

ITEM NO.	PartNo	DESCRIPTION	Material	QTY.
1	ASS001	Robot Arm (Body)		1
2	ASS002	Robot Arm (Gripper)		1
3	P033	IR Plate	Aluminium	1

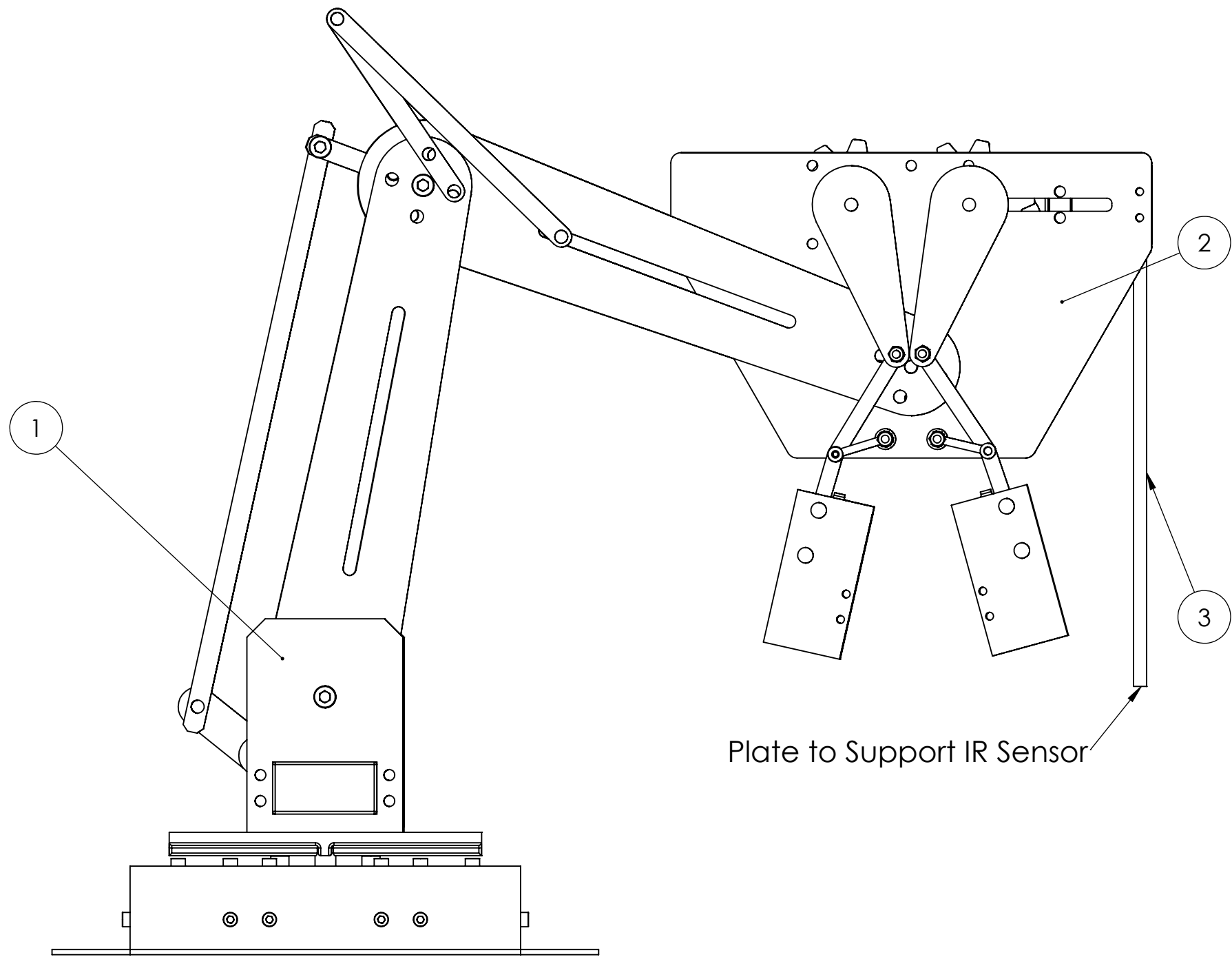
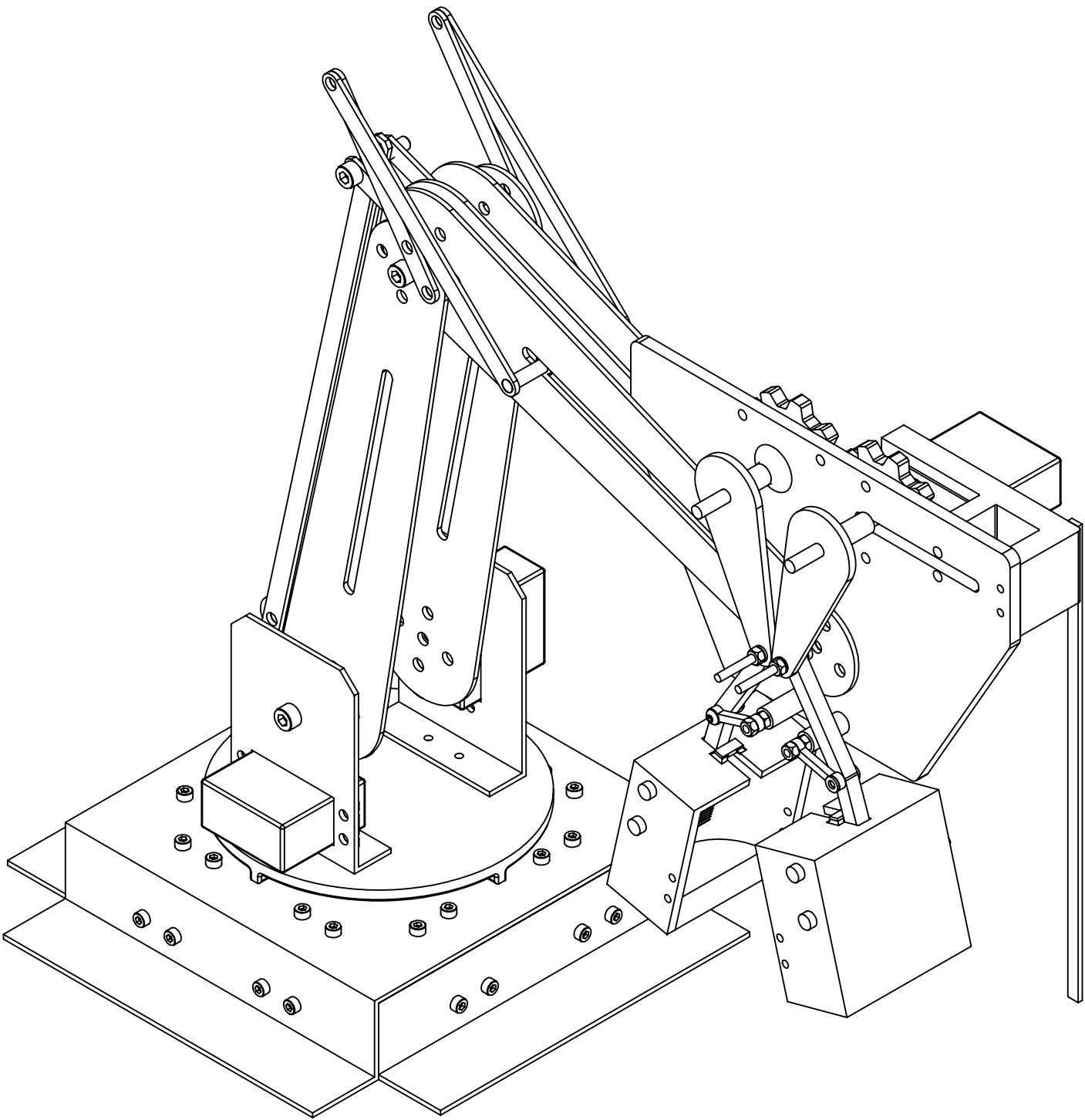

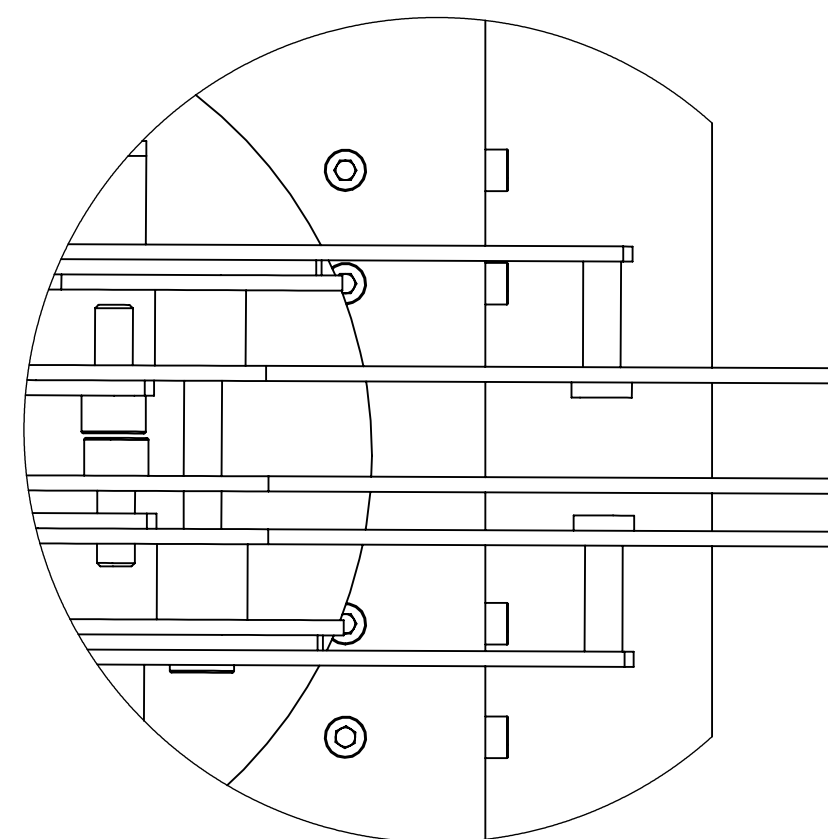
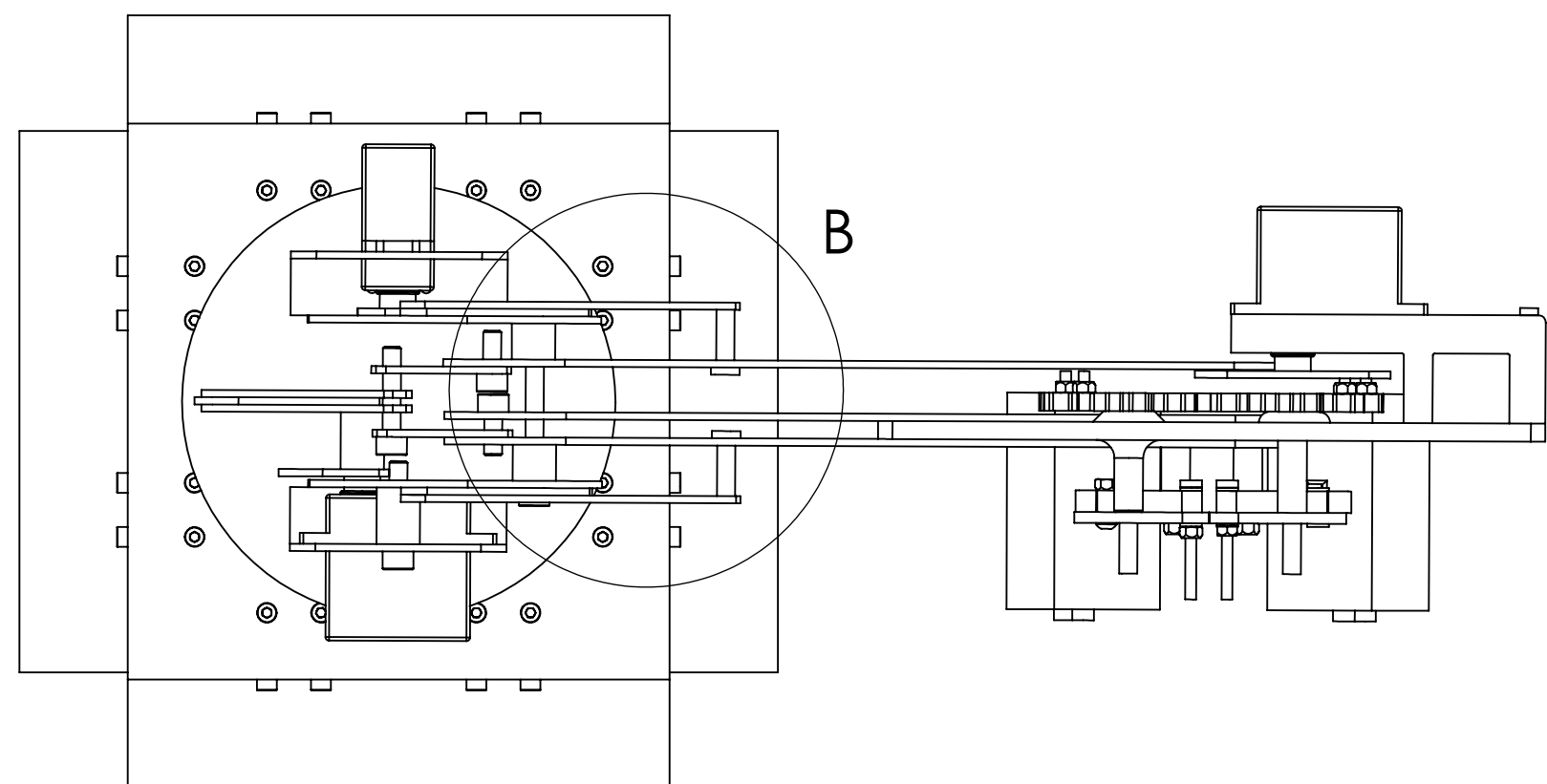
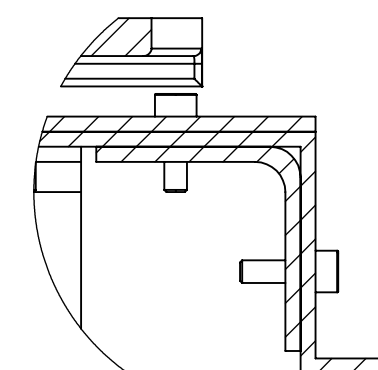


Plate to Support IR Sensor

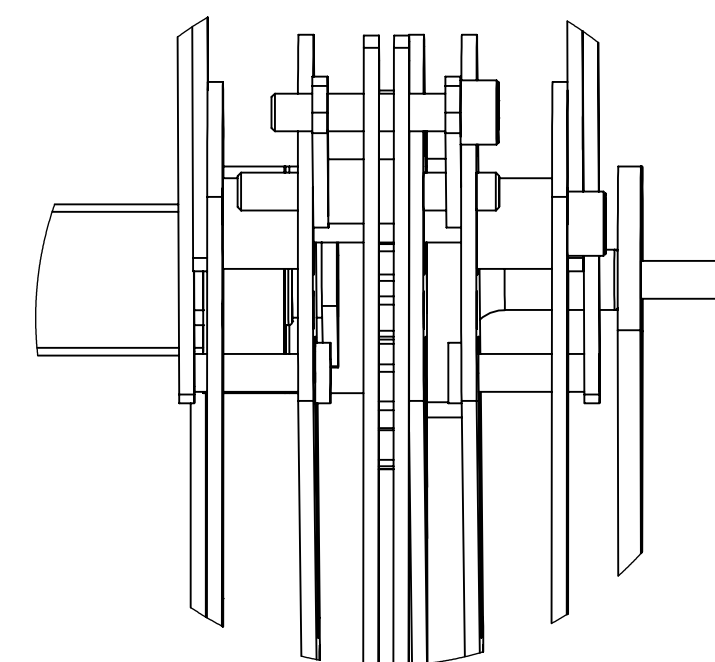
		 University of Nottingham UK CHINA MALAYSIA			
TOLERANCE LINEAR: ± 0.5 ANGULAR: ± 1		Robot Arm Assembly (Retracted)			
ALL DIMENSIONS IN MILLIMETRES	ISS. DATE 19/11/2018	REV A	DRN BY Group 7	DWG NO. ASS003	
DRAFTING STANDARD BS 8888	MODULE EEEE2054	SCALE 1:2	SIZE A2	SHEET 1 of 2	



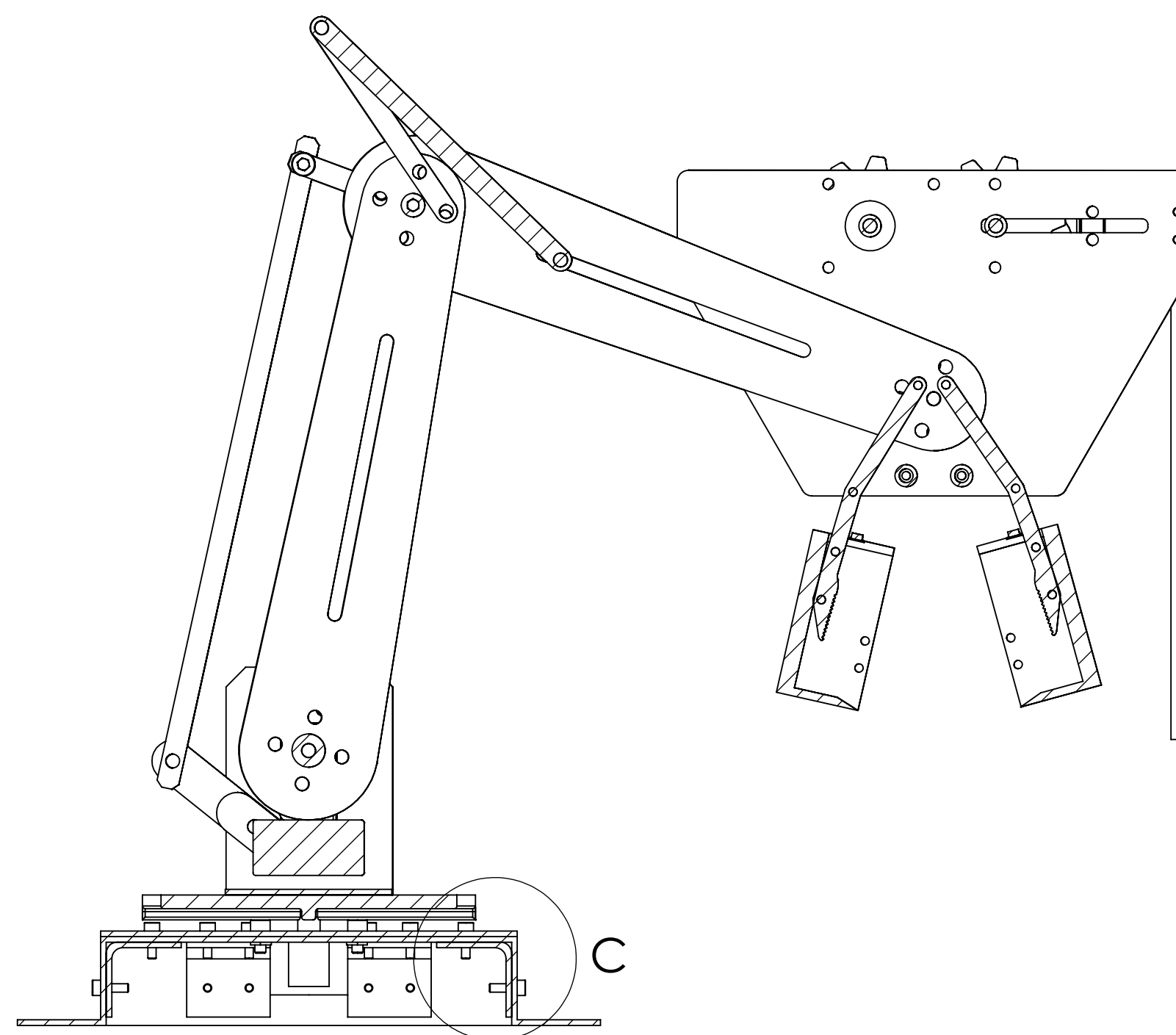
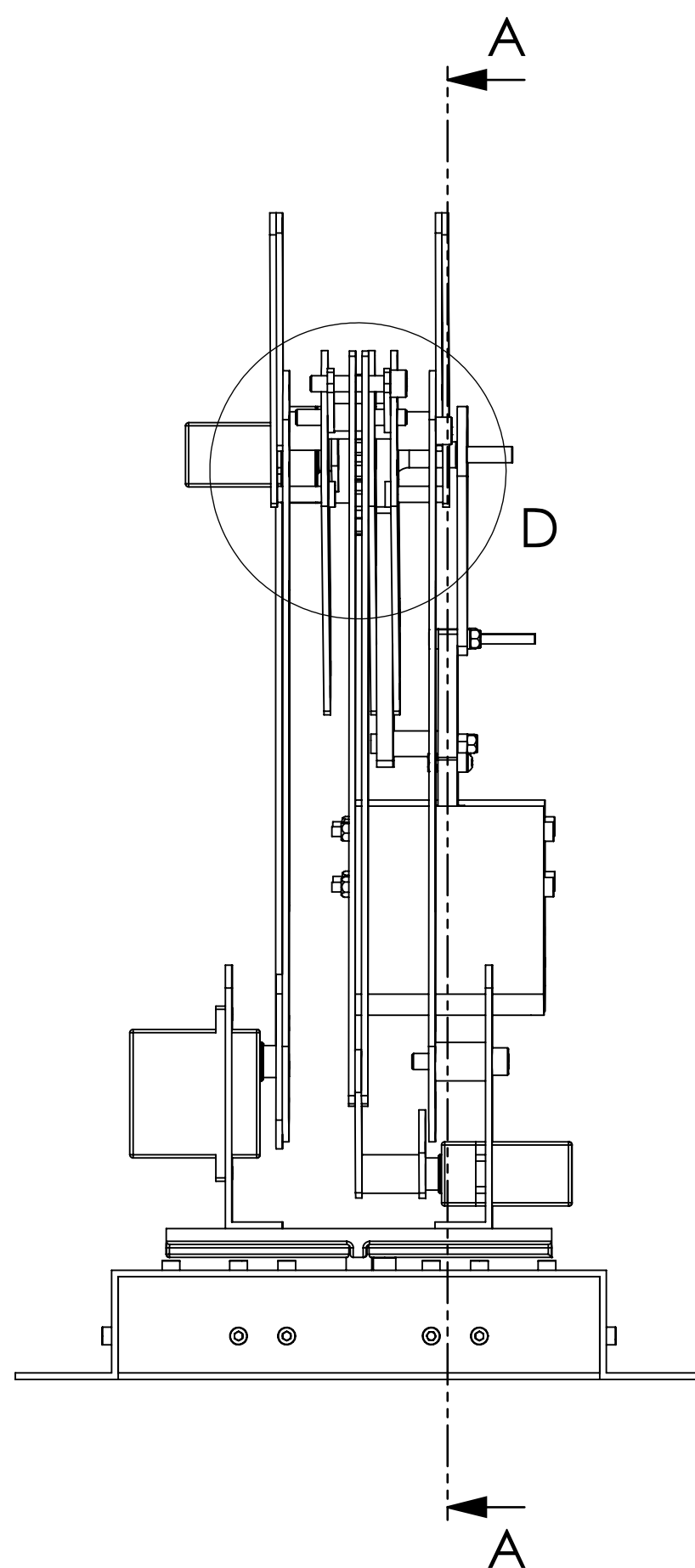
DETAIL B
SCALE 1 : 1




DETAIL C
SCALE 1 : 1



DETAIL D
SCALE 1 : 1



SECTION A-A

	 University of Nottingham <small>UK CHINA MALAYSIA</small>			
TOLERANCE LINEAR: ± 0.5 ANGULAR: ± 1		Robot Arm Assembly (Retracted)		
ALL DIMENSIONS IN MILLIMETRES		ISS. DATE 19/11/2018	REV A	DRN BY Group 7 DWG NO. ASS003
DRAFTING STANDARD BS 8888		MODULE EEEE2054	SCALE 1:2	SIZE A2 SHEET 2 of 2