EE2703 - Week 5

Santhosh S P ee21b119

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1 Importing and installing the requirements

```
[]: %matplotlib inline
from IPython.display import HTML
import matplotlib.pyplot as plt
import numpy as np
from matplotlib.animation import FuncAnimation
```

- %matplotlib inline is used to render plots in the notebook.
- matplotlib.pyplot and numpy are used for plotting and numerical computations.
- FuncAnimation from matplotlib.animation is used to create the animation.
- HTML module from Ipython.display and ffmpeg is used to convert the animation into a video and make it playable in the notebook.
- ipython can be installed using pip by pip3 install ipython and ffmpeg can be installed inside the python environment using sudo apt install ffmpeg.

2 Setting the plot, init() and update() functions

2.1 The init() and morph() function

- First we create an empty plot and initialise the variables.
- init() function initialises the graph by setting its x-axis and y-axis limits.
- morph(x1, y1, x2, y2, alpha) function can return any value xm in the range from x2 to x1 and any value ym from y2 to y1 based on different values of alpha. So on increasing the value of alpha from 0 to 1, the values change smoothly from x2 and y2 to x1 and y1.

2.2 The update() function

- Inside the update(frame) function, to make 10 transitions, we create 10 conditional statments after dividing the value of frame into 10 ranges. The value of frame goes from 0 to 1 (as defined using the FuncAnimation() function later), therefore we define the 10 ranges as 0 to 0.1, 0.1 to 0.2 and so on till 0.9 to 1 for each transition.
- For each transition, we use the morph() function with results of n_gon(t,n) function as arguments.
- n_gon(t,n) function (defined in the next cell), returns a x-coordinate array and a y-coordinate array for a general n-sided regular polygon with vertices on the unit circle. Here the argument, t refers to an array of uniformly spaced numbers in 0 to 2π , and n refers to the number of sides of the regular polygon.

- The argument alpha for morph() function in each transition, is modified in each case to make sure that it goes from 0 to 1, with each passing frame.
- The outputs of the morph() function are stored into the global variables xdata and ydata and added to the plot.

```
[]: ##creating an empty plot
     fig, ax = plt.subplots()
     xdata, ydata = [], []
     ln, = ax.plot([], [], 'r')
     #setting the axis limits inside the init() function
     def init():
         ax.set xlim(-1.2, 1.2)
         ax.set_ylim(-1.2, 1.2)
         return ln.
     #defining a linear morph function that goes from x2 to x1 and y2 to y1 as alpha
      ⇔goes from
     #0 to 1
     def morph(x1, y1, x2, y2, alpha):
         xm = alpha * x1 + (1-alpha)*x2
         ym = alpha * y1 + (1-alpha)*y2
         return xm, ym
     def update(frame):
             #to make sure that we're accessing the global varibles xdata and ydata
             global xdata, ydata
             #to make 10 transistion, we divide the values of frame into 10 regions
             #transition from triangle to square
             if frame>0 and frame<=0.1:</pre>
                 xdata, ydata = morph(n_gon(t,4)[0], n_gon(t,4)[1], n_gon(t,3)[0], 
      \rightarrown_gon(t,3)[1], 10*(frame))
             #transition from square to pentagon
             if frame>0.1 and frame<=0.2:</pre>
                 xdata, ydata = morph(n_gon(t,5)[0], n_gon(t,5)[1], n_gon(t,4)[0],
      \rightarrown_gon(t,4)[1], 10*(frame-0.1))
             #transition from pentagon to hexagon
             if frame>0.2 and frame<=0.3:</pre>
                 xdata, ydata = morph(n_gon(t,6)[0], n_gon(t,6)[1], n_gon(t,5)[0],
      \neg n_{gon(t,5)[1]}, 10*(frame-0.2))
```

```
#transition from hexagon to heptagon
       if frame>0.3 and frame<=0.4:</pre>
           xdata, ydata = morph(n_gon(t,7)[0], n_gon(t,7)[1], n_gon(t,6)[0],
\rightarrown_gon(t,6)[1], 10*(frame-0.3))
       #transition from heptagon to octagon
       if frame>0.4 and frame<=0.5:</pre>
           xdata, ydata = morph(n_gon(t,8)[0], n_gon(t,8)[1], n_gon(t,7)[0],
\neg n_{gon}(t,7)[1], 10*(frame-0.4))
       ##reverse transitions, going from an octagon back to triagle
       #transition from octagon to heptagon
       if frame>0.5 and frame<=0.6:
           xdata, ydata = morph(n_gon(t,7)[0], n_gon(t,7)[1], n_gon(t,8)[0],
n_{gon(t,8)[1]}, 10*(frame-0.5)
       #transition from heptagon to hexagon
       if frame>0.6 and frame<=0.7:</pre>
           xdata, ydata = morph(n_gon(t,6)[0], n_gon(t,6)[1], n_gon(t,7)[0],
\rightarrown_gon(t,7)[1], 10*(frame-0.6))
       #transition from hexagon to pentagon
       if frame>0.7 and frame<=0.8:</pre>
           xdata, ydata = morph(n_gon(t,5)[0], n_gon(t,5)[1], n_gon(t,6)[0],
\rightarrown_gon(t,6)[1], 10*(frame-0.7))
       #transition from pentagon to square
       if frame>0.8 and frame<=0.9:</pre>
           xdata, ydata = morph(n_gon(t,4)[0], n_gon(t,4)[1], n_gon(t,5)[0],
n_{gon}(t,5)[1], 10*(frame-0.8)
       #transition from square back to triangle
       if frame>0.9 and frame<=1:</pre>
           xdata, ydata = morph(n_gon(t,3)[0], n_gon(t,3)[1], n_gon(t,4)[0],
\rightarrown gon(t,4)[1], 10*(frame-0.9))
       ln.set_data(xdata, ydata)
      return ln,
```

3 Mathematics behind the animation

• The function r(theta, a, b, c) converts a straight line ax + by + c = 0 to polar form $r(\theta)$ according to

$$r(\theta) = \left| \frac{c}{\sqrt{a^2 + b^2}} \sec\left(\theta - \arctan\frac{a}{b}\right) \right|$$

- The function linefinder(p1,p2) takes two inputs p1, p2 (two tuples representing coordinates of two points) and returns a, b and c for the line ax + by + c = 0 that contains the two given points. We use the fact that points (a_1, b_1) and (a_2, b_2) lie on the line $(b_1 b_2)x + (a_2 a_1)y + a_1(b_2 b_1) b_1(a_2 a_1) = 0$
- The function sidemaker(point_list) generates arrays of x-coordinates and y-coordinates after inputting the vertices of the polygon as a list of tuples. It chooses all consecutive entries in the point_list and finds the parameters a, b and c of the line joining them.
- If the regular polygon has n sides, the array t (containing uniformly spaced values from 0 to 2π) is sliced into n parts. For the slice corresponding to a particular side, the function r(theta, a, b, c) is evaluated with theta as the corresponding slice of t and a, b, c as the values found from the linefinder(p1,p2) function with consecutive points.
- The array $r(\theta)$. $\cos \theta$ is added to the array with x-coordinates, and $r(\theta)$. $\sin \theta$ is added to the array with y-coordinates. This is done for each side with the corresponding slice of t as θ and the coordinate arrays are returned.
- n_gon(t,n) function, returns a x-coordinate array and a y-coordinate array for a general n-sided regular polygon with vertices on the unit circle. Here the argument, t refers to an array of uniformly spaced numbers in 0 to 2π, and n refers to the number of sides of the regular polygon. A array of points is made and stored in points, which is fed as the input to the function sidemaker() and the coordinate array is returned.

```
[]: \#converts \ ax+by+c=0 \ to \ polar \ form
     def r(theta,a,b,c):
         return np.abs(c/(np.sqrt(a**2+b**2)*np.cos(theta-np.arctan(b/a))))
     #returns a, b and c for a line ax+by+c=0 containing two points (a1,b1), (a2,b2)
     #takes two tuples as input
     \#a=b1-b2
     \#b = a2 - a1
     #c=a1*(b2-b1)-b1*(a2-a1)
     def linefinder(p1,p2):
         a1,b1=p1
         a2,b2=p2
         a=b1-b2
         b=a2-a1
         c=a1*(b2-b1)-b1*(a2-a1)
         return a, b, c
     #generates arrays of x-coordinates and y-coordinates after inputting the
      ⇔vertices of the polygon
```

```
#as a list of tuples
def sidemaker(point_list):
        #creating the arrays
        xp=np.array([])
        yp=np.array([])
        index=0
        #choosing all consecutive entries (except the line joining first and the
  \rightarrow last one)
        for p1, p2 in zip(point_list[:-1], point_list[1:]):
                 #p1 and p2 are tuples, referring to two points
                 #finding out the line joining the point
                a,b,c=linefinder(p1=p1, p2=p2)
                 #for each side we add r(theta).cos(theta) for all theta corresponding
  ⇔to that side in x-coord list
                 xp=np.concatenate([xp, r(t[int(index*len(t)/len(point_list)):
  int((index+1)*len(t)/len(point_list))],a,b,c)*np.cos(t[int(index*len(t)/
   #for each side we add r(theta).sin(theta) for all theta corresponding.
  →to that side in y-coord list
                yp=np.concatenate([yp, r(t[int(index*len(t)/len(point_list)):
   →int((index+1)*len(t)/len(point_list))],a,b,c)*np.sin(t[int(index*len(t)/
   index+=1
        #for the last pair (line joining the first and the last point)
        a,b,c=linefinder(p1=point_list[-1], p2=point_list[0])
        #similarly another set of x-coords and y-coords are added
        xp=np.concatenate([xp, r(t[int(index*len(t)/len(point_list)):
   dint((index+1)*len(t)/len(point_list))],a,b,c)*np.cos(t[int(index*len(t)///index*len(t)///index*len(t)///index*len(t)///index*len(t)///index*len(t)///index*len(t)///index*len(t)///index*len(t)///index*len(t)///index*len(t)///index*len(t)///index*len(t)///index*len(t)///index*len(t)///index*len(t)///index*len(t)///index*len(t)///index*len(t)///index*len(t)///index*len(t)///index*len(t)///index*len(t)///index*len(t)///index*len(t)///index*len(t)///index*len(t)///index*len(t)///index*len(t)///index*len(t)///index*len(t)///index*len(t)///index*len(t)///index*len(t)///index*len(t)///index*len(t)///index*len(t)///index*len(t)///index*len(t)///index*len(t)///index*len(t)///index*len(t)///index*len(t)///index*len(t)///index*len(t)///index*len(t)///index*len(t)///index*len(t)///index*len(t)///index*len(t)///index*len(t)//index*len(t)///index*len(t)///index*len(t)///index*len(t)///index*len(t)///index*len(t)///index*len(t)///index*len(t)///index*len(t)///index*len(t)///index*len(t)///index*len(t)///index*len(t)///index*len(t)///index*len(t)///index*len(t)///index*len(t)///index*len(t)///index*len(t)///index*len(t)///index*len(t)///index*len(t)///index*len(t)///index*len(t)///index*len(t)///index*len(t)///index*len(t)///index*len(t)///index*len(t)///index*len(t)///index*len(t)///index*len(t)///index*len(t)///index*len(t)///index*len(t)///index*len(t)///index*len(t)///index*len(t)///index*len(t)///index*len(t)//index*len(t)//index*len(t)//index*len(t)//index*len(t)//index*len(t)//index*len(t)//index*len(t)//index*len(t)//index*len(t)//index*len(t)//index*len(t)//index*len(t)//index*len(t)//index*len(t)//index*len(t)//index*len(t)//index*len(t)//index*len(t)//index*len(t)//index*len(t)//index*len(t)//index*len(t)//index*len(t)//index*len(t)//index*len(t)//index*len(t)//index*len(t)//index*len(t)//index*len(t)//index*len(t)//index*len(t)//index*len(t)//index*len(t)//index*len(t)//index*len(t)//index*len(t)//index*len(t)//index*len(t)//index*len(t)//index*len(t)//index*len(t)//index*len(t)//index*len(t)//index*len(t)//in
   →len(point_list)):int((index+1)*len(t)/len(point_list))])])
        yp=np.concatenate([yp, r(t[int(index*len(t)/len(point list)):
   int((index+1)*len(t)/len(point_list))],a,b,c)*np.sin(t[int(index*len(t)/
   →len(point_list)):int((index+1)*len(t)/len(point_list))])])
        return xp, yp
#returns a x-coordinate array and a y-coordinate array for a general n-sided
  ⇔regular polygon
#with vertices on the unit circle and plots it
def n_gon(t, n):
       points=[]
```

```
for i in range(n):
    points.append((np.cos(2*np.pi*i/n),np.sin(2*np.pi*i/n)))

xt,yt=sidemaker(point_list=points)
return xt,yt
```

4 Creating the animation and playing it as a video

- An array t is defined to contain 20160 values in the range 0 to 2π . It must be made sure that number of elements in t should be a multiple of LCM(3,4,5,6,7,8) to make sure that slices of t for each side of the polygon are of the same length.
- The animations is created by defining frames as an array of 528 values in the range 0 to 1, with the interval between frames being 20ms.
- The line HTML(ani.to_html5_video()) converts the FuncAnimation object to a video and makes it playable in the python notebook.
- The animation generated is slightly different from the one given because of a different kind of morphing function leading to a slightly different transition.

[]: <IPython.core.display.HTML object>