

1. Determine if b is a linear combination of a_1, a_2 , and a_3 . (Use row notation to show your steps)

$$a_1 = \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix} \quad a_2 = \begin{bmatrix} -2 \\ 3 \\ -2 \end{bmatrix} \quad a_3 = \begin{bmatrix} -6 \\ 7 \\ 5 \end{bmatrix} \quad b = \begin{bmatrix} 11 \\ -5 \\ 9 \end{bmatrix}$$

$$a_1 = \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix} \quad a_2 = \begin{bmatrix} -2 \\ 3 \\ -2 \end{bmatrix} \quad a_3 = \begin{bmatrix} -6 \\ 7 \\ 5 \end{bmatrix} \quad b = \begin{bmatrix} 11 \\ -5 \\ 9 \end{bmatrix}$$

$$x_1 a_1 + x_2 a_2 + x_3 a_3 = b ?$$

$$x_1 \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix} + x_2 \begin{bmatrix} -2 \\ 3 \\ -2 \end{bmatrix} + x_3 \begin{bmatrix} -6 \\ 7 \\ 5 \end{bmatrix} = \begin{bmatrix} 11 \\ -5 \\ 9 \end{bmatrix}$$

| same as

$$\begin{bmatrix} x_1 \\ 0x_1 \\ 0x_1 \end{bmatrix} + \begin{bmatrix} -2x_2 \\ 3x_2 \\ -2x_2 \end{bmatrix} + \begin{bmatrix} -6x_3 \\ 7x_3 \\ 5x_3 \end{bmatrix} = \begin{bmatrix} 11 \\ -5 \\ 9 \end{bmatrix} \text{ ad } \begin{bmatrix} x_1 - 2x_2 - 6x_3 \\ 0x_1 + 3x_2 + 7x_3 \\ 0x_1 - 2x_2 + 5x_3 \end{bmatrix} = \begin{bmatrix} 11 \\ -5 \\ 9 \end{bmatrix}$$

$$\begin{bmatrix} 1 & -2 & -6 & 11 \\ 0 & 3 & 7 & -5 \\ 1 & -2 & 5 & 9 \end{bmatrix} \xrightarrow{-1 \cdot R_1 + R_3} \begin{bmatrix} 1 & -2 & -6 & 11 \\ 0 & 3 & 7 & -5 \\ 0 & 0 & 11 & -2 \end{bmatrix}$$

$$\downarrow \frac{1}{11} \cdot R_3$$

$$\begin{bmatrix} 1 & -2 & -6 & 11 \\ 0 & 1 & \frac{7}{11} & -\frac{5}{11} \\ 0 & 0 & 11 & -2 \end{bmatrix} \xrightarrow{2R_2 + R_1 \Rightarrow R_1} \begin{bmatrix} 1 & -2 & -6 & 11 \\ 0 & 1 & \frac{7}{11} & -\frac{5}{11} \\ 0 & 0 & 11 & -2 \end{bmatrix}$$

$$\downarrow \frac{1}{11} \cdot R_3$$

$$\begin{bmatrix} 1 & 0 & -1.33 & 2.67 \\ 0 & 1 & \frac{7}{11} & -\frac{5}{11} \\ 0 & 0 & 1 & -2/11 \end{bmatrix} \xrightarrow{\frac{7}{11} \cdot R_3 + R_1 \Rightarrow R_1} \begin{bmatrix} 1 & 0 & 0 & 7.42 \\ 0 & 1 & \frac{7}{11} & -\frac{5}{11} \\ 0 & 0 & 1 & -2/11 \end{bmatrix}$$

$$\downarrow -\frac{7}{3} \cdot R_3 + R_2 \Rightarrow R_2$$

$$\begin{bmatrix} 1 & 0 & 0 & 7.42 \\ 0 & 1 & 0 & -1.24 \\ 0 & 0 & 1 & -2/11 \end{bmatrix}$$

(cont'd)

contd

$$v_1 = 27.42 \quad v_2 = -1.74 \quad v_3 = -2/11$$

$$7.42 \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix} - 1.74 \begin{bmatrix} -2 \\ 3 \\ -2 \end{bmatrix} - 2/11 \begin{bmatrix} -6 \\ 7 \\ 5 \end{bmatrix} = \begin{bmatrix} 1 \\ -5 \\ 9 \end{bmatrix}$$

$R_1? \checkmark$
 $R_2? \checkmark$
 $R_3? \checkmark$

b is a linear combination of v_1, v_2 , and v_3

2. Determine if b is a linear combination of the vectors formed from the columns of the matrix A.

$$A = \begin{bmatrix} 1 & -4 & 2 \\ 0 & 3 & 5 \\ -2 & 8 & -4 \end{bmatrix} \quad b = \begin{bmatrix} 3 \\ -7 \\ -3 \end{bmatrix}$$

$$A = \begin{bmatrix} 1 & -4 & 2 \\ 0 & 3 & 5 \\ -2 & 8 & -4 \end{bmatrix} \quad b = \begin{bmatrix} 3 \\ -7 \\ -3 \end{bmatrix} \quad \left[\begin{array}{ccc|c} 1 & -4 & 2 & 3 \\ 0 & 3 & 5 & -7 \\ -2 & 8 & -4 & -3 \end{array} \right]$$

An augmented matrix is
 $\begin{array}{l} R_3 + 2R_1 \rightarrow R_3 \\ R_3 \leftrightarrow R_2 \end{array}$

1 row got out of order
 $\begin{array}{l} R_2 \leftrightarrow R_3 \\ R_3 \rightarrow [0, 0, 0] \end{array}$

$\downarrow 2 \cdot R_1 + R_3 \rightarrow R_3$

$$\left[\begin{array}{ccc|c} 1 & -4 & 2 & 3 \\ 0 & 3 & 5 & -7 \\ 0 & 0 & 0 & 3 \end{array} \right]$$

No 3 rows form a linear combination of the columns of A.

3. For what value(s) of h is y in the plane generated by v_1 and v_2 ?

$$\mathbf{a}_1 = \begin{bmatrix} 1 \\ 3 \\ -1 \end{bmatrix} \quad \mathbf{a}_2 = \begin{bmatrix} -5 \\ -8 \\ 2 \end{bmatrix} \quad \mathbf{b} = \begin{bmatrix} 3 \\ -5 \\ h \end{bmatrix}$$

$Ax = b$

$$a_1 = \begin{bmatrix} 1 \\ 3 \\ -1 \end{bmatrix}, a_2 = \begin{bmatrix} -5 \\ -8 \\ 2 \end{bmatrix}, b = \begin{bmatrix} 3 \\ -5 \\ h \end{bmatrix}, [a_1 \ a_2] \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = b$$

$\xrightarrow{\text{R1}+R_2 \times 2, R_3 - R_2}$ $\begin{bmatrix} 1 & -5 & 3 \\ 0 & -1 & -2 \\ 0 & -3 & h+3 \end{bmatrix}$ $b_1, b_2 \in \text{Span}\{a_1, a_2\}$

$\xrightarrow{\text{R2} + R_3}$ $\begin{bmatrix} 1 & -5 & 3 \\ 0 & 1 & -2 \\ 0 & -3 & h+3 \end{bmatrix}$ $\xrightarrow{\text{R3} + 3R_2}$

$\xrightarrow{\text{R1}+R_2 \times 2}$ $\begin{bmatrix} 1 & 0 & -7 \\ 0 & 1 & -2 \\ 0 & 0 & h-3 \end{bmatrix}$ $\xrightarrow{\text{R2} \leftrightarrow \text{R3}}$ $\text{for linear dependence}$

$b \in \text{Span}\{a_1, a_2, b\}$

4. Let $A = \begin{bmatrix} 1 & 0 & -4 \\ 0 & 3 & -2 \\ -2 & 6 & 3 \end{bmatrix}$ and $\mathbf{b} = \begin{bmatrix} 4 \\ 1 \\ -4 \end{bmatrix}$.

Denote the columns of A by $\mathbf{a}_1, \mathbf{a}_2, \mathbf{a}_3$, and let $W = \text{Span}\{\mathbf{a}_1, \mathbf{a}_2, \mathbf{a}_3\}$.

1.

$$A = \begin{bmatrix} 1 & 0 & -4 \\ 0 & 3 & -2 \\ 2 & 6 & 3 \end{bmatrix} \quad b = \begin{bmatrix} 4 \\ 1 \\ -4 \end{bmatrix}$$

Denote the columns of A by a_1, a_2, a_3 ,
and let $W = \text{Span}\{a_1, a_2, a_3\}$

a) Is b in $\{a_1, a_2, a_3\}$? ←
 This has 2/3 vectors in the set and
 b would not be one of them so no.
 No

b) How many vectors are in $\{a_1, a_2, a_3\}$?
 3
 3 linearly independent vectors in $\{a_1, a_2, a_3\}$

(a) Is b in $\{a_1, a_2, a_3\}$?

No. There are only 3 vectors in the set and b is not one of them.

(b) How many vectors are in $\{a_1, a_2, a_3\}$?

3.

(c) Is b in W ? (Show your work)

B1
 Columns of matrix A
 6 linearly independent vectors of Span $\in \mathbb{R}^3$
 Is b in W, find if consistent and by
 a unique solution
 Get to REF $\rightarrow \left[\begin{array}{ccc|c} 1 & 0 & -4 & 4 \\ 0 & 3 & -2 & 1 \\ 0 & -2 & 6 & -4 \end{array} \right] \xrightarrow{2 \cdot R_2 + R_3 \rightarrow R_3} \left[\begin{array}{ccc|c} 1 & 0 & -4 & 4 \\ 0 & 3 & -2 & 1 \\ 0 & 0 & 2 & -3 \end{array} \right]$
 for Edah Form!
 $\downarrow 2 \cdot R_2 + R_3 \rightarrow R_3$
 $\left[\begin{array}{ccc|c} 1 & 0 & 0 & -4 \\ 0 & 1 & -2/3 & 1 \\ 0 & 0 & 1 & -1/2 \end{array} \right] \xrightarrow{\text{Edah Form!}} \left[\begin{array}{ccc|c} 1 & 0 & 0 & -4 \\ 0 & 1 & 0 & -1 \\ 0 & 0 & 1 & -1/2 \end{array} \right]$
 $\downarrow \frac{1}{3} \times R_2$
 $\left[\begin{array}{ccc|c} 1 & 0 & 0 & -4 \\ 0 & 1 & 0 & -1 \\ 0 & 0 & 1 & -1/2 \end{array} \right] \xrightarrow{\frac{1}{3} R_2 + R_1 \rightarrow R_1} \left[\begin{array}{ccc|c} 1 & 0 & 0 & -4 \\ 0 & 1 & 0 & -1 \\ 0 & 0 & 1 & -1/2 \end{array} \right] \xrightarrow{\text{Consistent}}$

C1D
 $\left[\begin{array}{ccc|c} 1 & 0 & 0 & -4 \\ 0 & 1 & 0 & -1 \\ 0 & 0 & 1 & -1/2 \end{array} \right] \xrightarrow{-1 \cdot R_3} \left[\begin{array}{ccc|c} 1 & 0 & 0 & -4 \\ 0 & 1 & 0 & -1 \\ 0 & 0 & 1 & 1/2 \end{array} \right]$
 \downarrow
 Thus, we get b is in W.
 If A was written as
 a matrix of columns
 b would be a possible
 solution!

(d) How many vectors are in W?

Infinitely many.

(e) Show that a1 is in W. [Hint Row operations are unnecessary.]

$$Q) \boxed{a_1 = a_1 + 5a_2 + 0a_3}$$

5. Use the definition of Ax to write the following matrix equation as a vector equation.

$$\begin{bmatrix} 1 & 2 & -3 & 1 \\ -2 & -3 & 1 & -1 \end{bmatrix} \begin{bmatrix} 2 \\ -1 \\ 1 \\ -1 \end{bmatrix} = \begin{bmatrix} -4 \\ 1 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 2 & -3 & 1 \\ -2 & -3 & 1 & -1 \end{bmatrix} \begin{bmatrix} 1 \\ -1 \\ 1 \\ -1 \end{bmatrix} = \begin{bmatrix} -4 \\ 1 \end{bmatrix} \quad \text{Vector eqn: } v_1 p_1 + v_2 p_2 = b$$

$$2 \begin{bmatrix} 1 \\ -2 \end{bmatrix} + (-1) \begin{bmatrix} 2 \\ -3 \end{bmatrix} + (1) \begin{bmatrix} -3 \\ 1 \end{bmatrix} + (-1) \begin{bmatrix} 1 \\ -1 \end{bmatrix} = \begin{bmatrix} -4 \\ 1 \end{bmatrix}$$

6. Use the definition of Ax to write the following vector equation as a matrix equation. Then write this vector equation as a system of equations.

Note: A matrix equation is not the same as an augmented matrix.

$$z_1 \begin{bmatrix} 2 \\ -4 \end{bmatrix} + z_2 \begin{bmatrix} -1 \\ 5 \end{bmatrix} + z_3 \begin{bmatrix} -4 \\ 3 \end{bmatrix} + z_4 \begin{bmatrix} 0 \\ 2 \end{bmatrix} = \begin{bmatrix} 5 \\ 12 \end{bmatrix}$$

$$6 \cdot z_1 \begin{bmatrix} 2 \\ -4 \end{bmatrix} + z_2 \begin{bmatrix} -1 \\ 5 \end{bmatrix} + z_3 \begin{bmatrix} 4 \\ 3 \end{bmatrix} + z_4 \begin{bmatrix} 0 \\ 2 \end{bmatrix} = \begin{bmatrix} 5 \\ 12 \end{bmatrix}$$

\downarrow

$$\left[\begin{array}{cccc} 2 & -1 & 4 & 0 \end{array} \right] \begin{bmatrix} z_1 \\ z_2 \\ z_3 \\ z_4 \end{bmatrix} = \begin{bmatrix} 5 \\ 12 \end{bmatrix}$$

and

$$\begin{aligned} 2z_1 + (-1)z_2 + 4z_3 + 0z_4 &= 5 \\ 4z_1 + 5z_2 + 3z_3 + 2z_4 &= 12 \end{aligned}$$

7. Given A and b, write the augmented matrix for the linear system that corresponds to the matrix equation $Ax = b$. Then solve the system and write the solution as a vector.

$$A = \begin{bmatrix} 1 & 3 & -4 \\ 1 & 5 & 2 \\ -3 & -7 & 6 \end{bmatrix} \quad \mathbf{b} = \begin{bmatrix} -2 \\ 4 \\ 12 \end{bmatrix}$$

7. $A = \begin{bmatrix} 1 & 3 & -4 \\ 1 & 5 & 2 \\ -3 & -7 & 6 \end{bmatrix}$ $b = \begin{bmatrix} -1 \\ 4 \\ 12 \end{bmatrix}$

RREF

$$\begin{array}{c|c} \begin{bmatrix} 1 & 3 & -4 & | & -1 \\ 1 & 5 & 2 & | & 4 \\ -3 & -7 & 6 & | & 12 \end{bmatrix} & \xrightarrow{-1 \cdot R_1 + R_2 \rightarrow R_2} \begin{bmatrix} 1 & 3 & -4 & | & -1 \\ 0 & 2 & 6 & | & 3 \\ -3 & -7 & 6 & | & 12 \end{bmatrix} \\ \xleftarrow{\downarrow \frac{1}{2} \cdot R_2} & \end{array}$$

$$\begin{array}{c|c} \begin{bmatrix} 1 & 3 & -4 & | & -1 \\ 0 & 1 & 3 & | & 3 \\ 0 & 2 & -6 & | & 6 \end{bmatrix} & \xleftarrow{3 \cdot R_1 + R_3 \rightarrow R_3} \begin{bmatrix} 1 & 3 & -4 & | & -1 \\ 0 & 1 & 3 & | & 3 \\ 0 & 0 & -6 & | & 12 \end{bmatrix} \\ \xleftarrow{\downarrow \frac{1}{2} \cdot R_3} & \end{array}$$

$$\begin{array}{c|c} \begin{bmatrix} 1 & 3 & -4 & | & -1 \\ 0 & 1 & 3 & | & 3 \\ 0 & 0 & -6 & | & 12 \end{bmatrix} & \xrightarrow{-1 \cdot R_2 + R_3 \rightarrow R_3} \begin{bmatrix} 1 & 3 & -4 & | & -1 \\ 0 & 1 & 3 & | & 3 \\ 0 & 0 & 0 & | & 0 \end{bmatrix} \\ \xleftarrow{\downarrow -\frac{1}{2} \cdot R_3} & \end{array}$$

$$\begin{array}{c|c} \begin{bmatrix} 1 & 0 & -13 & | & -1 \\ 0 & 1 & 3 & | & 3 \\ 0 & 0 & 1 & | & 0 \end{bmatrix} & \xleftarrow{-3 \cdot R_1 + R_1 \rightarrow R_1} \begin{bmatrix} 1 & 3 & -4 & | & -1 \\ 0 & 1 & 3 & | & 3 \\ 0 & 0 & 1 & | & 0 \end{bmatrix} \\ \xleftarrow{\downarrow 13 \cdot R_3 + R_1 \rightarrow R_1} & \end{array}$$

$$\begin{array}{c|c} \begin{bmatrix} 1 & 0 & 0 & | & -11 \\ 0 & 1 & 3 & | & 3 \\ 0 & 0 & 1 & | & 0 \end{bmatrix} & \xrightarrow{-3 \cdot R_3 + R_2 \rightarrow R_2} \begin{bmatrix} 1 & 0 & 0 & | & -11 \\ 0 & 1 & 0 & | & 3 \\ 0 & 0 & 1 & | & 0 \end{bmatrix} \\ \xleftarrow{\quad \quad \quad \swarrow} & \end{array}$$

$$b = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} -11 \\ 3 \\ 0 \end{bmatrix}$$

8. Let $A = \begin{bmatrix} 1 & -2 & -1 \\ -2 & 2 & 0 \\ 4 & -1 & 3 \end{bmatrix}$ and $\mathbf{b} = \begin{bmatrix} b_1 \\ b_2 \\ b_3 \end{bmatrix}$.

(a) Show that the equation $Ax = b$ does not have a solution for all possible b . (Meaning there is not a solution for every possible combination of b_1, b_2, b_3 .)

$A = \begin{bmatrix} 1 & -2 & -1 \\ -2 & 2 & 0 \\ 4 & -1 & 3 \end{bmatrix}$ and $b = \begin{bmatrix} b_1 \\ b_2 \\ b_3 \end{bmatrix}$ Set up $Ax = b$ as an augmented matrix

$$\textcircled{1} \quad \begin{bmatrix} 1 & -2 & -1 & b_1 \\ -2 & 2 & 0 & b_2 \\ 4 & -1 & 3 & b_3 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & -2 & -1 & b_1 \\ 0 & 2 & 0 & b_2 \\ 4 & -1 & 3 & b_3 \end{bmatrix}$$

$$\begin{bmatrix} 1 & -2 & -1 & b_1 \\ 0 & 1 & 0 & \frac{b_2}{2} \\ 4 & -1 & 3 & b_3 \end{bmatrix} \xrightarrow{R_1 \leftarrow R_1 + 2R_2} \begin{bmatrix} 1 & -2 & -1 & b_1 \\ 0 & 1 & 0 & \frac{b_2}{2} \\ 4 & -1 & 3 & b_3 \end{bmatrix} \xrightarrow{R_3 \leftarrow R_3 - 4R_1} \begin{bmatrix} 1 & -2 & -1 & b_1 \\ 0 & 1 & 0 & \frac{b_2}{2} \\ 0 & 7 & 7 & b_3 - 4b_1 \end{bmatrix}$$

$$\begin{bmatrix} 1 & -2 & -1 & b_1 \\ 0 & 1 & 0 & \frac{b_2}{2} \\ 0 & 7 & 7 & b_3 - 4b_1 \end{bmatrix} \xrightarrow{\frac{R_3 - 4R_1}{7}} \begin{bmatrix} 1 & -2 & -1 & b_1 \\ 0 & 1 & 0 & \frac{b_2}{2} \\ 0 & 1 & 1 & \frac{b_3 - 4b_1}{7} \end{bmatrix}$$

$$\begin{bmatrix} 1 & -2 & -1 & b_1 \\ 0 & 1 & 0 & \frac{b_2}{2} \\ 0 & 1 & 1 & \frac{b_3 - 4b_1}{7} \end{bmatrix} \xrightarrow{\frac{R_1 + R_2}{2}} \begin{bmatrix} 1 & -1 & -1 & \frac{b_1 + b_2}{2} \\ 0 & 1 & 0 & \frac{b_2}{2} \\ 0 & 1 & 1 & \frac{b_3 - 4b_1}{7} + \frac{b_1 + b_2}{2} \end{bmatrix}$$

$$\begin{bmatrix} 1 & -1 & -1 & \frac{b_1 + b_2}{2} \\ 0 & 1 & 0 & \frac{b_2}{2} \\ 0 & 1 & 1 & \frac{b_3 - 4b_1}{7} + \frac{b_1 + b_2}{2} \end{bmatrix} \xrightarrow{\frac{R_3 - R_2}{2}} \begin{bmatrix} 1 & -1 & -1 & \frac{b_1 + b_2}{2} \\ 0 & 1 & 0 & \frac{b_2}{2} \\ 0 & 0 & 1 & \frac{b_3 - 4b_1}{14} + \frac{b_1 + b_2}{2} \end{bmatrix}$$

$b_3 - 4b_1 + 7b_1 + 7b_2 = 0$

$b_3 + 3b_1 + 7b_2 = 0$

$\frac{3}{7} + 1 + \frac{1}{2} \neq \frac{3}{7} + 1\frac{1}{2}$

Say we only be consistent when $2b_3 + 6b_1 + 7b_2 = 0$ and so it is inconsistent. For example there are no solutions if $b = \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}$.

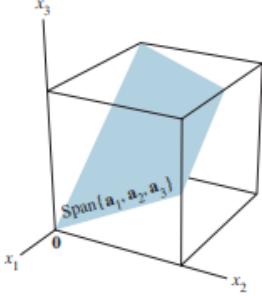
(b) Based on (a), do the columns of A span \mathbb{R}^3 ? In other words, can every vector in \mathbb{R}^3 be written as a linear combination of the columns of A? Why or why not?

No. It does not span \mathbb{R}^3 as it does not have 3 pivots when in echelon form.

(c) Describe the set of all b for which $Ax = b$ does have a solution.

If $2b_3 + 6b_1 + 7b_2 = 0$, then the system is consistent. For any b where the equation $2b_3 + 6b_1 + 7b_2 = 0$, there is a solution. You could also say that the set of all b such that b is a plane through the origin in \mathbb{R}^3 . *I decided to do more research and the page from the book below helped. Sorry, I can be slow at times.

1.4 The Matrix Equation $Ax = b$ 37



The reduced matrix in Example 3 provides a description of all \mathbf{b} for which the equation $Ax = \mathbf{b}$ is consistent: The entries in \mathbf{b} must satisfy

$$b_1 - \frac{1}{2}b_2 + b_3 = 0$$

This is the equation of a plane through the origin in \mathbb{R}^3 . The plane is the set of all linear combinations of the three columns of A . See Fig. 1.

The equation $Ax = \mathbf{b}$ in Example 3 fails to be consistent for all \mathbf{b} because the echelon form of A has a row of zeros. If A had a pivot in all three rows, we would not care about the calculations in the augmented column because in this case an echelon form of the augmented matrix could not have a row such as $[0 \ 0 \ 0 \ 1]$.

In the next theorem, the sentence “The columns of A span \mathbb{R}^m ” means that *every* \mathbf{b} in \mathbb{R}^m is a linear combination of the columns of A . In general, a set of vectors $\{\mathbf{v}_1, \dots, \mathbf{v}_p\}$ in \mathbb{R}^m **spans** (or **generates**) \mathbb{R}^m if every vector in \mathbb{R}^m is a linear combination of $\mathbf{v}_1, \dots, \mathbf{v}_p$ —that is, if $\text{Span}\{\mathbf{v}_1, \dots, \mathbf{v}_p\} = \mathbb{R}^m$.

FIGURE 1
The columns of
 $A = [a_1 \ a_2 \ a_3]$ span a plane
through 0.

9. For the following statements determine whether they are true or false. If false, then explain why it is false. If true, then point to a Theorem or definition that supports the statement.

(a) The solution set of the linear system whose augmented matrix is $[a_1 \ a_2 \ a_3 \ b]$ is the same as the solution set for $x_1a_1 + x_2a_2 + x_3a_3 = b$.

True. Refer to theorem 3 under section 1.4 on page 36. Also posted below.

THEOREM 3

If A is an $m \times n$ matrix, with columns $\mathbf{a}_1, \dots, \mathbf{a}_n$, and if \mathbf{b} is in \mathbb{R}^m , the matrix equation

$$A\mathbf{x} = \mathbf{b} \quad (4)$$

has the same solution set as the vector equation

$$x_1\mathbf{a}_1 + x_2\mathbf{a}_2 + \cdots + x_n\mathbf{a}_n = \mathbf{b} \quad (5)$$

which, in turn, has the same solution set as the system of linear equations whose augmented matrix is

$$\begin{bmatrix} \mathbf{a}_1 & \mathbf{a}_2 & \cdots & \mathbf{a}_n & \mathbf{b} \end{bmatrix} \quad (6)$$

(b) Asking whether the linear system corresponding to an augmented matrix $[a_1 \ a_2 \ a_3 \ b]$ has a solution amounts to asking whether b is in $\text{Span}\{a_1, a_2, a_3\}$.

True. Refer to page 30. See definition of span and theorem 4. *I don't know what to call this

definition, I just know this is my proof posted below (the explanation starts on the sentence with the highlighted part):

One of the key ideas in linear algebra is to study the set of all vectors that can be generated or written as a linear combination of a fixed set $\{\mathbf{v}_1, \dots, \mathbf{v}_p\}$ of vectors.

DEFINITION

If $\mathbf{v}_1, \dots, \mathbf{v}_p$ are in \mathbb{R}^n , then the set of all linear combinations of $\mathbf{v}_1, \dots, \mathbf{v}_p$ is denoted by $\text{Span}\{\mathbf{v}_1, \dots, \mathbf{v}_p\}$ and is called the **subset of \mathbb{R}^n spanned (or generated) by $\mathbf{v}_1, \dots, \mathbf{v}_p$** . That is, $\text{Span}\{\mathbf{v}_1, \dots, \mathbf{v}_p\}$ is the collection of all vectors that can be written in the form

$$c_1\mathbf{v}_1 + c_2\mathbf{v}_2 + \cdots + c_p\mathbf{v}_p$$

with c_1, \dots, c_p scalars.

Asking whether a vector \mathbf{b} is in $\text{Span}\{\mathbf{v}_1, \dots, \mathbf{v}_p\}$ amounts to asking whether the vector equation

$$x_1\mathbf{v}_1 + x_2\mathbf{v}_2 + \cdots + x_p\mathbf{v}_p = \mathbf{b}$$

has a solution, or, equivalently, asking whether the linear system with augmented matrix $[\mathbf{v}_1 \ \cdots \ \mathbf{v}_p \ \mathbf{b}]$ has a solution.

Note that $\text{Span}\{\mathbf{v}_1, \dots, \mathbf{v}_p\}$ contains every scalar multiple of \mathbf{v}_1 (for example), since $c\mathbf{v}_1 = c\mathbf{v}_1 + 0\mathbf{v}_2 + \cdots + 0\mathbf{v}_p$. In particular, the zero vector must be in $\text{Span}\{\mathbf{v}_1, \dots, \mathbf{v}_p\}$.

(c) The equation $A\mathbf{x} = \mathbf{b}$ is consistent if the augmented matrix $[A \ \mathbf{b}]$ has a pivot position in every row.

False. If the augmented matrix [A b] has a pivot position in “every” row, the equation $Ax = b$ may or may not be consistent. If the pivot position is in the column representing b, then we say it is not consistent.

(d) If the columns of an $m \times n$ matrix A span \mathbb{R}^m , then the equation $Ax = b$ is consistent for each b in \mathbb{R}^m .

True. If the columns span \mathbb{R}^m , this says that every b in \mathbb{R}^m is in the span of the columns, which is another way of saying that any b is a linear combination of the columns. Then the equation is consistent. You could also just look at the explanation and 4th theorem posted below:

In the next theorem, the sentence “The columns of A span \mathbb{R}^m ” means that *every* b in \mathbb{R}^m is a linear combination of the columns of A . In general, a set of vectors $\{v_1, \dots, v_p\}$ in \mathbb{R}^m spans (or generates) \mathbb{R}^m if every vector in \mathbb{R}^m is a linear combination of v_1, \dots, v_p —that is, if $\text{Span}\{v_1, \dots, v_p\} = \mathbb{R}^m$.

THEOREM 4

Let A be an $m \times n$ matrix. Then the following statements are logically equivalent. That is, for a particular A , either they are all true statements or they are all false.

- For each b in \mathbb{R}^m , the equation $Ax = b$ has a solution.
- Each b in \mathbb{R}^m is a linear combination of the columns of A .
- The columns of A span \mathbb{R}^m .
- A has a pivot position in every row.

(e) If the equation $Ax = b$ is consistent, then b is in the set spanned by the columns of A .

True. The equation $Ax = b$ has a non-empty solution set if and only if b is a linear combination of the columns of A . This is theorem 4 again, also posted below:

*You could also see existence of solutions in notes

t₃] span a plane

In the next theorem, the sentence “The columns of A span \mathbb{R}^m ” means that *every* \mathbf{b} in \mathbb{R}^m is a linear combination of the columns of A . In general, a set of vectors $\{\mathbf{v}_1, \dots, \mathbf{v}_p\}$ in \mathbb{R}^m **spans** (or **generates**) \mathbb{R}^m if every vector in \mathbb{R}^m is a linear combination of $\mathbf{v}_1, \dots, \mathbf{v}_p$ —that is, if $\text{Span}\{\mathbf{v}_1, \dots, \mathbf{v}_p\} = \mathbb{R}^m$.

THEOREM 4

Let A be an $m \times n$ matrix. Then the following statements are logically equivalent. That is, for a particular A , either they are all true statements or they are all false.

- a. For each \mathbf{b} in \mathbb{R}^m , the equation $A\mathbf{x} = \mathbf{b}$ has a solution.
- b. Each \mathbf{b} in \mathbb{R}^m is a linear combination of the columns of A .
- c. The columns of A span \mathbb{R}^m .
- d. A has a pivot position in every row.

(f) Any linear combination of vectors can always be written in the form $A\mathbf{x}$ for a suitable matrix A and vector \mathbf{x} .

True. I can't properly put it into words, but the image below explains it for me:

*True by definition of $A\mathbf{x}$

SOLUTION From the definition,

$$\begin{aligned} \begin{bmatrix} 2 & 3 & 4 \\ -1 & 5 & -3 \\ 6 & -2 & 8 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} &= x_1 \begin{bmatrix} 2 \\ -1 \\ 6 \end{bmatrix} + x_2 \begin{bmatrix} 3 \\ 5 \\ -2 \end{bmatrix} + x_3 \begin{bmatrix} 4 \\ -3 \\ 8 \end{bmatrix} \\ &= \begin{bmatrix} 2x_1 \\ -x_1 \\ 6x_1 \end{bmatrix} + \begin{bmatrix} 3x_2 \\ 5x_2 \\ -2x_2 \end{bmatrix} + \begin{bmatrix} 4x_3 \\ -3x_3 \\ 8x_3 \end{bmatrix} \quad (7) \\ &= \begin{bmatrix} 2x_1 + 3x_2 + 4x_3 \\ -x_1 + 5x_2 - 3x_3 \\ 6x_1 - 2x_2 + 8x_3 \end{bmatrix} \end{aligned}$$

The first entry in the product $A\mathbf{x}$ is a sum of products (sometimes called a *dot product*), using the first row of A and the entries in \mathbf{x} . That is,

$$\begin{bmatrix} 2 & 3 & 4 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 2x_1 + 3x_2 + 4x_3 \end{bmatrix}$$

This matrix shows how to compute the first entry in $A\mathbf{x}$ directly, without writing down all the calculations shown in (7). Similarly, the second entry in $A\mathbf{x}$ can be calculated at once by multiplying the entries in the second row of A by the corresponding entries in \mathbf{x} and then summing the resulting products:

$$\begin{bmatrix} -1 & 5 & -3 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} -x_1 + 5x_2 - 3x_3 \end{bmatrix}$$

Likewise, the third entry in $A\mathbf{x}$ can be calculated from the third row of A and the entries in \mathbf{x} . ■

Row–Vector Rule for Computing $A\mathbf{x}$

If the product $A\mathbf{x}$ is defined, then the i th entry in $A\mathbf{x}$ is the sum of the products of corresponding entries from row i of A and from the vector \mathbf{x} .