

# **ARTIFICIAL INTELLIGENCE**

## **DATA HANDLING - NOISE REDUCTION**

**CO -2**

**Session - 18**

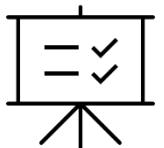
## AIM

To familiarize the students with the concept of Principal component analysis (PCA)



## INSTRUCTIONAL OBJECTIVES

This session is designed to:



1. **Noise reduction , outlier detection , imputation (KNN)**
2. Understand the Nature of Noise in Data
3. Explore the Impact of Noise on Data Analysis
4. Classify Types of Noise

## LEARNING OUTCOMES



At the end of this session, students will be able to:

Define and Identify Data Noise

Differentiate Between Types of Noise

Apply Noise Detection Techniques

# What is FFT?

- **Fast Fourier Transform (FFT)** is a mathematical algorithm used to convert **time-domain signals** into the **frequency domain**.
- It helps reveal the **frequency components** of a signal, making it easier to identify and remove **high-frequency noise**.

# Why Use FFT for Noise Reduction?

- **Noise often resides in high frequencies**, while important data patterns lie in lower frequencies.
- By transforming data into the frequency domain, we can:
  - Identify noise frequencies
  - Filter them out
  - Reconstruct a cleaner signal

# Steps for Noise Reduction Using FFT:

- **Input the Time-Domain Data**
  - For example: Sensor readings, ECG signal, audio wave, etc.
- **Apply FFT**
  - Use tools like `numpy.fft.fft()` in Python.
  - This transforms your signal into a spectrum of frequencies.
- **Analyze the Frequency Spectrum**
  - Plot the magnitude spectrum to observe peaks (signal) and clutter (noise).
- **Apply Frequency Filtering**
  - **Low-pass filter**: Retain low-frequency components (main signal), remove high-frequency noise.
  - Set a **threshold**: Zero out frequencies above a certain cutoff.
- **Apply Inverse FFT (IFFT)**
  - Convert the filtered frequency spectrum back into the time domain using `numpy.fft.ifft()`.
  - Result: **Smoothed, denoised signal**.

# Advantages of FFT for Noise Reduction

- Effective for **periodic signals** (audio, biomedical, vibration data)
- Allows **precise frequency filtering**
- Computationally efficient for large datasets

# What Is an Outlier?

- An **outlier** is a data point that lies far outside the range of the majority of other values in a dataset.  
These can distort statistical analyses and models, so detecting them is an essential step in **data handling**.

# Box Plot Overview (a.k.a. Box-and-Whisker Plot)

- A **box plot** is a graphical representation of data distribution using **five-number summary**:
- **Minimum**
- **First Quartile (Q1)** – 25th percentile
- **Median (Q2)** – 50th percentile
- **Third Quartile (Q3)** – 75th percentile
- **Maximum**
- Outliers are detected using the **IQR (Interquartile Range)**:
- **$IQR = Q3 - Q1$**
- **Lower Bound** =  $Q1 - 1.5 \times IQR$
- **Upper Bound** =  $Q3 + 1.5 \times IQR$
- Any data point **outside this range** is considered an **outlier**.

# Benefits of Box Plot for Outlier Detection

- Easy to visualize **spread and symmetry**
- Effective for **univariate outlier detection**
- Identifies **mild** and **extreme** outliers

# Imputation Using Measures of Centrality

- **Definition:**
- **Central tendency** methods replace missing values with a representative value of the dataset:
- **Mean** – average of all values
- **Median** – middle value (robust to outliers)
- **Mode** – most frequent value (used for categorical data)
-  **When to Use:**
- **Mean:** Symmetric distributions without outliers
- **Median:** Skewed distributions or presence of outliers
- **Mode:** Categorical or discrete values

# Imputation Using KNN (K-Nearest Neighbors)

- KNN imputation replaces missing values by finding the **k most similar (nearest) data points** and imputing the missing values using their feature values (mean, median, or weighted average).
- **When to Use:**
- Mixed data types
- Non-linear patterns
- Assumes data points with similar features likely have similar values

## How It Works:

- For each instance with missing values:
  - Compute **Euclidean distance** (or other) to all complete instances
  - Find the **K-nearest neighbors**
  - Replace missing value with the **mean (or median)** of those neighbors' corresponding values