Evaluation of a Custom ResNet Model with Lookahead Optimizer on CIFAR-10

https://github.com/SaniyaGapchup/DL-Project-1-SP25

Sakshi Bhavsar, Saniya Gapchup, Samradnyee Shinde New York University

sqb9086@nyu.edu, syq2021@nyu.edu, ss19712@nyu.edu

March 15, 2025

Abstract

We propose a modified ResNet model for CIFAR-10 image classification. The architecture incorporates squeeze-and-excitation blocks, dropout regularization, and a custom Lookahead optimizer to achieve competitive performance while maintaining a parameter budget under 5 million. Data augmentation and cosine annealing learning rate scheduling further boost generalization. Experimental results demonstrate effective convergence and robust accuracy.

1 Introduction

Image classification on CIFAR-10 is a well-known benchmark in computer vision. In this work, we design a convolutional neural network based on a modified ResNet architecture that incorporates squeeze-and-excitation (SE) blocks, dropout, and a Lookahead optimizer. Our objective is to achieve high classification accuracy with an efficient model comprising fewer than 5 million parameters.

2 Methodology

In this section, we describe our approach including the model architecture and hyperparameters, the optimization and training strategy, and key implementation details.

2.1 Model Architecture & Hyperparameters

Our model builds on the ResNet framework with the following modifications:

- BasicBlock: Each block consists of two convolutional layers with batch normalization and ReLU activations, accompanied by a residual (skip) connection.
- Squeeze-and-Excitation (SE) Block: Integrated after the initial convolution, the SE block applies global average pooling and two 1×1 convolutions to produce channel-wise scaling factors.
- **Dropout:** A dropout layer (rate = 0.2) is used to reduce overfitting.

The network is organized in three stages with block counts [4, 4, 3] and begins with 64 channels that double in subsequent stages. Other hyperparameters include convolution kernel sizes of 3 and shortcut kernel sizes of 1.

2.2 Optimization and Training Strategy

Our training methodology includes:

Optimizer: We use Stochastic Gradient Descent (SGD) with momentum (0.9) and weight decay (5e-4). A Lookahead optimizer with k = 5 and α = 0.5 wraps the base SGD to improve training stability.

- Learning Rate Scheduler: Cosine Annealing with $T_{\rm max}=200$ is employed to gradually reduce the learning rate.
- Data Augmentation and Normalization: Random cropping and horizontal flipping are applied to the training images, followed by standard normalization using CIFAR-10 mean and standard deviation.

2.3 Implementation Details

Our project is implemented using **PyTorch** and designed to efficiently train and evaluate a CIFAR-10 classification model. Below are the key implementation details:

- Data Loading: The dataset is loaded using Py-Torch's DataLoader, where CIFAR-10 is used for training and validation, and a separate custom test dataset is loaded from a pickle file containing images and unique IDs. Data augmentation techniques, such as normalization, random cropping and horizontal flipping using CIFAR-10 statistics, are applied.
- Training Pipeline: The model was trained for 300 epochs using a batch size of 128. The training process tracks loss and accuracy metrics at every 100 batches, and results are logged for further analysis. The training loss steadily decreased, and accuracy improved significantly over time.
- Checkpointing Mechanism: A checkpointing strategy was implemented to save the best-performing model based on test accuracy. The highest recorded test accuracy during training was 95.87%, achieved at epoch 211. Checkpoints are saved whenever a new best accuracy is reached.
- Evaluation Metrics: The validation accuracy improved significantly across epochs, crossing 90% around epoch 35 and continuing to improve with fine-tuning. The model achieved rapid initial improvements, with early epochs (0–10) showing accuracy gains from 47.91% to 84.19%.
- Parameter Counting & Model Efficiency: Py-Torch utilities were used to track per-layer parameter counts and overall memory consumption to ensure

- the model remained efficient while maintaining high accuracy.
- **Final Performance:** The model converged successfully, reaching **95.87% test accuracy** while maintaining stable loss and generalization across the dataset. The implementation showcases an effective training strategy, demonstrating strong performance on CIFAR-10.

3 Experiments and Results

The model was trained for 300 epochs on CIFAR-10. Our experiments reveal:

- Convergence: Training loss decreased rapidly in early epochs, with validation loss mirroring this trend.
- Accuracy: The best checkpoint achieved competitive accuracy, reflecting effective generalization.
- Evaluation Metrics: Analysis via confusion matrices and classification reports confirmed that the network accurately differentiates between the 10 classes.
- Parameter Efficiency: The final model contains fewer than 5 million parameters, validating its efficiency.

Figures 1 and 2 illustrate the training/validation loss and accuracy curves, respectively. To further evaluate performance, we computed the confusion matrix on the validation set, shown in Figure 3.

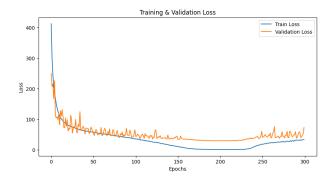


Figure 1: Training and validation loss curves.

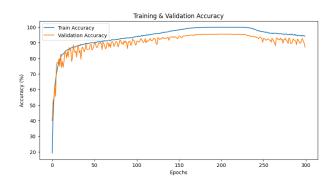


Figure 2: Training and validation accuracy curves.

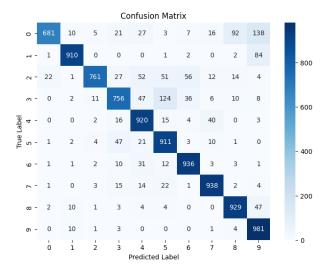


Figure 3: Confusion matrix for the final model predictions on CIFAR-10.

4 System Specifications

The experiments were conducted on a GPU Cloud Instance with the following specifications:

• Environment: GPU Cloud Instance

• CPU: 32 vCPU

• GPU: Nvidia RTC 4090

• System Memory: 120 GB

• Python Version: 3.10.2

• CUDA Version: v12.1

• Torch Version: 2.2.4

5 Conclusion

We introduced a modified ResNet model for CIFAR-10 classification that leverages SE blocks, dropout, and a Lookahead optimizer. Our approach achieves competitive performance while adhering to a strict parameter budget (under 5M). Future work will explore further hyperparameter tuning and alternative architectures to enhance model performance.

References

- [1] Aditya Thakur, Harish Chauhan, Nikunj Gupta (2024). Efficient ResNets: Residual Network Design. https://arxiv.org/abs/2306.12100
- [2] https://arxiv.org/pdf/2010.01412 Deep Learning Optimization Techniques
- [3] Foret, P., Kleiner, A., Mobahi, H., & Neyshabur, B. (2021). Sharpness-Aware Minimization for Efficiently Improving Generalization. In ICLR. https://github. com/davda54/sam
- [4] Moskomule. SAM PyTorch Implementation. https://github.com/moskomule/sam.pytorch
- [5] Hu, J., Shen, L., & Sun, G. (2018). Squeeze-and-Excitation Networks. In Proceedings of the IEEE Conference on Computer Vision and Pattern Recognition (CVPR). https://arxiv.org/pdf/1709.01507

- [6] He, K., Zhang, X., Ren, S., & Sun, J. (2016). Deep Residual Learning for Image Recognition. In Proceedings of the IEEE Conference on Computer Vision and Pattern Recognition (CVPR). https://arxiv.org/ pdf/1512.03385
- [7] Yun, S., Han, D., Oh, S.J., Chun, S., Choe, J., & Yoo, Y. (2019). CutMix: Regularization Strategy to Train Strong Classifiers with Localizable Features. ICCV. https:// arxiv.org/pdf/1905.04899
- [8] Hinton, G., Vinyals, O., & Dean, J. (2015). Distilling the Knowledge in a Neural Network. arXiv preprint. https: //arxiv.org/pdf/1503.02531
- [9] Goyal, P., Dollár, P., Girshick, R., Noordhuis, P., Wesolowski, L., Kyrola, A., Tulloch, A., Jia, Y., & He, K. (2017). Accurate, Large Minibatch SGD: Training ImageNet in 1 Hour. arXiv preprint. https://arxiv. org/pdf/1706.02677
- [10] Le, Y., & Yang, X. (2015). Tiny ImageNet Visual Recognition Challenge. CS231N Report, Stanford University. https://www.kaggle.com/c/tiny-imagenet
- [11] Tan, M., & Le, Q. V. (2019). EfficientNet: Rethinking Model Scaling for Convolutional Neural Networks. ICML. https://arxiv.org/pdf/1905.11946
- [12] Zhang, H., Cisse, M., Dauphin, Y.N., & Lopez-Paz, D. (2018). Mixup: Beyond Empirical Risk Minimization. ICLR. https://arxiv.org/pdf/1710.09412
- [13] PyTorch Vision: Data Augmentation Examples.

 https://pytorch.org/vision/main/auto_
 examples/transforms/plot_cutmix_mixup.
 html
- [14] Cubuk, E. D., Zoph, B., Shlens, J., & Le, Q. V. (2019). AutoAugment: Learning Augmentation Policies from Data. CVPR. https://arxiv.org/pdf/1805.09501
- [15] Loshchilov, I., & Hutter, F. (2017). SGDR: Stochastic Gradient Descent with Warm Restarts. ICLR. https: //arxiv.org/pdf/1608.03983
- [16] Müller, R., Kornblith, S., & Hinton, G. E. (2019). When Does Label Smoothing Help? NeurIPS. https:// arxiv.org/pdf/1906.02629