

$$\textcircled{1} \text{ a) } \begin{bmatrix} 1 & 0 & -3 & -2 \\ -3 & 1 & 6 & 3 \\ 2 & -2 & -1 & -1 \end{bmatrix} \xrightarrow{3R_1 + R_2 \rightarrow R_2} \begin{bmatrix} 1 & 0 & -3 & -2 \\ 0 & 1 & -3 & -3 \\ 0 & -2 & 5 & 3 \end{bmatrix} \xrightarrow{2R_2 + R_3 \rightarrow R_3} \begin{bmatrix} 1 & 0 & -3 & -2 \\ 0 & 1 & -3 & -3 \\ 0 & 0 & -1 & -3 \end{bmatrix} \rightarrow \begin{bmatrix} \sim & \sim & \sim & \sim \\ \sim & \sim & \sim & \sim \\ 0 & 0 & 1 & 3 \end{bmatrix} \rightarrow$$

$$\xrightarrow{3R_3 + R_2 \rightarrow R_2} \begin{bmatrix} 1 & 0 & 0 & 7 \\ 0 & 1 & 0 & 6 \\ 0 & 0 & 1 & 3 \end{bmatrix} \rightarrow \vec{x} = \begin{bmatrix} 7 \\ 6 \\ 3 \end{bmatrix} \rightarrow \text{unique, all entries accounted for.}$$

$$\xrightarrow{3R_3 + R_1 \rightarrow R_1} \quad \xrightarrow{-3R_1 + R_2 \rightarrow R_2} \quad \xrightarrow{-1R_2 + R_3 \rightarrow R_3} \quad \xrightarrow{3R_2 + R_1 \rightarrow R_4} \quad \xrightarrow{R_3 \leftrightarrow R_4}$$

$$\text{b) } \begin{bmatrix} 1 & -3 & 2 & 1 \\ 3 & -8 & 8 & 6 \\ 0 & 1 & 2 & 3 \\ 1 & 0 & 8 & 10 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & -3 & 2 & 1 \\ 0 & 1 & 2 & 3 \\ 0 & 1 & 2 & 3 \\ 1 & 0 & 8 & 10 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & -3 & 2 & 1 \\ 0 & 1 & 2 & 3 \\ 0 & 0 & 0 & 0 \\ 1 & 0 & 8 & 10 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 0 & 8 & 10 \\ 0 & 1 & 2 & 3 \\ 1 & 0 & 8 & 10 \\ 0 & 0 & 0 & 0 \end{bmatrix} \rightarrow$$

$$\xrightarrow{-R_1 + R_3 \rightarrow R_3} \begin{bmatrix} 1 & 0 & 8 & 10 \\ 0 & 1 & 2 & 3 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix} \rightarrow \begin{array}{l} x_1 + 8x_3 = 10 \\ x_2 + 2x_3 = 3 \\ x_3 = \text{free variable} \end{array} \rightarrow \begin{array}{l} x_1 = 10 - 8x_3 \\ x_2 = 3 - 2x_3 \\ x_3 = x_3 \end{array} \rightarrow \vec{x} = \begin{bmatrix} 10 - 8x_3 \\ 3 - 2x_3 \\ x_3 \end{bmatrix} = \begin{bmatrix} 10 \\ 3 \\ 0 \end{bmatrix} + x_3 \begin{bmatrix} -8 \\ -2 \\ 1 \end{bmatrix}$$

$$\hookrightarrow \text{let } x_3 = 1 \rightarrow$$

$$\vec{x} = \begin{bmatrix} 10 \\ 3 \\ 0 \end{bmatrix} + \begin{bmatrix} -8 \\ -2 \\ 1 \end{bmatrix} = \begin{bmatrix} 2 \\ 1 \\ 1 \end{bmatrix}$$

↓
a solution.

Not unique, there is a free variable.

(2) Want $T(\vec{x}) = \vec{0} \rightarrow A\vec{x} = \vec{0}$

$\frac{1}{2} R_1 \rightarrow R_1$
 $\frac{1}{4} R_4 \rightarrow R_4$

$-R_1 + R_3 \rightarrow R_3$
 $-R_1 + R_4 \rightarrow R_4$

$$\left[\begin{array}{cccc|c} 3 & 2 & 10 & -6 & 0 \\ 1 & 0 & 2 & -4 & 0 \\ 0 & 1 & 2 & 3 & 0 \\ 1 & 4 & 10 & 8 & 0 \end{array} \right] \xrightarrow{-3R_2 + R_1 \rightarrow R_1} \left[\begin{array}{cccc|c} 0 & 2 & 4 & 6 & 0 \\ 1 & 0 & 2 & -4 & 0 \\ 0 & 1 & 2 & 3 & 0 \\ 0 & 4 & 8 & 12 & 0 \end{array} \right] \xrightarrow{-1R_2 + R_4 \rightarrow R_4} \left[\begin{array}{cccc|c} 0 & 1 & 2 & 3 & 0 \\ 1 & 0 & 2 & -4 & 0 \\ 0 & 1 & 2 & 3 & 0 \\ 0 & 1 & 2 & 3 & 0 \end{array} \right] \rightarrow \left[\begin{array}{cccc|c} 0 & 1 & 2 & 3 & 0 \\ 1 & 0 & 2 & -4 & 0 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{array} \right] \rightarrow$$

$$\xrightarrow{R_1 \leftrightarrow R_2} \left[\begin{array}{cccc|c} 1 & 0 & 2 & -4 & 0 \\ 0 & 1 & 2 & 3 & 0 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{array} \right] \rightarrow \begin{cases} x_1 + 2x_3 - 4x_4 = 0 \\ x_2 + 2x_3 + 3x_4 = 0 \\ x_3, x_4 \text{ are free} \end{cases} \rightarrow \begin{cases} x_1 = -2x_3 + 4x_4 \\ x_2 = -2x_3 - 3x_4 \\ x_3 = x_3 \\ x_4 = x_4 \end{cases}$$

$$\rightarrow \vec{x} = \begin{bmatrix} -2x_3 + 4x_4 \\ -2x_3 - 3x_4 \\ x_3 \\ x_4 \end{bmatrix} = \begin{bmatrix} -2x_3 \\ -2x_3 \\ x_3 \\ 0 \end{bmatrix} + \begin{bmatrix} 4x_4 \\ -3x_4 \\ 0 \\ x_4 \end{bmatrix} = x_3 \begin{bmatrix} -2 \\ -2 \\ 1 \\ 0 \end{bmatrix} + x_4 \begin{bmatrix} 4 \\ -3 \\ 0 \\ 1 \end{bmatrix}$$

(3) Based on the information given we have that $T\left(\begin{bmatrix} 1 \\ 0 \end{bmatrix}\right) = \begin{bmatrix} 2 \\ 5 \end{bmatrix}$ and $T\left(\begin{bmatrix} 0 \\ 1 \end{bmatrix}\right) = \begin{bmatrix} -1 \\ 6 \end{bmatrix}$

a) We want $T\left(\begin{bmatrix} 5 \\ -3 \end{bmatrix}\right)$: Note that $\begin{bmatrix} 5 \\ -3 \end{bmatrix} = \begin{bmatrix} 5 \\ 0 \end{bmatrix} + \begin{bmatrix} 0 \\ -3 \end{bmatrix} = 5\begin{bmatrix} 1 \\ 0 \end{bmatrix} + (-3)\begin{bmatrix} 0 \\ 1 \end{bmatrix}$. Therefore,

by properties of linear transformations $T\left(\begin{bmatrix} 5 \\ -3 \end{bmatrix}\right) = T\left(5\begin{bmatrix} 1 \\ 0 \end{bmatrix} + (-3)\begin{bmatrix} 0 \\ 1 \end{bmatrix}\right)$

$$= 5T\left(\begin{bmatrix} 1 \\ 0 \end{bmatrix}\right) + (-3)T\left(\begin{bmatrix} 0 \\ 1 \end{bmatrix}\right)$$

$$= 5\left(\begin{bmatrix} 2 \\ 5 \end{bmatrix}\right) + (-3)\begin{bmatrix} -1 \\ 6 \end{bmatrix}$$

$$= \begin{bmatrix} 10 & + & 3 \\ 25 & - & 18 \end{bmatrix} = \begin{bmatrix} 13 \\ 7 \end{bmatrix}$$

b) Likewise, $\begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = x_1\begin{bmatrix} 1 \\ 0 \end{bmatrix} + x_2\begin{bmatrix} 0 \\ 1 \end{bmatrix}$, thus

$$T\left(\begin{bmatrix} x_1 \\ x_2 \end{bmatrix}\right) = x_1 T\left(\begin{bmatrix} 1 \\ 0 \end{bmatrix}\right) + x_2 T\left(\begin{bmatrix} 0 \\ 1 \end{bmatrix}\right)$$

$$= x_1 \begin{bmatrix} 2 \\ 5 \end{bmatrix} + x_2 \begin{bmatrix} -1 \\ 6 \end{bmatrix}$$

$$= \begin{bmatrix} 2x_1 - x_2 \\ 5x_1 + 6x_2 \end{bmatrix}$$

④ By the assumptions $\text{Span}\{\vec{v}_1, \dots, \vec{v}_p\} = \mathbb{R}^n$, so for any \vec{x} in \mathbb{R}^n

$$\vec{x} = c_1 \vec{a}_1 + c_2 \vec{a}_2 + \dots + c_p \vec{a}_p, \text{ thus } T(\vec{x}) = T(c_1 \vec{a}_1 + \dots + c_p \vec{a}_p)$$

$$(T \text{ is linear transform}) = c_1 T(\vec{a}_1) + c_2 T(\vec{a}_2) + \dots + c_p T(\vec{a}_p)$$

$$(\text{since } T(\vec{v}_i) = \vec{0}, \text{ for all } i=1, 2, \dots, p) \rightarrow = c_1 \cdot \vec{0} + c_2 \cdot \vec{0} + \dots + c_p \cdot \vec{0} = \vec{0}.$$

So, for any \vec{x} in \mathbb{R}^n , $T(\vec{x}) = \vec{0}$.

⑤ Note $5I_3 = \begin{bmatrix} 5 & 0 & 0 \\ 0 & 5 & 0 \\ 0 & 0 & 5 \end{bmatrix}$, So, $A - 5I_3 = \begin{bmatrix} 5-5 & -1-0 & 3-0 \\ -4-0 & 3-5 & -6-0 \\ -3-0 & 1-0 & 2-5 \end{bmatrix} = \begin{bmatrix} 0 & -1 & 3 \\ -4 & -2 & -6 \\ -3 & 1 & -3 \end{bmatrix} \checkmark$

and $(5I_3) \cdot A = \begin{bmatrix} 5 & 0 & 0 \\ 0 & 5 & 0 \\ 0 & 0 & 5 \end{bmatrix} \cdot \begin{bmatrix} 5 & -1 & 3 \\ -4 & 3 & -6 \\ -3 & 1 & 2 \end{bmatrix} = \begin{bmatrix} 5 \cdot 5 + 0 & -1 \cdot 5 + 0 & 3 \cdot 5 + 0 \\ -4 \cdot 5 + 0 & 3 \cdot 5 + 0 & -6 \cdot 5 + 0 \\ -3 \cdot 5 + 0 & 1 \cdot 5 + 0 & 2 \cdot 5 + 0 \end{bmatrix} = \begin{bmatrix} 25 & -5 & 15 \\ -20 & 15 & -30 \\ -15 & 5 & 10 \end{bmatrix} \checkmark$

⑥ By the assumption, A is invertible, and it also shows that A is row equivalent to I_n , so $A \sim I_n$ (not equal!). Thus, the system

$$\left[A \mid \begin{smallmatrix} 0 \\ 0 \\ 0 \end{smallmatrix} \right] \sim \left[I_n \mid \begin{smallmatrix} 0 \\ 0 \\ 0 \end{smallmatrix} \right] \text{ meaning that } \vec{x} = \vec{0} \text{ since there are no free variables,}$$

Since A is invertible and row equivalent to I_n , then A must have the same number of rows and columns.

HW-4 (2, 4, 7, 9, 10, 11) $-5R_1 + R_2 \rightarrow R_2$ $-R_2 + R_1 \rightarrow R_1$ $\frac{1}{2}R_2 \rightarrow R_2$

⑦ Consider $\left[\begin{array}{cc|cc} 1 & 2 & 1 & 0 \\ 5 & 12 & 0 & 1 \end{array} \right] \rightarrow \left[\begin{array}{cc|cc} 1 & 2 & 1 & 0 \\ 0 & 2 & -5 & 1 \end{array} \right] \rightarrow \left[\begin{array}{cc|cc} 1 & 0 & 6 & -1 \\ 0 & 2 & -5 & 1 \end{array} \right] \rightarrow \left[\begin{array}{cc|cc} 1 & 0 & 6 & -1 \\ 0 & 1 & -\frac{5}{2} & \frac{1}{2} \end{array} \right]$

Therefore, $A^{-1} = \begin{bmatrix} 6 & -1 \\ -\frac{5}{2} & \frac{1}{2} \end{bmatrix}$.

For $A\vec{x} = \vec{b}_1 \rightarrow \vec{x} = A^{-1}\vec{b}_1 \rightarrow \begin{bmatrix} 6 & -1 \\ -\frac{5}{2} & \frac{1}{2} \end{bmatrix} \cdot \begin{bmatrix} -1 \\ 3 \end{bmatrix} = \begin{bmatrix} 6(-1) + (-1)(3) \\ (-\frac{5}{2})(-1) + \frac{1}{2}(3) \end{bmatrix} = \begin{bmatrix} -6-3 \\ \frac{5}{2} + \frac{3}{2} \end{bmatrix} = \begin{bmatrix} -9 \\ 4 \end{bmatrix}$

For $A\vec{x} = \vec{b}_2 \rightarrow \vec{x} = A^{-1}\vec{b}_2 \rightarrow \begin{bmatrix} 6 & -1 \\ -\frac{5}{2} & \frac{1}{2} \end{bmatrix} \cdot \begin{bmatrix} 1 \\ -5 \end{bmatrix} = \begin{bmatrix} 6(1) + (-1)(-5) \\ (-\frac{5}{2})(1) + (\frac{1}{2})(-5) \end{bmatrix} = \begin{bmatrix} 6+5 \\ -\frac{5}{2} - \frac{5}{2} \end{bmatrix} = \begin{bmatrix} 11 \\ -5 \end{bmatrix}$

For $A\vec{x} = \vec{b}_3 \rightarrow \vec{x} = A^{-1}\vec{b}_3 \rightarrow \begin{bmatrix} 6 & -1 \\ -\frac{5}{2} & \frac{1}{2} \end{bmatrix} \cdot \begin{bmatrix} 2 \\ 6 \end{bmatrix} = \begin{bmatrix} 6(2) + (-1)(6) \\ (-\frac{5}{2})(2) + (\frac{1}{2})(6) \end{bmatrix} = \begin{bmatrix} 12-6 \\ -5+3 \end{bmatrix} = \begin{bmatrix} 6 \\ -2 \end{bmatrix}$

For $A\vec{x} = \vec{b}_4 \rightarrow \vec{x} = A^{-1}\vec{b}_4 = \begin{bmatrix} 6 & -1 \\ -\frac{5}{2} & \frac{1}{2} \end{bmatrix} \cdot \begin{bmatrix} 3 \\ 5 \end{bmatrix} = \begin{bmatrix} 6(3) + (-1)(5) \\ (-\frac{5}{2})(3) + (\frac{1}{2})(5) \end{bmatrix} = \begin{bmatrix} 18-5 \\ -\frac{15}{2} + \frac{5}{2} \end{bmatrix} = \begin{bmatrix} 13 \\ -5 \end{bmatrix}$

⑥ $\left[\begin{array}{cc|cccc} 1 & 2 & -1 & 1 & 2 & 3 \\ 5 & 12 & 3 & -5 & 6 & 5 \end{array} \right] \xrightarrow{\text{Same as top}} \left[\begin{array}{cc|cccc} 1 & 2 & -1 & 1 & 2 & 3 \\ 0 & 2 & 8 & -10 & -4 & -10 \end{array} \right]$

$\xrightarrow{\text{Same as top}} \left[\begin{array}{cc|cccc} 1 & 0 & -9 & 11 & 6 & 13 \\ 0 & 2 & 8 & -10 & -4 & -10 \end{array} \right] \xrightarrow{\text{Same as top}} \left[\begin{array}{cc|cccc} 1 & 0 & -9 & 11 & 6 & 13 \\ 0 & 1 & 4 & -5 & -2 & -5 \end{array} \right]$

⑧ P is invertible, thus P^{-1} exists and $P \cdot P^{-1} = I = P^{-1} \cdot P$

$$\begin{aligned} \text{So, } A &= PBP^{-1} \rightarrow A \cdot P = PB(P^{-1} \cdot P) \rightarrow (A \cdot P) = (P \cdot B) \rightarrow P^{-1}(A \cdot P) = P^{-1}(P \cdot B) \\ &= PBI = (P^{-1} \cdot P)B \\ &= IB \\ &= B \end{aligned}$$

$$\text{thus } B = P^{-1} \cdot A \cdot P,$$

⑨ A is invertible, thus A^{-1} exists and $A \cdot A^{-1} = I = A^{-1} \cdot A$

$$\text{So, } AD = I \rightarrow A^{-1} \cdot (AD) = A^{-1} \cdot I \rightarrow (A^{-1} \cdot A) \cdot D = A^{-1} \rightarrow I \cdot D = A^{-1} \rightarrow D = A^{-1}$$

⑩ A is invertible, thus $\exists A^{-1}$ such that $A \cdot A^{-1} = I = A^{-1} \cdot A$

$$\begin{aligned} \text{So, } AB &= AC \rightarrow A^{-1} \cdot (AB) = A^{-1} \cdot (AC) \rightarrow (A^{-1} \cdot A) \cdot B = (A^{-1} \cdot A) \cdot C \\ &\rightarrow I \cdot B = I \cdot C \rightarrow B = C. \end{aligned}$$

⑪ A few different answers work, but...

Since matrix A is invertible, then A^T is invertible, by the Invertible Matrix Theorem (IMT).

Since A^T is invertible, then by the IMT the columns of A are linearly independent.

⑫ No. Consider a $n \times n$ matrix A and the matrix equation $A\vec{x} = \vec{0}$.

If A has two identical rows, then A will have a free variable, thus there will be more than just the trivial solution meaning the columns of A are not linearly independent. By the IVM, A cannot be invertible.

⑬ AB is invertible, thus there exists a matrix w such that $(AB) \cdot w = I$.

Since $(AB)w = I$ then $A(Bw) = I$. Let $Bw = C$, then there exists a matrix C such that $AC = I$, thus A is invertible.