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CODE:
import cv2
import numpy as np
import tensorflow as tf
from tensorflow.keras import layers, models
import os
import glob
# Define paths to datasets
testing videos path = '/Users/karthik/Desktop/GWU/Sem2/Computer Vision/project
4/Avenue Dataset/testing videos'
training videos path = '/Users/karthik/Desktop/GWU/Sem2/Computer Vision/project
4/Avenue Dataset/training videos'
# Function to extract frames from a video
def extract frames(video path, frame count=200):
  """Extracts a specified number of frames from a video and resizes them to 224x224."""
  video = cv2.VideoCapture(video path)
 if not video.isOpened():
    print(f"Failed to open video: {video path}")
    return np.array([])
  frames = []
  frame_step = max(int(video.get(cv2.CAP_PROP_FRAME_COUNT) / frame_count), 1)
  current frame = 0
  while len(frames) < frame count:
    video.set(cv2.CAP PROP POS FRAMES, current frame)
    ret, frame = video.read()
    if not ret:
      print(f"Stopped reading frames at frame {current frame} of video: {video path}")
    gray_frame = cv2.cvtColor(frame, cv2.COLOR BGR2GRAY)
    resized frame = cv2.resize(gray frame, (224, 224))
    frames.append(resized frame)
    current frame += frame step
  video.release()
  return np.array(frames)
# Function to recursively load all videos from a directory and its subdirectories
def load data(directory):
  """Loads all videos from a directory and its subdirectories, extracting frames from each
video."""
  all frames = []
  for video file in glob.glob(os.path.join(directory, '*.avi')):
    frames = extract frames(video file)
    if frames.size == 0:
      print(f"No frames extracted from video: {video file}")
    else:
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all frames.append(frames)
  if not all frames:
    print(f"No frames extracted from any videos in directory: {directory}")
    return np.array([]) # Return an empty array if no frames were extracted
  return np.vstack(all frames)
# Build a more complex autoencoder model
def build autoencoder(input shape=(224, 224, 1)):
  """Builds a convolutional autoencoder with more layers and complexity."""
  input layer = layers.Input(shape=input shape)
  x = layers.Conv2D(32, (3, 3), activation='relu', padding='same')(input layer)
  x = layers.MaxPooling2D((2, 2), padding='same')(x)
  x = layers.Conv2D(16, (3, 3), activation='relu', padding='same')(x)
  x = layers.MaxPooling2D((2, 2), padding='same')(x)
  x = layers.Conv2D(8, (3, 3), activation='relu', padding='same')(x)
  encoded = layers.MaxPooling2D((2, 2), padding='same')(x)
  # Decoder
  x = layers.Conv2DTranspose(8, (3, 3), strides=2, activation='relu',
padding='same')(encoded)
  x = layers.Conv2DTranspose(16, (3, 3), strides=2, activation='relu', padding='same')(x)
  x = layers.Conv2DTranspose(32, (3, 3), strides=2, activation='relu', padding='same')(x)
  decoded = layers.Conv2D(1, (3, 3), activation='sigmoid', padding='same')(x)
  autoencoder = models.Model(input layer, decoded)
  autoencoder.compile(optimizer='adam', loss='binary crossentropy')
  return autoencoder
# Main Execution Block
if __name__ == "__main__":
  # Load data from training videos
  train data = load data(training videos path)
  if train data.size == 0:
    print("Insufficient data for training. Check the dataset directories and contents.")
  else:
    train data = train data[..., np.newaxis] / 255.0 # Normalize the frames
    # Initialize and train the model
    autoencoder = build autoencoder()
    autoencoder.fit(train data, train data, epochs=50, batch size=20)
    # Save the model
    autoencoder.save('autoencoder model.h5')
    # Load data from testing videos
    test data = load data(testing videos path)
    test data = test data[..., np.newaxis] / 255.0
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if test_data.size == 0:
    print("No testing data available.")
else:
    # Evaluate on testing data
    predictions = autoencoder.predict(test_data)
    mse = np.mean(np.square(test_data - predictions), axis=(1, 2, 3))
    print("Anomaly scores for testing data:", mse)
```

OUTPUT:

Anomaly scores for testing data: [0.00327693 0.0033585 0.00343525 ... 0.00502272 0.00510027 0.00519131]