

# Baez and Muniain - Gauge Fields, Knots and Gravity

## Part I: Electromagnetism

### 5 Rewriting Maxwell's Equations

**Exercise 50.** Consider a manifold  $\mathbb{R} \times S$ . Let  $E$  be a 1-form, and  $B$  a 2-form on  $S$ , such that, near  $p \in S$ ,

$$\begin{aligned} E &= E_i dx^i \\ B &= \frac{1}{2} B_{ij} dx^i \wedge dx^j \end{aligned}$$

Then, near  $(t, p) \in \mathbb{R} \times S$ , consider

$$B + E \wedge dt = \frac{1}{2} B_{ij} dx^i \wedge dx^j + E_i dx^i \wedge dt$$

But  $\{dx^i \wedge dx^j, dx^i \wedge dt\}$  spans  $\bigwedge^2 T_{(t,p)}^*(\mathbb{R} \times S)$ , so any 2-form  $F$  on  $\mathbb{R} \times S$  can be written in this way, locally. If  $F$  is globally defined, by thinking about its behaviour on the overlap between the chart we are working on and all intersecting charts, we see that also  $E$  and  $B$  must be, and we have this globally.

To show that writing  $F$  like this is unique, we just have to notice that  $\{dx^i \wedge dx^j, dx^i \wedge dt\}$  is linearly independent. Then locally,

$$\frac{1}{2} B'_{ij} dx^i \wedge dx^j + E'_i dx^i \wedge dt = \frac{1}{2} B_{ij} dx^i \wedge dx^j + E_i dx^i \wedge dt$$

only if  $B'_{ij} = B_{ij}$  and  $E'_i = E_i$ . This clearly extends to the whole manifold.

**Exercise 51.** Let  $\omega \in \Omega(\mathbb{R} \times S)$ . Locally,

$$\begin{aligned} d\omega &= d(\omega_I dx^I) \\ &= \partial_\mu \omega_I dx^\mu \wedge dx^I \\ &= dx^\mu \wedge \partial_\mu \omega_I dx^I \\ &= dx^0 \wedge \partial_0 \omega_I dx^I + dx^i \wedge \partial_i \omega_I dx^I \\ &= \partial_0 \omega_I dx^0 \wedge dx^I + \partial^i \omega_I dx^i \wedge dx^I \\ &= dt + \partial_t \omega + d_S \omega \end{aligned}$$

**Exercise 52.** Given  $v \in V$ , regard  $g(v, \cdot)$  as a map  $V \rightarrow \mathbb{R}$ . Then it can be identified as an element of  $V^*$ , and hence we have a map  $f : V \rightarrow V^*; v \mapsto g(v, \cdot)$ . Then  $\ker f = \{0\}$  by non-degeneracy, so this is injective. Then since  $V \cong V^*$ , injectivity implies surjectivity and hence this is a bijection, an isomorphism of vector spaces.

**Exercise 53.** Let the vector field  $v = v^\mu e_\mu$  correspond to the 1-form  $v_\nu f^\nu$  by  $g(v, w) = v_\nu f^\nu(w)$  for all vector fields  $w$ . Then

$$\begin{aligned} v^\mu w^\nu g_{\mu\nu} &= v_\mu f^\mu(w^\nu e_\nu) \\ &= v_\mu w^\mu \\ \Rightarrow v_\mu &= g_{\mu\nu} v^\nu \end{aligned}$$

**Exercise 54.** Let the 1-form  $\omega = \omega_\mu f^\mu$  correspond to the vector field  $\omega^\nu e_\nu$  by  $g(\omega^\nu e_\nu, v) = \omega(v)$  for all vector fields  $v$ . We could proceed as in the previous exercise, but since we already know that this correspondence is a bijection, we can just reverse that result by multiplying with the inverse metric:

$$\begin{aligned} g^{\mu\nu} \omega_\nu &= g^{\mu\nu} g_{\nu\lambda} \omega^\lambda \\ \Rightarrow \omega^\mu &= g^{\mu\nu} \omega_\nu \end{aligned}$$

**Exercise 55.** The Minkowski metric has signature (3,1), so  $\eta_{00} = \eta(e_0, e_0) = -1$  and  $\eta_{ii} = \eta(e_i, e_i) = 1$  for  $i = 1, 2, 3$ . Then in this basis

$$(\eta_{\mu\nu}) = \text{diag}(-1, 1, 1, 1)$$

**Exercise 56.**  $g^\mu_\nu = g^{\mu\lambda} g_{\lambda\nu} = \delta^\mu_\nu$  since the metric with raised indices is the inverse metric.

**Exercise 57.** Let  $(e^1, \dots, e^n)$  be an orthonormal basis with  $g(e^i, e^i) = \epsilon(i)$ , where  $\epsilon(i) = \pm 1$ . We know that

$$\{e^{i_1} \wedge \dots \wedge e^{i_p} \mid 1 \leq i_1 < \dots < i_p \leq n\}$$

gives a basis of  $p$ -forms. To see it is orthonormal, first consider

$$\langle e^{i_1} \wedge \dots \wedge e^{i_p}, e^{j_1} \wedge \dots \wedge e^{j_p} \rangle$$

If the two arguments are distinct, there is at least one  $i_k$  which is distinct from all the  $j_k$ s. Therefore there is at least one row of  $(g(e^i, e^j))$  which is full of zeroes, and hence the determinant vanishes. So this basis is orthogonal. Next consider

$$\begin{aligned}\langle e^{i_1} \wedge \dots \wedge e^{i_p}, e^{i_1} \wedge \dots \wedge e^{i_p} \rangle &= \det(g(e^{i_j}, e^{i_k})) \\ &= \prod_j g(e^{i_j}, e^{i_j}) \\ &= \prod_j \epsilon(j)\end{aligned}$$

This indeed has absolute value 1. So the basis is orthonormal. Now, the inner product is degenerate if for some  $\omega \neq 0$ ,  $\langle \omega, \eta \rangle = 0$  for all  $\eta$ . But for any  $\omega = \alpha e^{i_1} \wedge \dots \wedge e^{i_p}$ , we can always choose  $\eta = e^{i_1} \wedge \dots \wedge e^{i_p}$ , in which case

$$\langle \omega, \eta \rangle = \pm \alpha$$

which is non-zero if  $\omega$  is. So the inner product is non-degenerate.

**Exercise 58.** Consider  $\mathbb{R}^3$  with the Euclidean metric, and the 1-form

$$E = E_x dx + E_y dy + E_z dz$$

We have  $\langle dx^i, dx^j \rangle = \delta^{ij}$ , so

$$\langle E, E \rangle = E_x^2 + E_y^2 + E_z^2$$

Now consider the 2-form

$$B = B_x dy \wedge dz + B_y dz \wedge dx + B_z dx \wedge dy$$

Since the metric signature is strictly positive,

$$\langle dy \wedge dz, dy \wedge dz \rangle = 1$$

and so on, but since we need at least two non-zero components of  $g(e^i, e^j)$  for the determinant not to vanish, all the other inner products must be zero. Thus

$$\langle B, B \rangle = B_x^2 + B_y^2 + B_z^2$$

**Exercise 59.** Consider  $\mathbb{R}^4$  with the Minkowski metric, and the 2-form  $F = B + E \wedge dt$ .

$$\langle F, F \rangle = \langle B, B \rangle + 2 \langle B, E \wedge dt \rangle + \langle E \wedge dt, E \wedge dt \rangle$$

Now, the crossed term vanishes since at least two components of the corresponding matrix need to be non-zero to have a vanishing determinant. The matrix corresponding to the last term is block diagonal, so we can write

$$\langle E \wedge dt, E \wedge dt \rangle = \langle E, E \rangle \langle dt, dt \rangle = -\langle E, E \rangle$$

Thus

$$-\frac{1}{2} \langle F, F \rangle = \frac{1}{2} (\langle E, E \rangle - \langle B, B \rangle)$$

**Exercise 60.** Permuting elements of the basis of  $p$ -forms by  $\sigma \in S_p$  just introduces an additional factor  $\text{sgn } \sigma$  to the determinant, so even permutations preserve orientation, and odd ones flip it.

**Exercise 61.** Let  $M$  be oriented. Then there exists a nowhere-vanishing volume form  $\omega$  on  $M$ . Let  $(U_\alpha, \phi_\alpha)$  be a chart on  $M$ . In this chart, for some nowhere-zero function  $f$ , we can write

$$\omega = \phi_\alpha^*(f dx^1 \wedge \dots \wedge dx^n)$$

Either  $f$  is positive-definite or it is negative definite. If it is negative definite, define a new coordinate chart  $\phi'_\alpha$  on the same patch such that, if  $\phi_\alpha(p) = (x_1, \dots, x_n)$ ,  $\phi'_\alpha(p) = (x_1, \dots, x_{n-1}, -x_n)$ . Then the corresponding function  $f'$  will be positive-definite. Then, we can construct an atlas using whichever of  $\phi_\alpha$  or  $\phi'_\alpha$  gives a positive-definite  $f$  by repeating this everywhere, which is possible since  $M$  is orientable.

**Exercise 62.** We say a diffeomorphism is orientation-preserving if the pullback it induces of a basis has the same orientation as that basis. Let  $\{(U_\alpha, \phi_\alpha)\}$  be a chart on a manifold  $M$ , such that all the  $\psi_{\alpha\beta} = \phi_\alpha \circ \phi_\beta^{-1}$  are orientation-preserving. We have the standard volume form  $dx^1 \wedge \dots \wedge dx^n$  on  $\mathbb{R}^n$ , and pullbacks  $\phi_\alpha^*(dx^1 \wedge \dots \wedge dx^n)$ . Since all the transition functions are orientation-preserving, we can choose all the charts to be either orientation-preserving or orientation-reversing. Similarly to in the previous exercise, we can assume WLOG that they are all orientation-preserving. Then  $\phi_\alpha^*(dx^1 \wedge \dots \wedge dx^n)$  and  $\phi_\beta^*(dx^1 \wedge \dots \wedge dx^n)$  are volume forms on  $M$  with the same orientation, agreeing on the overlap  $U_\alpha \cap U_\beta$ . So by the smoothness of transition functions, we have a volume form everywhere on  $M$ . So  $M$  is orientable.

**Exercise 63.** Let  $M$  be oriented, and  $\{e^\mu\}$  a positively-oriented basis of  $T_p^*M$ . Write  $e^\mu = T^\mu_\nu dx^\nu$ , and regard  $T$  as a linear transformation. This transformation must be invertible,

and

$$\begin{aligned} dx^1 \wedge \dots \wedge dx^n &= (T^{-1})_{\nu_1}^1 \dots (T^{-1})_{\nu_n}^n e^{\nu_1} \wedge \dots \wedge e^{\nu_n} \\ &= \det T^{-1} e^1 \wedge \dots \wedge e^n \end{aligned}$$

But  $g_{\mu\nu}$  is calculated using two factors of  $\partial_\mu$ , so  $\det g$  transforms in the opposite way, as  $\det T^2$ . That is,

$$\text{vol}_p = \sqrt{|\det(g_{\mu\nu})_p|} dx^1 \wedge \dots \wedge dx^n = \frac{|\det T|}{\det T} e^1 \wedge \dots \wedge e^n$$

So if  $T$  is orientation preserving, i.e. if the  $e^i$  basis is of the orientation defined by the volume form, then

$$\text{vol}_p = \sqrt{|\det(g_{\mu\nu})_p|} dx^1 \wedge \dots \wedge dx^n = e^1 \wedge \dots \wedge e^n$$

**Exercise 64.** By linearity of the wedge product and Hodge star, it is sufficient to consider the  $p$ -forms

$$\begin{aligned} \omega &= e^{\mu_1} \wedge \dots \wedge e^{\mu_p} \\ \mu &= e^{\nu_1} \wedge \dots \wedge e^{\nu_p} \end{aligned}$$

From the definition of the Hodge star, we have

$$\omega \wedge * \mu = e^{\mu_1} \wedge \dots \wedge e^{\mu_p} \wedge (\pm 1) e^{\nu_{p+1}} \wedge \dots \wedge e^{\nu_n}$$

for some sign. If  $\mu_i = \nu_j$  for some  $1 \leq i \leq p$  and  $p+1 \leq j \leq n$ , this is zero, but so is  $\langle \omega, \mu \rangle$ , so certainly in that case  $\omega \wedge * \mu = \langle \omega, \mu \rangle \text{vol}$ . So we assume that this is not the case, so the  $\mu_i$  and  $\nu_j$  are distinct and we can replace  $\mu_i \rightarrow \nu_i$  for  $1 \leq i \leq p$  without any ambiguity. Then we have

$$\omega \wedge * \mu = \pm e^{\nu_1} \wedge \dots \wedge e^{\nu_n}$$

By the previous exercise, this is

$$\omega \wedge * \mu = \pm \text{vol}$$

Now, the sign is

$$\text{sgn}(\sigma_{i_1 \dots i_n}) \epsilon(i_1) \dots \epsilon(i_n) = \text{sgn}(\sigma_{i_1 \dots i_n}) g(e^{i_1}, e^{i_1}) \dots g(e^{i_n}, e^{i_n})$$

The metric factors together give the sign of the determinant when we calculate  $\langle \omega, \mu \rangle$  in the basis  $\{e^{i_1} \dots e^{i_n}\}$ , so including the permutation sign, this entire factor is the sign of the determinant when we calculate  $\langle \omega, \mu \rangle$  in the basis  $\{e^1, \dots, e^n\}$ . That is,

$$\text{sgn}(\sigma_{i_1 \dots i_n}) g(e^{i_1}, e^{i_1}) \dots g(e^{i_n}, e^{i_n}) = \det(g(e^{\mu_i}, e^{\nu_j})) = \langle \omega, \mu \rangle$$

Therefore we have

$$\omega \wedge * \mu = \langle \omega, \mu \rangle \text{vol}$$

as desired.

**Exercise 65.** Let  $\omega \in \Omega^1(\mathbb{R}^3)$  be given by  $\omega = \omega_i dx^i$ . Then

$$\begin{aligned} d\omega &= \partial_i \omega_j dx^i \wedge dx^j \\ *d\omega &= \partial_i \omega_j \varepsilon_{ijk} dx^k \end{aligned}$$

Explicitly,

$$*d\omega = \left( \frac{\partial \omega_y}{\partial z} - \frac{\partial \omega_z}{\partial y} \right) dx + \left( \frac{\partial \omega_z}{\partial x} - \frac{\partial \omega_x}{\partial z} \right) dy + \left( \frac{\partial \omega_x}{\partial y} - \frac{\partial \omega_y}{\partial x} \right) dz$$

(cf.  $\nabla \times \omega$ )

**Exercise 66.** Let  $\omega \in \Omega^1(\mathbb{R}^3)$  be given by  $\omega = \omega_i dx^i$ . Then

$$\begin{aligned} *\omega &= \omega_i \varepsilon_{ijk} dx^j \wedge dx^k \\ d * \omega &= \partial_i \omega_i dx \wedge dy \wedge dz \\ *d * \omega &= \partial_i \omega_i \\ &= \frac{\partial \omega_x}{\partial x} + \frac{\partial \omega_y}{\partial y} + \frac{\partial \omega_z}{\partial z} \end{aligned}$$

(cf.  $\nabla \cdot \omega$ )

**Exercise 67.** Consider  $\mathbb{R}^4$  with the Minkowski metric, and positively-oriented 1-form basis  $(dt, dx, dy, dz)$ . On 1-forms,

$$\begin{aligned} *dt &= -dx \wedge dy \wedge dz \\ *dx &= -dt \wedge dy \wedge dz \\ *dy &= dt \wedge dz \wedge dx \\ *dz &= -dt \wedge dx \wedge dy \end{aligned}$$

On 2-forms,

$$\begin{aligned} *dt \wedge dx &= -dy \wedge dz \\ *dt \wedge dy &= dx \wedge dz \\ *dt \wedge dz &= -dx \wedge dy \\ *dx \wedge dy &= dt \wedge dz \\ *dy \wedge dz &= dt \wedge dx \\ *dz \wedge dx &= dt \wedge dy \end{aligned}$$

On 3-forms,

$$\begin{aligned} *dt \wedge dx \wedge dy &= -dz \\ *dt \wedge dy \wedge dz &= -dx \\ *dt \wedge dz \wedge dx &= -dy \\ *dx \wedge dy \wedge dz &= -dt \end{aligned}$$

And on 4-forms,

$$*dt \wedge dx \wedge dy \wedge dz = 1$$

It is easy to check that here

$$*^2 = (-1)^{p(4-p)+1}$$

**Exercise 68.** Now we want to generalise this observation to manifolds  $M$  with signature  $(s, n-s)$ . We will use the result of Exercise 69 for simplicity. Let  $\omega$  be a  $p$ -form, in local coordinates

$$\omega = \frac{1}{p!} \omega_{i_1 \dots i_p} dx^{i_1} \wedge \dots \wedge dx^{i_p}$$

Then we have

$$\begin{aligned} *\omega &= \frac{1}{p!} \omega_{i_1 \dots i_p} \varepsilon^{i_1 \dots i_p}_{j_1 \dots j_{n-p}} e^{j_1} \wedge \dots \wedge e^{j_{n-p}} \\ *^2 \omega &= \frac{1}{p!} \omega_{i_1 \dots i_p} \varepsilon^{i_1 \dots i_p}_{j_1 \dots j_{n-p}} \varepsilon^{j_1 \dots j_{n-p}}_{k_1 \dots k_p} e^{k_1} \wedge \dots \wedge e^{k_p} \\ &= \frac{1}{p!} \omega_{i_1 \dots i_p} g^{i_1 i'_1} \dots g^{i_p i'_p} g_{k_1 k'_1} \dots g_{k_p k'_p} \varepsilon_{i'_1 \dots i'_p j_1 \dots j_{n-p}} \varepsilon^{j_1 \dots j_{n-p} k'_1 \dots k'_p} e^{k_1} \wedge \dots \wedge e^{k_p} \\ &= \frac{1}{p!} \omega_{i_1 \dots i_p} g^{i_1 i'_1} \dots g^{i_p i'_p} g_{k_1 k'_1} \dots g_{k_p k'_p} (-1)^{(n-p)p} \varepsilon_{j_1 \dots j_{n-p} i'_1 \dots i'_p} \varepsilon^{j_1 \dots j_{n-p} k'_1 \dots k'_p} e^{k_1} \wedge \dots \wedge e^{k_p} \\ &= \frac{1}{p!} \omega_{i_1 \dots i_p} g^{i_1 i'_1} \dots g^{i_p i'_p} g_{k_1 k'_1} \dots g_{k_p k'_p} (-1)^{(n-p)p} \delta_{i'_1}^{k'_1} \dots \delta_{i'_p}^{k'_p} e^{k_1} \wedge \dots \wedge e^{k_p} \\ &= (-1)^{(n-p)p} \frac{1}{p!} \omega_{i_1 \dots i_p} (-1)^s \delta_{k_1}^{i_1} \dots \delta_{k_p}^{i_p} e^{k_1} \wedge \dots \wedge e^{k_p} \\ &= (-1)^{(n-p)p+s} \omega \end{aligned}$$

Thus

$$*^2 = (-1)^{(n-p)p+s}$$

**Exercise 69.** Let

$$\omega = \frac{1}{p!} \omega_{i_1 \dots i_p} e^{i_1} \wedge \dots \wedge e^{i_p}$$

Then

$$\begin{aligned} *\omega &= \frac{1}{p!} \omega_{i_1 \dots i_p} * (e^{i_1} \wedge \dots \wedge e^{i_p}) \\ &= \frac{1}{p!} \omega_{i_1 \dots i_p} \binom{i_1 \dots i_p}{j_1 \dots j_{n-p}} e^{j_1} \wedge \dots \wedge e^{j_{n-p}} \end{aligned}$$

The missing factor has given indices, and is the sign of the permutation

$$\{1, \dots, n\} \mapsto \{i_1, \dots, i_p, j_1, \dots, j_{n-p}\}$$

multiplied by  $\epsilon(i_1) \dots \epsilon(i_p)$ . Therefore for fixed indices what we are looking for is the number

$$\epsilon(i_1) \dots \epsilon(i_p) \varepsilon_{i_1 \dots i_p j_1 \dots j_{n-p}}$$

but the indices aren't quite right here. However, note that

$$\begin{aligned} \varepsilon_{j_1 \dots j_{n-p}}^{i_1 \dots i_p} &= g^{i_1 k_1} \dots g^{i_p k_p} \varepsilon_{k_1 \dots k_p j_1 \dots j_{n-p}} \\ &= \epsilon(i_1) \dots \epsilon(i_p) \varepsilon_{k_1 \dots k_p j_1 \dots j_{n-p}} \end{aligned}$$

Thus what we want is just

$$\varepsilon_{j_1 \dots j_{n-p}}^{i_1 \dots i_p}$$

So

$$*\omega = \frac{1}{p!} \omega_{i_1 \dots i_p} \varepsilon_{j_1 \dots j_{n-p}}^{i_1 \dots i_p} e^{j_1} \wedge \dots \wedge e^{j_{n-p}}$$

**Exercise 70.** Recall from Exercise 66 that if  $\omega$  is a 1-form on  $\mathbb{R}^3$ ,  $*d*\omega$  can be identified as the curl of the corresponding vector. So

$$*_s d_s *_s E = \nabla \cdot E = \rho$$

Now consider the 2-form  $B$ . We have

$$\begin{aligned} B &= B_x dy \wedge dz + B_y dz \wedge dx + B_z dx \wedge dy \\ *_s B &= B_x dx + B_y dy + B_z dz \\ d_s *_s B &= \left( \frac{\partial B_z}{\partial y} - \frac{\partial B_y}{\partial z} \right) dy \wedge dz + \left( \frac{\partial B_x}{\partial z} - \frac{\partial B_z}{\partial x} \right) dz \wedge dx + \left( \frac{\partial B_y}{\partial x} - \frac{\partial B_x}{\partial y} \right) dx \wedge dy \\ *_s d_s *_s B &= \left( \frac{\partial B_z}{\partial y} - \frac{\partial B_y}{\partial z} \right) dx + \left( \frac{\partial B_x}{\partial z} - \frac{\partial B_z}{\partial x} \right) dy + \left( \frac{\partial B_y}{\partial x} - \frac{\partial B_x}{\partial y} \right) dz \end{aligned}$$

So

$$-\partial_t E + *_s d_s *_s B = j$$

is equivalent to

$$-\partial_t \mathbf{E} \cdot d\mathbf{x} + (\nabla \times \mathbf{B}) \cdot d\mathbf{x} = \mathbf{j} \cdot d\mathbf{x}$$

i.e.

$$-\partial_t \mathbf{E} + \nabla \times \mathbf{B} = \mathbf{j}$$



**Exercise 71.** We have

$$\begin{aligned} *E \wedge dt &= *(E_i dx^i \wedge dt) \\ &= E_x dy \wedge dz + E_y dz \wedge dx + E_z dy \wedge dx \\ &= *_s E \end{aligned}$$

Then

$$\begin{aligned} *B &= *(B_x dy \wedge dz + B_y dz \wedge dx + B_z dx \wedge dy) \\ &= B_x dt \wedge dx + B_y dt \wedge dy + B_z dt \wedge dz \end{aligned}$$

and

$$*_s B = B_x dx + B_y dy + B_z dz$$

so

$$*B = - *_s B \wedge dt$$

Thus we have

$$*F = *_s E - *_s B \wedge dt$$

Then

$$\begin{aligned} d *_s E &= \partial_t dt \wedge *_s E + d_s *_s E \\ &= *_s E \wedge dt + d_s *_s E \end{aligned}$$

since  $*_s E$  is a 2-form, and

$$d *_s B \wedge dt = d_s *_s B \wedge dt$$

Thus we have

$$d * F = *_s \partial_t E \wedge dt + d_s *_s E - d_s *_s B \wedge dt$$

Next, we have

$$\begin{aligned} (*_s \partial_t E \wedge dt) &= \partial_t *(E_x dy \wedge dz \wedge dt + E_y dz \wedge dx \wedge dt + E_z dx \wedge dy \wedge dt) \\ &= \partial_t (-E_x dx - E_y dy - E_z dz) \\ &= -\partial_t E \end{aligned}$$

Then

$$\begin{aligned} d_s *_s E &= d_s (E_x dy \wedge dz + E_y dz \wedge dx + E_z dx \wedge dy) \\ &= (\partial_x E_x + \partial_y E_y + \partial_z E_z) dx \wedge dy \wedge dz \end{aligned}$$

So

$$*d_s *_s E = -(\partial_x E_x + \partial_y E_y + \partial_z E_z) dt$$

but

$$*_s d_s *_s E = \partial_x E_x + \partial_y E_y + \partial_z E_z$$

So

$$*_s d_s *_s E = - *_s d_s *_s E \wedge dt$$

Lastly, we have

$$\begin{aligned} d_s *_s B \wedge dt &= -d_s(B_x dt \wedge dx + B_y dt \wedge dy + B_z dt \wedge dz) \\ &= (\partial_x B_y - \partial_y B_x) dt \wedge dx \wedge dy + (\partial_y B_z - \partial_z B_y) dt \wedge dy \wedge dz + (\partial_z B_x - \partial_x B_z) dt \wedge dz \wedge dx \end{aligned}$$

So

$$*_s d_s *_s B \wedge dt = -(\partial_x B_y - \partial_y B_x) dz - (\partial_y B_z - \partial_z B_y) dx - (\partial_z B_x - \partial_x B_z) dy$$

On the other hand,

$$\begin{aligned} *_s B &= B_x dx + B_y dy + B_z dz \\ d_s *_s B &= (\partial_x B_y - \partial_y B_x) dx \wedge dy + (\partial_y B_z - \partial_z B_y) dy \wedge dz + (\partial_z B_x - \partial_x B_z) dz \wedge dx \\ *_s d_s *_s B &= (\partial_x B_y - \partial_y B_x) dz + (\partial_y B_z - \partial_z B_y) dx + (\partial_z B_x - \partial_x B_z) dy \end{aligned}$$

Thus,

$$*_s d_s *_s B \wedge dt = - *_s d_s *_s B$$

So finally we have

$$*d * F = -\partial_t E - *_s d_s *_s E \wedge dt + *_s d_s *_s B$$

Then setting  $*d * F = J$ , we have the two equations

$$\begin{aligned} -\partial_t E + *_s d_s *_s B &= j \\ *_s d_s *_s E &= \rho \end{aligned}$$

as desired.

**Exercise 72.** Take  $F_\pm = \frac{1}{2}(F \pm *F)$ . Then certainly  $F = F_+ + F_-$ , and

$$\begin{aligned} *F_\pm &= \frac{1}{2}(*F \pm **F) \\ &= \frac{1}{2}(*F \pm F) \\ &= \pm F_\pm \end{aligned}$$

**Exercise 73.** Take  $F_{\pm} = \frac{1}{2}(iF \pm *F)$ . Then certainly  $F = F_+ + F_-$ , and

$$\begin{aligned} *F_{\pm} &= \frac{1}{2}(i * F \mp F) \\ &= \frac{1}{2}i(*F \pm iF) \\ &= \pm iF_{\pm} \end{aligned}$$

**Exercise 74.** On 1-forms  $*_s^2 = (-1)^{(3-1)} = 1$ , so

$$\begin{aligned} *_s E = iB &\Rightarrow E = i *_s B \\ *_s B &= -iE \end{aligned}$$

So all we need to show that  $F$  is self-dual is  $*_s E = iB$ . In order for this to be the case, we need

$$*_s(E_x dx + E_y dy + E_z dz) = i(B_z dy \wedge dz + B_y dz \wedge dx + B_x dx \wedge dy)$$

i.e.  $E_i = iB_i$ , so

$$B = -i(E_x dy \wedge dz + E_y dz \wedge dx + E_z dx \wedge dy)$$

Then obviously  $*_s B = -iE$  follows.

**Exercise 75.** The second Maxwell equation is

$$\partial_t B + d_s E = 0$$

We have

$$\partial_t B = ik_0 B$$

and

$$d_s E = iE \wedge k_j dx^j$$

So

$$\begin{aligned} k_0 B + E \wedge k_j dx^j &= 0 \\ k_0 \mathbf{B} + \mathbf{E} \wedge k_j dx^j &= 0 \\ k_j dx^j \wedge \mathbf{E} &= k_0 \mathbf{B} \end{aligned}$$

i.e.  $\mathbf{k} \times \mathbf{E} \propto \mathbf{B}$ . Equivalently,

$$k_j dx^j \wedge \mathbf{E} = -ik_0 *_s \mathbf{E}$$

**Exercise 76.** We have

$$\begin{aligned} *_s \mathbf{E} &= e^{ik_\mu x^\mu} *_s (E_x dx + E_y dy + E_z dz) \\ &= e^{ik_\mu x^\mu} (E_x dy \wedge dz + E_y dz \wedge dx + E_z dx \wedge dy) \end{aligned}$$

so

$$k_j dx^j \wedge (E_x dx + E_y dy + E_z dz) = -ik_0 (E_x dy \wedge dz + E_y dz \wedge dx + E_z dx \wedge dy)$$

This can be written in the form  $K\mathbf{E} = 0$ :

$$\begin{pmatrix} ik_0 & -k_z & k_y \\ k_z & ik_0 & -k_x \\ -k_y & k_x & ik_0 \end{pmatrix} \begin{pmatrix} E_x \\ E_y \\ E_z \end{pmatrix} = 0$$

Therefore

$$\det K = ik_0(-k_0^2 + k_x^2 + k_z^2 + k_y^2) = 0$$

so

$$k_\mu k^\mu = 0$$

**Exercise 77.** The electric 1-form is

$$E = (dy - idz)e^{i(t-x)}$$

so the associated electric 3-vector field is

$$\mathbf{E} = (0, e^{i(t-x)}, -ie^{i(t-x)})$$

Then

$$\begin{aligned} B &= -i *_s (dy - idz)e^{i(t-x)} \\ &= -i(dz \wedge dx - idx \wedge dy)e^{i(t-x)} \end{aligned}$$

so the associated magnetic 3-vector field is

$$\mathbf{B} = (0, -ie^{i(t-x)}, -e^{i(t-x)})$$

**Exercise 78.** WLOG, take  ${}^3k$  to be in the  $x$ -direction. We have already done the self-dual case, seeing how the solution is left-circularly polarised. Now consider the anti-self-dual case, where  $B = i *_s E$ . The first equation,  $d_s B = 0$ , does not change from the self-dual case. The second equation,  $\partial_t B + d_s E = 0$ , again gives us

$${}^3k \wedge E = k_0 \mathbf{B}$$

but now this is

$${}^3k \wedge E = ik_0 *_s E$$

Therefore the determinant we have to set to zero is slightly different:

$$\begin{vmatrix} -ik_0 & -k_z & k_y \\ k_z & -ik_0 & -k_x \\ -k_y & k_z & -ik_0 \end{vmatrix} = 0$$

However, this again yields

$$ik_0(k_0^2 - k_x^2 - k_z^2 - k_y^2) = 0$$

i.e.  $k_\mu k^\mu = 0$ . Then we can take, WLOG,

$$k = dt - dx$$

Now, by  $d_s B = 0$ ,  $\mathbf{B} \wedge {}^3k = 0$ , so

$$\langle \mathbf{E}, {}^3k \rangle = 0$$

as before, and hence we can write  $E = ady + bdz$  for some  $a, b$ . But then the second equation,  ${}^3k \wedge E = ik_0 *_s E$ , reads

$$\begin{aligned} (dt - dx) \wedge (ady + bdz) &= i *_s (ady + bdz) \\ &= i(adz \wedge dx + bdx \wedge dy) \end{aligned}$$

Therefore  $b = ia$ , so  $\mathbf{E} \propto (0, 1, i)$ , and hence the solution is right-circularly polarised.

**Exercise 79.** The parity transformation is  $P : \mathbb{R}^4 \rightarrow \mathbb{R}^4; (t, x, y, z) \mapsto (t, -x, -y, -z)$ . Recall that  $F = B + E \wedge dT$  is self-dual if

$$*_s E = iB, \quad *_s B = -iE$$

or anti-self-dual if

$$*_s E = -iB, \quad *_s B = iE$$

Now, we have  $P^* B = B$  and  $P^* E = -E$ , so if  $F$  is self-dual,

$$\begin{aligned} *_s P^* B &= *_s B \\ &= -iE \\ &= iP^* E \end{aligned}$$

and

$$\begin{aligned} *_s P^* E &= i *_s E \\ &= -iB \\ &= -iP^* B \end{aligned}$$

So if  $(E, B)$  constitute a self-dual solution,  $(P^* E, P^* B)$  constitute an anti-self-dual solution. The converse follows from  $P^2 = \text{id}$ .