

# MEAN CONNECTOME

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## 1. POSED STATISTICAL DECISION THEORETIC

This is an attempt to follow my notes from class and replicate what we discussed.

1.1. **Sample Space.**  $\Omega = \mathcal{A}_n = \{0, 1\}^{n \times n}$ , the set of adjacency matrices  $\mathcal{A}_n$  on graphs  $\mathcal{G}_n = (V, E, Y)$ .

1.2. **Model.**  $P = SBM_n^k(\rho, \beta)$ . We posit the probability of an edge between  $u, v$  is given by  $P(u \sim v) = P_{uv}$  and the distribution of edges between any pair of vertices  $u, v$  is  $a_{u,v} \sim \text{Bern}(P_{uv})$

1.3. **Action Space.**  $A = (0, 1)^n \subseteq \Theta$ , where  $\Theta$  is the parameter space. This is desirable since this is a parameter estimation problem.

1.4. **Decision Rule Class.** The decision rule is to minimize the loss defined by the loss function below.

1.5. **Loss Function.**  $l : \Theta \times A \rightarrow \mathbb{R}_{>0}$  where  $l(\theta, \delta(\Omega))$  is the cost of action  $\delta$  under parameter  $\theta$ . More explicitly,  $l(\theta, \delta(\Omega)) = \prod_{uv} \hat{P}_{uv}^{a_{uv}} (1 - \hat{P}_{uv}^{1-a_{uv}})$ , where  $\hat{P}_{uv} = \frac{1}{m} \sum^m a_{uv} + \frac{\epsilon}{m^2}$  such that  $\frac{\epsilon}{m^2} \leftarrow 0$  asymptotically. Since  $P_{uv} \in [0, 1]$ , you have issues at the boundaries when  $P_{uv} = 0$  or  $1$ , as the whole estimation becomes zero probability. Thus the use of  $\hat{P}$  is a necessary smoothing.

1.6. **Risk Function.**  $R(\theta, \delta) = E_p(L(\theta, \delta(\Omega)))$ . The risk function is taken as the expected loss.