

FLOWER CLASSIFICATION MODEL USING CNN



INTRODUCTION

AI algorithms will be incorporated into more and more everyday applications. For example, we might want to include an image classifier in a smart phone app. To do this, we'd use a deep learning model trained on hundreds of thousands of images as part of the overall application architecture. A large part of software development in the future will be using these types of models as common parts of applications.

The project which I chose is to create a model which when provide the image of a flower will tell its name. We can imagine like converting it in an app which will use the camera, and when camera is pointed at a flower the species name will popup.

Well, there are already so many apps for doing the same thing. Some models are trained so much on few species of plants so that they can even tell if that plant is healthy or have some disease. Such a model can be seen in the link below

<u>Crop Disease Detection Using</u> <u>Machine Learning and Computer</u> <u>Vision - KDnuggets</u>.

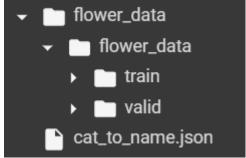
ABOUT MY MODEL AND DATA SET

My model takes in an image of flower from the user and then using CNN it tries to predict its species. This model can differentiate between 102 different species of flower.

Dataset

To train my model I used community provided dataset from the site <u>kaggle.com</u>. Link to my dataset is <u>here</u>. This data set contains two folder train and valid and a cat_to_name.json file.

The two folders are then sub divided into 102 folder labeled from 1 to 102, each of the folder contains varying



number of images of the flower, but one folder contains only one species of flower. The cat_to_name.json file contains texts which are like python dictionary that maps the folder number to the species type of flower.

```
cat_to_name.json X
     "21": "fire lily",
 2
     "3": "canterbury bells",
    "45": "bolero deep blue",
    "1": "pink primrose",
     "34": "mexican aster",
    "27": "prince of wales feathers",
    "7": "moon orchid",
    "16": "globe-flower",
    "25": "grape hyacinth",
10
     "26": "corn poppy",
11
    "79": "toad lily",
12
13
     "39": "siam tulip",
14
     "24": "red ginger",
    "67": "spring crocus",
15
     "35": "alpine sea holly",
16
```

WORKFLOW

This project has been broken into multiple steps

- 1. Load and preprocess the image data
- 2. Creating model
- 3. Training model
- 4. Finetuning pretrained resnet34 model

Although each and every step has already been explained in the notebook, so I will explain in short here.

Load and Preprocess image data

1. The first step is always to import the module you think will be needed the modules I imported are

```
# importing libraries which might be required
import torch as T #for palying with tensors
                          #for using nn.Module while creating own model
import torch.nn as nn
import torchvision
import torch.nn.functional as F #torch module containg activition functions
import torch.optim as optim #torch module containing optimizers
import numpy as np
import matplotlib
                       #for plotting graphs
import matplotlib.pyplot as plt
%matplotlib inline
import seaborn as sns
                         # for plotting bar graph
import os
                         # for getting downloaded data dir
from tqdm.notebook import tqdm
                                 # for showing progress bar while training
```

2. Then downloading data from Kaggle

```
#install opendatasets and importing in colab
!pip install opendatasets
import opendatasets as od
```

```
# Downloading dataset from kaggle.com
dataset_url = "https://www.kaggle.com/nunenuh/pytorch-
challange-flower-dataset"
od.download(dataset_url)
```

3. Then now we need to understand the data and create a dataset and dataloader

In this dataset, we are provided with two folder namely train and valid so, I will be using valid folder as a test folder and will divide the train folder into two parts in the ratio 75:25 for training and validating.

Now Creating dataset

Everything has been explained in detail in notebook too.

Ok so now data has been transformed and I made sure that all images are of size 224 x 224

Now dividing dataset into two parts

Great!!, Now lets look at the some of the images

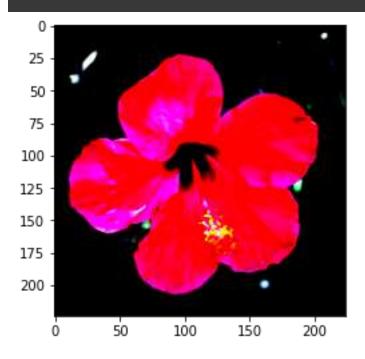
Since our tensor is of the form (channel, height, width) we need to convert it to the form (height, width, channel) so that pyplot can display it

A user defined function we do this all

```
def show_img(ds, ind):  #takes dataset and image index number as input
   """
   Pass the dataset and the index of the image.
   """
   img, label = ds[ind]  #here image is storing the image but label is storing the index number of the category from the classes.
```

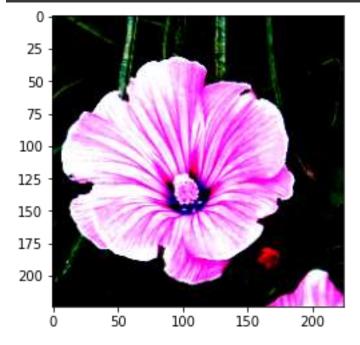
```
cls_ind = dataset.classes[label]
print(f"Label : {cls_ind}: {mapped_label(label)}")
plt.imshow(img.permute(1, 2, 0))
show_img(train_ds,2)
```

```
Label : 83: hibiscus
Clipping input data to the valid range for imshow with RGB data ([0..1] for floats or [0..255] for integers).
```



Lets look one more image,

```
show_img(train_ds, 4300)
Clipping input data to the valid range for imshow with RGB data ([0..1] for floats or
[0..255] for integers).
Label: 86: tree mallow
```



Now its time to create DataLoaders

Lets check how a batch from training data set looks,

```
#visualising dataloader batches
from torchvision.utils import make grid
def disp batches(dl):
   for img, label in dl:
      for i in label:
         print(dl.dataset.dataset.classes[i],cat to name dict[dl.dataset.dataset.class
es[i], end = ", ")
      fig, ax = plt.subplots(figsize = (15, 15))
      ax.set xticks([]); ax.set yticks([])
      ax.imshow(make grid(img, padding = 10).permute(1, 2, 0))
disp batches(train dl)
29 artichoke, 31 carnation, 11 snapdragon, 57 gaura, 62 japanese anemone, 94 foxglove,
61 cautleya spicata, 12 colt's foot, 89 watercress, 31 carnation, 78 lotus lotus, 8
bird of paradise, 23 fritillary, 89 watercress, 44 poinsettia, 65 californian poppy, 3
canterbury bells, 39 siam tulip, 12 colt's foot, 41 barbeton daisy, 101 trumpet
creeper, 51 petunia, 21 fire lily, 70 tree poppy, 83 hibiscus, 45 bolero deep blue, 72 azalea, 74 rose, 85 desert-rose, 18 peruvian lily, 66 osteospermum, 77 passion flower, 3 canterbury bells, 99 bromelia, 70 tree poppy, 55 pelargonium, 39 siam tulip, 77 passion flower, 65 californian poppy, 99 bromelia, 92 bee balm, 43 sword lily, 86 tree mallow, 97 mallow, 30 sweet william, 77 passion flower, 33 love in the mist, 29
artichoke, 18 peruvian lily, 76 morning glory, 73 water lily, 43 sword lily, 26 corn poppy, 37 cape flower, 37 cape flower, 86 tree mallow, 79 toad lily, 77 passion flower, 5 english marigold, 89 watercress, 91 hippeastrum, 47 marigold, 77 passion flower,
Clipping input data to the valid range for imshow with RGB data ([0..1] for floats or
```



The color of these images are due to the normalization applied above while creating a data set

Lets move on to the next step.

Creating Own Model

Here I tried to create my own model.

First I defined the , functions which might be required while training a model

```
def training step(self, batch):
  images, labels = batch
  out = self(images)
  loss = F.cross entropy(out, labels) # Calculate loss
def validation step(self, batch):
  tot correct = 0
  images, labels = batch
  out = self(images)
  loss = F.cross entropy(out, labels)
  acc = accuracy(out, labels)
  tot correct = get num correct(out, labels) #get total number of corect
  return {"val loss": loss.detach(), "val acc": acc, "tot correct": tot correct}
def validation epoch end(self, outputs):
  tot correct = 0
  batch losses = [x['val loss'] for x in outputs]
  epoch loss = T.stack(batch losses).mean()
  batch accs = [x['val acc'] for x in outputs]
  epoch acc = T.stack(batch accs).mean()
  tot correct = sum([x['tot correct'] for x in outputs])
  return {"val loss": epoch loss.item(), "val acc": epoch acc.item(), "tot correc
def epoch end(self, epoch, result):
```

```
print(f"Epoch {epoch+1}, Train loss : {result['train_loss']}, Val. Loss : {result['val_loss']}, val_acc : {result['val_acc']}, Total_Correct : {result['tot_correct']}")
```

Then Defining the Neural Network

```
#defining neural network model
 def init (self,input channels,output classes):
   self.input channels = input channels
   self.output classes = output classes
   super(). init ()
   self.network= nn.Sequential(
           nn.Conv2d(self.input channels,64,kernel size = 3, padding=1),
           nn.ReLU(),
           nn.Conv2d(64,72,kernel_size = 3, padding=1),#conv layer 2
           nn.ReLU(),
           nn.MaxPool2d(2,2), # 72x 112 x 112
           nn.Conv2d(72, 80, kernel size=3, stride=1, padding=1), #conv layer 3
           nn.ReLU(),
           nn.Conv2d(80, 88, kernel size=3, stride=1, padding=1), #conv layer 4
           nn.ReLU(),
           nn.MaxPool2d(2, 2), # output: 88 x 56 x 56
           nn.Conv2d(88, 96, kernel size=3, stride=1, padding=1), #conv layer
           nn.Conv2d(96, 104, kernel size=3, stride=1, padding=1,),
           nn.ReLU(),
           nn.MaxPool2d(2, 2), # output: 104 x 28 x 28
           nn.Conv2d(104,112, kernel size=3, stride=1, padding=1),
           nn.ReLU(),
           nn.Conv2d(112, 120, kernel size=3, stride=1, padding=1,), #conv laye
           nn.ReLU(),
           nn.MaxPool2d(2, 2), # output: 120 x 14 x 14
```

```
nn.Flatten(),  #Flatting the image tensor to pass it to linear
layer

nn.Linear(in_features = 120*14*14, out_features = output_classes),
)

def forward(self, t):  #this method is required while creating a model return self.network(t)
```

Now defining a function to train and validate a model

```
@T.no grad() #turning off pytorch's gradient feature
def evaluate(model, dloader):
   model.eval()
    outputs = [model.validation step(batch) for batch in dloader]
    return model.validation_epoch_end(outputs)
def fit(model, train dloader, val dloader, epochs = 1, lr = 0.01):
 history = [] #list to store the result after each epoch
  optimizer = optim.Adam(model.parameters(), lr)
  for epoch in range (epochs):
    print(f"Epoch : {epoch+1} of {epochs}:\nTraining ")
   model.train()
    train losses = []
    for batch in tqdm(train dloader):
     loss = model.training step(batch)
     train losses.append(loss)
     optimizer.zero grad()
     loss.backward()
      optimizer.step()
    print("Validating ")
    print("\n\t")
    result["train loss"] = T.stack(train losses).mean().item()
    model.epoch end(epoch, result)
    history.append(result)
  return history
```

The codes above are copied from note book, so check the notebook for more details

Training the model

Now here comes the training part,

First, an instance of the model is created then its accuracy is checked before training and then it is trained and validated using test data.

```
input channel = 3
output classes = len(classes)
fcmodel =Flower Classification Model(input channel,output classes) #creating an
instance of the model
fcmodel =to device(fcmodel, device)
print(fcmodel)
Flower Classification Model(
  (network): Sequential(
    (0): Conv2d(3, 64, kernel size=(3, 3), stride=(1, 1), padding=(
    (1): ReLU()
    (2): Conv2d(64, 72, kernel_size=(3, 3), stride=(1, 1), padding=(1,
    (3): ReLU()
    (4): MaxPool2d(kernel_size=2, stride=2, padding=0, dilation=1, ceil_mode=False)
    (5): Conv2d(72, 80, kernel size=(3, 3), stride=(1, 1), padding=(1, 1))
    (6): ReLU()
    (7): Conv2d(80, 88, kernel size=(3, 3), stride=(1, 1), padding=(1, 1))
    (8): ReLU()
    (9): MaxPool2d(kernel_size=2, stride=2, padding=0, dilation=1, ceil_mode=False)
    (10): Conv2d(88, 96, kernel size=(3, 3), stride=(1, 1), padding=(1, 1))
    (11): ReLU()
    (12): Conv2d(96, 104, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
    (13): ReLU()
    (14): MaxPool2d(kernel size=2, stride=2, padding=0, dilation=1,
ceil mode=False)
    (15): Conv2d(104, 112, kernel size=(3, 3), stride=(1, 1), padding=(1, 1))
    (16): ReLU()
    (17): Conv2d(112, 120, kernel size=(3, 3), stride=(1, 1), padding=(1, 1))
    (18): ReLU()
    (19): MaxPool2d(kernel size=2, stride=2, padding=0, dilation=1,
ceil mode=False)
    (20): Flatten(start dim=1, end dim=-1)
    (21): Linear(in_features=23520, out_features=102, bias=True)
```

The above code's output is what we call a model architecture.

My model has 8 convolutional layers and 1 linear network, i used Adam optimizer and for calculating loss, its Cross Entropy.

Before training lets check the accuracy of the model.

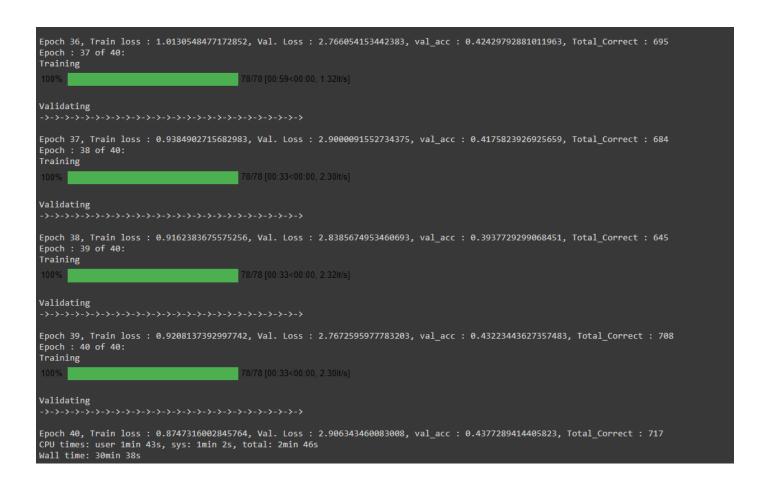
```
%%time
evaluate(fcmodel, val_dl)
->->->->->->->-> sys: 907
ms, total: 2.16 s
```

```
Wall time: 12.1 s
{'tot_correct': 35,
'val_acc': 0.021367521956562996,
'val_loss': 4.624234676361084}
```

As expected the accuracy is very bad its only 2 percent.

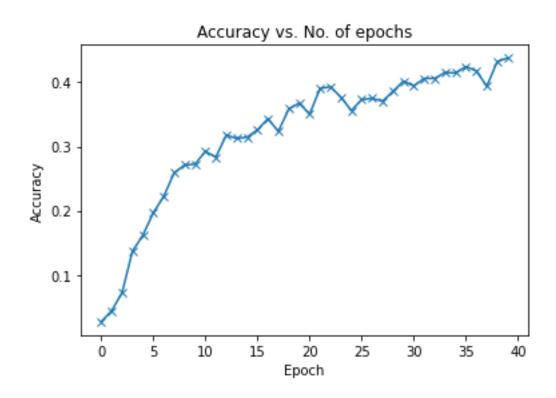
Now lets train the model

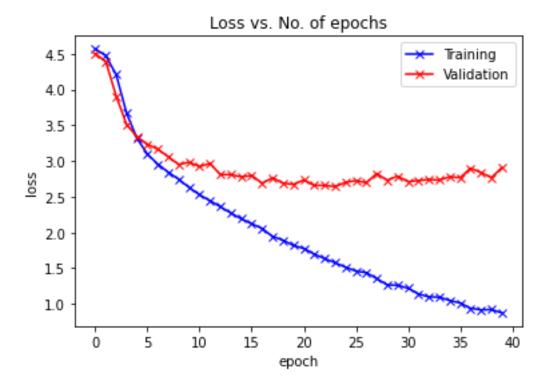
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Now after 40 epochs the accuracy of my model is only 43.77% which is very bad because it will do a lot of mis-predictions

Graphically validation accuracy per epochs has been represented below





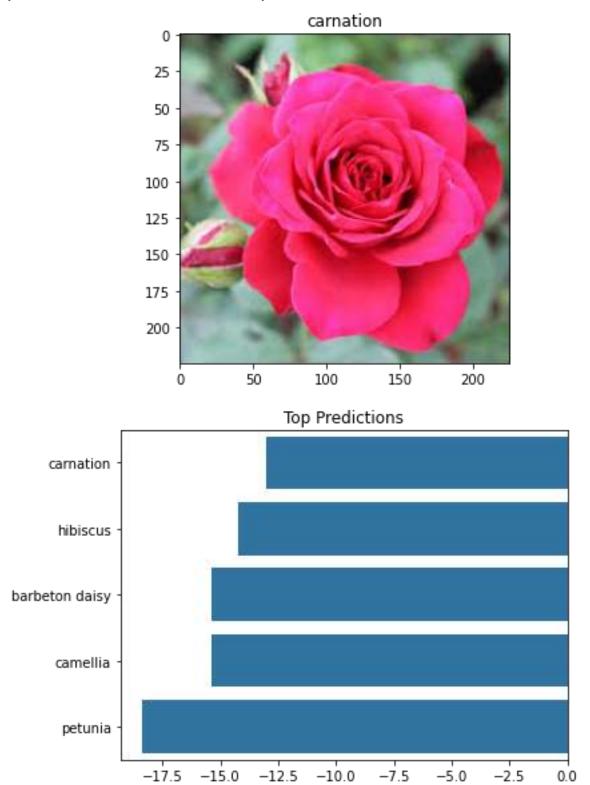
Now, let's see what's the accuracy of my model on test dataset and then after uploading an image what predictions it will be making.

```
1 evaluate(fcmodel, test_dl)
->->->->->->->->->{'tot_correct': 352,
  'val_acc': 0.3834422826766968,
  'val_loss': 2.8641252517700195}
```

So finally the accuracy of custom model is 38.34%

Now I uploaded and image of a Rose and the top 5 predictions made by my model are given below

(code is in the notebook)



So due to bad training it predicted the wrong label.

Using resnet34 model

Since it was my first time creating a model even if the accuracy of the above model was not that much good, for me it was exciting ,so for the sake of this project I used resnet34 model too

Which in the end gave good results

<u>About resnet34 model</u>

Resnet34 is a 34 layer convolutional neural network that can be utilized as a state-of-the-art image classification model. This is a model that has been pre-trained on the ImageNet dataset--a dataset that has 100,000+ images across 200 different classes. However, it is different from traditional neural networks in the sense that it takes residuals from each layer and uses them in the subsequent connected layers (similar to residual neural networks used for text prediction).

Architecture of resnet34 model used in notebook

```
PreTrainedClassificationModel(
  (network): ResNet(
    (conv1): Conv2d(\overline{3}, 64, kernel size=(7, 7), stride=(2, 2), padding=(3, 3),
bias=False)
    (bn1): BatchNorm2d(64, eps=1e-05, momentum=0.1, affine=True,
track running stats=True)
    (relu): ReLU(inplace=True)
    (maxpool): MaxPool2d(kernel size=3, stride=2, padding=1, dilation=1,
ceil mode=False)
    (layer1): Sequential(
      (0): BasicBlock(
        (conv1): Conv2d(64, 64, kernel size=(3, 3), stride=(1, 1), padding=(1, 1),
bias=False)
        (bn1): BatchNorm2d(64, eps=1e-05, momentum=0.1, affine=True,
track running stats=True)
        (relu): ReLU(inplace=True)
        (bn2): BatchNorm2d(64, eps=1e-05, momentum=0.1, affine=True,
track running stats=True)
```

```
(1): BasicBlock(
        (conv1): Conv2d(64, 64, kernel size=(3, 3), stride=(1, 1), padding=(1, 1),
bias=False)
        (bn1): BatchNorm2d(64, eps=1e-05, momentum=0.1, affine=True,
track running stats=True)
        (relu): ReLU(inplace=True)
        (conv2): Conv2d(64, 64, kernel size=(3, 3), stride=(1, 1), padding=(1, 1),
bias=False)
        (bn2): BatchNorm2d(64, eps=1e-05, momentum=0.1, affine=True,
track running stats=True)
      (2): BasicBlock(
        (conv1): Conv2d(64, 64, kernel size=(3, 3), stride=(1, 1), padding=(1, 1),
bias=False)
        (bn1): BatchNorm2d(64, eps=1e-05, momentum=0.1, affine=True,
track running stats=True)
        (relu): ReLU(inplace=True)
        (conv2): Conv2d(64, 64, kernel size=(3, 3), stride=(1, 1), padding=(1, 1),
bias=False)
        (bn2): BatchNorm2d(64, eps=1e-05, momentum=0.1, affine=True,
track_running stats=True)
    (layer2): Sequential(
      (0): BasicBlock(
        (conv1): Conv2d(64, 128, kernel size=(3, 3), stride=(2, 2), padding=(1, 1),
bias=False)
        (bn1): BatchNorm2d(128, eps=1e-05, momentum=0.1, affine=True,
track running stats=True)
        (relu): ReLU(inplace=True)
        (conv2): Conv2d(128, 128, kernel size=(3, 3), stride=(1, 1), padding=(1,
1), bias=False)
        (bn2): BatchNorm2d(128, eps=1e-05, momentum=0.1, affine=True,
track running stats=True)
        (downsample): Sequential(
          (0): Conv2d(64, 128, kernel size=(1, 1), stride=(2, 2), bias=False)
          (1): BatchNorm2d(128, eps=1e-05, momentum=0.1, affine=True,
track_running stats=True)
       )
      (1): BasicBlock(
        (conv1): Conv2d(128, 128, kernel size=(3, 3), stride=(1, 1), padding=(1,
1), bias=False)
        (bn1): BatchNorm2d(128, eps=1e-05, momentum=0.1, affine=True,
track running stats=True)
        (relu): ReLU(inplace=True)
        (conv2): Conv2d(128, 128, kernel_size=(3, 3), stride=(1, 1), padding=(1,
1), bias=False)
        (bn2): BatchNorm2d(128, eps=1e-05, momentum=0.1, affine=True,
track running stats=True)
      (2): BasicBlock(
        (conv1): Conv2d(128, 128, kernel size=(3, 3), stride=(1, 1), padding=(1,
1), bias=False)
        (bn1): BatchNorm2d(128, eps=1e-05, momentum=0.1, affine=True,
track running stats=True)
        (relu): ReLU(inplace=True)
        (conv2): Conv2d(128, 128, kernel size=(3, 3), stride=(1, 1), padding=(1, 1)
1), bias=False)
        (bn2): BatchNorm2d(128, eps=1e-05, momentum=0.1, affine=True,
track running stats=True)
```

```
(3): BasicBlock(
        (conv1): Conv2d(128, 128, kernel size=(3, 3), stride=(1, 1), padding=(1,
1), bias=False)
        (bn1): BatchNorm2d(128, eps=1e-05, momentum=0.1, affine=True,
track running stats=True)
        (relu): ReLU(inplace=True)
        (conv2): Conv2d(128, 128, kernel size=(3, 3), stride=(1, 1), padding=(1,
1), bias=False)
        (bn2): BatchNorm2d(128, eps=1e-05, momentum=0.1, affine=True,
track running stats=True)
    (layer3): Sequential(
      (0): BasicBlock(
        (conv1): Conv2d(128, 256, kernel size=(3, 3), stride=(2, 2), padding=(1,
1), bias=False)
        (bn1): BatchNorm2d(256, eps=1e-05, momentum=0.1, affine=True,
track running stats=True)
        (relu): ReLU(inplace=True)
        (conv2): Conv2d(256, 256, kernel size=(3, 3), stride=(1, 1), padding=(1,
1), bias=False)
        (bn2): BatchNorm2d(256, eps=1e-05, momentum=0.1, affine=True,
track running stats=True)
        (downsample): Sequential(
          (0): Conv2d(128, 256, kernel size=(1, 1), stride=(2, 2), bias=False)
          (1): BatchNorm2d(256, eps=1e-05, momentum=0.1, affine=True,
track running stats=True)
      (1): BasicBlock(
        (conv1): Conv2d(256, 256, kernel size=(3, 3), stride=(1, 1), padding=(1,
1), bias=False)
        (bn1): BatchNorm2d(256, eps=1e-05, momentum=0.1, affine=True,
track running stats=True)
        (relu): ReLU(inplace=True)
        (conv2): Conv2d(256, 256, kernel size=(3, 3), stride=(1, 1), padding=(1,
1), bias=False)
        (bn2): BatchNorm2d(256, eps=1e-05, momentum=0.1, affine=True,
track running stats=True)
      (2): BasicBlock(
        (conv1): Conv2d(256, 256, kernel size=(3, 3), stride=(1, 1), padding=(1,
1), bias=False)
        (bn1): BatchNorm2d(256, eps=1e-05, momentum=0.1, affine=True,
track running stats=True)
        (relu): ReLU(inplace=True)
        (conv2): Conv2d(256, 256, kernel_size=(3, 3), stride=(1, 1), padding=(1,
1), bias=False)
        (bn2): BatchNorm2d(256, eps=1e-05, momentum=0.1, affine=True,
track running stats=True)
      (3): BasicBlock(
        (conv1): Conv2d(256, 256, kernel_size=(3, 3), stride=(1, 1), padding=(1,
1), bias=False)
        (bn1): BatchNorm2d(256, eps=1e-05, momentum=0.1, affine=True,
track running stats=True)
        (relu): ReLU(inplace=True)
        (conv2): Conv2d(256, 256, kernel size=(3, 3), stride=(1, 1), padding=(1,
1), bias=False)
        (bn2): BatchNorm2d(256, eps=1e-05, momentum=0.1, affine=True,
track running stats=True)
```

```
(4): BasicBlock(
        (conv1): Conv2d(256, 256, kernel size=(3, 3), stride=(1, 1), padding=(1,
1), bias=False)
        (bn1): BatchNorm2d(256, eps=1e-05, momentum=0.1, affine=True,
track running stats=True)
        (relu): ReLU(inplace=True)
        (conv2): Conv2d(256, 256, kernel size=(3, 3), stride=(1, 1), padding=(1,
1), bias=False)
        (bn2): BatchNorm2d(256, eps=1e-05, momentum=0.1, affine=True,
track running stats=True)
      (5): BasicBlock(
        1), bias=False)
        (bn1): BatchNorm2d(256, eps=1e-05, momentum=0.1, affine=True,
track running stats=True)
        (relu): ReLU(inplace=True)
        (conv2): Conv2d(256, 256, kernel size=(3, 3), stride=(1, 1), padding=(1,
1), bias=False)
        (bn2): BatchNorm2d(256, eps=1e-05, momentum=0.1, affine=True,
track_running stats=True)
    (layer4): Sequential(
      (0): BasicBlock(
        (conv1): Conv2d(256, 512, kernel size=(3, 3), stride=(2, 2), padding=(1,
1), bias=False)
        (bn1): BatchNorm2d(512, eps=1e-05, momentum=0.1, affine=True,
track running stats=True)
        (relu): ReLU(inplace=True)
        (conv2): Conv2d(512, 512, kernel size=(3, 3), stride=(1, 1), padding=(1,
1), bias=False)
        (bn2): BatchNorm2d(512, eps=1e-05, momentum=0.1, affine=True,
track running stats=True)
        (downsample): Sequential(
          (0): Conv2d(256, 512, kernel size=(1, 1), stride=(2, 2), bias=False)
          (1): BatchNorm2d(512, eps=1e-05, momentum=0.1, affine=True,
track_running_stats=True)
       )
      (1): BasicBlock(
        (conv1): Conv2d(512, 512, kernel size=(3, 3), stride=(1, 1), padding=(1,
1), bias=False)
        (bn1): BatchNorm2d(512, eps=1e-05, momentum=0.1, affine=True,
track running stats=True)
        (relu): ReLU(inplace=True)
        (conv2): Conv2d(512, 512, kernel_size=(3, 3), stride=(1, 1), padding=(1,
1), bias=False)
        (bn2): BatchNorm2d(512, eps=1e-05, momentum=0.1, affine=True,
track running stats=True)
      (2): BasicBlock(
        (conv1): Conv2d(512, 512, kernel size=(3, 3), stride=(1, 1), padding=(1,
1), bias=False)
        (bn1): BatchNorm2d(512, eps=1e-05, momentum=0.1, affine=True,
track running stats=True)
        (relu): ReLU(inplace=True)
        (conv2): Conv2d(512, 512, kernel size=(3, 3), stride=(1, 1), padding=(1,
1), bias=False)
        (bn2): BatchNorm2d(512, eps=1e-05, momentum=0.1, affine=True,
track running stats=True)
```

```
)
(avgpool): AdaptiveAvgPool2d(output_size=(1, 1))
(fc): Linear(in_features=512, out_features=102, bias=True)
)
```

For tuning the resnet34 model as per my need, I had to define some functions to fit it., the complete code is in the notebook, the fit function is given below

```
def fit one cycle(epochs, max lr, model, train loader, val loader,
                  weight decay=0, grad clip=None, opt func=optim.SGD):
     T.cuda.empty cache()
   history = []
   optimizer = opt func(model.parameters(), max lr, weight decay=weight decay) # Set up
   sched = T.optim.lr scheduler.OneCycleLR(optimizer, max lr, epochs=epochs,
                                                 steps per epoch=len(train loader))
   for epoch in range (epochs):
       print(f"Epoch : {epoch+1} of {epochs}:\nTraining")
       model.train()
       for batch in tqdm(train loader):
           loss = model.training step(batch)
           train losses.append(loss)
           loss.backward()
           if grad clip:
                nn.utils.clip grad value (model.parameters(), grad clip)
           optimizer.step()
           optimizer.zero grad()
           lrs.append(get lr(optimizer))
           sched.step()
       print("\n\t")
```

```
result['train_loss'] = T.stack(train_losses).mean().item()
result['lrs'] = lrs
model.epoch_end(epoch, result)
history.append(result)
return history
```

Creating an instance of the resnet34 model

```
output_classes = len(dataset.classes)
print(output_classes)
fcmodel2 = PreTrainedClassificationModel(output_classes,pretrained = True)
fcmodel2 = to_device(fcmodel2, device)
```

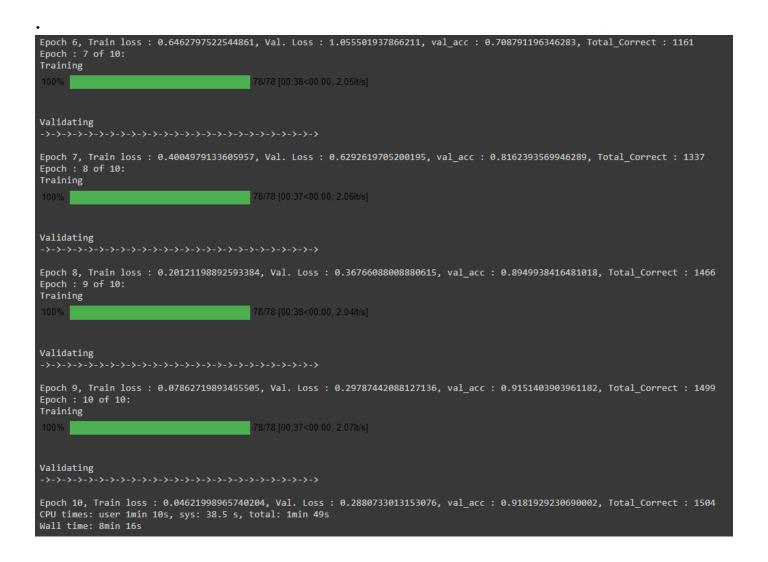
Checking accuracy before tuning.

```
history2 = [evaluate(fcmodel2, val_dl)]
print(history2)
->->->->->[{'val_loss':
4.918607234954834, 'val_acc': 0.007326007820665836, 'tot_correct': 12}]
```

The accuracy is low only 0.7 %.

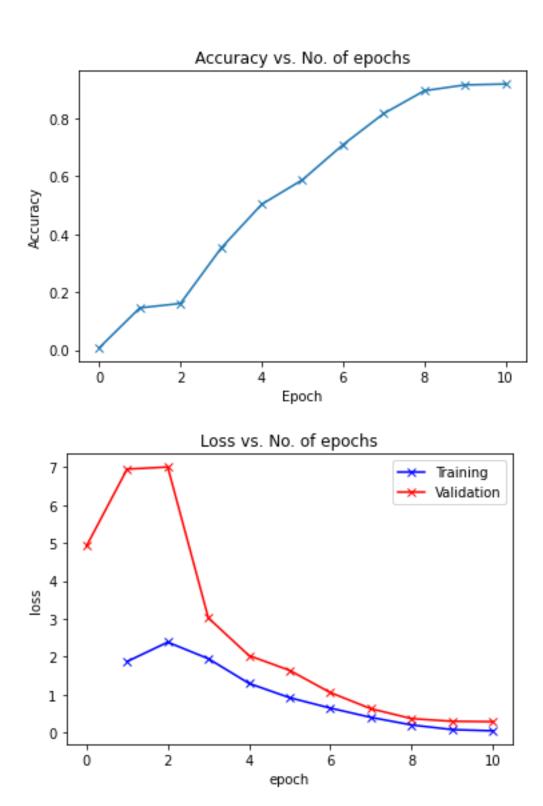
Let's train this model.

```
epochs = 10
max_lr = 0.01
[77]
          grad_clip = 0.1
          weight_decay = 1e-4
          opt_func = optim.Adam
0
          %%time
          history2 += fit_one_cycle(epochs, max_lr, fcmodel2, train_dl, val_dl,
                                     grad_clip=grad_clip, weight_decay=weight_decay,
                                     opt_func = opt_func)
     Epoch : 1 of 10:
₽
     Training
                                                78/78 [04:02<00:00, 3.11s/it]
     Validating
     Epoch 1, Train loss : 1.8736412525177002, Val. Loss : 6.946482181549072, val_acc : 0.14529913663864136, Total_Correct : 238
     Epoch : 2 of 10:
     Training
                                                78/78 [03:13<00:00, 2.48s/it]
     Validating
     Epoch 2, Train loss : 2.383558750152588, Val. Loss : 7.000977516174316, val_acc : 0.160561665892601, Total_Correct : 263 Epoch : 3 of 10:
     Training
                                                78/78 [02:23<00:00, 1.84s/it]
     Validating
     Epoch 3, Train loss: 1.9479068517684937, Val. Loss: 3.0207314491271973, Val_acc: 0.35164836049079895, Total_Correct: 576 Epoch: 4 of 10:
     Training
                                                78/78 [01:34<00:00, 1.21s/it]
```



Wow!!! The accuracy of the resnet34 model is 91.81%

Accuracy and loss graphs per epochs.

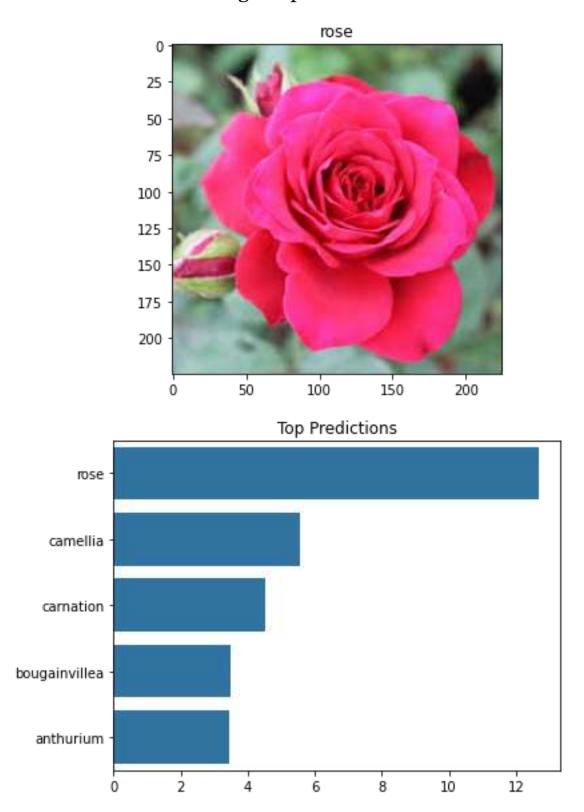


Checking accuracy on test dataset

```
1 evaluate(fcmodel2,test_dl)
->->->->->->->->{'tot_correct': 752,
'val_acc': 0.9281045198440552,
'val_loss': 0.2897782623767853}
```

On test data set it gave the accuracy of 92.81 %

And the result of the image I uploaded is below"



Finally, while custom model took 30 mins to train for 40 epochs and gave only 38.34% accuracy on test data, the resnet34 model gave 92% accuracy on same test data, and it just took 10 epochs and less than 10 minutes

Why is this so? What could be the reason?

Well, what I think is this model is denser than my model, and has already been trained over a very large data set when it was created, so its weight are way more flexible then my model, with a little bit of adjustments it can give really high accuracy about 97%, while when creating a model from the scratch we have to play a lot with hyper parameters.

References:

- 1. Kaggle.com
- 2. Towards Data science
- 3. Analytics Vidhya
- 4. Some random github repositories
- 5. <u>Deeplizard.com</u>
- 6. And some random youtube videos