Data Structures (COM 2000) Assignment 2

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Available Date: Tuesday, March 01, 2016

Due Date: 11.50 PM, Thursday, March 17, 2016

Total Mark: 80 marks

Assessment

Coursework: 40%

Assignments (20%): A1 (7%), A2 (7%), A3 (6%)

Coursework exams (20%): CWE1 (10%), CWE2 (10%)

Final Examination: 60% (one two-hour writing exam)
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Assignment Requirements

I. Part 1 [30 marks] Binary search tree

A node of a binary search tree (BST) of integers is defined as

```
typedef struct {
   int data;
   struct Node* left;
   struct Node* right;
} Node;
```

A binary search tree **root** is declared by

```
treePtr root = NULL;
```

where treePtr is defined as below.

```
typedef Node* treePtr;
```

Write a complete program **BST.c** to demonstrate basic operations on a binary search tree of integers. Your program should show the following options.

```
    Insert a new node (iteration)
    Insert a new node (recursion)
    Tree traversal
    Search a node (iteration)
    Search a node (recursion)
    Count number of nodes in tree
    Count number of leaves in tree
    Height of tree (root level = 0)
    Height of tree (root level = 1)
    Find the node with minimum key (iteration)
    Find the node with maximum key (iteration)
    Find the node with maximum key (iteration)
```

- 13. Find the node with maximum key (recursion)
- 14. Delete a node from BST (iteration)
- 15. Delete a node from BST (recursion)
- 16. Find the inorder successor (without using parent link)
- 17. Breadth-first traversal (BFT)
- 18. Exit

Select your choice (1-18):

The program allows a user to choose one of the above options by entering an integer from 1 to 18 to perform the corresponding action.

The marks are given as follows.

- 1. [1 mark] Insert a new node (iteration). The **insert()** function allows the user to iteratively insert a new element into the BST.
- 2. [1 mark] Insert a new node (recursion). The **insertR()** function allows the user to recursively add a new element into the BST.
- **3**. [1 mark] Tree traversal. This option allows the user to select the inorder, preorder, or postorder traversal by entering an integer 1, 2, or 3, respectively, to perform the corresponding action.
- 4. [2 marks] Search a node (iteration). The **search()** function iteratively searches on the BST for the specified search key **x**, where **x** is input by the user. The **search()** function returns the node containing **x** if it is found; otherwise **NULL** is returned.
- 5. [2 marks] Search a node (recursion). The **searchR()** function recursively searches on the BST for the specified search key **x**, where **x** is entered by the user. The **searchR()** function returns the node containing **x** if it is found; otherwise **NULL** is returned.
- **6**. [1 mark] Count number of nodes in tree. The **countNodes()** function returns the number of nodes in the BST.
- 7. [1 mark] Count number of leaves in tree. The **countLeaves()** function returns the number of leaf nodes in the BST.
- **8**. [1 mark] Height of tree (root level = 0). The **compHeight()** function returns the height of the BST, where the height of a tree is the length of the longest simple path from the root to a leaf and the root is counted as level 0.
- 9. [1 mark] Height of tree (root level = 1). The **numLevels()** function returns the height of the BST, where the height of a tree is the number of levels in the tree and the root is counted as level 1.
- 10. [1 mark] Find the node with minimum key (iteration). The **findMin()** function iteratively searches on the BST for the node with the smallest value **m** of the data member. The **findMin()** function returns the node containing **m**.
- 11. [1 mark] Find the node with minimum key (recursion). The **findMinR()** function recursively searches on the BST for the node with the smallest value **m** of the data member. The **findMinR()** function returns the node containing **m**.
- 12. [1 mark] Find the node with maximum key (iteration). The **findMax()** function iteratively searches on the BST for the node with the largest value **M** of the data member. The **findMax()** function returns the node containing **M**.

- 13. [1 mark] Find the node with maximum key (recursion). The **findMaxR()** function recursively searches on the BST for the node with the largest value **M** of the data member. The **findMaxR()** function returns the node containing **M**.
- 14. [5 marks] Delete a node from BST (iteration). The **Delete()** function iteratively deletes an arbitrary node of the BST. Specifically, the program asks the user to enter the data member **x** of the node to be deleted. The **Delete()** function performs the deletion operation if **x** exists in the tree and returns 1; otherwise 0 is returned. The to-be-deleted node **x** is replaced with the leftmost node of the right subtree of **x**.
- 15. [5 marks] Delete a node from BST (recursion). The **DeleteR()** function recursively deletes an arbitrary node of the BST. Specifically, the program asks the user to enter the data member **x** of the node to be deleted. The **Deleterr()** function performs the deletion operation if **x** exists in the tree and returns the new tree (i.e., the tree with **x** has been deleted); otherwise displays the message "Not found". The to-be-deleted node **x** is replaced with the leftmost node of the right subtree of **x**.
- 16. [2 marks] Find the inorder successor (without using parent link). The inorderSuccessor() function allows the user to find the inorder successor of a given node in the BST. The inorder successor of a given node is the node comes after the node in the inorder traversal of the BST. The rightmost node of the BST has no inorder successor.
- 17. [3 marks] Breadth-first traversal (BFT). The **BFT()** function traverses the tree level by level, staring at the root. At each level, the nodes are traversed from left to right.
- **18**. Quit your program.

II. Part 2 [50 marks] Hashing methods

Write the following complete C (or C++) programs.

1. LP.c to implement the linear probing method.	[10 marks]
2. QP.c to implement the quadratic probing method.	[10 marks]
3. DH.c to implement the double hashing method.	[10 marks]
4. CC.c to implement the coalesced chaining method.	[10 marks]
5. SC.c to implement the separate/direct chaining method.	[10 marks]

- Each of the above programs should displays the following menu when it is executed.
- 1. Insert a new key
- 2. Search a given key
- 3. Delete a given key
- 4. Display hash table
- 5. Quit

Select your option (1-5):

• Each of the above programs has the Insert(), Search(), Delete(), and Display() functions to perform the insertion, searching, deletion, and displaying operations, respectively. The Insert() function allows a user to insert a new key k into the hash table. It is supposed that the keys are distinct nonnegative integers. The Search() function allows a user to search

the hash table for a given key k. The **Delete()** function allows a user to delete a given key k from the hash table. The **Display()** function shows the hash table contents on the screen.

- For the **LP.c** program, the size of the hash table is M = 10. The hash function is defined as f(k) = k % M, where the symbol % is the modulo operator and the key k is a nonnegative integer. The rehash function is $f_i(k) = (f(k) + t) \% M$, where the collision count t = 1, 2, ... The **Search()** function returns the index i of k, $0 \le i \le M 1$, if k is found; otherwise, returns M. Each node of the hash table is defined by **typedef struct { int k; } Node;**
- For the QP.c program, the size of the hash table is M = 10. The hash function is defined as f(k) = k % M, where the symbol % is the modulo operator and the key k is a nonnegative integer. The rehash function is $f_t(k) = (f(k) + t^2) \% M$, where the collision count t = 1, 2, ... The Search() function returns the index i of k, $0 \le i \le M 1$, if k is found; otherwise, returns M. Each node of the hash table is defined by typedef struct { int k; } Node;
- For the **DH**.c program, the size of the hash table is M = 11. The hash function is defined as f(k) = k % M, where the symbol % is the modulo operator and the key k is a nonnegative integer. The rehash function is $f_t(k) = (f_{t-1}(k) + g(k)) \% M$, where the collision count t = 1, 2,, the second hash function is g(k) = c (k % c), the constant c = 5, $f_0(k) = f(k)$. The **Search()** function returns the index i of k, $0 \le i \le M 1$, if k is found; otherwise, returns M. Each node of the hash table is defined by **typedef struct** $\{$ **int** k; $\}$ **Node**;
- For the CC.c program, the size of the hash table is M = 10. The Search() function returns the index i of k, $0 \le i \le M 1$, if k is found; otherwise, returns M. The Delete() function works as the following illustration. Each node of the hash table is defined by typedef struct { int k; int next; } Node;

Suppose that the current state of the hash table is as follows.

Index	k	next
0	10	9
1	-1	-1
2	-1	-1
3	-1	-1
4	-1	-1
5	15	8
6	26	-1
7	35	-1
8	25	7
9	30	-1

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Index	k	next
0	10	-1
1	-1	-1
2	-1	-1
3	-1	-1
4	-1	-1
5	15	8
6	26	-1
7	35	-1
8	25	7
9	-1	-1

If 30 is deleted.

Index	k	next
0	30	-1
1	-1	-1
2	-1	-1
3	-1	-1
4	-1	-1
5	15	8
6	26	-1
7	35	-1
8	25	7
9	-1	-1

If 10 is deleted.

Index	k	next
0	10	9
1	-1	-1
2	-1	-1
3	-1	-1
4	-1	-1
5	15	8
6	26	-1
7	-1	-1
8	25	-1
9	30	-1

Index	k	next
0	10	9
1	-1	-1
2	-1	-1
3	-1	-1
4	-1	-1
5	15	8
6	26	-1
7	-1	-1
8	35	-1
9	30	-1

Index	k	next
0	10	9
1	-1	-1
2	-1	-1
3	-1	-1
4	-1	-1
5	25	8
6	26	-1
7	-1	-1
8	35	-1
9	30	-1

If 35 is deleted.

If 25 is deleted.

If 15 is deleted.

• For the SC.c program, the size of the hash table is M=10. The Search() function returns the pointer to the node containing k if k is found; otherwise, returns NULL. Each node of the hash table is defined by typedef struct { int k; struct Node *next; } Node;

Submission: **carefully** submit your source program files (i.e., *.c) to Mr. Sterling Ramroach via the email: sramroach@gmail.com.

• At the top of your program, you should include the following information.

```
/* Student Full Name:
   Student ID:
   E-mail:
   Course Code:
*/
```