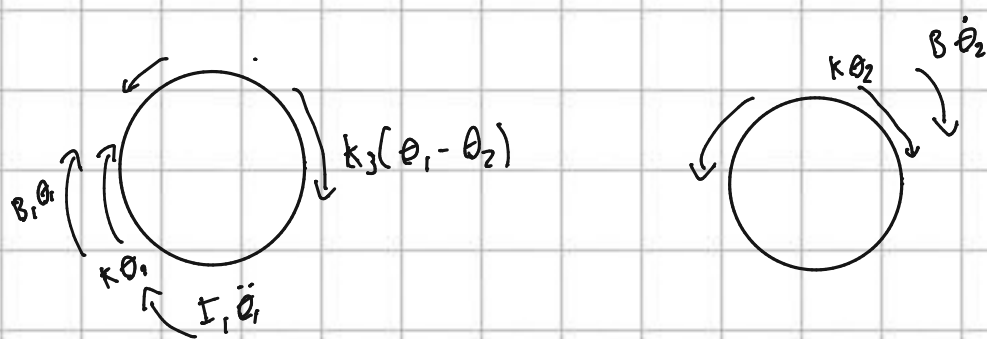
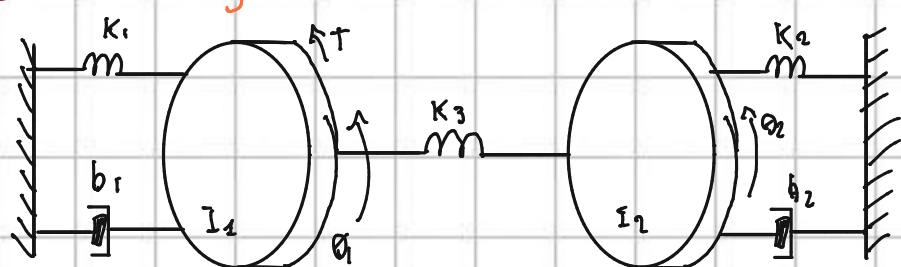


# Tareas Segundo Corte

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$$T = I_1 \ddot{\theta}_1 + B_1 \dot{\theta}_1 + K_1 \theta_1 + K_3 (\theta_1 - \theta_2)$$

$$T = I_1 \ddot{\theta}_1 + B_1 \dot{\theta}_1 + K_1 \theta_1 + K_3 \theta_1 - K_3 \theta_2$$

$$T = I_1 \ddot{\theta}_1 + B_1 \dot{\theta}_1 + (K_1 + K_3) \theta_1 - K_3 \theta_2 \quad (1)$$

$$K_3 (\theta_1 - \theta_2) - K_2 \theta_2 - B_2 \dot{\theta}_2 - I_2 \ddot{\theta}_2 = 0$$

$$K_3 \theta_1 - K_3 \theta_2 - K_2 \theta_2 - B_2 \dot{\theta}_2 - I_2 \ddot{\theta}_2 = 0$$

$$I_2 \ddot{\theta}_2 + B_2 \dot{\theta}_2 - K_3 \theta_1 + (K_2 + K_3) \theta_2 = 0$$

$$T = I_1 \ddot{\theta}_1 + B_1 \dot{\theta}_1 + (K_1 + K_3) \theta_1 - K_3 \theta_2 \quad (1)$$

$$(1) \quad \ddot{\theta}_1 = \frac{B_1 \dot{\theta}_1}{I_1} - \frac{K_1 + K_3}{I_1} \theta_1 + \frac{K_3 \theta_2}{I_1} + \frac{T}{I_1}$$

$$q_1 = \theta_1$$

$$q_2 = \dot{q}_1 = \dot{\theta}_1$$

$$q_2' = \ddot{\theta}_1$$

$$q_3 = \theta_2$$

$$q_4 = \dot{q}_3 = \dot{\theta}_2$$

$$q_4' = \ddot{\theta}_2$$

$$(2) \quad I_2 \ddot{\theta}_2 + B_2 \dot{\theta}_2 - K_3 \theta_1 + (K_2 + K_3) \theta_2 = 0$$

$$\ddot{\theta}_2 = \frac{B_2 \dot{\theta}_2}{I_2} - \frac{K_3 \theta_1}{I_2} + \frac{(K_2 + K_3) \theta_2}{I_2} \quad (2)$$

$$\begin{bmatrix} \dot{q}_1 \\ \dot{q}_2 \\ \dot{q}_3 \\ \dot{q}_4 \end{bmatrix} = \begin{bmatrix} 0 & 1 & 0 & 0 \\ -\frac{(K_1 + K_3)}{I_1} & -\frac{B_1}{I_1} & \frac{K_3}{I_1} & 0 \\ 0 & 0 & 0 & 1 \\ \frac{K_3}{I_2} & 0 & -\frac{(K_2 + K_3)}{I_2} & -\frac{B_2}{I_2} \end{bmatrix} \begin{bmatrix} q_1 \\ q_2 \\ q_3 \\ q_4 \end{bmatrix} + \begin{bmatrix} 0 \\ \frac{T}{I_1} \\ 0 \\ 0 \end{bmatrix} T$$

$$\begin{bmatrix} \theta_1 \\ \theta_2 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \end{bmatrix} \begin{bmatrix} q_1 \\ q_2 \\ q_3 \\ q_4 \end{bmatrix} + OM$$