

Tutorial-6.

1) Expected payoff of player playing S

$$= a(1-x) + bx$$

where x fraction of population use strategy T.

similarly, expected payoff of player playing T = $c(1-x) + dx$

S is evolutionarily stable if for all sufficiently small values of $x > 0$,

$$a(1-x) + bx > c(1-x) + dx$$

As $x \rightarrow 0$,

if $a > c$, L.H.S $>$ R.H.S

if $a < c$; L.H.S $<$ R.H.S

if $a = c$, L.H.S $>$ R.H.S when $b > d$

So, S is evolutionarily stable when

i) $a > c$ or

ii) $a = c$, $b > d$.

$$2) \begin{pmatrix} 2, 2 & 1, 2 \\ 2, 1 & 2, 2 \end{pmatrix}; A = \begin{pmatrix} 2 & 1 \\ 2 & 2 \end{pmatrix}$$

$$B = \begin{pmatrix} 2 & 2 \\ 1 & 2 \end{pmatrix}$$

NE \rightarrow

$$(e_1, e_1)$$

$$(e_2, e_2)$$

Now check whether such strategies are evolutionary stable.

• a strategy (\hat{x}, \hat{y}) is an ESS if for all $\epsilon > 0$ and all $(x, y) \in (\Delta_A \setminus \{\hat{x}\}) \times (\Delta_B \setminus \{\hat{y}\})$

$$x \cdot A(\epsilon y + (1-\epsilon)\hat{y}) < \hat{x} \cdot A(\epsilon y + (1-\epsilon)\hat{y})$$

$$(\epsilon x + (1-\epsilon)\hat{x}) \cdot B y < (\epsilon x + (1-\epsilon)\hat{x}) \cdot B \hat{y}$$

check for $(\hat{x}, \hat{y}) = (e_1, e_1)$

choose a point $\left(\left(\frac{1}{2}, \frac{1}{2}\right), \left(\frac{1}{2}, \frac{1}{2}\right)\right)$,

$$x \cdot A(\epsilon y + (1-\epsilon)\hat{y})$$

$$= \begin{pmatrix} \frac{1}{2} \\ \frac{1}{2} \end{pmatrix} \begin{pmatrix} 2 & 1 \\ 2 & 2 \end{pmatrix} \begin{pmatrix} 1-\epsilon/2 \\ \epsilon/2 \end{pmatrix}$$

$$= 2 - \frac{\epsilon}{4} > 2 - \epsilon/2$$

$$= \begin{pmatrix} 1 \\ 0 \end{pmatrix} \begin{pmatrix} 2-\epsilon/2 \\ 2 \end{pmatrix}$$

$$= \begin{pmatrix} 1 \\ 0 \end{pmatrix} \begin{pmatrix} 2 & 1 \\ 2 & 2 \end{pmatrix} \begin{pmatrix} 1-\epsilon/2 \\ \epsilon/2 \end{pmatrix}$$

$$= \hat{x} \cdot A(\epsilon y + (1-\epsilon)\hat{y})$$

$\therefore (e_1, e_1)$ is not an ESS.

on the other hand for $(\hat{x}, \hat{y}) = (e_2, e_2)$

$$x \cdot A(\epsilon y + (1-\epsilon)\hat{y}) = \begin{pmatrix} x_1 \\ 1-x_1 \end{pmatrix} \begin{pmatrix} 2 & 1 \\ 2 & 2 \end{pmatrix} \begin{pmatrix} \epsilon y_1 \\ 1-\epsilon y_1 \end{pmatrix}$$

$$= \begin{pmatrix} 0 \\ 1 \end{pmatrix} \begin{pmatrix} 1+\epsilon y_1 \\ 2 \end{pmatrix} < 2x_1 + 2(1-x_1) = 2$$

$$= \begin{pmatrix} 0 \\ 1 \end{pmatrix} \begin{pmatrix} 1+\epsilon y_1 \\ 2 \end{pmatrix}$$

$$= \begin{pmatrix} 0 \\ 1 \end{pmatrix} \begin{pmatrix} 2 & 1 \\ 2 & 2 \end{pmatrix} \begin{pmatrix} \epsilon y_1 \\ 1-\epsilon y_1 \end{pmatrix} = \hat{x} \cdot A(\epsilon y + (1-\epsilon)\hat{y})$$

and

$$(\epsilon x + (1-\epsilon)\hat{x}). By =$$

$$\begin{pmatrix} \epsilon x_1 \\ 1-\epsilon x_1 \end{pmatrix} \begin{pmatrix} 2 & 2 \\ 1 & 2 \end{pmatrix} \begin{pmatrix} y_1 \\ 1-y_1 \end{pmatrix}$$

$$= 2\epsilon x_1 + (2-y_1)(1-\epsilon x_1)$$

$$< 2\epsilon x_1 + 2(1-\epsilon x_1) = 2$$

$$= \begin{pmatrix} \epsilon x_1 \\ 1-\epsilon x_1 \end{pmatrix} \begin{pmatrix} 2 & 2 \\ 1 & 2 \end{pmatrix} \begin{pmatrix} 0 \\ 1 \end{pmatrix}$$

$$= \hat{y}^T B (\epsilon x + (1-\epsilon)\hat{x})$$

$\therefore (e_1, e_2)$ is an ESS.

$$\underline{3} \quad \begin{pmatrix} 1, -1 & 0, 0 \\ 0, 0 & 1, 1 \end{pmatrix}$$

Replicator eqn:-

$$\dot{x}_i = x_i ((Ay)_i - x \cdot Ay)$$

$$= x_i ((-1)^{i+1} y_i - x_1 y_1 + x_2 y_2)$$

$$\dot{y}_j = y_j ((x^T B)_j - x \cdot B y)$$

$$= y_j ((-1)^j x_j + x_1 y_1 - x_2 y_2)$$

$$x_2 = 1 - x_1, \quad y_2 = 1 - y_1$$

$$\dot{x}_1 = x_1(1 - x_1)$$

$$\dot{y}_1 = -y_1(1 - y_1)$$



$(0,1) \rightarrow \text{sink}$

$(0,0), (1,1) \rightarrow \text{saddle}$

$(1,0) \rightarrow \text{sink}$

4)

	L	R
U	0, 0	(2, 2)
D	(1, 5)	(1, 5)

Shares of U, D be $x, 1-x$

Shares of L, R be $y, 1-y$

Expected payoff of a U type individual =
 $0 \cdot y + 2 \cdot (1-y)$
 $= 2 - 2y$

U " " " " " " " =
 $1 \cdot y + 1 \cdot (1-y)$
 $= 1$

U " " " " " " " = $5 - 5x$

U " " " " " " " = $2x + 5(1-x)$
 $= 5 - 3x$

Average = $x \cdot 2(1-y) + (1-x) \cdot 1$

Replicator eqn

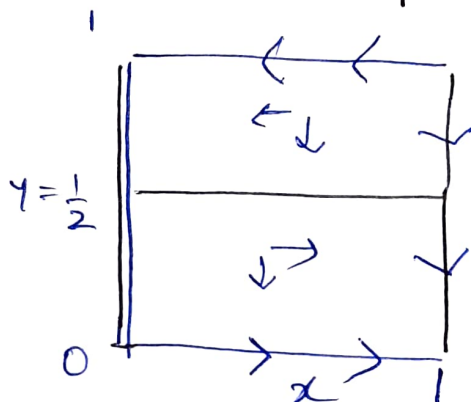
$$\frac{dx}{dt} = x [2(1-y) - x [2(1-y)] - (1-x)]$$

$$= x(1-x)(1-2y) \quad \left| \quad y = \frac{1}{2} \right.$$

$$\frac{dy}{dt} = y(1-y)(-2x)$$

Black lines $\rightarrow \frac{dx}{dt} = 0$

Blue line $\rightarrow \frac{dy}{dt} = 0$



Rest points :

$$\{ (0, y) \mid 0 \leq y \leq 1 \} \cup \{ (1, 0) \} \cup \{ (1, 1) \}$$

$$\text{if } 1 > y \geq \frac{1}{2}, 0 < x < 1 \Rightarrow \frac{dx}{dt}, \frac{dy}{dt} < 0$$

$(1, 0) \rightarrow$ stable rest point

(U, R)

observe that (U, R) is a NE as well.

\rightarrow The observation that a stable rest point of the replicator dynamics is a strict NE (This is an iff condition for 2×2 bimatrix game)
 \rightarrow Try to prove.

5

$$\begin{pmatrix} 0 & 1 & 1 \\ 1 & 0 & 1 \\ 1 & 1 & 1 \end{pmatrix}$$

$$NE :- e_3, \left(\frac{1}{2}, \frac{1}{2}, 0\right)$$

Case 1:- e_3 is an ESS or not?

for e_3 to be an ESS,

$$x \cdot A(\epsilon x + (1-\epsilon)e_3) < e_3 \cdot A(\epsilon x + (1-\epsilon)e_3)$$

Now since $x \cdot Ae_3 = 1$ for all $x \in \Delta$,

$$\Rightarrow x \cdot Ax < e_3 \cdot Ax$$

$$x \cdot Ax = \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} \begin{pmatrix} 10x_2 + x_3 \\ 10x_1 + x_3 \\ 1 \end{pmatrix} \\ = 20x_1x_2 + (1+x_1+x_2)x_3$$

$$e_3 \cdot Ax = 1$$

$$\text{choose } \tilde{x} = \begin{pmatrix} \frac{1}{2} \\ \frac{1}{2} \\ 0 \end{pmatrix} \in \Delta - \{e_3\}$$

$$\text{then } \tilde{x} \cdot A\tilde{x} = 5 > 1 = e_3 \cdot A\tilde{x}$$

$\therefore e_3$ is not an ESS.

Case 2:- For $\tilde{x} = \left(\frac{1}{2}, \frac{1}{2}, 0\right)$ to be an ESS,

$y \cdot Ay < \tilde{x} \cdot Ay$ holds for all $y \neq \tilde{x}$ in the neighbourhood of \tilde{x} .

let $y = \left(\frac{1}{2} + \delta_1, \frac{1}{2} + \delta_2, 1 - \delta_1 - \delta_2\right)$, where $\delta_1 + \delta_2 \leq 0$ (not both 0 at a time)

Then,

$$y \cdot Ay = \left(\frac{1}{2} + \delta_1\right) (5 + 10\delta_2 - \delta_1 - \delta_2) + \\ \left(\frac{1}{2} + \delta_2\right) (5 + 10\delta_1 - \delta_1 - \delta_2) - \\ \delta_1 - \delta_2$$

$$= \left(\frac{1}{2} + \delta_1\right) (5 + 9\delta_2 - \delta_1) + \\ \left(\frac{1}{2} + \delta_2\right) (5 + 9\delta_1 - \delta_2) - \\ \delta_1 - \delta_2$$

$$= 5 + 8\delta_1 + 8\delta_2 + 18\delta_1\delta_2 - \delta_1^2 - \delta_2^2$$

Similarly,

$$\tilde{x} \cdot Ay = 5 + 5\delta_1 + 5\delta_2 - \delta_1 - \delta_2 \\ = 5 + 4(\delta_1 + \delta_2)$$

$$\Rightarrow 4(\delta_1 + \delta_2) + 18\delta_1\delta_2 - \delta_1^2 - \delta_2^2 < 0 \rightarrow (1)$$

w.l.o.g assume $|\delta_2| \leq |\delta_1|$ and $\delta_2 = \lambda \delta_1$
with $|\lambda| \leq 1$

$$\Rightarrow (\lambda + 1)\delta_1 \leq 0$$

\therefore either $\delta_1 < 0$ and $\lambda \in (-1, 1]$

or $\delta_1 > 0$ and $\lambda = -1$.

so (1) becomes,
 $4(\lambda + 1)\delta_1 + 18\lambda\delta_1^2 - (\lambda^2 + 1)\delta_1^2 < 0$

with $\delta_1 < 0$, $\lambda \in (-1, 1]$ or $\delta_1 > 0$, $\lambda = -1$.

If $\delta_1 < 0$, $\lambda \in (-1, 1]$ then (2) becomes,

$$4(\lambda+1) + 18\lambda s_1 - (\lambda^2+1)s_1 > 0$$

which obviously holds for $|s_1|$ small.

If $s_1 > 0$, $\lambda = -1$ then (2) is equivalent to $-18s_1 - 2s_1 < 0$ which again holds.

$\therefore \tilde{x}$ is an ESS.

$$b). \quad B = A + \begin{pmatrix} 1 & 0 & 0 \\ 1 & 0 & 0 \\ 1 & 0 & 0 \end{pmatrix}$$

$$\dot{x}_i = x_i ((Bx)_i) - x \cdot Bx$$

$$= x_i \left(\left(Ax + \begin{pmatrix} 1 & 0 & 0 \\ 1 & 0 & 0 \\ 1 & 0 & 0 \end{pmatrix} x \right) \right) -$$

$$x \cdot Ax - x \cdot \begin{pmatrix} 1 & 0 & 0 \\ 1 & 0 & 0 \\ 1 & 0 & 0 \end{pmatrix} x$$

$$= x_i \left(\left(Ax + \begin{pmatrix} x_1 \\ x_1 \\ x_1 \end{pmatrix} \right) \right) -$$

$$x \cdot Ax - x_1(x_1 + x_2 + x_3)$$

$$= x_i ((Ax)_i + x_1 - x \cdot Ax - x_1)$$

$$= x_i ((Ax)_i - x \cdot Ax)$$

The replicator dynamics of B is same as replicator dynamics of A .