

Xue Bin (Jason) Peng
Year 2, Master of Science in Computer Science
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EDUCATION/AWARDS

- **MSc in Computer Science**, *University of British Columbia* 2015 – expected 2017
 - NSERC Canada Graduate Scholarship Master’s Award
 - Theodore E Arnold Fellowship
 - CS Merit Award
- **Computer Science Honours**, *University of British Columbia* 2010 – 2015
 - Grade average: 95.6 %
 - Governor-General’s Silver Medal in Science
 - Norman A M MacKenzie Scholarship
 - President’s Entrance Scholarship
 - Trek Excellence Scholarship
 - Greer Family Scholarship
 - Charles and Jane Banks Scholarship
 - Marie Kendall Memorial Scholarship in Science
 - Computer Science Scholarship
- **School of Interactive Arts and Technology**, *Simon Fraser University* 2009 – 2010
 - Gordon M. Shrum Scholarship

PUBLICATIONS

Refereed Journals/Conferences

- **Peng, X. B.**, Berseth, G., and van de Panne, M. Terrain-adaptive locomotion skills using deep reinforcement learning. *ACM Transactions on Graphics (Proc. SIGGRAPH 2016)* 35, 5 (2016).
- **Peng, X. B.**, Berseth, G., and van de Panne, M. Dynamic Terrain Traversal Skills Using Reinforcement Learning. *ACM Transactions on Graphics (Proc. SIGGRAPH 2015)* 34, 4 (2015).

Non-Refereed

- **Peng, X. B.**, and van de Panne, M. Learning Locomotion Skills Using DeepRL: Does the Choice of Action Space Matter? *arXiv preprint arXiv:1611.01055*. (2016).

Posters and Abstracts

- **Peng, X. B.**, Berseth, G., and van de Panne, M. Learning Locomotion Skills Using DeepRL: Does the Choice of Action Space Matter? *NIPS Deep Reinforcement Learning Workshop*, (2016).
- **Peng, X. B.**, Berseth, G., and van de Panne, M. Terrain-adaptive locomotion skills using deep reinforcement learning. *NIPS Deep Learning Symposium*, (2016).
- **Peng, X. B.**, Berseth, G., and van de Panne, M. Dynamic Locomotion Across Variable Terrains Using Deep Reinforcement Learning. *Dynamic Walking*, (2016).
- **Peng, X. B.**, Berseth, G., and van de Panne, M. Dynamic Locomotion Skills for Obstacle Sequences Using Reinforcement Learning. *Dynamic Walking*, (2015).

- **Peng, X. B.,** Berseth, G., and van de Panne, M. Learning Dynamic Locomotion Skills for Terrains with Obstacles. Reinforcement Learning and Decision Making, (2015).

WORK EXPERIENCE

Research Assistant, University of British Columbia 2015 - 2017

- Developed methods to train motion control policies for physics-based character simulation

Graduate Teaching Assistant, University of British Columbia Jan – April 2017

- Hosted office hours
- Wrote code for assignments
- Graded assignments and exams

Research Intern, Adobe Research May – Aug, 2015

- Explored methods for physically-plausible motion control of simulated characters

Lab Associate (Intern), Disney Research Pittsburgh Jan – May, 2015

- Developed models of human gameplay strategies through imitation learning
- Instrumented game to collect player data

Undergraduate Teaching Assistant, University of British Columbia 2011 - 2014

- Directed labs and hosted office hours
- Wrote code for assignments
- Graded assignments and exams

Intern Software Developer, Microsoft Studios May – Nov, 2013

- Developed real-time analytic approximation of area lights with different BRDFs
- Implemented clustered forward lighting
- Implemented environment map volumes and parallax correction

Co-op Rendering Engineer, Capcom Vancouver Jan – Aug, 2012

- Designed and created various rendering features through HLSL and C++
- Designed a system for physically inspired image based lighting, utilizing real-time generation of dynamic environment maps
- Implemented subsurface scattering for skin, distance field text and decal rendering, vertex animation, deferred lights, HDR cubemap support for Maya, and a variety of post-effects

TECHNICAL SKILLS

| Programming Languages : | Software : |
|--|---|
| <ul style="list-style-type: none"> • Most fluent: C++, Matlab, HLSL/GLSL • C#, Python, Java, Haskell, Prolog | <ul style="list-style-type: none"> • Microsoft Visual Studio • Photoshop • Git • Perforce |

PROJECTS

Deep Terrain RL (2016):

- Applied deep reinforcement learning to train policies that enable simulated characters to agilely traverse across irregular terrain
- Developed mixture model policy representation that enable specialization of sub-policies
- Implemented locomotion controllers
- Integrated Caffe deep learning framework
- Build parallel training framework to speed up training of neural networks

GPU Fluid Simulation (2014) :

- Developed a real-time smoke simulation using an Eulerian discretization
- Implemented vorticity confinement and GPU solid voxelization of meshes
- Added a real-time volumetric scattering with an isotropic model for smoke rendering

Soft Body Simulation (2014) :

- Implemented Fast Lattice Shape Matching for mesh deformation
- Created a CPU voxelizer to generate space deformation cages for meshes

Personal Rendering Projects (2012) :

- GPU 3D fractal raymarcher with distance estimators
- Implemented Preetham/Hosek physics-based sky model
- Created Crepuscular rays as a post effect

Fractal Flakes (2011) :

- Create an interactive program that generates various 2D fractals