Secure Computation for Machine Learning With SPDZ

Abstract

Secure Multi-Party Computation (MPC) is an area of cryptography that enables the computation on sensitive data from multiple sources while maintaining privacy guarantees. However, theoretical MPC protocols often do not scale efficiently to real-world data. This project investigates the efficiency of of the SPDZ framework [1], which provides an implementation of an MPC protocol with malicious security, in the context of popular machine learning (ML) algorithms. In particular, we chose applications such as linear regression and logistic regression, which have been implemented and evaluated using semi-honest MPC techniques [2, 8]. We demonstrate that the SPDZ framework outperforms these previous implementations while providing stronger security.

11 1 Introduction

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Many machine learning techniques, including regression analysis, aim to build a model that fits a 12 set of predictors to a dependent variable. Such techniques are widely used to model and analyze 13 big data. In many settings, however, the input data for such ML analysis tools is partitioned among 14 different parties, which have strict privacy policies. For example, if the Center for Disease Control is interested in identifying disease outbreak, they might want to incorporate patient data from many individual hospitals. The problem is that openly sharing this data for prediction or model-building 17 18 purposes is against modern day privacy laws as it would leak private individual data. This is one of 19 many examples, which could benefit from MPC which would allow the parties to evaluate the output 20 of the analysis without revealing more about the private inputs.

1.1 Multi-Party Computation

Secure MPC addresses the above problem by providing a mechanism through which different parties can run a joint computation over their private inputs with guarantees that the only thing revealed 23 about the inputs is the output of the computation and whatever can be inherently inferred from it. 24 There are two main types of MPC protocols in terms of their security guarantees: semi-honest and 25 malicious protocols [3, 5]. In semi-honest security, it is assumed that the parties will follow the 26 protocol as specified, but they can try to infer information about the input from the protocol messages. 27 In malicious security, dishonest parties may attempt to deviate from the specified protocol, and the 28 protocol must guarantee that these parties cannot learn about the inputs. Since malicious protocols 29 have to satisfy stronger guarantees in general, such construction are less efficient than semi-honest 31

Two recent works [2, 8] propose efficient implementation for several central building blocks for machine learning such as conjugate gradient decent (CGD) and stochastic gradient descent (SGD) as well as applications using them such as linear and logistic regression. The work of Gascon et al. [2] uses the framework for semi-honest computation Obliv-C [9] and proposes several different methods for solving systems of linear equations. Their main premise is to use an iterative method such as CGD and demonstrate trade-offs that saves computation and hence efficiency for the MPC in return for a small accuracy loss. They further propose a modification of CGD that has stable behavior using fixed-point arithmetic as emulating floating point with the underlying MPC representation introduces substantial efficiency overhead.

- The work of Mohassel and Zhang [8] considers stochastic gradient descent as a method for linear 41
- regression and logistic regression with the incorporation of different activation functions. The 42
- authors consider arithmetic representation for the computation and propose new secure computation 43
- techniques for matrix computation, which generalize the approach for generating multiplicative triples 44
- in a preprocessing step. Similarly to the work of Gascon et al. [2], this paper considers techniques 45
- for approximation that save computation. For example, they use a piece-wise approximation of 46
- the logistic function. The authors also propose new techniques for more efficient approximate 47
- computation of fixed-point encodings. 48
- The techniques in both of the above works are restricted to the setting of two party computation. 49
- We selected the SPDZ [1, 6, 7] framework for our experiments since it is one of the main and most 50
- comprehensive implementations for multiparty computation protocols, which provide malicious 51
- security and support more than two parties.

ML Functionalities 53

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- For our implementation we consider the same algorithms and functionalities as in the above two 54
- papers. Next we provide a brief overview of these classic algorithms (details can be found in [4]). 55

2.1 Direct vs. Iterative Decomposition for Solving a Linear System

- Solving a system of linear equations, which underlies linear regression learning, can be done using 57
- techniques for direct and indirect decomposition. LDLT and Cholesky are both variants of direct 58
- decomposition methods which decompose a Hermitian, positive-definite matrix into a lower triangular 59
- matrix and its conjugate transpose. The algorithms are cubic in complexity with asymptotic run time 60
- of $O(d^3)$, where d is the dimension of the input matrix. The difference between LDLT and Cholesky 61
- 62 is that Cholesky requires a square root. The representation of square root computation as an arithmetic
- circuit used in the MPC computation in SPDZ introduces considerable overhear. That is why we used 63
- the iterative Newton method as a way of approximating the square root computation. It computes x_i , 64
- where $x_i^2 = S$, with repetition of the following update function $x_{n+1} = 1/2(x_n + S/x_n)$. 65
- In terms of an iterative approach to regression, we used the approach proposed by Gascon et al. [2], 66
- which uses a normalized version of CGD that preserves stability and convergence rate with fixed-point 67
- number representation. Similarly to other MPC implementations using floating point representation
- in SPDZ introduces substantial efficiency overhead.

2.2 Stochastic Gradient Descent

- Stochastic gradient descent is an iterative approximation method that converges to the global minimum 71
- for convex problems, like linear and logistic regression. It is also a driving mechanism for non-convex 72
- problems like neural networks. An SGD iteration updates a weight vector w using a randomly 73
- selected sample from the training input as follows: $w_i := w_i \alpha(\partial C_i(\mathbf{w})/\partial w_i)$ with learning rate 74
- α . In this update C_i is the cost function, which can be instantiated with different concrete functions 75
- to obtain computation for linear regression and logistic regression. A common technique for SGD 76
- computation is called *mini-batch* instead of selecting one sample per iteration, a small batch of size 77
- B samples are selected and the update function is performed averaging the partial derivatives across 78
- all samples. We use the mini-batch SGD in our implementation to obtain accuracy benefits. While 79
- the work of Mohassel and Zhang [8] has optimizations for matrix computation, which can be used
- with mini-batch, for SPDZ this does not lead to additional savings. 81

2.2.1 Linear and Non-Linear Activation Functions 82

- To obtain a solution for linear regression using SGD, we instantiate the update function to a learned
- weight as $w_j = w_j \alpha(X_i \cdot w * -y_i)X_{ij}$, where X is the input matrix and y is the input vector. 84
- In this update function, the weights are adjusted element-wise by the error from the predicted and 85
- expected value at a rate determined by α . 86
- Logistic regression is a classification algorithm for modeling a binary dependent variable. Logistic 87
- regression fits the logistic function $f(u) = \frac{1}{1+e^-u}$ to the input. The corresponding update function for mini-batched SGD for logistic regression is $w = w \frac{1}{|B|} \alpha X_B^T \times f(X_B \times w Y_B)$, where f maps

the predicted value into the binary output space. Mohassel and Zhang [8] proposed the following piecewise function as approximation for f:

$$f(u) = \begin{cases} 0 & \text{if } u < -0.5\\ u + 0.5 & \text{if } -0.5 \le u \le 0.5\\ 1 & \text{if } u > 0.5 \end{cases}$$

We compare the results of this MPC-friendly piecewise function to a more standard approximation approach of taking the Taylor Series expansion to varying degrees.

94 3 Experiments

95 3.1 Experimental Setup

For our evaluation, we implemented all algorithms both in the SPDZ framework as well as in python 96 as a plaintext verification of the algorithm. The main metrics of evaluations were the latency of the 97 MPC computation and the accuracy error, and we aimed to explore the trade-offs between accuracy 98 and efficiency. We varied the precision after the decimal point depending on what was used in the works that we compared against (32 and 64 bits for the linear regression, less for SGD). 100 101 We evaluated our methods on both real-world datasets (MNIST, Arcene, and 9 other UCI open-source datasets) as well as synthetically generated data. These real-world datasets allow us to compare the 102 accuracy results to existing works and to demonstrate that SPDZ can be used in practical settings. We 103 used synthetic data in order to explore larger ranges of data characteristics such as dimension (d = 10, 104 20, 50, 100, 200, 500), condition number (cd = [1,10]), and number of examples (n = 1000, 100000). 105 Most of our experiments were ran using machines on the same local area network where there is no 106 107 network latency. We performed tests where both parties were deployed on separate Amazon EC2 m4.large instances (see Figure 4). We also ran experiment with up to four parties (see Figure 3). 108

3.2 Results

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In this section we present empirical results for our SPDZ implementations evaluated with real and synthetic databases. We compare the five different algorithms in terms of accuracy and run time for various parameters.

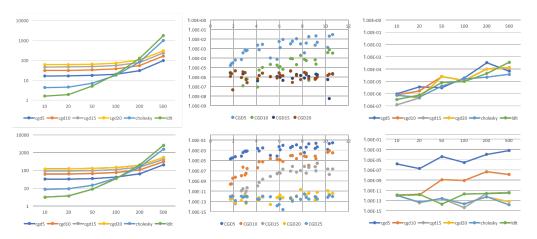


Figure 1: (Left) Run time as a function of input dimension. (Middle) Condition number as a function of accuracy. (Right) Accuracy as a function of the input dimension. (Top) Fixed-point with 60 bits of precision. (Bottom) Fixed-point with 28 bits of precision

For LDLT, Cholesky and various iterations of CGD, we evaluated on synthetically generated data of varying sizes and condition numbers. The larger the condition number is, the larger the error in approximations of the solution is. The direct decomposition methods grew exponentially in run time

as input size increases, which is shown in the left column of Figure 1 – this unlikely to be suitable for large size real data. Alternatively, the iterative CGD runtime increases at a much slower rate. In the middle column of Figure 2, we find that about 20 iterations are sufficient to reach maximum accuracy given the number of allocated bits even with varying condition numbers. Particularly for the 64-bit case, shown on the bottom right, the accuracy is identical for CGD after 15 iterations and Cholesky/LDLT.

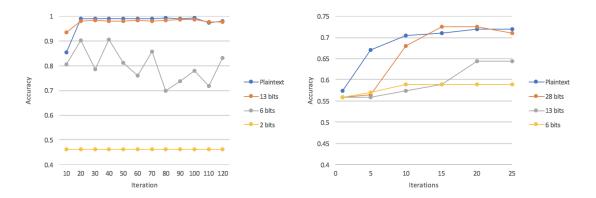


Figure 2: Comparing accuracy of privacy preserving linear regression with various fixed point precisions and plaintext training on floating point for MNIST (left) and Arcene (right).

Figure 2 compares SGD on MNIST and Arcene results. It shows that the number of bits of precision needed to get good accuracy is highly dependent on the dataset. For MNIST, 13 bits was sufficient to match plaintext accuracy, but 28 bits were needed for Arcene. The MNIST data contains only 784 features while there are 10,000 in the Arcene data, 3,000 of which are considered "probes" with no predictive power, which could explain the lower overall accuracy of [8]. While the numbers in the MNIST data ranged from 0 to 9, Mohassel and Zhang [8] only used 0s and 1s labels from the dataset, reducing it to a binary problem. We replicated this approach and present the results below. We did run the computation to predict all 10 digits, but found that SGD only achieved a much lower accuracy of about 19%. We also compared the root mean squared error (RMSE) of SGD on 9 UCI open-sourced datasets of ranging sizes to results in [2]. Our results in the SPDZ secure setting typically increased RMSE by about 5-20% compared to plaintext computation, but still outperformed RMSE results from [2] in both CGD and SGD.

In terms of logistic regression, for SPDZ, we did not find that the new activation function was a better alternative to taking a Taylor Series approximation for the exponential function as shown in Table 1.
We found that for SPDZ, which is based on arithmetic circuits, the extra time to take a few extra degrees in the approximation was negligible.

Table 1: Comparing the validation accuracy for different activation functions for logistic regression.

	Plaintext	New Activation function	Polynomial Approximation			
			degree 2	degree 5	degree 7	degree 10
MNIST	99.9%	95%	97%	85%	91%	99.5%
Arcene	72.0%	44.0%	44.0%	44.5%	65%	72%

3.3 Conclusion

SPDZ was able to achieve comparable accuracy for LDLT, Cholesky, and CGD when compared to Obliv-C with runtime faster by an order of magnitude on larger matrix sizes even in a distributed machine setting. SPDZ also achieved lower RMSE than Obliv-C using SGD. SPDZ was able to match accuracy and latency results for SecureML on SGD and Logistic Regression. This result is promising for SPDZ to be extended to more complex algorithms including neural networks with hidden layers.

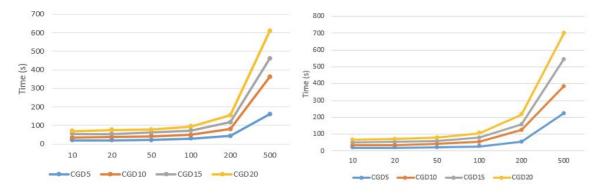
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Supplementary Material

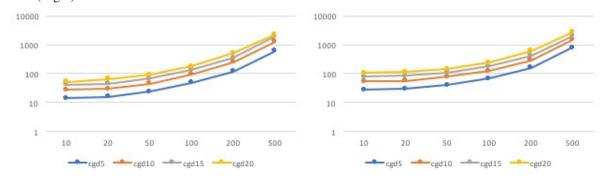
174 3.4 Three and four party runtimes

Figure 3: Run time results for 3 and 4 players in 32 bits. (Left) 3 Players. (Right) 4 Players.



175 3.5 EC2 runtimes

Figure 4: Run time results for 2 players deployed on EC2 instances averaged over 15 runs. (Left) 32 bits. (Right) 64 bits.



76 3.6 Activation function runtime comparison

Table 2: Comparison of efficiency for the proposed activation function in [8] and Taylor Series approximation in SPDZ.

	MNI	ST	Arcene		
	Compile	Run	Compile	Run	
New Activation Function	26.01	18.8	220.14	224.47	
2 Polynomial	27.79	19.28	222.85	239.98	
5 Polynomial	30.32	19.8	225.33	241.59	
7 Polynomial	31.99	20.65	228.33	239.11	
10 Polynomial	34.24	20.71	230.81	240.79	

177 3.7 RMSE results

Table 3: SGD Results for 9 open sourced UCI datasets.

Dataset Name	SGD Plaintext	SPDZ (28 bit) error / time		SPDZ (13 bit) error / time	
Student Performance	0.11	0.12 (+8.34%)	2.174	0.12(+8.34%)	2.616
Auto MPG	0.56	0.68 (+21.4%)	0.663	0.68(+21.4%)	0.704
Communities and Crime	0.06	0.17 (+183%)	10.352	0.19 (+216%)	12.363
Wine Quality	0.18	0.19 (+5.55%)	0.809	0.19 (+5.55%)	0.969
Bike Sharing	0.23	0.24 (+4.34%)	0.910	0.25 (+8.69%)	1.097
Blog Feedback	0.04	0.04 (+0.0%)	9.455	0.04 (+0.0%)	9.091
CT Slices	0.22	0.22 (+0.0%)	16.458	0.22 (+0.0%)	16.295
Year Prediction MSD	0.06	0.06 (+0.0%)	7.146	0.06 (+0.0%)	8.513
Gas Sensor Array	0.20	0.36 (+20.0%)	1.151	0.36 (+20.0%)	1.559