# **Experiment - 6**

# 6. Implementation of Monkey Banana Problem using LISP/PROLOG

## Monkey-Banana.pl Program

```
%Monkey-Banana Problem:-
% initial state: Monkey is at door,
%
           Monkey is on floor,
%
           Box is at window,
%
           Monkey doesn't have a banana.
%
% prolog structure: structName(val1, val2, ...)
% state(Monkey location in the room, Monkey onbox/onfloor, box location, has/hasnot banana)
% legal actions
do( state(middle, onbox, middle, hasnot), % grab banana
  grab,
  state(middle, onbox, middle, has) ).
do( state(L, onfloor, L, Banana),
                                      % climb box
  climb,
  state(L, onbox, L, Banana)).
do( state(L1, onfloor, L1, Banana),
                                       % push box from L1 to L2
  push(L1, L2),
  state(L2, onfloor, L2, Banana)).
do( state(L1, onfloor, Box, Banana),
                                        % walk from L1 to L2
  walk(L1, L2),
  state(L2, onfloor, Box, Banana)).
% canget(State): monkey can get banana in State
```

```
canget(state(_, _, _, has)).
                                 % Monkey already has it, goal state
                               % not goal state, do some work to get it
canget(State1):-
                                   % do something (grab, climb, push, walk)
   do(State1, Action, State2),
   canget(State2).
                               % canget from State2
% get plan = list of actions
canget(state( , , , has), []).
                                  % Monkey already has it, goal state
canget(State1, Plan):-
                                 % not goal state, do some work to get it
                                   % do something (grab, climb, push, walk)
   do(State1, Action, State2),
   canget(State2, PartialPlan),
                                   % canget from State2
                                    % add action to Plan
   add(Action, PartialPlan, Plan).
add(X,L,[X|L]).
%----->
%?- canget(state(atdoor, onfloor, atwindow, hasnot), Plan).
% Plan = [walk(atdoor, atwindow), push(atwindow, middle), climb, grasp]
% Yes
%?- canget(state(atwindow, onbox, atwindow, hasnot), Plan).
% No
%?- canget(state(Monkey, onfloor, atwindow, hasnot), Plan).
% Monkey = atwindow
% Plan = [push(atwindow, middle), climb, grasp]
% Yes
```

### **Output:**

SWI-Prolog (AMD64, Multi-threaded, version 9.0.3)

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?-

Warning: c:/users/admin/desktop/mbp.pl:37:

Warning: Singleton variables: [Action]

% c:/Users/admin/Desktop/MBP.pl compiled 0.00 sec, 9 clauses

?- canget(state(atdoor, onfloor, atwindow, hasnot)).

#### true

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?\_

Warning: c:/users/admin/desktop/monkey-banana.pl:37:

Warning: Singleton variables: [Action]

% c:/Users/admin/Desktop/Monkey-Banana.pl compiled 0.00 sec, 9 clauses

?- canget(state(Monkey, onfloor, atwindow, hasnot), Plan).

Monkey = atwindow,

Plan = [push(atwindow, middle), climb, grab]