

Segmentation algorithms

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3rd February, 2024

Agenda

Definition

Algorithms

Conclusion

What is segmentation?

- ▶ Assignment of labels to pixels
- ▶ Input: Image
- ▶ Output: Matrix with various elements specifying the object instance to which each pixel belongs
- ▶ Based on? color, intensity, contrast, boundary, texture

What role does segmentation play in AI?

- ▶ Reduces the complexity of the image
- ▶ Enables further processing or analysis of each image segment
- ▶ Example: Object Detection
- ▶ Use an image segmentation algorithm to find objects of interest
- ▶ Detector can operate on a bounding box already defined
- ▶ Prevents processing the entire image (improves accuracy, reduces time)

More real life examples

- ▶ Medical image analysis
- ▶ Computer vision for autonomous vehicles
- ▶ Face recognition and detection, video surveillance
- ▶ Satellite image analysis
- ▶ Compression

General types of algorithms

- ▶ Thresholding (Global, Adaptive)
- ▶ Edge-based (Canny, Sobel, Laplacian of Gaussian)
- ▶ Clustering (K-means, Mean shift, Hierarchical Agglomerative)
- ▶ Neural network based

K-means

- ▶ A top-down algorithm
- ▶ k = number of clusters to split into, given by user
- ▶ Steps:
 - ▶ Initialize k centroids
 - ▶ Assign each data point to the closest centroid
 - ▶ Compute the new centroid of each cluster
 - ▶ Repeat till convergence
- ▶ "closest"?
- ▶ "initialize"?

K-means (contd.)

- ▶ Choice of K is often ambiguous (Elbow method)
- ▶ The Random Initialization Trap
- ▶ Pros: scalability, ease of interpretation, guarantees convergence
- ▶ Cons: need to pre-determine k , sensitivity to outliers, risk of getting stuck in local minima
- ▶ Time Complexity: running a fixed number t of iterations of the algorithm takes $O(t \cdot k \cdot n \cdot d)$, for n (d -dimensional) points, where k is the number of clusters

K-means (contd.)

$$\arg \min_{\mathbf{S}} \sum_{i=1}^k \sum_{\mathbf{x}_j \in S_i} \|\mathbf{x}_j - \boldsymbol{\mu}_i\|^2$$

- ▶ k = number of clusters
- ▶ μ_i = centroid of cluster i
- ▶ j = number of cases for cluster i
- ▶ Want to minimize this value

Mean Shift Clustering

- ▶ A density-based algorithm
- ▶ Shifts each data point towards the mode (i.e., the highest density) of the distribution of points within a certain radius
- ▶ Does not require specifying the number of clusters or the initial cluster centers
- ▶ Steps:
 - ▶ Initialize the data points as cluster centroids.
 - ▶ Choose a window size (aka 'Bandwidth Parameter').
 - ▶ Compute the mean of all points within the window for each data point.
 - ▶ Shift the window to mean location and repeat until convergence or maximum iterations have passed
 - ▶ Select the final clusters by deleting overlapping windows or merging close windows.

Mean Shift (contd.)

- ▶ Pros:
 - ▶ Does not need data regarding clusters, it is auto-determined
 - ▶ Can handle noise and outliers by simply ignoring the clusters formed by them
 - ▶ Does not make assumption on data distribution, allowing it to handle arbitrary shapes
- ▶ Cons:
 - ▶ Computationally expensive
 - ▶ Heavily sensitive to the Bandwidth parameter: Too small a value overfits and too large underfits the clusters.
 - ▶ Can have difficulty in finding clusters of different densities, as a single bandwidth may not be suitable for all regions of the data space.

Mean Shift (contd.)

- ▶ Time Complexity: $O(n^2)$, n = no of Data points
- ▶ Space Complexity: $O(n)$, n = no of Data points

$$f_K(\mathbf{u}) = \frac{1}{nh^d} \sum_{i=1}^n K\left(\frac{\mathbf{u} - \mathbf{u}_i}{h}\right)$$

- ▶ \mathbf{u} = central point of cluster
- ▶ n = number of datapoints
- ▶ h = Bandwidth Parameter
- ▶ d = dimensions of data
- ▶ \mathbf{u}_i = subpoints in the cluster
- ▶ K = Kernel Function: $K(u) = \frac{1}{\sqrt{2\pi}} e^{-\frac{u^2}{2}}$

Plan of action

- ▶ Implement both of these algorithms
- ▶ Analyze their space and time complexities, their pros and cons, particular use cases
- ▶ Come up with a modified algo based on the merits of these two algos

Thank you!

Open to any questions and suggestions