
STM32
CubeMX

1. Description

1.1. Project

Project Name	ros_robot
Board Name	NUCLEO-F446RE
Generated with:	STM32CubeMX 6.10.0
Date	03/22/2024

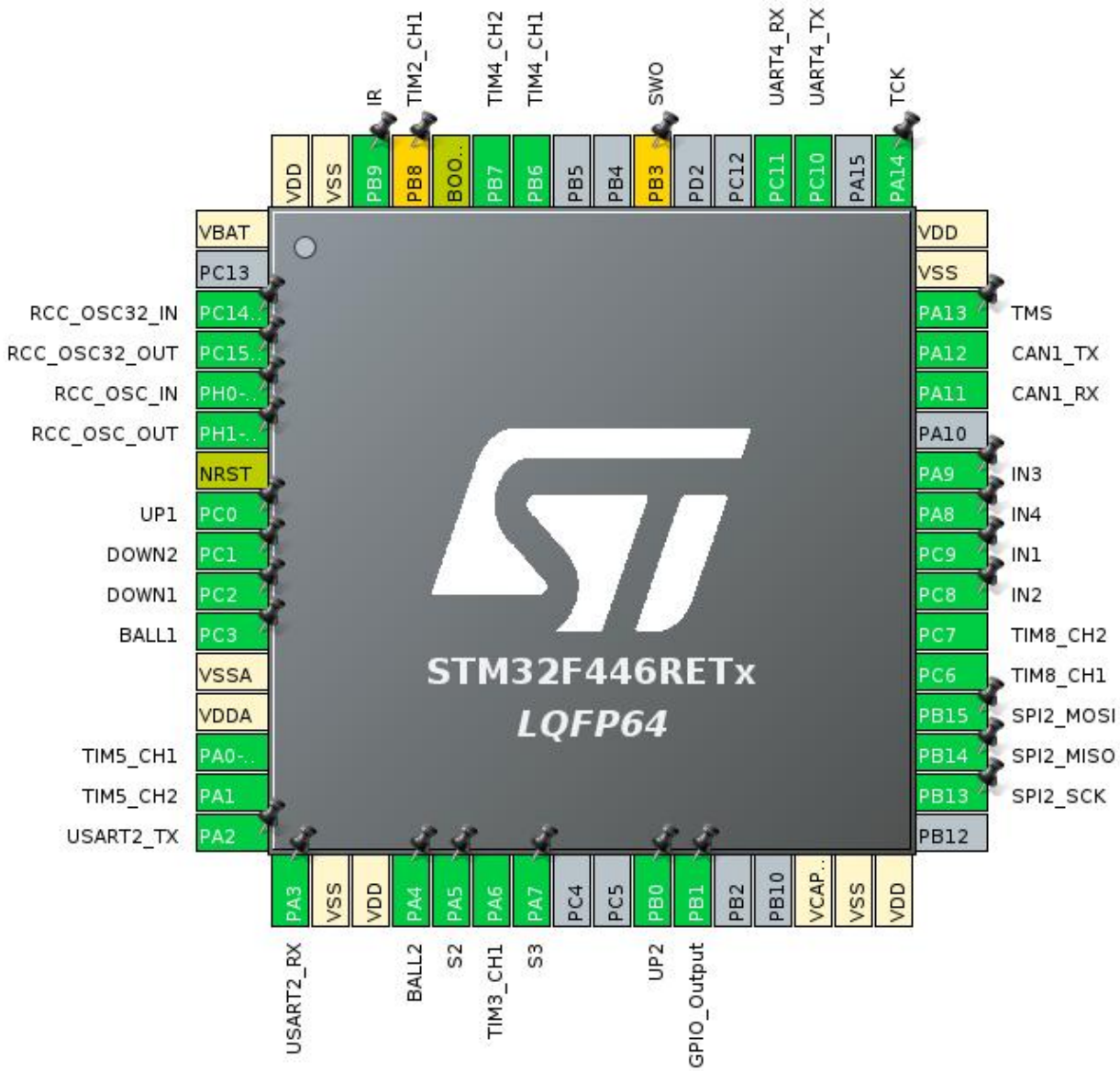
1.2. MCU

MCU Series	STM32F4
MCU Line	STM32F446
MCU name	STM32F446RETx
MCU Package	LQFP64
MCU Pin number	64

1.3. Core(s) information

Core(s)	Arm Cortex-M4

2. Pinout Configuration



3. Pins Configuration

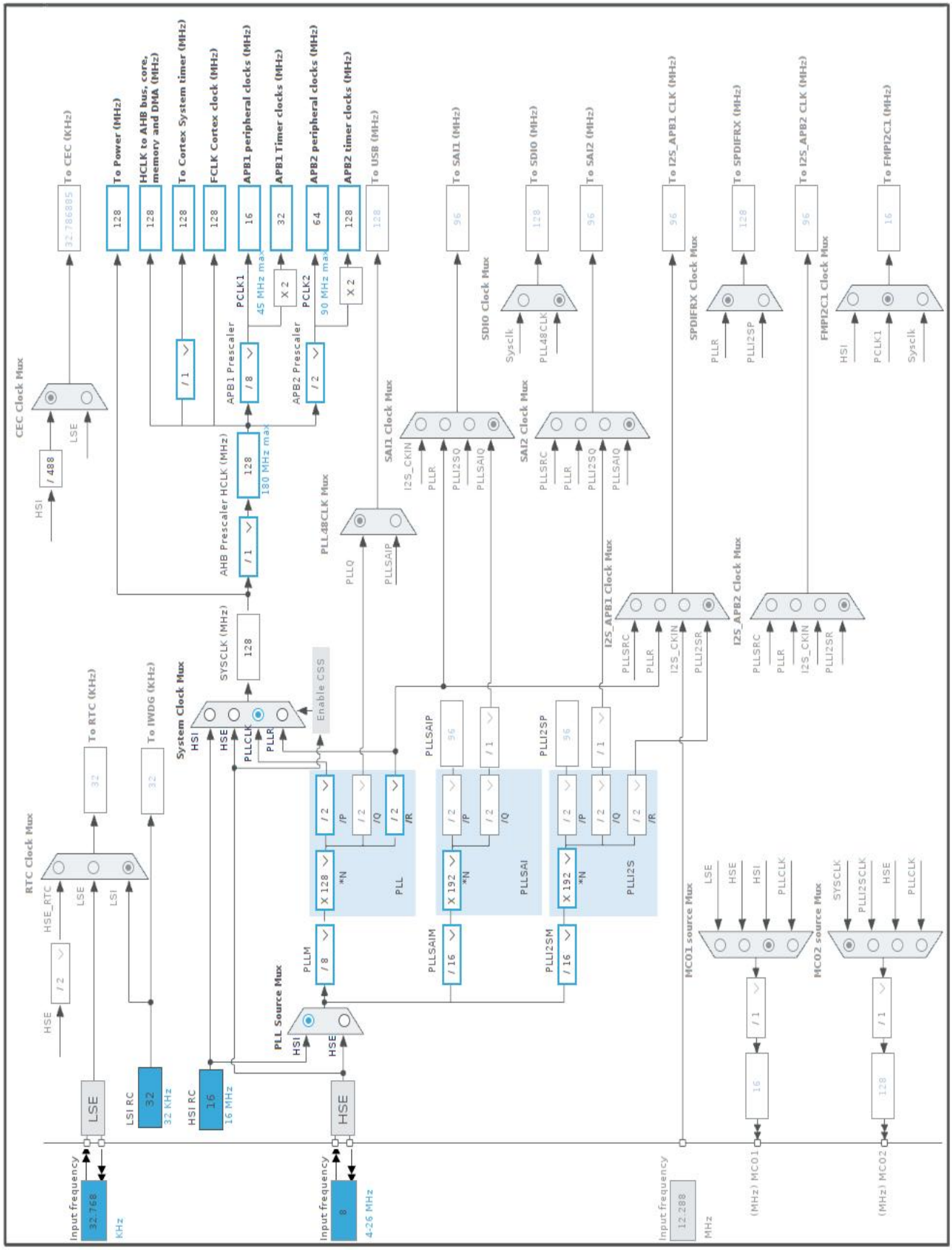
Pin Number LQFP64	Pin Name (function after reset)	Pin Type	Alternate Function(s)	Label
1	VBAT	Power		
3	PC14-OSC32_IN	I/O	RCC_OSC32_IN	
4	PC15-OSC32_OUT	I/O	RCC_OSC32_OUT	
5	PH0-OSC_IN	I/O	RCC_OSC_IN	
6	PH1-OSC_OUT	I/O	RCC_OSC_OUT	
7	NRST	Reset		
8	PC0 *	I/O	GPIO_Input	UP1
9	PC1 *	I/O	GPIO_Input	DOWN2
10	PC2 *	I/O	GPIO_Input	DOWN1
11	PC3 *	I/O	GPIO_Input	BALL1
12	VSSA	Power		
13	VDDA	Power		
14	PA0-WKUP	I/O	TIM5_CH1	
15	PA1	I/O	TIM5_CH2	
16	PA2	I/O	USART2_TX	
17	PA3	I/O	USART2_RX	
18	VSS	Power		
19	VDD	Power		
20	PA4 *	I/O	GPIO_Input	BALL2
21	PA5 *	I/O	GPIO_Output	S2
22	PA6	I/O	TIM3_CH1	
23	PA7 *	I/O	GPIO_Output	S3
26	PB0 *	I/O	GPIO_Input	UP2
27	PB1 *	I/O	GPIO_Output	
30	VCAP_1	Power		
31	VSS	Power		
32	VDD	Power		
34	PB13	I/O	SPI2_SCK	
35	PB14	I/O	SPI2_MISO	
36	PB15	I/O	SPI2_MOSI	
37	PC6	I/O	TIM8_CH1	
38	PC7	I/O	TIM8_CH2	
39	PC8 *	I/O	GPIO_Output	IN2
40	PC9 *	I/O	GPIO_Output	IN1
41	PA8 *	I/O	GPIO_Output	IN4
42	PA9 *	I/O	GPIO_Output	IN3

Pin Number LQFP64	Pin Name (function after reset)	Pin Type	Alternate Function(s)	Label
44	PA11	I/O	CAN1_RX	
45	PA12	I/O	CAN1_TX	
46	PA13	I/O	SYS_JTMS-SWDIO	TMS
47	VSS	Power		
48	VDD	Power		
49	PA14	I/O	SYS_JTCK-SWCLK	TCK
51	PC10	I/O	UART4_TX	
52	PC11	I/O	UART4_RX	
55	PB3 **	I/O	SYS_JTDO-SWO	SWO
58	PB6	I/O	TIM4_CH1	
59	PB7	I/O	TIM4_CH2	
60	BOOT0	Boot		
61	PB8 **	I/O	TIM2_CH1	
62	PB9 *	I/O	GPIO_Input	IR
63	VSS	Power		
64	VDD	Power		

* The pin is affected with an I/O function

** The pin is affected with a peripheral function but no peripheral mode is activated

4. Clock Tree Configuration



5. Software Project

5.1. Project Settings

Name	Value
Project Name	ros_robot
Project Folder	/home/tutu/STM32CubeIDE/workspace_1.14.0/ros_robot
Toolchain / IDE	STM32CubeIDE
Firmware Package Name and Version	STM32Cube FW_F4 V1.28.0
Application Structure	Advanced
Generate Under Root	Yes
Do not generate the main()	No
Minimum Heap Size	0x200
Minimum Stack Size	0x400

5.2. Code Generation Settings

Name	Value
STM32Cube MCU packages and embedded software	Copy only the necessary library files
Generate peripheral initialization as a pair of '.c/.h' files	No
Backup previously generated files when re-generating	No
Keep User Code when re-generating	Yes
Delete previously generated files when not re-generated	Yes
Set all free pins as analog (to optimize the power consumption)	No
Enable Full Assert	No

5.3. Advanced Settings - Generated Function Calls

Rank	Function Name	Peripheral Instance Name
1	SystemClock_Config	RCC
2	MX_GPIO_Init	GPIO
3	MX_DMA_Init	DMA
4	MX_USART2_UART_Init	USART2
5	MX_CAN1_Init	CAN1
6	MX_UART4_Init	UART4
7	MX_SPI2_Init	SPI2
8	MX_TIM3_Init	TIM3
9	MX_TIM5_Init	TIM5
10	MX_TIM8_Init	TIM8
11	MX_TIM4_Init	TIM4

1. Power Consumption Calculator report

1.1. Microcontroller Selection

Series	STM32F4
Line	STM32F446
MCU	STM32F446RETx
Datasheet	DS10693_Rev6

1.2. Parameter Selection

Temperature	25
Vdd	3.3

1.3. Battery Selection

Battery	Li-SOCL2(A3400)
Capacity	3400.0 mAh
Self Discharge	0.08 %/month
Nominal Voltage	3.6 V
Max Cont Current	100.0 mA
Max Pulse Current	200.0 mA
Cells in series	1
Cells in parallel	1

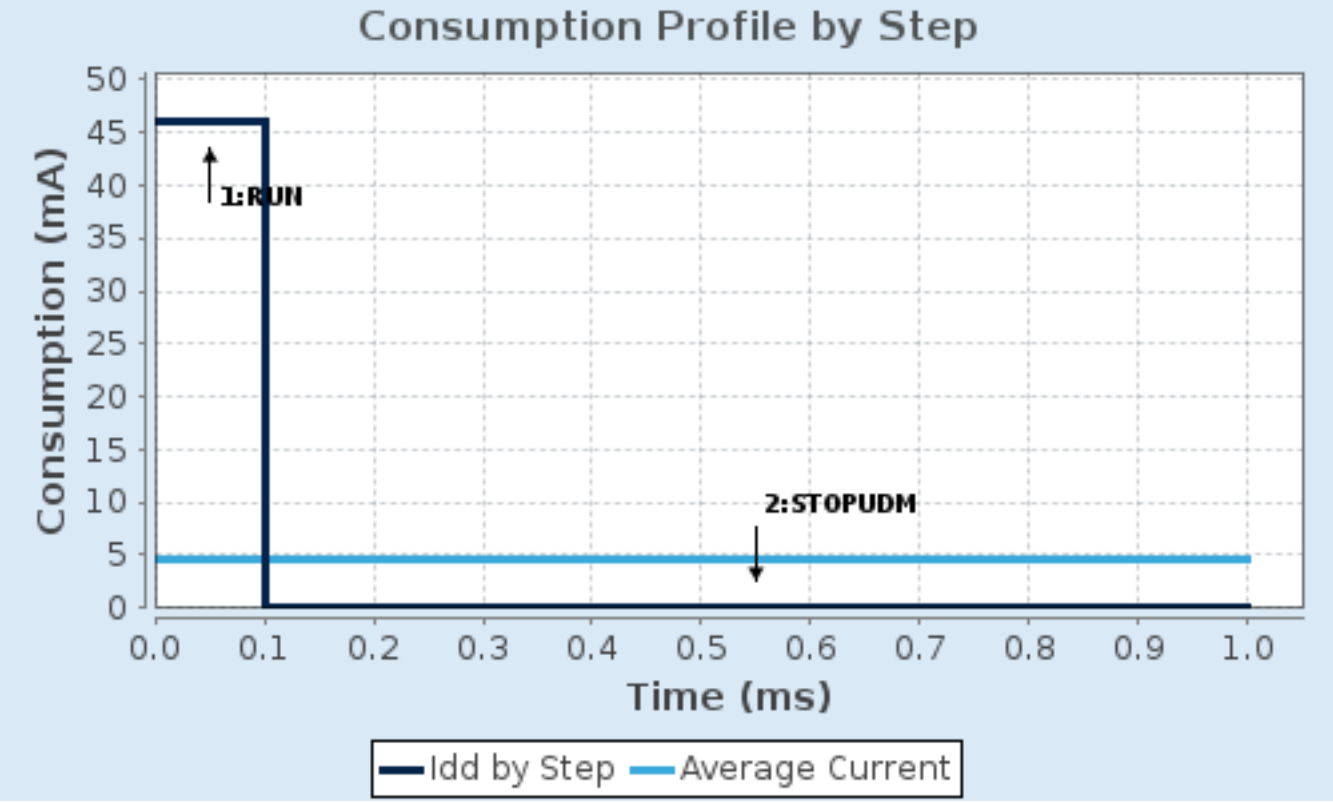
1.4. Sequence

Step	Step1	Step2
Mode	RUN	STOP_UDM (Under Drive)
Vdd	3.3	3.3
Voltage Source	Battery	Battery
Range	Scale1-High	No Scale
Fetch Type	RAM/FLASH/REGON/ART/PREFETCH	n/a
CPU Frequency	180 MHz	0 Hz
Clock Configuration	HSE PLL	Regulator_LP Flash-PwrDwn
Clock Source Frequency	4 MHz	0 Hz
Peripherals		
Additional Cons.	0 mA	0 mA
Average Current	46 mA	55 µA
Duration	0.1 ms	0.9 ms
DMIPS	225.0	0.0
Ta Max	98.02	104.99
Category	In DS Table	In DS Table

1.5. Results

Sequence Time	1 ms	Average Current	4.65 mA
Battery Life	1 month	Average DMIPS	225.0 DMIPS

1.6. Chart


Consumption Profile by Step
Consumption (mA)
50
45
40
35
30
25
20
15
10
5
0
1:RUN
2:STOPUDM
0.0
0.1
0.2
0.3
0.4
0.5
0.6
0.7
0.8
0.9
1.0
Time (ms)
Idd by Step
Average Current

2. Peripherals and Middlewares Configuration

2.1. CAN1

mode: Activated

2.1.1. Parameter Settings:

Bit Timings Parameters:

Prescaler (for Time Quantum)	**1 ***
Time Quantum	**62.5 ***
Time Quanta in Bit Segment 1	**13 Times ***
Time Quanta in Bit Segment 2	**2 Times ***
Time for one Bit	1000
Baud Rate	**1000000 ***
ReSynchronization Jump Width	1 Time

Basic Parameters:

Time Triggered Communication Mode	Disable
Automatic Bus-Off Management	Disable
Automatic Wake-Up Mode	Disable
Automatic Retransmission	**Enable ***
Receive Fifo Locked Mode	Disable
Transmit Fifo Priority	Disable

Advanced Parameters:

Operating Mode	Normal

2.2. RCC

High Speed Clock (HSE): Crystal/Ceramic Resonator

Low Speed Clock (LSE) : Crystal/Ceramic Resonator

2.2.1. Parameter Settings:

System Parameters:

VDD voltage (V)	3.3
Instruction Cache	Enabled
Prefetch Buffer	Enabled
Data Cache	Enabled
Flash Latency(WS)	4 WS (5 CPU cycle)

RCC Parameters:

HSI Calibration Value	16
TIM Prescaler Selection	Disabled

HSE Startup Timout Value (ms)	100
LSE Startup Timout Value (ms)	5000

Power Parameters:

Power Regulator Voltage Scale	Power Regulator Voltage Scale 2
Power Over Drive	Disabled

2.3. SPI2

Mode: Full-Duplex Master

2.3.1. Parameter Settings:

Basic Parameters:

Frame Format	Motorola
Data Size	8 Bits
First Bit	**LSB First ***

Clock Parameters:

Prescaler (for Baud Rate)	**256 ***
Baud Rate	**62.5 KBits/s ***
Clock Polarity (CPOL)	**High ***
Clock Phase (CPHA)	**2 Edge ***

Advanced Parameters:

CRC Calculation	Disabled
NSS Signal Type	Software

2.4. SYS

Debug: Serial Wire

Timebase Source: TIM1

2.5. TIM3

Clock Source : Internal Clock

Channel1: Input Capture direct mode

2.5.1. Parameter Settings:

Counter Settings:

Prescaler (PSC - 16 bits value)	0
Counter Mode	Up
Counter Period (AutoReload Register - 16 bits value)	65535

Internal Clock Division (CKD)	No Division
auto-reload preload	Disable

Trigger Output (TRGO) Parameters:

Master/Slave Mode (MSM bit)	Disable (Trigger input effect not delayed)
Trigger Event Selection	Reset (UG bit from TIMx_EGR)

Input Capture Channel 1:

Polarity Selection	Rising Edge
IC Selection	Direct
Prescaler Division Ratio	No division
Input Filter (4 bits value)	0

2.6. TIM4

mode: Clock Source

Channel1: PWM Generation CH1

Channel2: PWM Generation CH2

2.6.1. Parameter Settings:

Counter Settings:

Prescaler (PSC - 16 bits value)	**640-1 ***
Counter Mode	Up
Counter Period (AutoReload Register - 16 bits value)	**1000-1 ***
Internal Clock Division (CKD)	No Division
auto-reload preload	Disable

Trigger Output (TRGO) Parameters:

Master/Slave Mode (MSM bit)	Disable (Trigger input effect not delayed)
Trigger Event Selection	Reset (UG bit from TIMx_EGR)

PWM Generation Channel 1:

Mode	PWM mode 1
Pulse (16 bits value)	0
Output compare preload	Enable
Fast Mode	Disable
CH Polarity	High

PWM Generation Channel 2:

Mode	PWM mode 1
Pulse (16 bits value)	0
Output compare preload	Enable
Fast Mode	Disable
CH Polarity	High

2.7. TIM5

Combined Channels: Encoder Mode

2.7.1. Parameter Settings:

Counter Settings:

Prescaler (PSC - 16 bits value)	0
Counter Mode	Up
Counter Period (AutoReload Register - 32 bits value)	4294967295
Internal Clock Division (CKD)	No Division
auto-reload preload	**Enable ***

Trigger Output (TRGO) Parameters:

Master/Slave Mode (MSM bit)	Disable (Trigger input effect not delayed)
Trigger Event Selection	Reset (UG bit from TIMx_EGR)

Encoder:

Encoder Mode	**Encoder Mode TI1 and TI2 ***
____ Parameters for Channel 1 ____	
Polarity	**Falling Edge ***
IC Selection	Direct
Prescaler Division Ratio	No division
Input Filter	0
____ Parameters for Channel 2 ____	
Polarity	**Falling Edge ***
IC Selection	Direct
Prescaler Division Ratio	No division
Input Filter	0

2.8. TIM8

Clock Source : Internal Clock

Channel1: PWM Generation CH1

Channel2: PWM Generation CH2

2.8.1. Parameter Settings:

Counter Settings:

Prescaler (PSC - 16 bits value)	**26500-1 ***
Counter Mode	Up

Counter Period (AutoReload Register - 16 bits value)	**100-1 ***
Internal Clock Division (CKD)	No Division
Repetition Counter (RCR - 8 bits value)	0
auto-reload preload	Disable

Trigger Output (TRGO) Parameters:

Master/Slave Mode (MSM bit)	Disable (Trigger input effect not delayed)
Trigger Event Selection	Reset (UG bit from TIMx_EGR)

Break And Dead Time management - BRK Configuration:

BRK State	Disable
BRK Polarity	High

Break And Dead Time management - Output Configuration:

Automatic Output State	Disable
Off State Selection for Run Mode (OSSR)	Disable
Off State Selection for Idle Mode (OSSI)	Disable
Lock Configuration	Off

PWM Generation Channel 1:

Mode	PWM mode 1
Pulse (16 bits value)	0
Output compare preload	Enable
Fast Mode	Disable
CH Polarity	High
CH Idle State	Reset

PWM Generation Channel 2:

Mode	PWM mode 1
Pulse (16 bits value)	0
Output compare preload	Enable
Fast Mode	Disable
CH Polarity	High
CH Idle State	Reset

2.9. UART4

Mode: Asynchronous

2.9.1. Parameter Settings:

Basic Parameters:

Baud Rate	115200
Word Length	8 Bits (including Parity)
Parity	None
Stop Bits	1

Advanced Parameters:

Data Direction	Receive and Transmit
Over Sampling	16 Samples

2.10. USART2

Mode: Asynchronous

2.10.1. Parameter Settings:

Basic Parameters:

Baud Rate	115200
Word Length	8 Bits (including Parity)
Parity	None
Stop Bits	1

Advanced Parameters:

Data Direction	Receive and Transmit
Over Sampling	16 Samples

2.11. FREERTOS

Interface: CMSIS_V1

2.11.1. Config parameters:

API:

FreeRTOS API	CMSIS v1

Versions:

FreeRTOS version	10.3.1
CMSIS-RTOS version	1.02

MPU/FPU:

ENABLE_MPU	Disabled
ENABLE_FPU	Disabled

Kernel settings:

USE_PREEMPTION	Enabled
CPU_CLOCK_HZ	SystemCoreClock
TICK_RATE_HZ	1000
MAX_PRIORITIES	7
MINIMAL_STACK_SIZE	128
MAX_TASK_NAME_LEN	16
USE_16_BIT_TICKS	Disabled

IDLE_SHOULD_YIELD	Enabled
USE_MUTEXES	Enabled
USE_RECURSIVE_MUTEXES	Disabled
USE_COUNTING_SEMAPHORES	Disabled
QUEUE_REGISTRY_SIZE	8
USE_APPLICATION_TASK_TAG	Disabled
ENABLE_BACKWARD_COMPATIBILITY	Enabled
USE_PORT_OPTIMISED_TASK_SELECTION	Enabled
USE_TICKLESS_IDLE	Disabled
USE_TASK_NOTIFICATIONS	Enabled
RECORD_STACK_HIGH_ADDRESS	Disabled

Memory management settings:

Memory Allocation	Dynamic / Static
TOTAL_HEAP_SIZE	15360
Memory Management scheme	heap_4

Hook function related definitions:

USE_IDLE_HOOK	Disabled
USE_TICK_HOOK	Disabled
USE_MALLOC_FAILED_HOOK	Disabled
USE_DAEMON_TASK_STARTUP_HOOK	Disabled
CHECK_FOR_STACK_OVERFLOW	Disabled

Run time and task stats gathering related definitions:

GENERATE_RUN_TIME_STATS	Disabled
USE_TRACE_FACILITY	Disabled
USE_STATS_FORMATTING_FUNCTIONS	Disabled

Co-routine related definitions:

USE_CO_ROUTINES	Disabled
MAX_CO_ROUTINE_PRIORITIES	2

Software timer definitions:

USE_TIMERS	Disabled

Interrupt nesting behaviour configuration:

LIBRARY_LOWEST_INTERRUPT_PRIORITY	15
LIBRARY_MAX_SYSCALL_INTERRUPT_PRIORITY	5

Added with 10.2.1 support:

MESSAGE_BUFFER_LENGTH_TYPE	size_t
USE_POSIX_ERRNO	Disabled

2.11.2. Include parameters:

Include definitions:

vTaskPrioritySet	Enabled

uxTaskPriorityGet	Enabled
vTaskDelete	Enabled
vTaskCleanUpResources	Disabled
vTaskSuspend	Enabled
vTaskDelayUntil	**Enabled ***
vTaskDelay	Enabled
xTaskGetSchedulerState	Enabled
xTaskResumeFromISR	Enabled
xQueueGetMutexHolder	Disabled
xSemaphoreGetMutexHolder	Disabled
pcTaskGetTaskName	Disabled
uxTaskGetStackHighWaterMark	Disabled
xTaskGetCurrentTaskHandle	Disabled
eTaskGetState	Disabled
xEventGroupSetBitFromISR	Disabled
xTimerPendFunctionCall	Disabled
xTaskAbortDelay	Disabled
xTaskGetHandle	Disabled
uxTaskGetStackHighWaterMark2	Disabled

2.11.3. Advanced settings:

Newlib settings (see parameter description first):

USE_NEWLIB_REENTRANT	Disabled

Project settings (see parameter description first):

Use FW pack heap file	Enabled

*** User modified value**

3. System Configuration

3.1. GPIO configuration

IP	Pin	Signal	GPIO mode	GPIO pull/up pull down	Max Speed	User Label
CAN1	PA11	CAN1_RX	Alternate Function Push Pull	No pull-up and no pull-down	**Very High ***	
	PA12	CAN1_TX	Alternate Function Push Pull	No pull-up and no pull-down	**Very High ***	
RCC	PC14-OSC32_IN	RCC_OSC32_IN	n/a	n/a	n/a	
	PC15-OSC32_OUT	RCC_OSC32_OUT	n/a	n/a	n/a	
	PH0-OSC_IN	RCC_OSC_IN	n/a	n/a	n/a	
	PH1-OSC_OUT	RCC_OSC_OUT	n/a	n/a	n/a	
SPI2	PB13	SPI2_SCK	Alternate Function Push Pull	No pull-up and no pull-down	**Very High ***	
	PB14	SPI2_MISO	Alternate Function Push Pull	**Pull-up ***	**Very High ***	
	PB15	SPI2_MOSI	Alternate Function Push Pull	No pull-up and no pull-down	**Very High ***	
SYS	PA13	SYS_JTMS-SWDIO	n/a	n/a	n/a	TMS
	PA14	SYS_JTCK-SWCLK	n/a	n/a	n/a	TCK
TIM3	PA6	TIM3_CH1	Alternate Function Push Pull	No pull-up and no pull-down	Low	
TIM4	PB6	TIM4_CH1	Alternate Function Push Pull	No pull-up and no pull-down	Low	
	PB7	TIM4_CH2	Alternate Function Push Pull	No pull-up and no pull-down	Low	
TIM5	PA0-WKUP	TIM5_CH1	Alternate Function Push Pull	No pull-up and no pull-down	Low	
	PA1	TIM5_CH2	Alternate Function Push Pull	No pull-up and no pull-down	Low	
TIM8	PC6	TIM8_CH1	Alternate Function Push Pull	No pull-up and no pull-down	Low	
	PC7	TIM8_CH2	Alternate Function Push Pull	No pull-up and no pull-down	Low	
UART4	PC10	UART4_TX	Alternate Function Push Pull	No pull-up and no pull-down	**Very High ***	
	PC11	UART4_RX	Alternate Function Push Pull	No pull-up and no pull-down	**Very High ***	
USART2	PA2	USART2_TX	Alternate Function Push Pull	No pull-up and no pull-down	**Very High ***	

IP	Pin	Signal	GPIO mode	GPIO pull/up pull down	Max Speed	User Label
	PA3	USART2_RX	Alternate Function Push Pull	No pull-up and no pull-down	**Very High ***	
Single Mapped Signals	PB3	SYS_JTDO-SWO	n/a	n/a	n/a	SWO
	PB8	TIM2_CH1	Alternate Function Push Pull	No pull-up and no pull-down	Low	
GPIO	PC0	GPIO_Input	Input mode	No pull-up and no pull-down	n/a	UP1
	PC1	GPIO_Input	Input mode	No pull-up and no pull-down	n/a	DOWN2
	PC2	GPIO_Input	Input mode	No pull-up and no pull-down	n/a	DOWN1
	PC3	GPIO_Input	Input mode	No pull-up and no pull-down	n/a	BALL1
	PA4	GPIO_Input	Input mode	No pull-up and no pull-down	n/a	BALL2
	PA5	GPIO_Output	Output Push Pull	No pull-up and no pull-down	Low	S2
	PA7	GPIO_Output	Output Push Pull	No pull-up and no pull-down	Low	S3
	PB0	GPIO_Input	Input mode	No pull-up and no pull-down	n/a	UP2
	PB1	GPIO_Output	Output Push Pull	No pull-up and no pull-down	Low	
	PC8	GPIO_Output	Output Push Pull	No pull-up and no pull-down	Low	IN2
	PC9	GPIO_Output	Output Push Pull	No pull-up and no pull-down	Low	IN1
	PA8	GPIO_Output	Output Push Pull	No pull-up and no pull-down	Low	IN4
	PA9	GPIO_Output	Output Push Pull	No pull-up and no pull-down	Low	IN3
	PB9	GPIO_Input	Input mode	No pull-up and no pull-down	n/a	IR

3.2. DMA configuration

DMA request	Stream	Direction	Priority
USART2_RX	DMA1_Stream5	Peripheral To Memory	**High ***
USART2_TX	DMA1_Stream6	Memory To Peripheral	**High ***
UART4_RX	DMA1_Stream2	Peripheral To Memory	**High ***
UART4_TX	DMA1_Stream4	Memory To Peripheral	**High ***

USART2_RX: DMA1_Stream5 DMA request Settings:

Mode:	**Circular ***
Use fifo:	Disable
Peripheral Increment:	Disable
Memory Increment:	**Enable ***
Peripheral Data Width:	Byte
Memory Data Width:	Byte

USART2_TX: DMA1_Stream6 DMA request Settings:

Mode:	Normal
Use fifo:	Disable
Peripheral Increment:	Disable
Memory Increment:	**Enable ***
Peripheral Data Width:	Byte
Memory Data Width:	Byte

UART4_RX: DMA1_Stream2 DMA request Settings:

Mode:	**Circular ***
Use fifo:	Disable
Peripheral Increment:	Disable
Memory Increment:	**Enable ***
Peripheral Data Width:	Byte
Memory Data Width:	Byte

UART4_TX: DMA1_Stream4 DMA request Settings:

Mode:	Normal

Use fifo:	Disable
Peripheral Increment:	Disable
Memory Increment:	**Enable ***
Peripheral Data Width:	Byte
Memory Data Width:	Byte

3.3. NVIC configuration

3.3.1. NVIC

Interrupt Table	Enable	Preenmption Priority	SubPriority
Non maskable interrupt	true	0	0
Hard fault interrupt	true	0	0
Memory management fault	true	0	0
Pre-fetch fault, memory access fault	true	0	0
Undefined instruction or illegal state	true	0	0
System service call via SWI instruction	true	0	0
Debug monitor	true	0	0
Pendable request for system service	true	15	0
System tick timer	true	15	0
DMA1 stream2 global interrupt	true	5	0
DMA1 stream4 global interrupt	true	5	0
DMA1 stream5 global interrupt	true	5	0
DMA1 stream6 global interrupt	true	5	0
CAN1 RX0 interrupt	true	5	0
TIM1 update interrupt and TIM10 global interrupt	true	15	0
TIM3 global interrupt	true	5	0
USART2 global interrupt	true	5	0
UART4 global interrupt	true	5	0
PVD interrupt through EXTI line 16	unused		
Flash global interrupt	unused		
RCC global interrupt	unused		
CAN1 TX interrupt	unused		
CAN1 RX1 interrupt	unused		
CAN1 SCE interrupt	unused		
TIM4 global interrupt	unused		
SPI2 global interrupt	unused		
TIM8 break interrupt and TIM12 global interrupt	unused		
TIM8 update interrupt and TIM13 global interrupt	unused		
TIM8 trigger and commutation interrupts and TIM14 global interrupt	unused		
TIM8 capture compare interrupt	unused		
TIM5 global interrupt	unused		
FPU global interrupt	unused		

3.3.2. NVIC Code generation

Enabled interrupt Table	Select for init	Generate IRQ	Call HAL handler

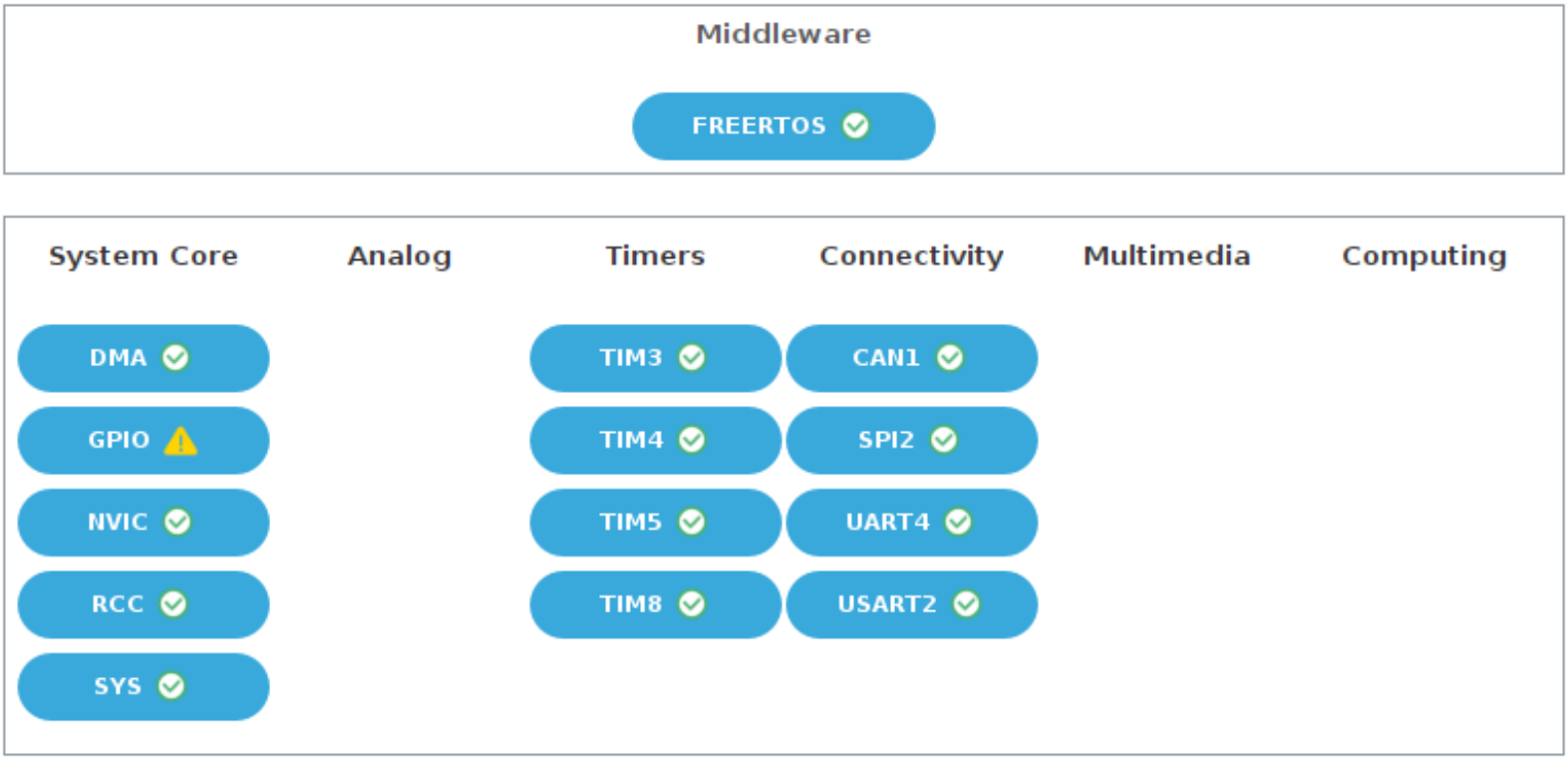
Enabled interrupt Table	Select for init sequence ordering	Generate IRQ handler	Call HAL handler
Non maskable interrupt	false	true	false
Hard fault interrupt	false	true	false
Memory management fault	false	true	false
Pre-fetch fault, memory access fault	false	true	false
Undefined instruction or illegal state	false	true	false
System service call via SWI instruction	false	false	false
Debug monitor	false	true	false
Pendable request for system service	false	false	false
System tick timer	false	false	true
DMA1 stream2 global interrupt	false	true	true
DMA1 stream4 global interrupt	false	true	true
DMA1 stream5 global interrupt	false	true	true
DMA1 stream6 global interrupt	false	true	true
CAN1 RX0 interrupt	false	true	true
TIM1 update interrupt and TIM10 global interrupt	false	true	true
TIM3 global interrupt	false	true	true
USART2 global interrupt	false	true	true
UART4 global interrupt	false	true	true

*** User modified value**

4. System Views

4.1. Category view

4.1.1. Current



5. Docs & Resources

Type	Link