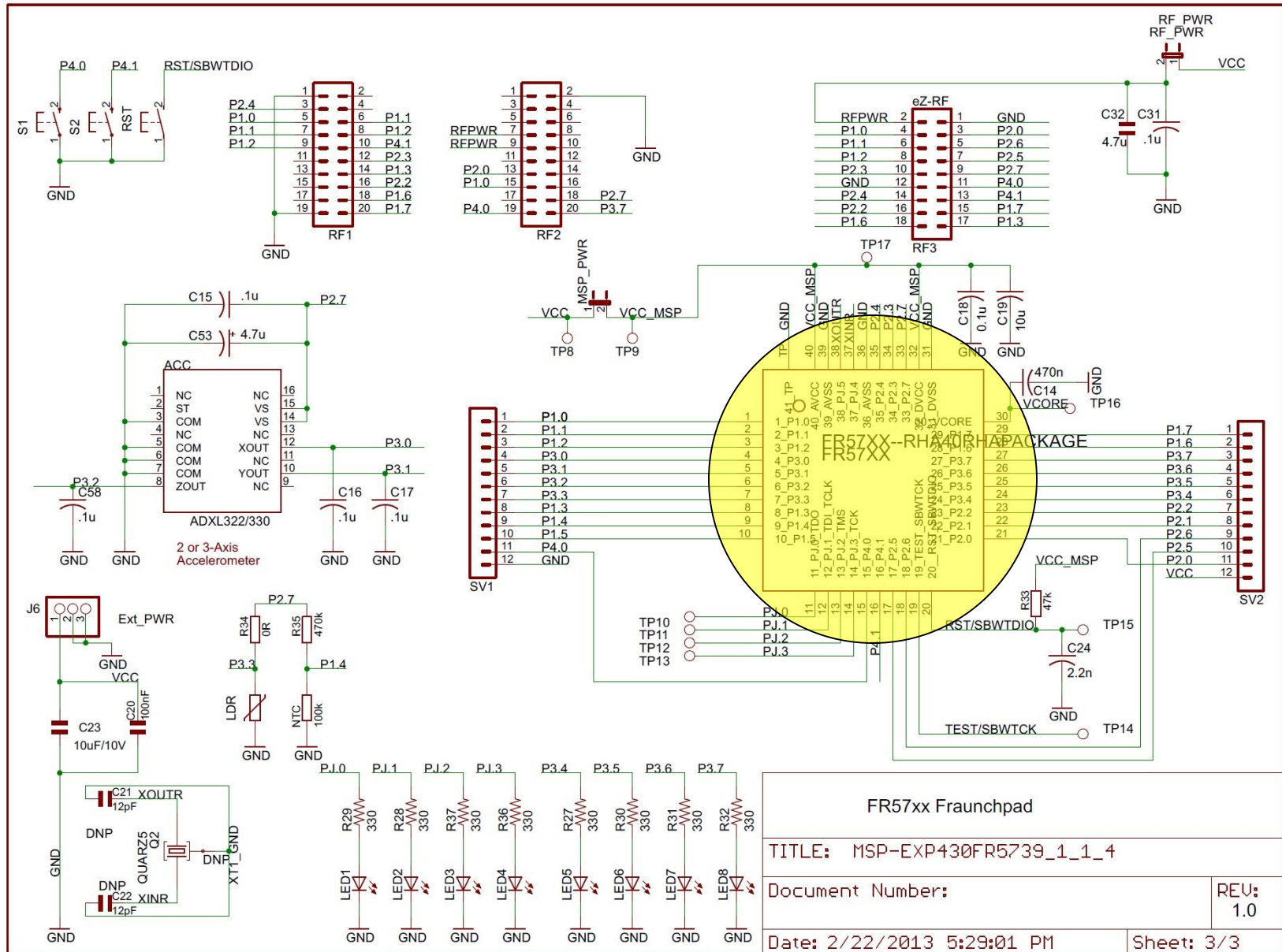


# MSP430 Port Determinations

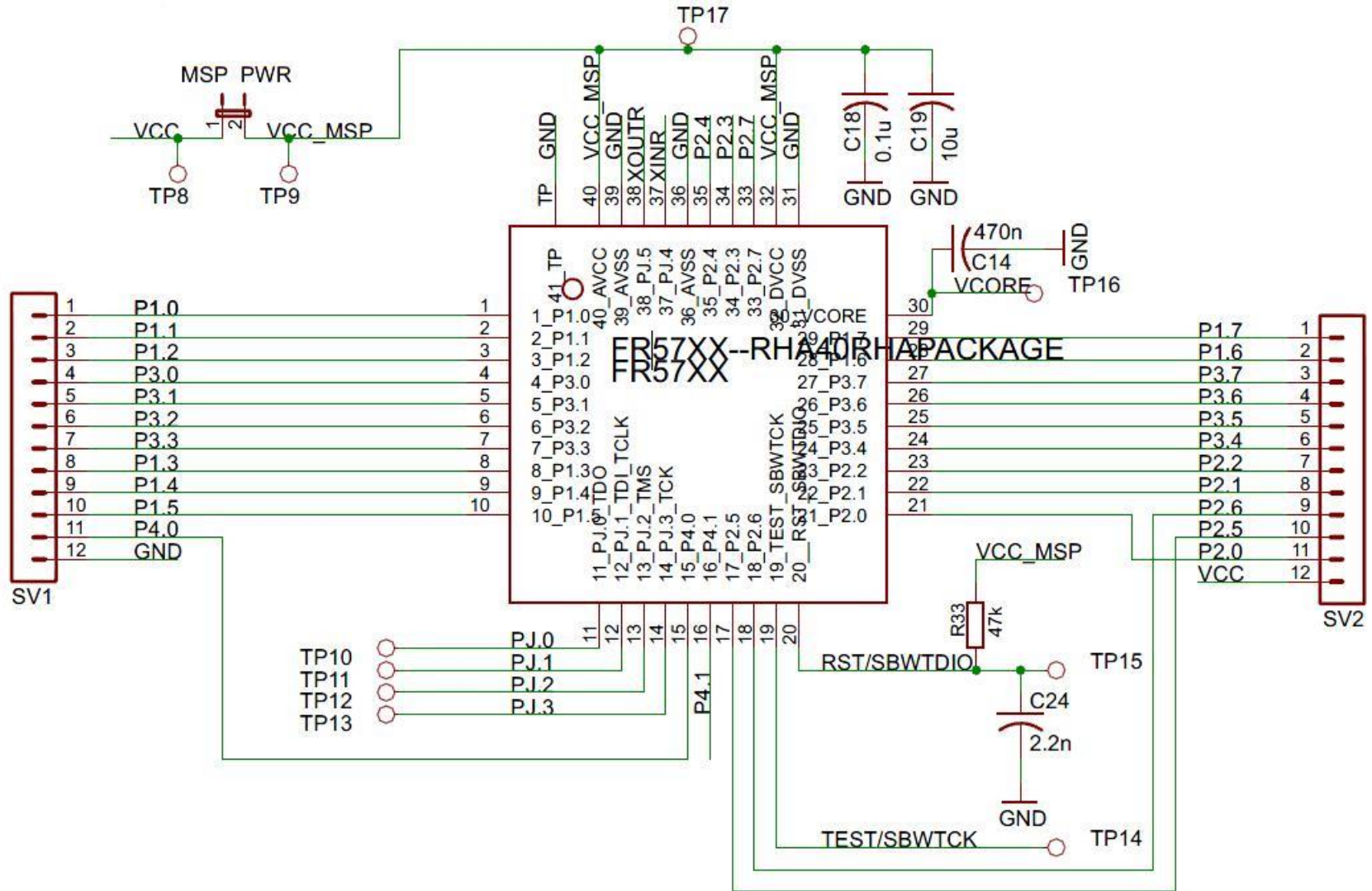
# From MSP-EXP430FR5739 SCH



# From MSP-EXP430FR5739 SCH

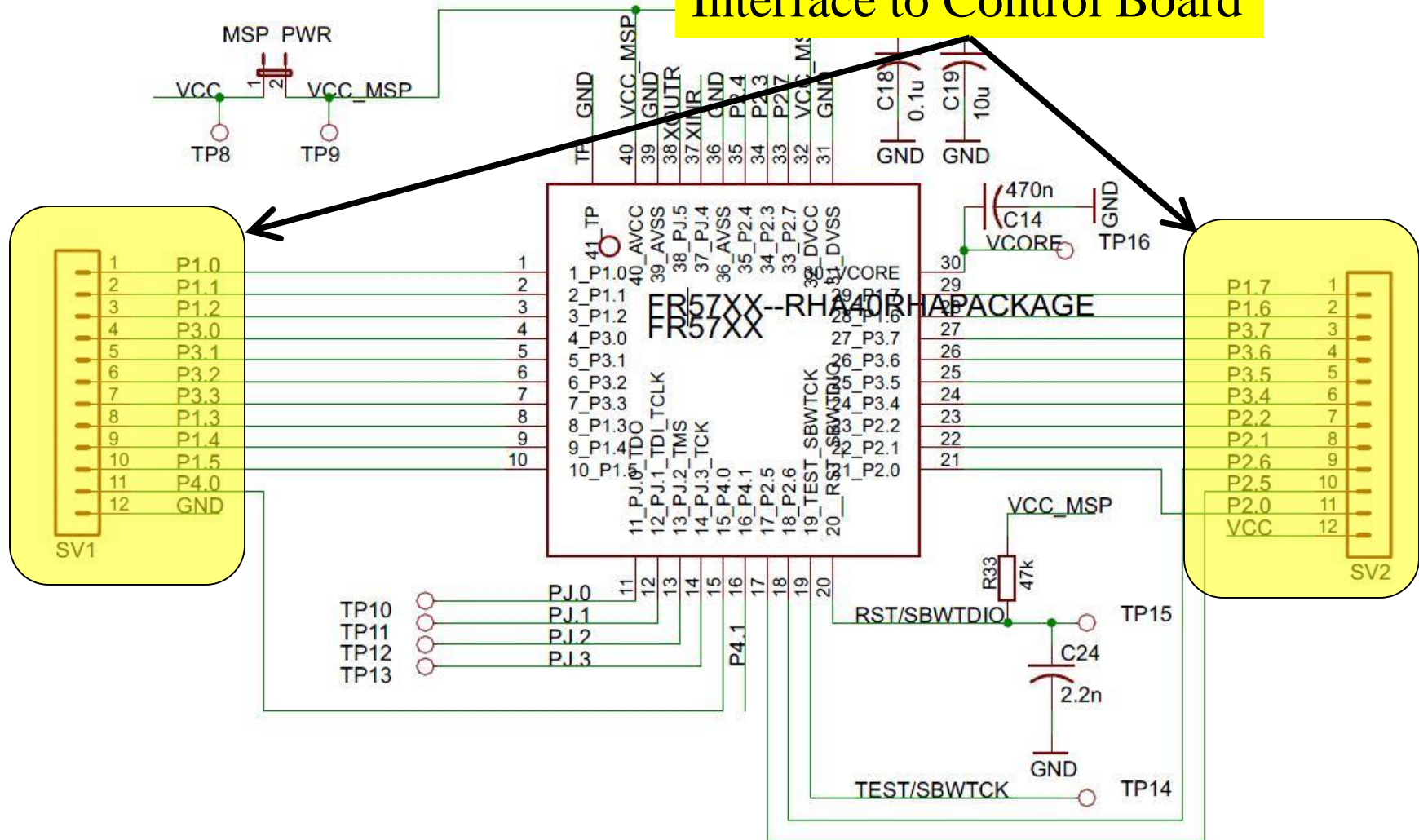


# From MSP-EXP430FR5739\_SCH



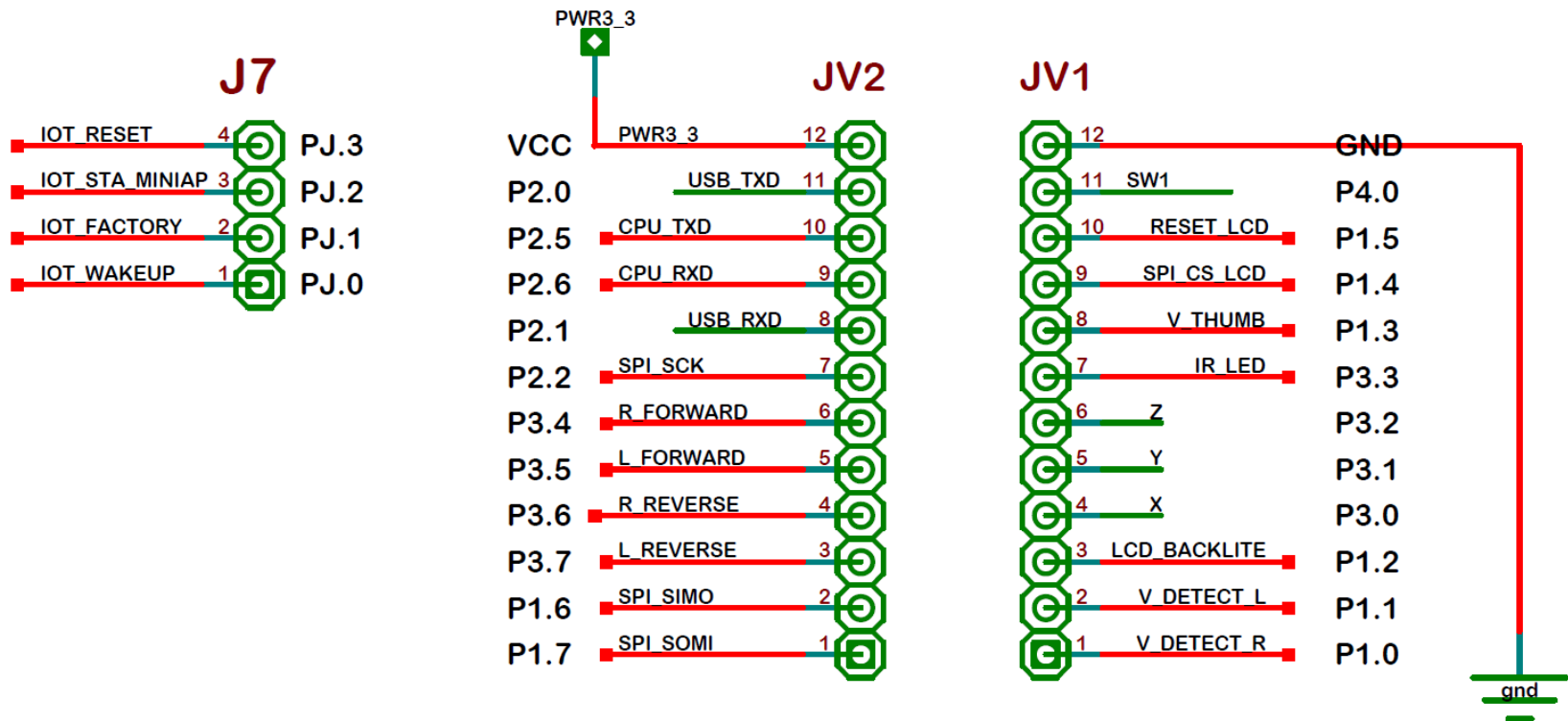


## Interface to Control Board

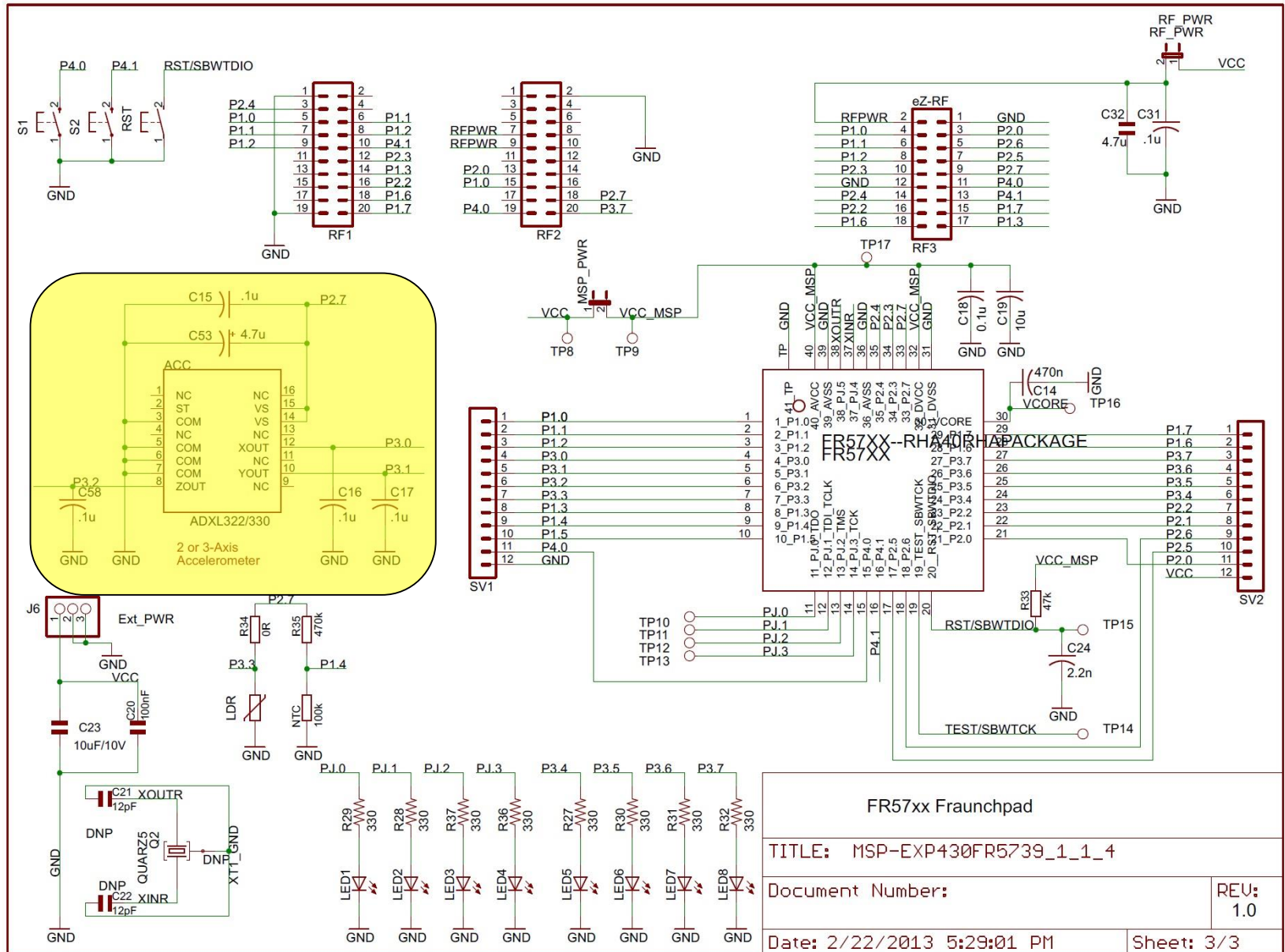


# From SCH\_FRAM\_II

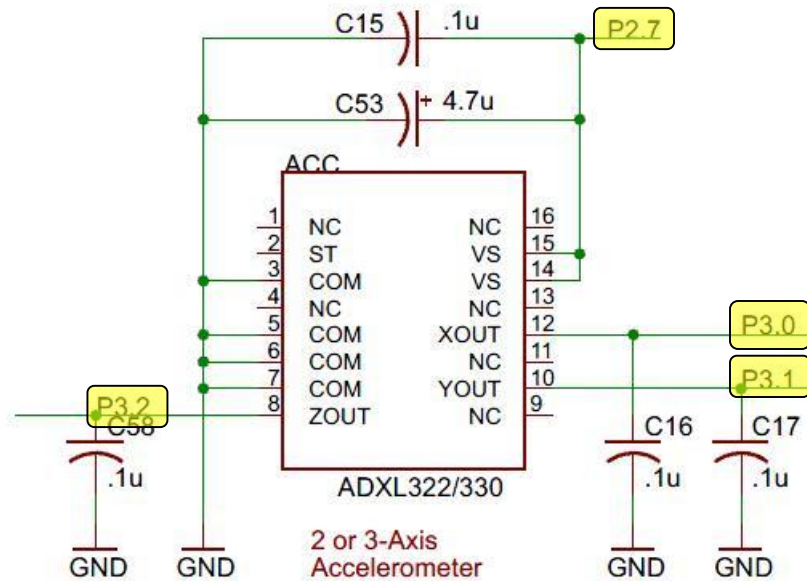
## Interconnect



# From MSP-EXP430FR5739 SCH



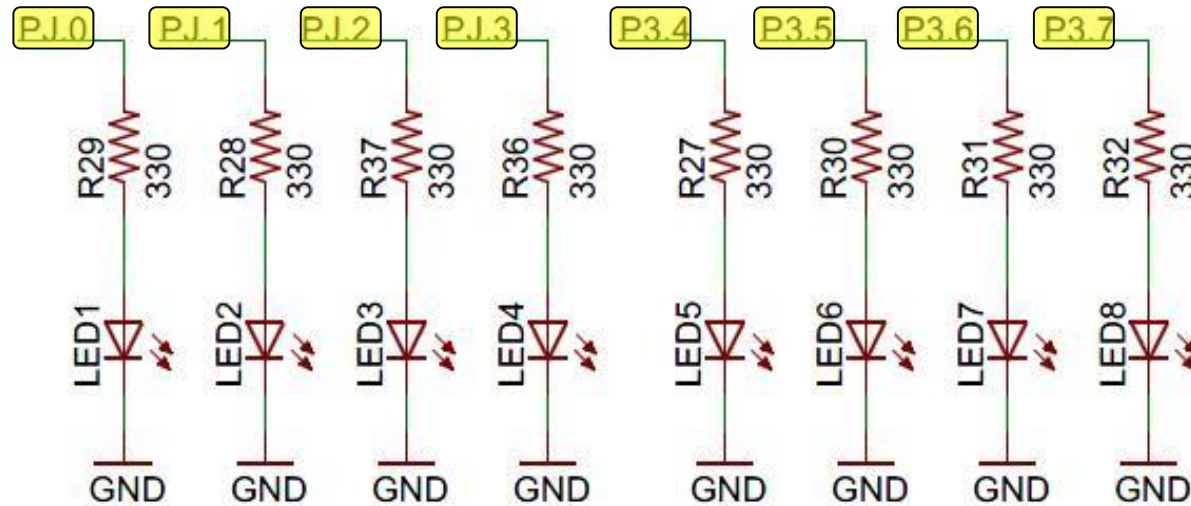
# From MSP-EXP430FR5739\_SCH







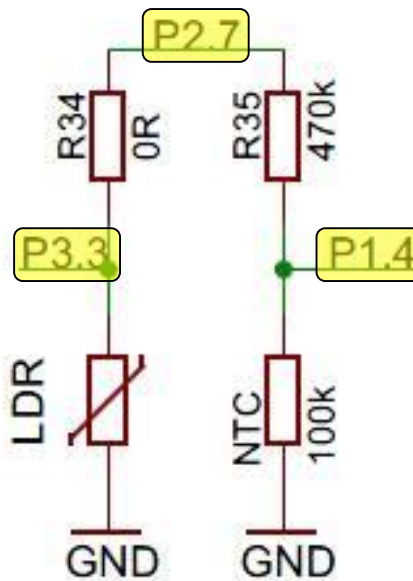
# From MSP-EXP430FR5739\_SCH



## 11



# From MSP-EXP430FR5739\_SCH

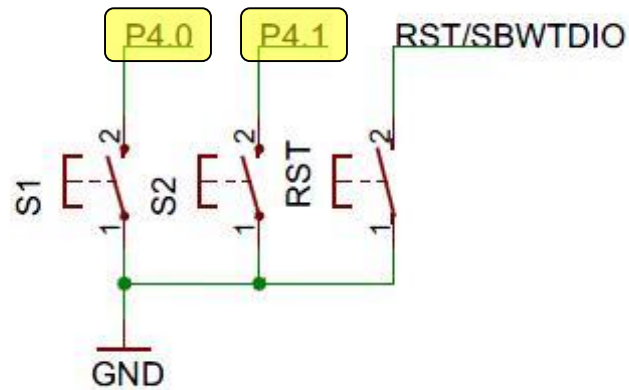








# From MSP-EXP430FR5739\_SCH

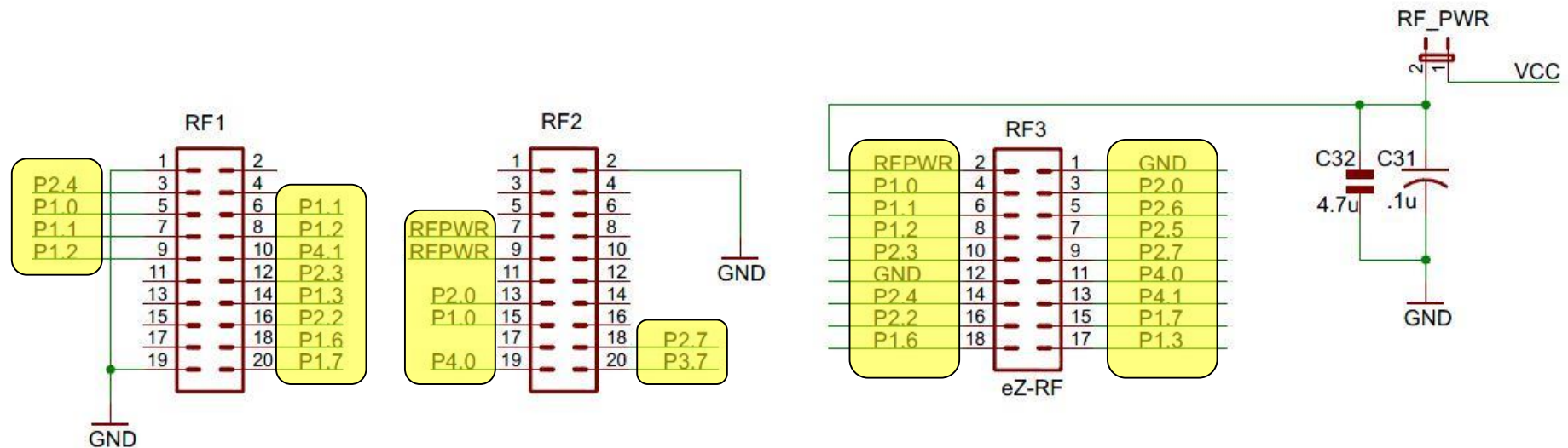


## FR57xx Fraunchpad

REV:  
1.0

Sheet: 3/3

# From MSP-EXP430FR5739\_SCH



## Start With a Spread Sheet

[illegible]

# Enter Ports and Pins

Port	Pin	Signal Name	GP I/O or Function	Direction / Function	SEL1	SEL0	Initial Value	Pull-UP
1	0							
1	1							
1	2							
1	3							
1	4							
1	5							
1	6							
1	7							
2	0							
2	1							
2	2							
2	3							
2	4							
2	5							
2	6							
2	7							
3	0							
3	1							
3	2							
3	3							
3	4							
3	5							
3	6							
3	7							
4	0							
4	1							
J	0							
J	1							
J	2							
J	3							



# Capture Schematic Names

Port	Pin	Signal Name	GP I/O or Function	Direction / Function	SEL1	SEL0	Initial Value	Pull-UP
1	0	V_DETECT_R						
1	1	V_DETECT_L						
1	2	LCD_BACKLITE						
1	3	V_THUMB						
1	4	SPI_CS_LCD						
1	5	RESET_LCD						
1	6	SPI_SIMO						
1	7	SPI_SOMI						
2	0							
2	1							
2	2							
2	3							
2	4							
2	5							
2	6							
2	7							
3	0							
3	1							
3	2							
3	3							
3	4							
3	5							
3	6							
3	7							
4	0							
4	1							
J	0							
J	1							
J	2							
J	3							

# Identify GP I/O or Function

Port	Pin	Signal Name	GP I/O or Function	Direction / Function	SEL1	SEL0	Initial Value	Pull-UP
1	0	V_DETECT_R	Function					
1	1	V_DETECT_L	Function					
1	2	LCD_BACKLITE	GP I/O					
1	3	V_THUMB	Function					
1	4	SPI_CS_LCD	GP I/O					
1	5	RESET_LCD	GP I/O					
1	6	SPI_SIMO	Function					
1	7	SPI_SOMI	Function					
2	0							
2	1							
2	2							
2	3							
2	4							
2	5							
2	6							
2	7							
3	0							
3	1							
3	2							
3	3							
3	4							
3	5							
3	6							
3	7							
4	0							
4	1							
J	0							
J	1							
J	2							
J	3							

# Direction for GP I/O and what function [Page 68 of Data Sheet]

Port	Pin	Signal Name	GP I/O or Function	Direction / Function	SEL1	SEL0	Initial Value	Pull-UP
1	0	V_DETECT_R	Function	ADC - A0				
1	1	V_DETECT_L	Function	ADC - A1				
1	2	LCD_BACKLITE	GP I/O	Output				
1	3	V_THUMB	Function	ADC - A3				
1	4	SPI_CS_LCD	GP I/O	Output				
1	5	RESET_LCD	GP I/O	Output				
1	6	SPI_SIMO	Function	UCB0SIMO/UCB0SDA				
1	7	SPI_SOMI	Function	UCB0SOMI/UCB0SCL				
2	0							
2	1							
2	2							
2	3							
2	4							
2	5							
2	6							
2	7							
3	0							
3	1							
3	2							
3	3							
3	4							
3	5							
3	6							
3	7							
4	0							
4	1							
J	0							
J	1							
J	2							
J	3							

## From Data Sheet capture SEL bit values

Port	Pin	Signal Name	GP I/O or Function	Direction / Function	SEL1	SEL0	Initial Value	Pull-UP
1	0	V_DETECT_R	Function	ADC - A0	1	1		
1	1	V_DETECT_L	Function	ADC - A1	1	1		
1	2	LCD_BACKLITE	GP I/O	Output	0	0		
1	3	V_THUMB	Function	ADC - A3	1	1		
1	4	SPI_CS_LCD	GP I/O	Output	0	0		
1	5	RESET_LCD	GP I/O	Output	0	0		
1	6	SPI_SIMO	Function	UCB0SIMO/UCB0SDA	1	0		
1	7	SPI_SOMI	Function	UCB0SOMI/UCB0SCL	1	0		
2	0							
2	1							
2	2							
2	3							
2	4							
2	5							
2	6							
2	7							
3	0							
3	1							
3	2							
3	3							
3	4							
3	5							
3	6							
3	7							
4	0							
4	1							
J	0							
J	1							
J	2							
J	3							

## What are the desired starting values

Port	Pin	Signal Name	GP I/O or Function	Direction / Function	SEL1	SEL0	Initial Value	Pull-UP
1	0	V_DETECT_R	Function	ADC - A0	1	1	0	
1	1	V_DETECT_L	Function	ADC - A1	1	1	0	
1	2	LCD_BACKLITE	GP I/O	Output	0	0	0	
1	3	V_THUMB	Function	ADC - A3	1	1	0	
1	4	SPI_CS_LCD	GP I/O	Output	0	0	1	
1	5	RESET_LCD	GP I/O	Output	0	0	0	
1	6	SPI_SIMO	Function	UCB0SIMO/UCB0SDA	1	0	0	
1	7	SPI_SOMI	Function	UCB0SOMI/UCB0SCL	1	0	0	
2	0							
2	1							
2	2							
2	3							
2	4							
2	5							
2	6							
2	7							
3	0							
3	1							
3	2							
3	3							
3	4							
3	5							
3	6							
3	7							
4	0							
4	1							
J	0							
J	1							
J	2							
J	3							



# What Input signals require pull-ups / pull-downs

Port	Pin	Signal Name	GP I/O or Function	Direction / Function	SEL1	SEL0	Initial Value	Pull-UP
1	0	V_DETECT_R	Function	ADC - A0	1	1		
1	1	V_DETECT_L	Function	ADC - A1	1	1		
1	2	LCD_BACKLITE	GP I/O	Output	0	0	1	
1	3	V_THUMB	Function	ADC - A3	1	1		
1	4	SPI_CS_LCD	GP I/O	Output	0	0	1	
1	5	RESET_LCD	GP I/O	Output	0	0	0	
1	6	SPI_SIMO	Function	UCB0SIMO/UCB0SDA	1	0		
1	7	SPI_SOMI	Function	UCB0SOMI/UCB0SCL	1	0		1
2	0							
2	1							
2	2							
2	3							
2	4							
2	5							
2	6							
2	7							
3	0							
3	1							
3	2							
3	3							
3	4							
3	5							
3	6							
3	7							
4	0							
4	1							
J	0							
J	1							
J	2							
J	3							

## Repeat for all ports

Port	Pin	Signal Name	GP I/O or Function	Direction / Function	SEL1	SEL0	Out Value	Resistor
1	0	V_DETECT_R	Function / In Analog	ADC - A0	1	1	0	n/a
1	1	V_DETECT_L	Function / In Analog	ADC - A1	1	1	0	n/a
1	2	LCD_BACKLITE	GP I/O	Output	0	0	0	n/a
1	3	V_THUMB	Function / In Analog	ADC - A3	1	1	0	n/a
1	4	SPI_CS_LCD	GP I/O	Output	0	0	1	n/a
1	5	RESET_LCD	GP I/O	Output	0	0	0	n/a
1	6	SPI_SIMO	Function	UCB0SIMO/UCB0SDA	1	0	0	n/a
1	7	SPI_SOMI	Function / In Digital	UCB0SOMI/UCB0SCL	1	0	0	1
2	0	USB_TXD	Function / Out Digital	UCA0TXD/UCA0SIMO	1	0	0	n/a
2	1	USB_RXD	Function / In Digital	UCA0RXD/UCA0SOMI	1	0	0	0
2	2	SPI_SCK	Function / Out Digital	UCB0CLK	1	0	1	n/a
2	3	UNKNOWN	GP I/O	Input	0	0	0	0
2	4	UNKNOWN	GP I/O	Input	0	0	0	0
2	5	CPU_TXD	Function / Out Digital	UCA1TXD/UCA1SIMO	1	0	0	n/a
2	6	CPU_RXD	Function / In Digital	UCA1RXD/UCA1SOMI	1	0	0	0
2	7	UNKNOWN	GP I/O	Input	0	0	0	0
3	0	X	GP I/O	Input	0	0	0	0
3	1	Y	GP I/O	Input	0	0	0	0
3	2	Z	GP I/O	Input	0	0	0	0
3	3	IR_LED	GP I/O	Output	0	0	0	n/a
3	4	R_FORWARD	GP I/O	Output	0	0	0	n/a
3	5	L_FORWARD	GP I/O	Output	0	0	0	n/a
3	6	R_REVERSE	GP I/O	Output	0	0	0	n/a
3	7	L_REVERSE	GP I/O	Output	0	0	0	n/a
4	0	SW1	GP I/O	Input	0	0	1	1
4	1	SW2	GP I/O	Input	0	0	1	1
J	0	IOT_WAKEUP	GP I/O	Output	0	0	0	n/a
J	1	IOT_FACTORY	GP I/O	Output	0	0	0	n/a
J	2	IOT_STA_MINIAP	GP I/O	Output	0	0	0	n/a
J	3	IOT_RESET	GP I/O	Output	0	0	0	n/a

# Configure Port 1

```

void Init_Port1(void){
// Configure Port 1 -----
// V_DETECT_R      (0x01) // Voltage from Right Detector
// V_DETECT_L      (0x02) // Voltage from Right Detector
// LCD_BACKLITE    (0x04) // Control Signal for LCD_BACKLITE
// V_THUMB         (0x08) // Voltage from Thumb Wheel
// SPI_CS_LCD      (0x10) // LCD Chip Select
// RESET_LCD       (0x20) // LCD Reset
// SIMO_B          (0x40) // SPI mode - slave in/master out of USCI_B0
// SOMI_B          (0x80) // SPI mode - slave out/master in of USCI_B0
//-----
P1SEL0 = 0x00;          // P1 set as I/O
P1SEL1 = 0x00;          // P1 set as I/O
P1DIR = 0x00;          // Set P1 direction to input

P1SEL0 |= V_DETECT_R;   // V_DETECT_R selected
P1SEL1 |= V_DETECT_R;   // V_DETECT_R selected

P1SEL0 |= V_DETECT_L;   // V_DETECT_L selected
P1SEL1 |= V_DETECT_L;   // V_DETECT_L selected

P1SEL0 &= ~LCD_BACKLITE; // LCD_BACKLITE GPIO selected
P1SEL1 &= ~LCD_BACKLITE; // LCD_BACKLITE GPIO selected
P1OUT |= LCD_BACKLITE;   // LCD_BACKLITE Port Pin set low
P1DIR |= LCD_BACKLITE;   // Set LCD_BACKLITE direction to output

P1SEL0 |= V_THUMB;      // V_THUMB selected
P1SEL1 |= V_THUMB;      // V_THUMB selected

P1SEL0 &= ~SPI_CS_LCD;   // SPI_CS_LCD GPIO selected
P1SEL1 &= ~SPI_CS_LCD;   // SPI_CS_LCD GPIO selected
P1OUT |= SPI_CS_LCD;    // SPI_CS_LCD Port Pin set high
P1DIR |= SPI_CS_LCD;    // Set SPI_CS_LCD output direction

P1SEL0 &= ~RESET_LCD;    // RESET_LCD GPIO selected
P1SEL1 &= ~RESET_LCD;    // RESET_LCD GPIO selected
P1OUT &= ~RESET_LCD;     // RESET_LCD Port Pin set low
P1DIR |= RESET_LCD;     // Set RESET_LCD output direction

P1SEL0 &= ~SIMO_B;       // SIMO_B selected
P1SEL1 |= SIMO_B;        // SIMO_B selected
P1DIR |= SIMO_B;         // SIMO_B set to Output
P1SEL0 &= ~SOMI_B;       // SOMI_B is used on the LCD

P1SEL1 |= SOMI_B;        // SOMI_B is used on the LCD
P1OUT |= SOMI_B;         // SOMI_B Port Pin set for Pull-up
P1DIR &= ~SOMI_B;        // SOMI_B set to Input
P1REN |= SOMI_B;         // Enable pullup resistor
//-----

```

# Configure Port J

```
void Init_PortJ(void){
//-----
// Port J Pins
// LED1                (0x01) // LED 5
// LED2                (0x02) // LED 6
// LED3                (0x04) // LED 7
// LED4                (0x08) // LED 8
// XINR                (0x10) // XINR
// XOUTR               (0x20) // XOUTR
//-----
PJSEL0 = 0x00;          // PJ set as I/O
PJSEL1 = 0x00;          // PJ set as I/O
PJDIR = 0x00;           // Set PJ direction to output

PJSEL0 &= ~LED1;
PJSEL1 &= ~LED1;
PJOUT &= ~LED1;
PJDIR |= LED1;          // Set PJ Pin 1 direction to output

PJSEL0 &= ~LED2;
PJSEL1 &= ~LED2;
PJOUT &= ~LED2;
PJDIR |= LED2;          // Set PJ Pin 2 direction to output

PJSEL0 &= ~LED3;
PJSEL1 &= ~LED3;
PJOUT &= ~LED3;
PJDIR |= LED3;          // Set PJ Pin 3 direction to output

PJSEL0 &= ~LED4;
PJSEL1 &= ~LED4;
PJDIR |= LED4;          // Set PJ Pin 4 direction to output
PJOUT &= ~LED4;

// XT1 Setup
// PJSEL0 |= XINR;
// PJSEL0 |= XOUTR;

//-----
}
```

# Configure Port J

```

void Init_PortJ(void){
//-----
// Port J Pins
// LED1                (0x01) // LED 5
// LED2                (0x02) // LED 6
// LED3                (0x04) // LED 7
// LED4                (0x08) // LED 8
// XINR                (0x10) // XINR
// XOUTR               (0x20) // XOUTR
//-----
PJSEL0 = 0x00;           // PJ set as I/O
PJSEL1 = 0x00;           // PJ set as I/O
PJDIR = 0x00;           // Set PJ direction to output

PJSEL0 &= ~LED1;
PJSEL1 &= ~LED1;
PJOUT &= ~LED1;
PJDIR |= LED1;           // Set PJ Pin 1 direction to output

PJSEL0 &= ~LED2;
PJSEL1 &= ~LED2;
PJOUT &= ~LED2;
PJDIR |= LED2;           // Set PJ Pin 2 direction to output

PJSEL0 &= ~LED3;
PJSEL1 &= ~LED3;
PJOUT &= ~LED3;
PJDIR |= LED3;           // Set PJ Pin 3 direction to output

PJSEL0 &= ~LED4;
PJSEL1 &= ~LED4;
PJDIR |= LED4;           // Set PJ Pin 4 direction to output
PJOUT &= ~LED4;

// XT1 Setup
// PJSEL0 |= XINR;
// PJSEL0 |= XOUTR;

//-----
}

```

## What is Wrong?