## **VC Dimension**

#### **PAC** and Agnostic Learning

Finite H, assume target function c ∈ H

$$Pr(\exists h \in H, \ s.t. \ (error_{train}(h) = 0) \land (error_{true}(h) > \epsilon) \ ) \le |H|e^{-\epsilon m}$$

• Suppose we want this to be at most  $\delta$ . Then m examples suffice:

$$m \ge \frac{1}{\epsilon} (\ln|H| + \ln(1/\delta))$$

Finite H, agnostic learning: perhaps c not in H

$$P(\exists h \in H, |\epsilon(h) - \hat{\epsilon}(h)| > \gamma) \leqslant 2k \exp(-2\gamma^2 m)$$

• 
$$\rightarrow$$
  $m \ge \frac{1}{2\gamma^2} \log \frac{2k}{\delta}$ 

with probability at least (1-δ) every h in H satisfies

$$\epsilon(\hat{h}) \le \left(\min_{h \in H} \epsilon(h)\right) + 2\sqrt{\frac{1}{m}\log\frac{2k}{\delta}}$$

### What if H is not finite?

Can't use our result for infinite H

- Need some other measure of complexity for H
  - Vapnik-Chervonenkis (VC) dimension!

## Shattering a Set of Instances



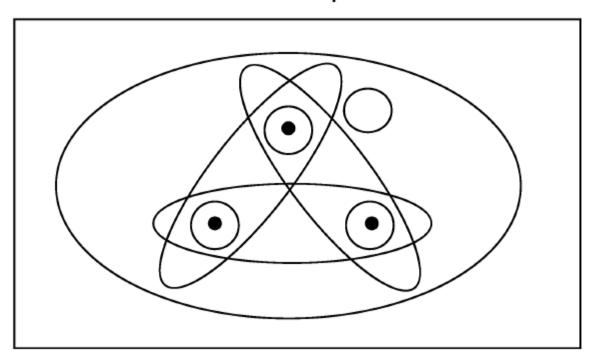
• Definition: Given a set  $S = \{x^{(1)}, \dots, x^{(m)}\}$  (no relation to the training set) of points  $x^{(i)} \in X$ , we say that  $\mathcal{H}$  shatters S if  $\mathcal{H}$  can realize any labeling on S.

I.e., if for any set of labels  $\{y^{(1)}, \dots, y^{(d)}\}$ , there exists some  $h \in \mathcal{H}$  so that  $h(x^{(i)}) = y^{(i)}$  for all  $i = 1, \dots, m$ .

• There are 2<sup>m</sup> different ways to separate the sample into two sub-samples (a dichotomy)

#### Three Instances Shattered

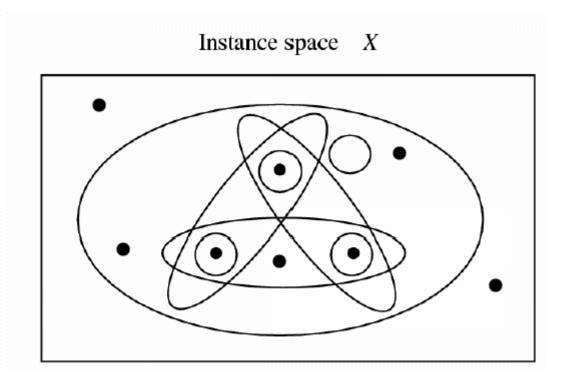
#### Instance space X



# The Vapnik-Chervonenkis Dimension



• Definition: The Vapnik-Chervonenkis dimension, VC(H), of hypothesis space H defined over instance space X is the size of the largest finite subset of X shattered by H. If arbitrarily large finite sets of X can be shattered by H, then  $VC(H) \equiv \infty$ .



## VC dimension: examples

Consider  $X = \mathbb{R}$ , want to learn c:  $X \rightarrow \{0,1\}$ What is VC dimension of

Open intervals:

H1: if x>a, then y=1 else y=0

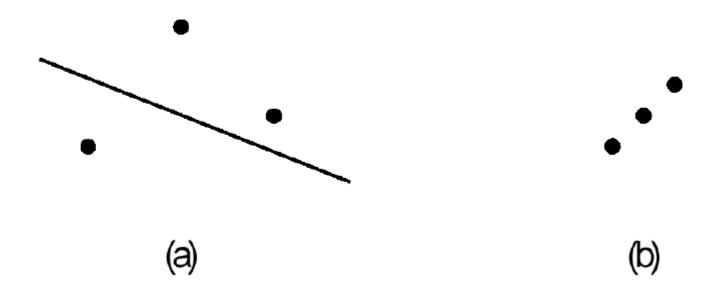
Closed intervals:

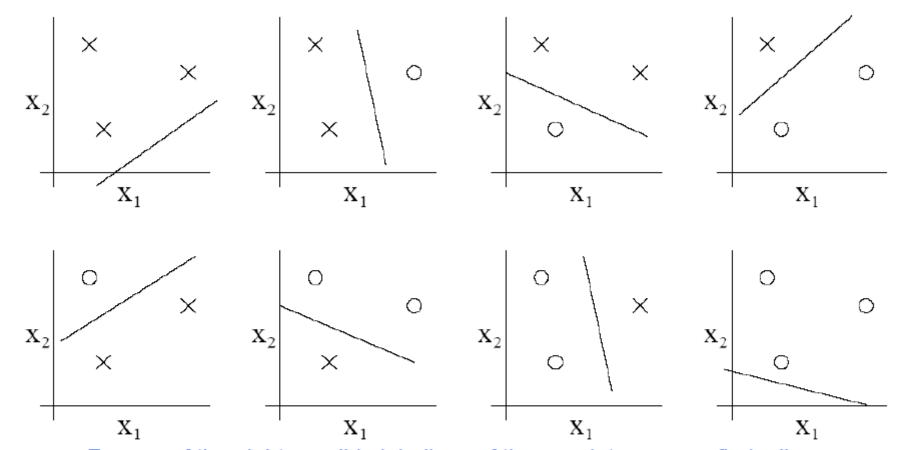
H2: if a < x < b, then y = 1 else y = 0

## VC dimension: examples

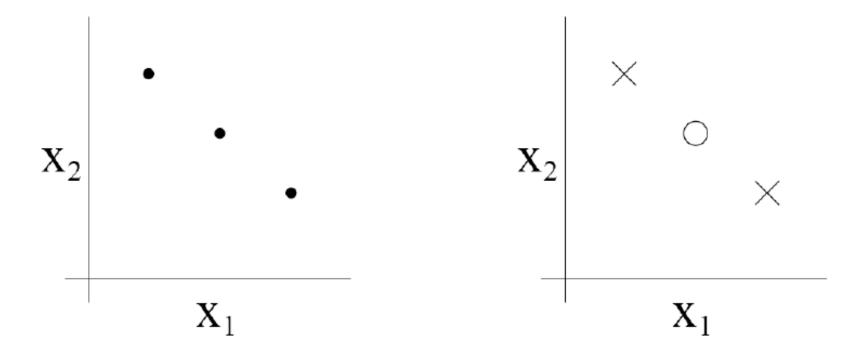
Consider  $X = \mathbb{R}^2$ , want to learn c:  $X \rightarrow \{0,1\}$ 

What is VC dimension of lines in a plane?
 H= { ((wx+b)>0 → y=1) }





- For any of the eight possible labelings of these points, we can find a linear classier that obtains "zero training error" on them.
- Moreover, it is possible to show that there is no set of 4 points that this hypothesis class can shatter.



- The VC dimension of H here is 3 even though there may be sets of size 3 that it cannot shatter.
- under the definition of the VC dimension, in order to prove that VC(H) is at least
  d, we need to show only that there's at least one set of size d that H can shatter.

 Theorem Consider some set of m points in R<sup>n</sup>. Choose any one of the points as origin. Then the m points can be shattered by oriented hyperplanes if and only if the position vectors of the remaining points are linearly independent.

• **Corollary**: The VC dimension of the set of oriented hyperplanes in  $\mathbb{R}^n$  is n+1.

Proof: we can always choose n + 1 points, and then choose one of the points as origin, such that the position vectors of the remaining n points are linearly independent, but can never choose n + 2 such points (since no n + 1 vectors in  $\mathbb{R}^n$  can be linearly independent).

## Sample Complexity from VC Dimension



 How many randomly drawn examples suffice to ε-exhaust VS<sub>H,S</sub> with probability at least (1 - δ)?

ie., to guarantee that any hypothesis that perfectly fits the training data is probably  $(1-\delta)$  approximately  $(\epsilon)$  correct on testing data from the same distribution

$$m \ge \frac{1}{\varepsilon} (4 \log_2(2/\delta) + 8VC(H) \log_2(13/\varepsilon))$$

Compare to our earlier results based on |H|:

$$m \ge \frac{1}{2\varepsilon^2} (\ln |H| + \ln(1/\delta))$$

#### The Vapnik-Chervonenkis dimension

- The Vapnik-Chervonenkis dimension of H is d if there exists such an S, |S|=d which it can shatter, but it cannot shatter any S for |S|=d+1 (If it can shatter any finite S then  $VCD=\infty$ .)
- Theorem: Let C be a concept class,a and H a representation set for which VCD(H)=d. Let L be a learning algorithm that learns  $c \in C$  by getting a set S of training samples with |S|=m, and it outputs a hypothesis  $h \in H$  which is consistent with S. The learning of C over H is PAC learning if

$$m \ge c_0 \frac{1}{\varepsilon} \left( d \log \frac{1}{\varepsilon} + \log \frac{1}{\delta} \right)$$

(where  $c_0$  is a proper constant)

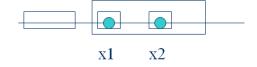
• Remark: In contrary to the finite case, the bound obtained here is tight (that is, m samples are not only sufficient, but in certain cases they are necessary as well).

#### The Vapnik-Chervonenkis dimension

- Let's compare the bounds obtained for the finite and infinite cases:
- Finite case:  $m \ge \frac{1}{\varepsilon} (\ln |H| + \ln(\frac{1}{\delta}))$
- Infinite case:  $m \ge c_0 \frac{1}{\varepsilon} \left( d \log \frac{1}{\varepsilon} + \log \frac{1}{\delta} \right)$
- The two formulas look quite similar, but the role of |H| is taken by the Vapnik-Chervonenkis dimension in the infinite case
  - Both formulas increase relatively slowly as a function of  $\varepsilon$  and  $\delta$ , so in this sense these are not bad boundaries...

#### **Examples of VC-dimension**

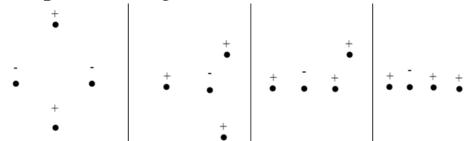
- Finite intervals over the line: VCD=2
  - VCD≥2, as **these** two points can be shattered:
     (=separated for all label configurations)



– VCD<3, as **no** 3 points can be shattered:



- Separating the two classes by lines on the plane: VCD=3 (in d-dimensional space: VCD=d+1)
  - VCD ≥3, as these 3 points can be shattered:
     (all labeling configurations should be tried!) :
  - VCD<4, as no 4 points can be shattered:</li>
     (all point arrangements should be tried!)



#### **Examples of VC-dimension**

- Axis-aligned rectangles on the plane: VCD=4
  - VCD≥4, as these 4 points can be shattered:
  - VCD<5, as **no** 5 points can be shattered:



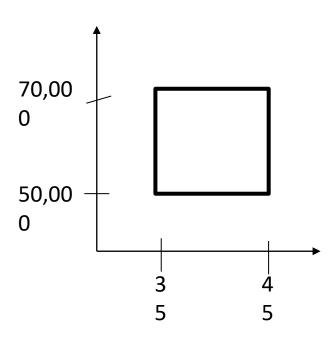
- Convex poligons on the prane: v = 2d+1 (d is the number of vertices) (the book proofs only one of the directions)
- Conjunctions of literals over  $\{0,1\}^n$ : VCD=n (See Mitchell's book, only one direction is proved)

## Examples

- Intervals of the real axis:
  - $Vcdim = 2, H[n] = O(n^2)$
- Rectangle with axis-parallel edges:
  - $Vcdim = 4, H[n] = O(n^4)$
- Union of 2 intervals of the real axis (Divide an orders set of numbers into two different intervals)
  - $-Vcdim = 4, H[n] = O(n^4)$
- Convex polygons:
  - $-Vcdim \rightarrow \infty$ ,  $H[n] = 2^n$

## Example

- Consider a database consisting of the salary and age for a random sample of the adult population in the United States.
- We are interested in using the database to answer the question:
- What fraction of the adult population in the US has:
- age between 35 and 45
- salary between 50,000\$ and 70,000\$?



#### Axis Aligned Rectangles

Let  $\mathcal{H}$  be the class of axis aligned rectangles, formally:

$$\mathcal{H} = \{h_{(a_1, a_2, b_1, b_2)} : a_1 \le a_2 \text{ and } b_1 \le b_2\}$$

where

$$h_{(a_1,a_2,b_1,b_2)}(x_1,x_2) = \begin{cases} 1 & \text{if } a_1 \le x_1 \le a_2 \text{ and } b_1 \le x_2 \le b_2 \\ 0 & \text{otherwise} \end{cases}$$
 (6.2)

#### The Natarajan Dimension

Natarajan dimension, which is a generalization of the VC dimension to classes of multiclass predictors.

let  $\mathcal{H}$  be a hypothesis class of multiclass predictors; namely, each  $h \in \mathcal{H}$  is a function from  $\mathcal{X}$  to [k].

To define the Natarajan dimension, we first generalize the definition of shattering. DEFINITION 29.1 (Shattering (Multiclass Version)) We say that a set  $C \subset \mathcal{X}$  is shattered by  $\mathcal{H}$  if there exist two functions  $f_0, f_1 : C \to [k]$  such that

- For every  $x \in C$ ,  $f_0(x) \neq f_1(x)$ .
- For every  $B \subset C$ , there exists a function  $h \in \mathcal{H}$  such that

$$\forall x \in B, h(x) = f_0(x) \text{ and } \forall x \in C \setminus B, h(x) = f_1(x).$$

DEFINITION 29.2 (Natarajan Dimension) The Natarajan dimension of  $\mathcal{H}$ , denoted Ndim( $\mathcal{H}$ ), is the maximal size of a shattered set  $C \subset \mathcal{X}$ .

It is not hard to see that in the case that there are exactly two classes,  $Ndim(\mathcal{H}) = VCdim(\mathcal{H})$ . Therefore, the Natarajan dimension generalizes the VC dimension. We next show that the Natarajan dimension allows us to generalize the fundamental theorem of statistical learning from binary classification to multiclass classification.

## Thanks