
Stat 433

STOCHASTIC PROCESSES

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1 DTMC

1.1 Review of Probability

A **random variable (r.v.)** X is a real valued function of the outcomes of a random experiment.

$$X : \Omega \rightarrow \mathbb{R}$$

Where $\Omega = \{\omega_1, \omega_2, \dots\}$ is the **sample space** corresponding to all possible outcomes ω_i . The outcomes can in principle be any objects (numbers, strings, etc.). We say that X maps each outcome ω to a real number $\omega \mapsto X(\omega) \in \mathbb{R}$.

A **stochastic process** is a family of random variables $\{X_t\}_{t \in T}$, defined on a common sample space Ω . T is referred to as the index set for the stochastic process which is often understood as time. The index set T can take a discrete spectrum,

$$T = \{0, 1, 2, \dots\} \quad \{X_n \mid n = 0, 1, 2, \dots\}$$

Alternatively, T can take on a continuous spectrum,

$$T = \{t \mid t \geq 0\} = [0, \infty)$$

The **state space** S is the collection of all possible values of X_t 's. It is important to understand the distinction of between sample space and state space. Additionally, the state space can either have discrete or continuous spectrum.

A question remains, *Why do we need the family of random variables to be defined on a common sample space?* The answer being that we would like to be able to discuss the joint behaviour of X_t 's. If X_1 has domain Ω_1 and X_2 has domain Ω_2 (where $\Omega_1 \neq \Omega_2$), then one can *not* talk about common ideas of correlations and associations between X_1 and X_2 . As such we assert that all members of a stochastic process share the same sample space domain Ω .

1.2 Discrete-time Markov Chain

A **discrete-time stochastic process** $\{X_n \mid n \in 0, 1, 2, \dots\}$ is said to be a **Discrete-time Markov Chain (DTMC)** if the following conditions hold:

1. The state space is at most *countable*¹ (i.e. finite or countable).

$$S = \{0, 1, \dots, k\} \quad \text{or} \quad S = \{0, 1, 2, \dots\}$$

2. **Markov Property:** For any $n = 0, 1, 2, \dots$,

$$P(X_{n+1} = x_{n+1} \mid X_n = x_n, X_{n-1} = x_{n-1}, \dots, X_0 = x_0) = P(X_{n+1} = x_{n+1} \mid X_n = x_n)$$

We use capital letters X to denote the random variable and lower case letters x to denote a specific realization or valuation of X . The motivation of the Markov property is that future events $X_{n+1} = x_{n+1}$ are independent of past histories $\{X_i = x_i \mid i = 0, 1, \dots, n-1\}$ given the immediate past state $X_n = x_n$. The intuition being that the future and the past are probabilistically independent.

Given the present, the future and the past are independent.

¹Countable meaning there is a one-to-one mapping from the state space to the natural numbers.

1.3 Transition Probability

The **transition probability** from a state $i \in S$ at time n to state $j \in S$ (at time $n + 1$) is given by,

$$P_{n,i,j} \equiv P(X_{n+1} = j \mid X_n = i) \quad n = 0, 1, 2, \dots \quad (1.1)$$

In full generality, the transition probability could depend on time n but in this course we will restrict ourselves to transition probabilities that *do not* depend on time n ($P_{n,i,j} = P_{i,j}$). We say that the MC is **(time-)homogeneous** if this property holds. From now on, this will be our default setting.

The matrix of all transition probabilities $P = \{P_{i,j} \mid i, j \in S\}$ is called the **one-step transition (probability) matrix** for $\{X_n \mid n \in T\}$.

$$P = \begin{pmatrix} P_{00} & P_{01} & \cdots & P_{0j} & \cdots \\ P_{10} & P_{11} & \cdots & P_{1j} & \cdots \\ \vdots & \vdots & \ddots & \vdots & \cdots \\ P_{i0} & P_{i1} & \cdots & P_{ij} & \cdots \\ \vdots & \vdots & \vdots & \vdots & \ddots \end{pmatrix}$$

The one-step transition matrix P has the following properties,

$$P_{i,j} \geq 0 \quad (1.2)$$

$$\forall i : \sum_{j \in S} P_{ij} = 1 \quad (1.3)$$

The entries are non-negative because they represent probabilities and the row sums for P are always unitary.

The **n-step transition probability** is defined via the homogeneous property,

$$\forall i, j \in S : P_{ij}^{(n)} \equiv P(X_{n+m} = j \mid X_n = i) = P(X_n = j \mid X_0 = i)$$

Analogously, the **n-step transition matrix** is the matrix,

$$P^{(n)} = \{P_{ij}^{(n)} \mid i, j \in S\}$$

Theorem 1. *There is a simple relation between the n-step transition matrix $P^{(n)}$ and the one step transition matrix P .*

$$P^{(n)} = P^{(n-1)} \cdot P = \underbrace{P \cdot P \cdot \dots \cdot P}_n = P^n$$

Proof. Proof by induction:

$$P^{(1)} = P \quad \text{By definition.}$$

We also have $P^{(0)} = P^0 = \mathbb{I}$ is the identity matrix. We now assume $P^{(n)} = P^n$. Then $\forall i, j \in S$,

$$\begin{aligned} P_{ij}^{(n+1)} &= P(X_{n+1} = j \mid X_0 = i) \\ &= \sum_{k \in S} P(X_{n+1} = j, X_n = k \mid X_0 = i) \quad \text{Total probability} \\ &= \sum_{k \in S} \frac{P(X_{n+1} = j, X_n = k, X_0 = i)}{P(X_0 = i)} \\ &= \sum_{k \in S} \frac{P(X_{n+1} = j, X_n = k, X_0 = i)}{P(X_n = k, X_0 = i)} \frac{P(X_n = k, X_0 = i)}{P(X_0 = i)} \\ &= \sum_{k \in S} P(X_{n+1} = j \mid X_n = k, X_0 = i) \cdot P(X_n = k \mid X_0 = i) \quad \text{Conditional total probability} \end{aligned}$$

$$\begin{aligned}
&= \sum_{k \in S} P(X_{n+1} = j \mid X_n = k) \cdot P(X_n = k \mid X_0 = i) \quad \text{Use Markov Property} \\
&= \sum_{k \in S} P_{kj} \cdot P_{ik}^{(n)} \quad \text{Matrix terms} \\
&= \left(P \cdot P^{(n)} \right)_{ij} \quad \text{Matrix product} \\
&= \left(P^{n+1} \right)_{ij} \quad \text{Inductive Hypothesis}
\end{aligned}$$

There we have proved that $P^{(n+1)} = P^{n+1}$ and so we have a complete proof that $P^{(n)} = P^n$. □

Corollary 2. *As a corollary, we have obtained that,*

$$P^{(n)} = P^{(m)} \cdot P^{(n-m)} \quad \forall 0 \leq m \leq n$$

*Or equivalently the **Chapman-Kolmogorov Equation** or simply C-K equation,*

$$P_{ij}^{(n)} = \sum_{k \in S} P_{ik}^{(m)} P_{kj}^{(n-m)} \quad \forall i, j \in S, \forall 0 \leq m \leq n \quad (1.4)$$

So far, we have only been discussing transition probabilities. We will now divert our attention to actual distributions for a stochastic process.

Let $\alpha_n = (\alpha_{n,0}, \alpha_{n,1}, \dots)$ be the **probability distribution vector** for X_n at time n .

$$\alpha_{n,k} = P(X_n = k) \quad \forall k \in S$$

Note that $\alpha_{n,k} \geq 0$ and $\sum_{k \in S} \alpha_{n,k} = 1$ and $n = 0, 1, 2, \dots$. We also define the initial distribution α_0 ,

$$\alpha_0 = (P(X_0 = 0), P(X_0 = 1), \dots)$$

Theorem 3. *The transition probability matrix reveals the following relationship between the distribution α_n at time n and the distribution α_0 at time 0,*

$$\alpha_n = \alpha_0 \cdot P^n \quad (1.5)$$

Proof. The proof eq. (1.5) is quite trivial:

$$\begin{aligned}
\forall j \in S \quad \alpha_{n,j} &= P(X_n = j) \\
&= \sum_{i \in S} P(X_n = j \mid X_0 = i) \cdot P(X_0 = i) \\
&= \sum_{i \in S} \alpha_{0,i} \cdot P_{ij}^n \\
&= \alpha_{0,0} \cdot P_{0j}^n + \alpha_{0,1} \cdot P_{1j}^n + \dots \\
&= (\alpha_0 \cdot P^n)_j
\end{aligned}$$

□

More generally, for any $n = 1, 2, \dots$ the finite dimensional distribution can be obtained from the following process iterative process,

$$\begin{aligned}
P(X_n = x_n, X_{n-1} = x_{n-1}, \dots, X_0 = x_0) &= \\
&P(X_0 = x_0) \cdot \\
&P(X_1 = x_1 \mid X_0 = x_0) \cdot \\
&P(X_2 = x_2 \mid X_1 = x_1, X_0 = x_0) \cdots
\end{aligned}$$

$$P(X_n = x_n \mid X_{n-1} = x_{n-1}, \dots, X_0 = x_0)$$

But by the Markov condition, it must be that,

$$\begin{aligned} P(X_n = x_n, X_{n-1} = x_{n-1}, \dots, X_0 = x_0) = \\ P(X_0 = x_0) \cdot \\ P(X_1 = x_1 \mid X_0 = x_0) \cdot \\ P(X_2 = x_2 \mid X_1 = x_1) \cdots \\ P(X_n = x_n \mid X_{n-1} = x_{n-1}) \end{aligned}$$

First recognize the first term on the RHS ($P(X_0 = x_0) = \alpha_{0,x_0}$), and also the remaining terms are transition probabilities as per eq. (1.1). Therefore it must be that,

$$P(X_n = x_n, X_{n-1} = x_{n-1}, \dots, X_0 = x_0) = \alpha_{0,x_0} P_{x_0 x_1} P_{x_1 x_2} \cdots P_{x_{n-1} x_n}$$

Even more generally, for $0 \leq t_1 < t_2 < \cdots < t_n$,

$$P(X_{t_n} = x_{t_n}, X_{t_{n-1}} = x_{t_{n-1}}, \dots, X_{t_1} = x_{t_1}) = P(X_{t_1} = x_{t_1}) (P^{t_2-t_1})_{x_{t_1} x_{t_2}} (P^{t_3-t_2})_{x_{t_2} x_{t_3}} \cdots (P^{t_n-t_{n-1}})_{x_{t_{n-1}} x_{t_n}}$$

Since $P(X_{t_1} = x_{t_1}) = \alpha_{t_1 x_{t_1}} = \sum_{k \in S} \alpha_{0,k} P_{k,x_{t_1}}^{t_1}$,

$$\alpha_{t_1} = \alpha_0 \cdot P^{t_1}$$

This means the probabilistic properties of a DTMC are fully characterized by two things:

1. The initial distribution α_0
2. Transition matrix P

1.4 Classification of States

State j is **accessible** from state i (denoted $i \rightarrow j$) if there exists $n = 0, 1, \dots$ such that $P_{ij}^{(n)} > 0$. Intuitively, one can transition from state i to state j in finite steps n with positive probability. If i is also accessible from j , then we say i and j **communicate**, denoted as $i \leftrightarrow j$.

$$i \leftrightarrow j \Leftrightarrow \exists m, n \geq 0, P_{ij}^{(m)} > 0, P_{ji}^{(n)} > 0$$

Theorem 4. The binary communication relation “ \leftrightarrow ” is in fact a equivalence relation:

- Reflexivity $i \leftrightarrow i$
- Symmetry $i \leftrightarrow j \implies j \leftrightarrow i$
- Transitivity $i \leftrightarrow j, j \leftrightarrow k \implies i \leftrightarrow k$

Proof. First, reflexivity is easy to prove by definition. Let $n = 0$ and recognize that $P_{ii}^{(0)}$ has a certain probability by definition,

$$P_{ii}^{(0)} = 1 \implies i \leftrightarrow i$$

Second, symmetry follows by definition,

$$P_{ij}^{(m)} > 0, P_{ji}^{(n)} > 0 \Leftrightarrow P_{ji}^{(n)} > 0, P_{ij}^{(m)} > 0$$

Third, transitivity can be proving by letting m and n be the unknown quantifiers:

$$\exists m \quad P_{ij}^{(m)} > 0, \exists n \quad P_{jk}^{(n)} > 0$$

Then by the CK equation eq. (1.4),

$$P_{ik}^{(m+n)} = \sum_{l \in S} P_{il}^{(m)} P_{lk}^{(n)}$$

Let $l = j$ be a single, fixed entry in the summation,

$$P_{ik}^{(m+n)} \geq P_{ij}^{(m)} P_{jk}^{(n)} > 0$$

Therefore we have that k is accessible from i ($i \rightarrow j$). Analogously we have that $i \rightarrow j$ therefore $i \leftrightarrow k$. \square

The communication equivalence relations then divides the state space S into different equivalence classes. That is, the states in one class comm with each other; the states in different classes do not comm. The equivalent classes form a *partition* of the state space S .

The family $\{S_1, S_2, \dots, S_n\}$ is a **partition** of S if,

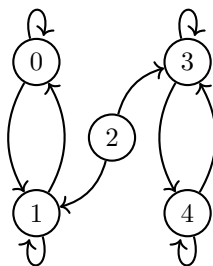
1. $S_i \subset S \mid \forall i \in 1, 2, \dots, n$
2. $S_i \cap S_j \neq \emptyset$ for all $i \neq j$
3. $\bigcup_i S_i = S$

We can find the equivalent classes by drawing a graph where the states in S are the nodes of the graph and a directed edge is placed going from i to j if j is accessible from i in one-step: $P_{ij} > 0$. Then identifying the the equivalent classes corresponds to identifying the loops of this graph within one step.

Example 1. As an example, consider the transition matrix P as follows.

$$P = \begin{matrix} & \begin{matrix} 0 & 1 & 2 & 3 & 4 \end{matrix} \\ \begin{matrix} 0 \\ 1 \\ 2 \\ 3 \\ 4 \end{matrix} & \begin{pmatrix} 0.2 & 0.8 & 0 & 0 & 0 \\ 0.6 & 0.4 & 0 & 0 & 0 \\ 0 & 0.5 & 0 & 0.5 & 0 \\ 0 & 0 & 0 & 0.7 & 0.3 \\ 0 & 0 & 0 & 0.1 & 0.9 \end{pmatrix} \end{matrix}$$

The associated one-step accessibility graph is then,



Where the loops of $S = \{0, 1, 2, 3, 4\}$ form the following partition,

$$S_1 = \{0, 1\} \quad S_2 = \{2\} \quad S_3 = \{3, 4\}$$

These equivalent classes are useful for Markov chains because it allows one to separate the behaviour of the equivalence classes and study them individually. A MC which has only one equivalent class is called **irreducible**.

Furthermore, let us define the **period** of state i as,

$$d(i) = \gcd\{n \in \mathbb{Z}^+ \mid P_{ij}^n > 0\}$$

Additionally, if $P_{ii}^n = 0$ holds for all $n > 0$, we say that $d(i) = \infty$. If the period of i happens to be $d(i) = 1$ then the state i is said to be **aperiodic**. Alternatively, locus of steps that we can go back by are *co-prime*. A MC is called aperiodic if all its states S are aperiodic.

The period of a state is useful do to the following theorem,

Theorem 5. *The period of a state is a class property. If $i \leftrightarrow j$, then $d(i) = d(j)$.*

Proof. If $i = j$ we are already done. If $i \neq j$, since $i \leftrightarrow j$, then $\exists n, m$ such that,

$$P_{ij}^n > 0 \quad P_{ji}^m > 0$$

Then for any l such that $P_{jj}^l > 0$,

$$P_{ii}^{n+m+l} \geq P_{ij}^n P_{jj}^l P_{ji}^m \quad (1.6)$$

Because $P_{ij}^n P_{jj}^l P_{ji}^m$ happens to be a specific way for P_{ii}^{n+m+l} to occur. Since $i \leftrightarrow j$ and l was chosen carefully,

$$P_{ii}^{n+m+l} > 0$$

Moreover, we also have that,

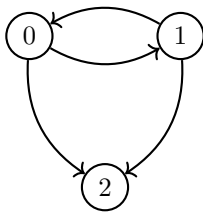
$$P_{ii}^{n+m} \geq P_{ij}^n P_{ji}^m \quad (1.7)$$

Since $d(i)$ divides both $n + m$ and $n + m + l$ by eqs. (1.7) and (1.6), then $d(i)$ also divides l . This holds for all l such that $P_{jj}^l > 0$. This implies that $d(i)$ is a common divisor of $\{l \mid P_{jj}^l > 0\}$ and thus $d(i)$ divides,

$$d(j) = \gcd\{l \mid P_{jj}^l > 0\}$$

By symmetry $d(j)$ divides $d(i)$. Therefore $d(i) = d(j)$. □

Remark 1. It is important to note that $d(i) = k \nmid P_{ii}^{(k)} > 0$. As a counterexample consider the following one step accessibility graph,



Evidently $P_{00} = 0$ but we have $d(0) = 1$ because $d(0) = \gcd\{2, 3, \dots\}$.

Remark 2. If the MC is irreducible (having only one class) then all the states have the same period. In this case we ascribe the entire MC the period $d(i)$ for some representative $i \in S$.

1.5 Recurrence and Transience

For $n \in \mathbb{Z}^+$ define,

$$f_{ij}^{(n)} = P(X_n = j, X_{n-1} \neq j, \dots, X_1 \neq j \mid X_0 = i) \quad \forall i, j \in S$$

Intuitively, $f_{ij}^{(n)}$ is the probability that X visits state j at time n for the first time since $X_0 = i$. A looming question: What is the relation between $f_{ij}^{(n)}$ and $P_{ij}^{(n)}$? First notice that,

$$P_{ij}^{(n)} \geq f_{ij}^{(n)}$$

These reads: the probability that X visits j at time n is more larger that the probability that X visits j at time n provided it did not visit j prior. A more detailed equality is the following,

$$P_{ij}^{(n)} = \sum_{k=1}^n f_{ij}^{(k)} P_{jj}^{(n-k)} \quad (1.8)$$

Expanded out gives,

$$P_{ij}^{(n)} = f_{ij}^{(n)} + \sum_{k=1}^{n-1} f_{ij}^{(k)} P_{jj}^{(n-k)}$$

Proof.

$$\begin{aligned} P_{ij}^{(n)} &= P(X_n = j \mid X_0 = i) \\ &= \sum_{k=1}^n P(X_n = j, X \text{ first visits } j \text{ at time } k \mid X_0 = i) \\ &= \sum_{k=1}^n P(X_n = j, \mid X \text{ first visits } j \text{ at time } k, X_0 = i) \cdot P(X \text{ first visits } j \text{ at time } k \mid X_0 = i) \\ &= \sum_{k=1}^n P(X_n = j, \mid X_k = j, X_{k-1} \neq j, \dots, X_1 \neq j, X_0 = i) \cdot P(X_k = j, X_{k-1} \neq j, \dots, X_1 \neq j \mid X_0 = i) \\ &= \sum_{k=1}^n P(X_n = j, \mid X_k = j, X_{k-1} \neq j, \dots, X_1 \neq j, X_0 = i) \cdot f_{ij}^{(k)} \\ &= \sum_{k=1}^n P(X_n = j, \mid X_k = j) \cdot f_{ij}^{(k)} \quad \text{Markov Condition} \\ &= \sum_{k=1}^n P_{jj}^{(n-k)} \cdot f_{ij}^{(k)} \end{aligned}$$

□

In fact eq. (1.8) defines a recurrence relation to compute $f_{ij}^{(n)}$ from $f_{ij}^{(k)}$ where $k < n$,

$$f_{ij}^{(n)} = P_{ij}^{(n)} - \sum_{k=1}^{n-1} f_{ij}^{(k)} P_{jj}^{(n-k)}$$

We now define f_{ij} *without* the superscript to be,

$$f_{ij} = \sum_{n=1}^{\infty} f_{ij}^{(n)}$$

The probability that X will *ever* reach state $j \in S$ provided it started at i ($f_{ij} \leq 1$). Whether or not f_{ij} is certain or not defines the following two properties.

A state i is called **transient** if $f_{ii} < 1$; and **recurrent** if $f_{ii} = 1$. Intuitively, f_{ii} is the probability the MC returns to state i given it started in state i . If i is transient, then there is a non-negative probability that the MC does not return to i and if $f_{ii} = 1$ then the MC always returns to state i .

Another way to characterize recurrence and transience: Define M_i to be the total number of times the MC (re)visits i after time 0. In more mathematical terms,

$$M_i = \sum_{n=1}^{\infty} \mathbb{I}_{[X_n=i]}$$

Where $\mathbb{I}_{[X_n=i]}$ is the indicator defined by,

$$\mathbb{I}_{[X_n=i]} = \begin{cases} 1 & X_n = i \\ 0 & X_n \neq i \end{cases}$$

If $f_{ii} < 1$ we have that the probability of visiting state i k times is given by,

$$P(M_i = k \mid X_0 = i) = \underbrace{f_{ii} \cdot f_{ii} \cdots f_{ii}}_k \underbrace{(1 - f_{ii})}_{\text{never return}}$$

Where $(1 - f_{ii})$ is necessary because it guarantees that we never return to state i more than k times. Given $X_0 = i$, M_i follows a geometric distribution with parameter $(1 - f_{ii})$. Thus,

$$\mathbb{E}(M_i \mid X_0 = i) = \frac{f_{ii}}{1 - f_{ii}} < \infty$$

Therefore if i is transient, there a finite number revisits are expected. In contrast if $f_{ii} = 1$ we have that,

$$\mathbb{E}(M_i \mid X_0 = i) = \lim_{f_{ii} \rightarrow 1} \frac{f_{ii}}{1 - f_{ii}} \rightarrow \infty$$

Alternatively, we can look at $\mathbb{E}(M_i \mid X_0 = i)$ as,

$$\mathbb{E}(M_i \mid X_0 = i) = \sum_{k=1}^{\infty} P(M_i \geq k \mid X_0 = i) \quad (1.9)$$

The proof of eq. (1.9) is left as an exercise to the reader. Clearly if $f_{ii} = 1$,

$$P(M_i \geq k \mid X_0 = i) = f_{ii}^k = 1 \quad \forall k \quad (1.10)$$

Therefore,

$$\mathbb{E}(M_i \mid X_0 = i) = \sum_{k=1}^{\infty} 1 = \infty$$

Theorem 6. *Therefore i is recurrent if and only if $P(M_i \geq k \mid X_0 = i) = \infty$ and i is transient if and only if $P(M_i \geq k \mid X_0 = i) < \infty$.*

Remark 3. We actually also have that i is recurrent if and only if $M_i = \infty$. This can be seen from eq. (1.10). Since $P(M_i \geq k \mid X_0 = i)$ is strictly positive for all k , then $M_i = \infty$. Analogously, we have that i is transient if and only if $M_i < \infty$.

Yet *another* way to characterize recurrence and transience is much more tractable. First,

Theorem 7. *The expectation of the indicator is given by $\mathbb{E}(\mathbb{I}_A) = P(A)$ for any event A .*

Therefore,

$$\begin{aligned} \mathbb{E}(M_i \mid X_0 = i) &= \mathbb{E}\left(\sum_{n=1}^{\infty} \mathbb{I}_{[X_n=i]} \mid X_0 = i\right) \\ &= \sum_{n=1}^{\infty} \mathbb{E}(\mathbb{I}_{[X_n=i]} \mid X_0 = i) \quad \text{Fubini's Theorem} \\ &= \sum_{n=1}^{\infty} P(X_n = i \mid X_0 = i) \\ &= \sum_{n=1}^{\infty} P_{ii}^{(n)} \end{aligned}$$

Thus i is recurrent if and only if $\sum_{n=1}^{\infty} P_{ii}^{(n)} = \infty$ and i is transient if and only if $\sum_{n=1}^{\infty} P_{ii}^{(n)} < \infty$.

Theorem 8. *Recurrence/transience are class properties. If $i \leftrightarrow j$ and i is recurrent, then j is recurrent.*

Proof. Since $i \leftrightarrow j$, $\exists m, n \geq 0$ such that,

$$P_{ij}^{(m)} > 0 \quad P_{ji}^{(n)} > 0$$

We now want to show that $\sum_{s=1}^{\infty} P_{jj}^{(s)}$ is infinite,

$$\sum_{s=1}^{\infty} P_{jj}^{(s)} \geq \sum_{s=n+m+1}^{\infty} P_{jj}^{(s)}$$

Now exchange of variables $l = s - n - m$,

$$\sum_{s=1}^{\infty} P_{jj}^{(s)} \geq \sum_{l=1}^{\infty} P_{jj}^{(n+l+m)}$$

Then by the eq. (1.4),

$$\sum_{l=1}^{\infty} P_{jj}^{(n+l+m)} \geq \sum_{l=1}^{\infty} P_{ji}^{(n)} P_{ii}^{(l)} P_{ij}^{(m)} = P_{ji}^{(n)} P_{ij}^{(m)} \left\{ \sum_{l=1}^{\infty} P_{ii}^{(l)} \right\}$$

But since i is recurrent, $\sum_{l=1}^{\infty} P_{ii}^{(l)} = \infty$. Also, $P_{ji}^{(n)} P_{ij}^{(m)} > 0$ by the choice of m, n . Therefore $\sum_{l=1}^{\infty} P_{jj}^{(n+l+m)} = \infty$ and thus $\sum_{s=1}^{\infty} P_{jj}^{(s)} = \infty$. Therefore j is also recurrent. \square

Corollary 9. *If $i \leftrightarrow j$ and i is transient, then j is transient.*

As a result, if we know that if a MC is irreducible (admitting only one class), then either all states are transient or they are all recurrent. Also, it is *impossible* for all states to be transient if the state space S is finite. If all states are transient then each state $i \in S$ has a time k that is the *last* visit time for all states, this is impossible because $P_{ij} \neq 0$ for at least some choice $i, j \in S$.

Theorem 10. *If i is recurrent, and i does not communicate with j , then $P_{ij} = 0$.*

Proof. Proof by contradiction. Assume that $P_{ij} > 0$. Since i and j do not communicate, then either j is not accessible from i or vice versa. But if $P_{ij} > 0$ then j is accessible from i . It must be that i is not accessible from j . Recall that f_{ii} is the probability that the MC ever revisits the state i given the starting state was i . Therefore $1 - f_{ii}$ is the probability that the MC never revisits state i .

$$f_{ii} \leq 1 - P_{ij} < 1$$

This inequality holds because if $X_1 = j$ then the MC never revisits i (i is not accessible from j). But there are other ways it never revisits i . Therefore,

$$P(X_1 = j \mid X_0 = i) = P_{ij} \leq P(\text{MC never revisits } i \mid X_0 = i)$$

But if $f_{ii} < 1$, then i is not recurrent; it is transient. Therefore the assumption that $P_{ij} > 0$ is wrong; $P_{ij} = 0$. \square