

Experiment 4: Interrupts in Atmel AVR Atmega through Assembly Programming

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1 Task 1: Code for making the LED blink using INT1

```
.org 0
rjmp reset

.org 0x0002
rjmp int1_ISR

.org 0x0100

reset:
    LDI R16,0x70
    OUT SPL,R16
    LDI R16,0x00
    OUT SPH,R16

    LDI R16,0x01
    OUT DDRB,R16

    LDI R16,0x00
    OUT DDRD,R16

    IN R16,MCUCR;Load MCUCR register
    ORI R16,0x80
    OUT MCUCR,R16

    IN R16,GICR; Load GICR register
    ORI R16,0x80
    OUT GICR,R16

    LDI R16,0x00
    OUT PORTB,R16
```

```

    SEI
ind_loop:rjmp ind_loop

int1_ISR: IN R16,SREG
    PUSH R16

    LDI R16,0x0A
    MOV R0,R16

c1:  LDI R16,0x02
    OUT PORTB,R16

    LDI R16,0xFF
a1:  LDI R17,0xFF
a2:  DEC R17
    BRNE a2
    DEC R16
    BRNE a1

    LDI R16,0x00
    OUT PORTB,R16

    LDI R16,0xFF
b1:  LDI R17,0xFF
b2:  DEC R17
    BRNE b2
    DEC R16
    BRNE b1

    DEC R0
    BRNE c1
    POP R16
    OUT SREG,R16

    RETI

```

2 Task 2: Using INT0 for the above task

```
.org 0
rjmp reset

.org 0x0001
rjmp int0_ISR

.org 0x0100

reset:
    LDI R16,0x70
    OUT SPL,R16
    LDI R16,0x00
    OUT SPH,R16

    LDI R16,0x01
    OUT DDRB,R16

    LDI R16,0x00
    OUT DDRD,R16

    IN R16,MCUCR;Load MCUCR register
    ORI R16,0x80
    OUT MCUCR,R16

    IN R16,GICR; Load GICR register
    ORI R16,0x80
    OUT GICR,R16

    LDI R16,0x00
    OUT PORTB,R16

    SEI
ind_loop:rjmp ind_loop

int1_ISR: IN R16,SREG
    PUSH R16

    LDI R16,0x0A
    MOV R0,R16

c1:  LDI R16,0x02
    OUT PORTB,R16

    LDI R16,0xFF
```

```

a1:  LDI R17,0xFF
a2:  DEC R17
     BRNE a2
     DEC R16
     BRNE a1

     LDI R16,0x00
     OUT PORTB,R16

     LDI R16,0xFF
b1:  LDI R17,0xFF
b2:  DEC R17
     BRNE b2
     DEC R16
     BRNE b1

     DEC R0
     BRNE c1
     POP R16
     OUT SREG,R16

     RETI

```

3 Task 3: Rewriting using C

3.1 C code to implement INT1:

```

//defining the CPU clock frequency
#define F_CPU 1000000

//including the required header files
#include <avr/io.h>
#include <util/delay.h>
#include <avr/interrupt.h>

ISR (INT1_vect)
{
    for (j=0;j<10;j=j+1)
        //making the led blink 10 times
    {
        //makes the last bit in PORTB high
        PORTB=0x01;
        //stays there for a second
        _delay_ms(1000);
        //makes the last bit in PORTB low
    }
}

```

```

        PORTB=0x00;
        //stays there for a second
        _delay_ms(1000);
    }

}

int main(void)
{

    DDRD=0x00;

    //Set PB0 to output
    DDRB=0x00;

    //Set MCU Control Register to level triggered
    MCUCR=0x80;

    //Enabling INT1
    GICR=0x00;

    PORTB=0x00;
    sei();
    // global interrupt flag

    //setting an infinite loop
    while (1)
    {

    }
}

```

3.2 C code to implement INT0:

```

//defining the clock frequency
#define F_CPU 1000000

//including the required header files
#include <avr/io.h>
#include <util/delay.h>
#include <avr/interrupt.h>

ISR (INT0_vect)
{
    //making the led blink 10 times
    for(int i=0; i<10; i=i+1)

```

```

    {
        //makes the last bit in PORTB high
        PORTB = 0x01;
        //waits for a second
        _delay_ms(1000);
        //makes the last bit in PORTB low
        PORTB = 0x00;
        //waits for a second
        _delay_ms(1000);
    }
}

int main (void)
{
    //declaring i/o configuration of ports
    DDRD = 0x00;
    DDRB = 0x01;
    MCUCR = 0x02;
    GICR = 0x40;
    PORTB = 0x00;

    sei();
    //global interrupt flag

    //infinite loop
    while (1)
    {

    }
}

```

4 Task 4: All demonstrations and outputs

4.1 Outputs for INT1:

Video: Making the LED blink ten times using INT1

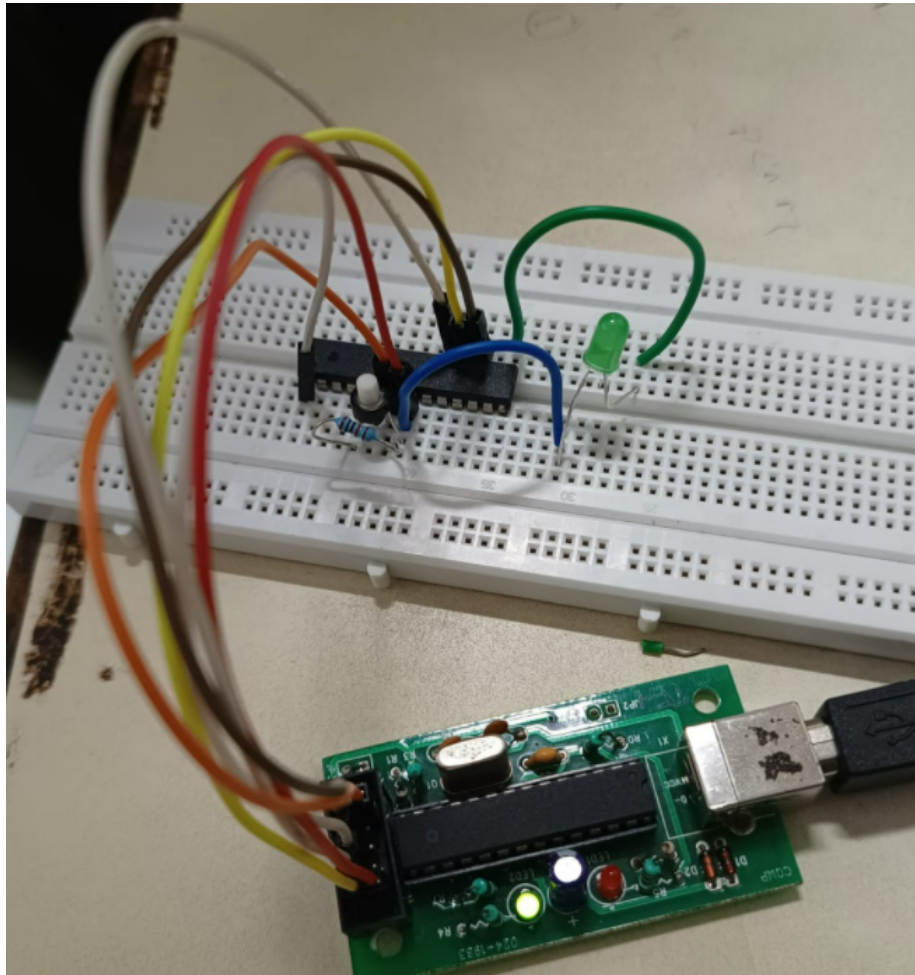


Figure 1: Circuit to implement int1

4.2 Outputs for INT0:

Video: Making the LED blink ten times using INT0

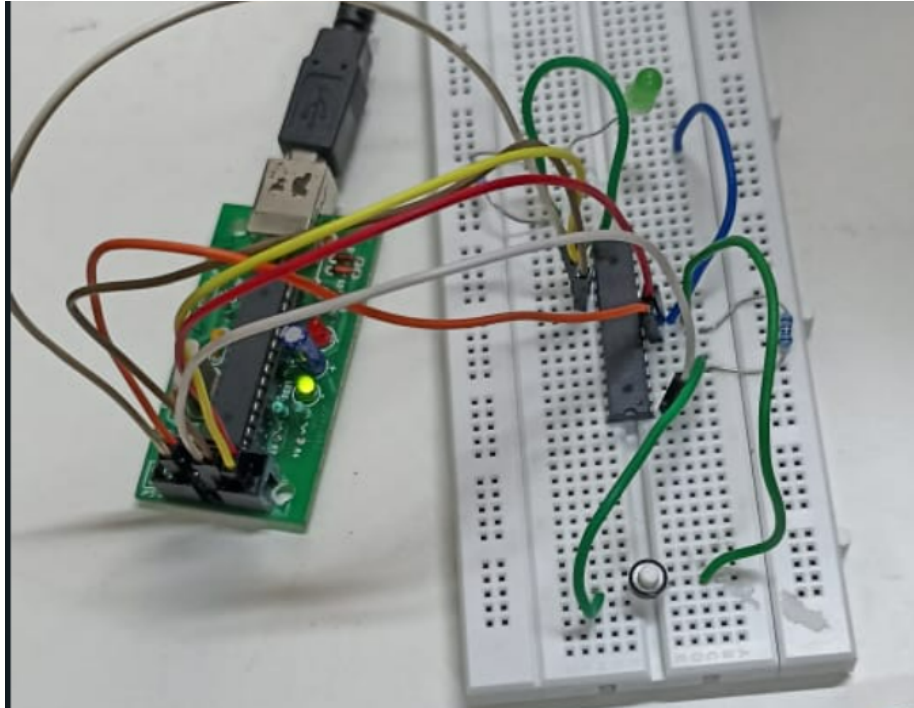


Figure 2: Circuit to implement int0