

# 16 - Lines and Curves

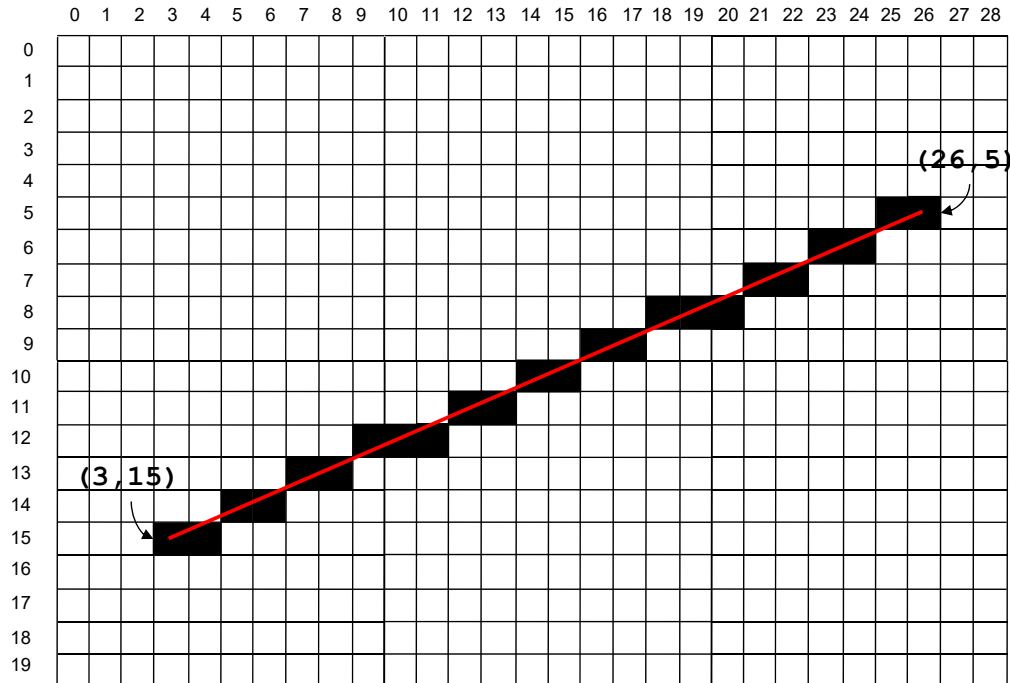
Computer Science Department  
California State University, Sacramento

CScC133 Lecture Notes  
16 - Lines and Curves

## Overview

- **Rasterization**
- **Line-based Graphical Primitives**
- **Parametric Line Representation**
- **Quadratic & Cubic Bezier Curves**
  - **Geometric and analytical definitions**
- **Rendering Via Recursive Subdivision**
- **Applications of Curves**

# Rasterization



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# The Simple DDA Algorithm

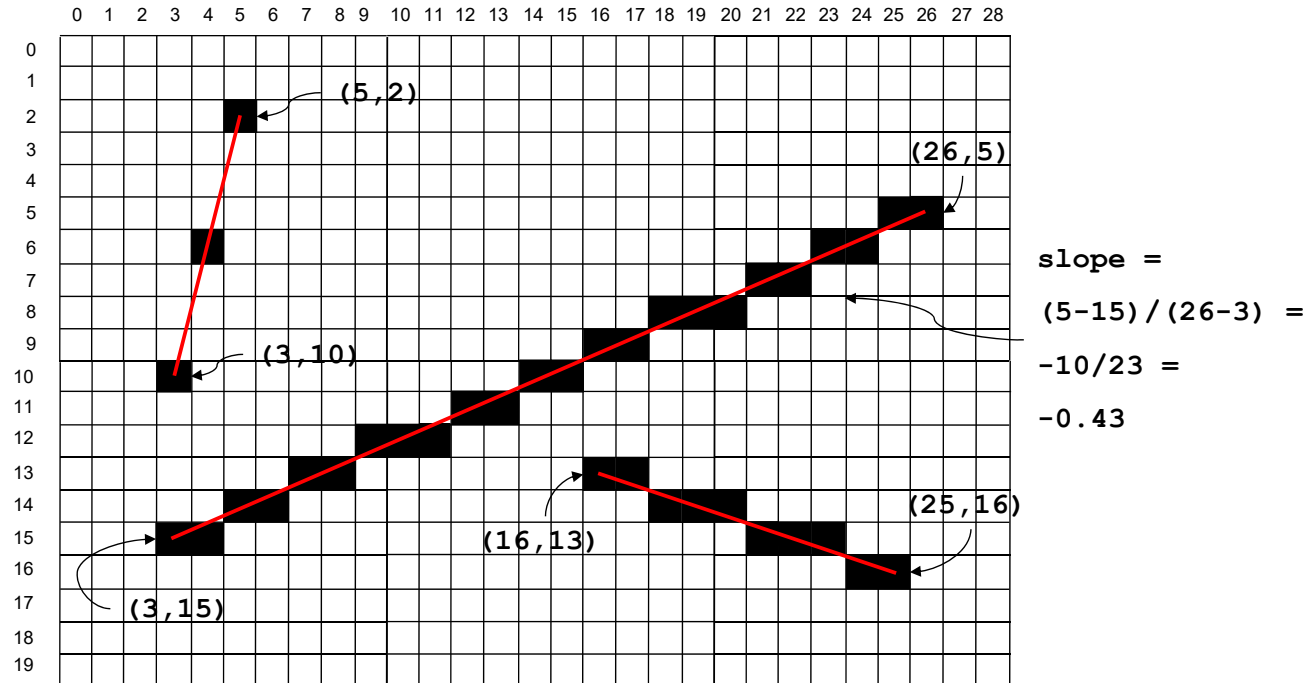
```
/** Sets pixels on the line between points (xa,ya) and (xb,yb)
 * to a specified color. This simple version assumes the absolute value of the
 * slope of the line is < 1.
 */
```

```
void simpleLineDDA (int xa,ya, xb,yb; Color rgb) {
    int dx = xb - xa ;           // X-extent of the line
    int dy = yb - ya ;           // Y-extent of the line
    int xIncr = 1 ;              // increase in X per step = 1
    double yIncr = dy/dx ;       // increase in Y per step = slope
    double x = xa ;              // start at first input point
    double y = ya ;
    setPixel ((int)x, (int)y, rgb) ;
    for (int k=1; k<=dx; k++) {
        x = x + xIncr ;
        y = y + yIncr ;
        setPixel (round(x), round(y), rgb) ;
    }
}
```

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# Applying The DDA Algorithm



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## Full DDA Algorithm

```
/** Sets pixels on the line between points (xa,ya) and (xb,yb) to a specified color.
 * Works for lines of arbitrary slope with positive or negative direction.
 */
```

```
void LineDDA (int xa,ya, xb,yb; Color rgb) {
    int dx, dy ;           // distance in X and Y for the line
    int factor ;           // denominator used in xIncr and yIncr formulas
    double x, y ;          // 'current' loc on the line
    double xIncr, yIncr ;  // increment per step in X and Y
    dx = xb - xa ;         // X-extent of the line
    dy = yb - ya ;         // Y-extent of the line
    if abs(dy/dx) < 1 then
        factor = abs (dx) // if abs(slope) < 1, to take unit steps in X, factor = abs(dx)= dx
    else
        factor = abs (dy) ; // if abs(slope) >= 1, to take unit steps in Y, factor = abs(dy)
    xIncr = dx / factor ; // increase in X per step. If abs(slope)<1, xIncr = 1. If
                          // abs(slope)>=1, xIncr = 1/abs(slope)= abs(dx)/abs(dy) = dx/abs(dy)
    yIncr = dy / factor ; // increase in Y per step. If abs(slope)>=1, yIncr = 1 (if slope is
                          // positive) OR yIncr = -1 (if slope is negative). If abs(slope)<1,
                          // yIncr = slope = dy/dx = dy/abs(dx)
    x = xa ;              // start at first input point
    y = ya ;
    setPixel ((int)x, (int)y, rgb) ;
    for (int k=1; k<=steps; k++) {
        x = x + xIncr ;
        y = y + yIncr ;
        setPixel (round(x), round(y), rgb) ;
    }
}
```

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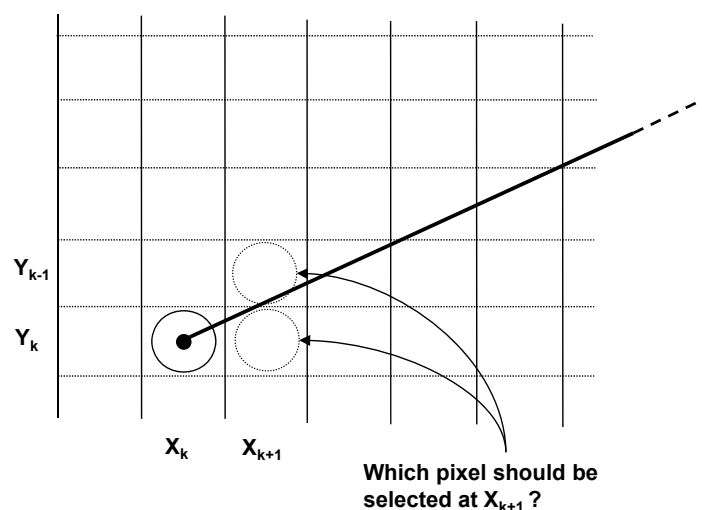
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# Problem with DDA Algorithm

- In the for-loop located at the end of algorithm it does a floating point arithmetic:
  - It is expensive when repeated many times.
  - It can cause a floating point error.
- These problems can result in highly inaccurate rasterization results.

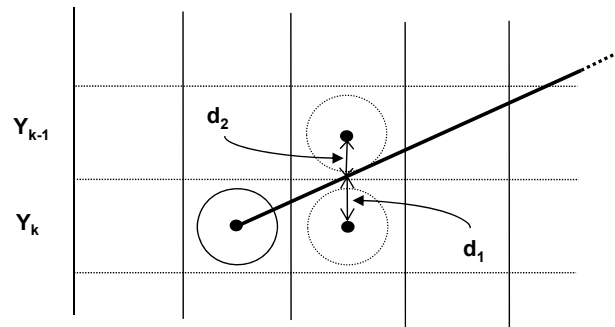
# The “Pixel Selection” Decision

- Basic question: which is the best “next pixel”?



# The “Pixel Decision” Parameter

- Choose the pixel *closest to the true line*



```
if ((d1-d2) > 0)
    choose pixel Y_{k-1}
else
    choose pixel Y_k
```

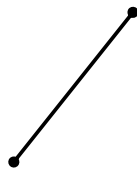
Same as “sign(d1-d2) is +”

## Bresenham’s Algorithm

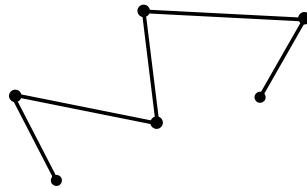
- Bresenham [IBM, 1962] figured out how to make the “sign(d1-d2) is positive” test using only integer arithmetic.
- No floating point involved!
- This results in rasterization that is at the same time faster and also more accurate (because it always chooses the “best next pixel”).

# Graphical Primitives

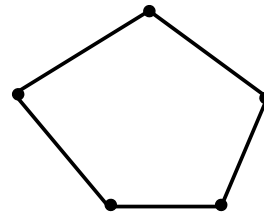
- Point- and Line-based



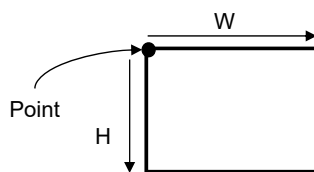
Line



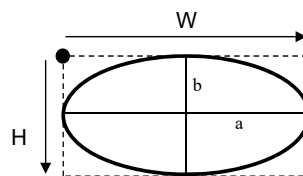
"Polyline"



"Polygon"



Rectangle

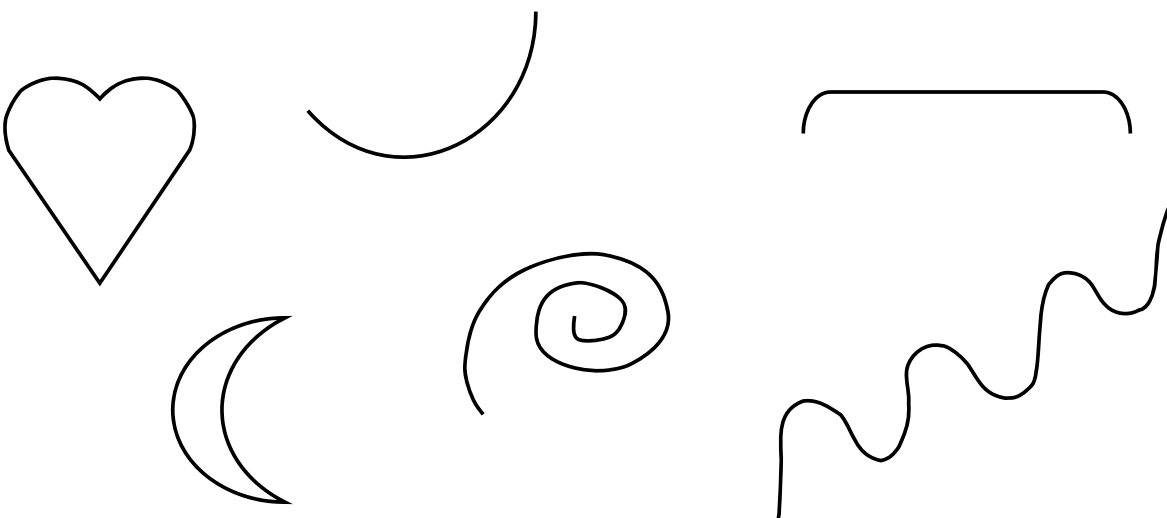


Oval

$$\frac{(x - x_{Center})^2}{a^2} + \frac{(y - y_{Center})^2}{b^2} = 1$$

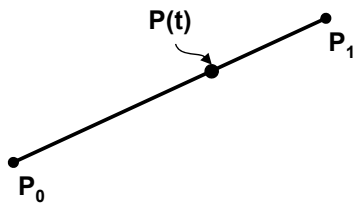
# Curves Of Higher Complexity

- What if we want to draw shapes like these?



# Parametric Line Representation

- Lines can be represented in terms of known quantities in several ways :
  - $Y = mX + b$  // line with slope “m” and Y-intercept “b”
  - $(P_0, P_1)$  // line containing  $P_0$  and  $P_1$
- Any point on  $(P_0, P_1)$  can be represented with a single *parameter value* ‘ $t$ ’



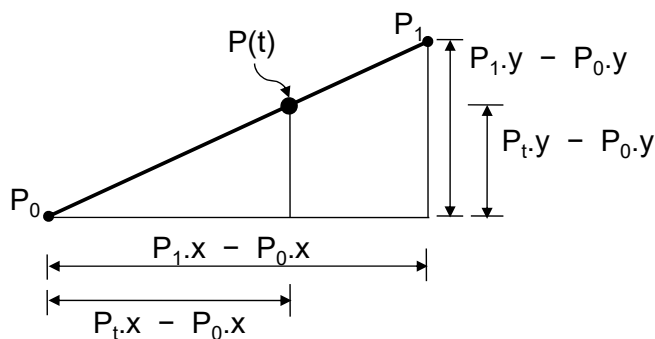
- ‘ $t$ ’ is the ratio of [distance from  $P_0$  to  $P(t)$ ] to [distance from  $P_0$  to  $P_1$ ]
- Every point on the line has a unique ‘ $t$ ’ value

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# Parametric Line Representation (cont.)

- Parametric equation for points  $P(t)$  on a line:



$$t = \frac{P_t - P_0}{P_1 - P_0}$$

$$t(P_1 - P_0) = P_t - P_0$$

$$P_t = P_0 + t(P_1 - P_0)$$

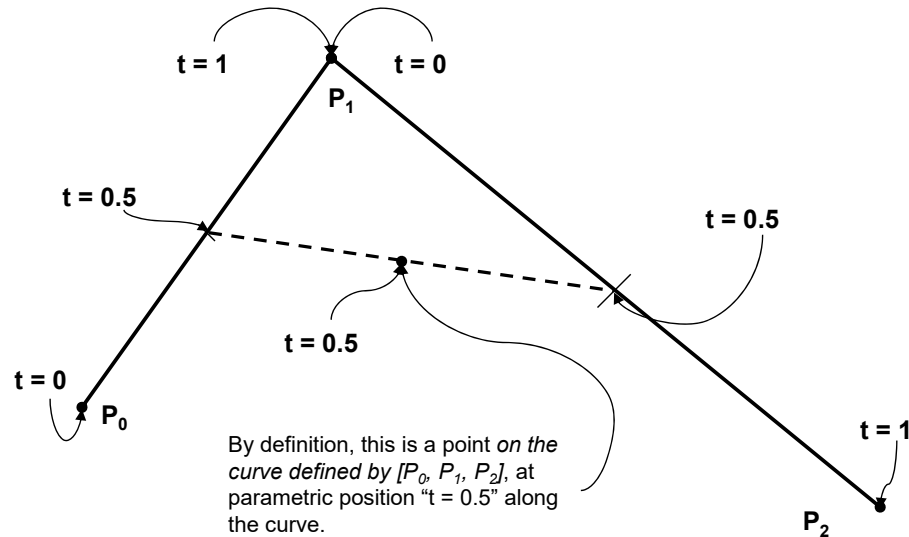
$$P_t = (1-t)P_0 + tP_1$$

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# Quadratic Bezier Curves

- Geometric description

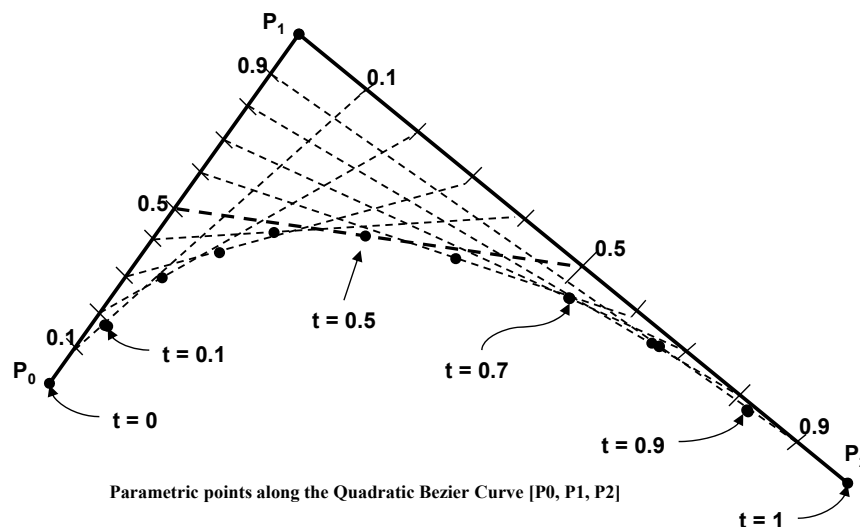


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# Quadratic Bezier Curves (cont.)

- Connecting points of equal parametric value generates a curve:



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# Quadratic Bezier Curves (cont.)

- Analytic definition

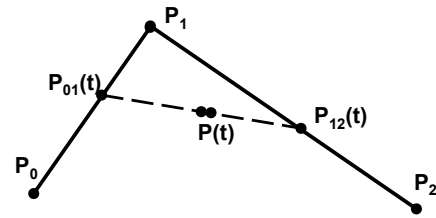
$$P_{01}(t) = t \cdot P_1 + (1-t) \cdot P_0 \quad [1]$$

and

$$P_{12}(t) = t \cdot P_2 + (1-t) \cdot P_1 \quad [2]$$

and a point on the curve  $[P_0 \ P_1 \ P_2]$  is defined as

$$P(t) = t \cdot (P_{12}(t)) + (1-t) \cdot (P_{01}(t)) \quad [3]$$



Substituting [1] and [2] into [3] gives

$$P(t) = t \cdot (t \cdot P_2 + (1-t) \cdot P_1) + (1-t) \cdot (t \cdot P_1 + (1-t) \cdot P_0)$$

Factoring and combining the constant terms  $P_0$ ,  $P_1$ , and  $P_2$  gives

$$P(t) = (1-t)^2 \cdot P_0 + (-2t^2 + 2t) \cdot P_1 + (t^2) \cdot P_2$$

# Curves as Weighted Sums

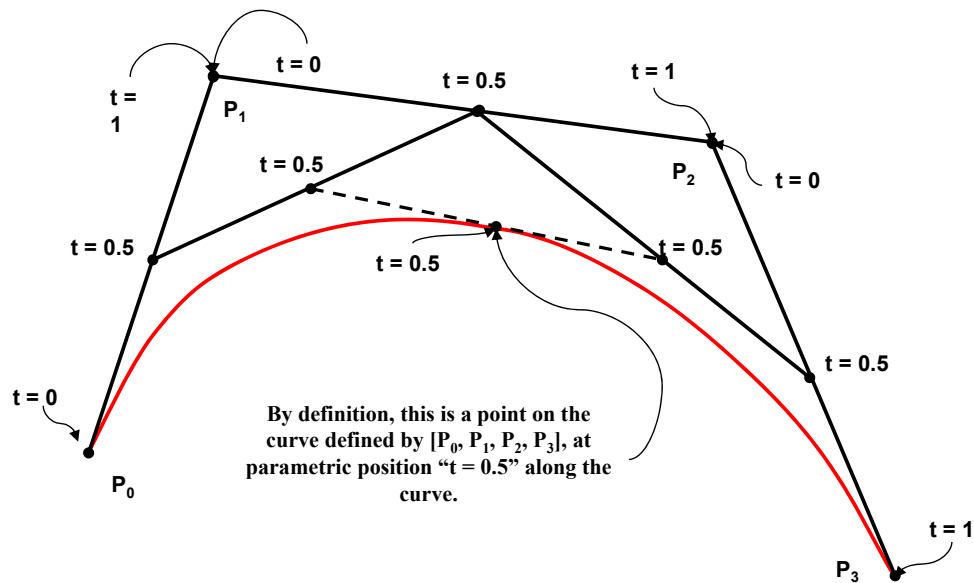
$$P(t) = (1-t)^2 \cdot P_0 + (-2t^2 + 2t) \cdot P_1 + (t^2) \cdot P_2$$

$$P(t) = \sum_{i=0}^2 P_i \cdot B_i(t), \text{ where } \begin{cases} B_0(t) = (1-t)^2 \\ B_1(t) = (-2t^2 + 2t) \\ B_2(t) = t^2 \end{cases}$$

- A point on the curve is a weighted sum of the three “control points”
  - The “weightings” are the quadratic polynomials, evaluated at “t”

# Cubic Bezier Curves

- Geometric description



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# Cubic Bezier Curves (cont.)

- Analytic definition

$$P_{01}(t) = t \cdot P_1 + (1-t) \cdot P_0$$

$$P_{12}(t) = t \cdot P_2 + (1-t) \cdot P_1$$

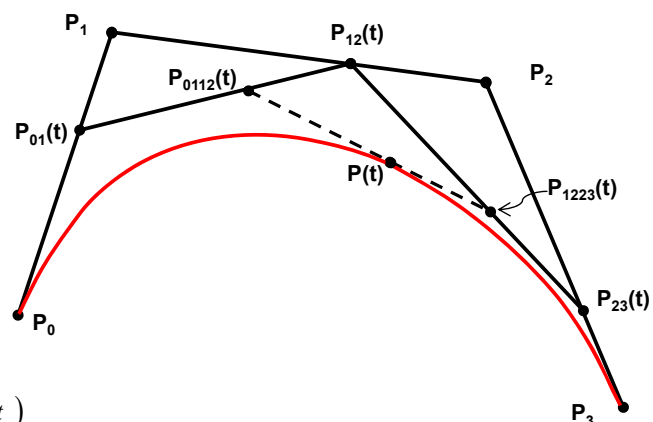
$$P_{23}(t) = t \cdot P_3 + (1-t) \cdot P_2$$

$$P_{0112}(t) = t \cdot P_{12}(t) + (1-t) \cdot P_{01}(t)$$

$$P_{1223}(t) = t \cdot P_{23}(t) + (1-t) \cdot P_{12}(t)$$

and a point on the curve  $[P_0 \ P_1 \ P_2 \ P_3]$  is defined as

$$P(t) = t \cdot (P_{1223}(t)) + (1-t) \cdot (P_{0112}(t))$$

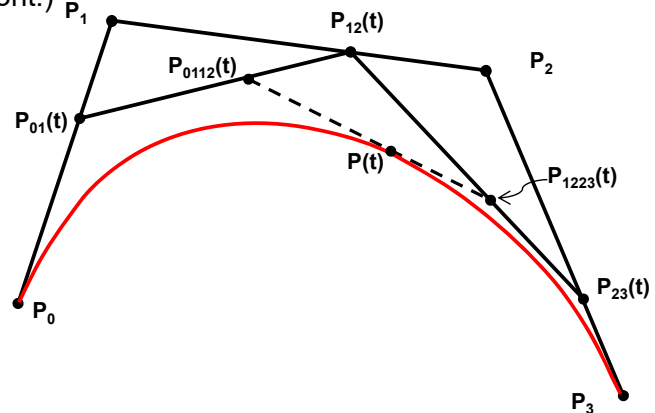


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# Cubic Bezier Curves (cont.)

- Analytic definition (cont.)



$$\begin{aligned}
 P(t) &= t \cdot (P_{1223}(t)) + (1-t) \cdot (P_{0112}(t)) \\
 &= \underline{(1-t)^3} \cdot P_0 + \underline{(3t^3 - 6t^2 + 3t)} \cdot P_1 + \underline{(-3t^3 + 3t^2)} \cdot P_2 + \underline{(t^3)} \cdot P_3 \\
 &= \sum_{i=0}^3 P_i \cdot B_{i,3}(t)
 \end{aligned}$$

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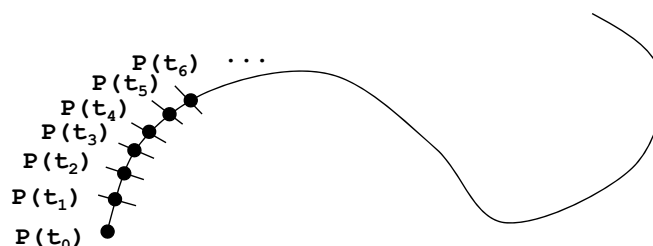
# Drawing Bezier Curves

- Iterative approach

```

moveTo (P(t0));
drawTo (P(t1));
drawTo (P(t2));
drawTo (P(t3));
...

```



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# Drawing Bezier Curves (cont.)

```

/** A routine to draw the (cubic) Bezier Curve represented by the (1x4) input
 * Control Point Array using iterative plotting along the curve and an explicit
 * computation which produces a weighted sum of control points for each new point.
 * Note: This is (Java-like) pseudo code, not real Java code.
 */

void drawBezierCurve (controlPointArray) {
    currentPoint = controlPointArray [0] ; // start drawing at first control point
    t = 0 ; // vary the parametric value "t" over the length of the curve
    while ( t<=1 ) {
        // compute next point on the curve as the sum of the Control Points, each
        // weighted by the appropriate polynomial evaluated at 't'.
        nextPoint = (0,0) ;
        for (int i=0; i<=3; i++) {
            nextPoint = nextPoint + ( blendingFunction(i,t) * controlPointArray[i] ) ;
        }
        drawLine (currentPoint,nextPoint);
        currentPoint = nextPoint;
        t = t + smallFloatIncrement;
    }
}

```

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# Drawing Bezier Curves (cont.)

```

/** Returns the value of the "ith" cubic Bernstein polynomial blending
 * function at parametric location 't'
 */

double blendingFunction (int i, double t) {
    switch (i) {
        case 0: return ( (1-t) * (1-t) * (1-t) ) ; //  $(1-t)^3$ 
        case 1: return ( 3 * t * (1-t) * (1-t) ) ; //  $3t(1-t)^2$ 
        case 2: return ( 3 * t * t * (1-t) ) ; //  $3t^2(1-t)$ 
        case 3: return ( t * t * t ) ; //  $t^3$ 
    }
}

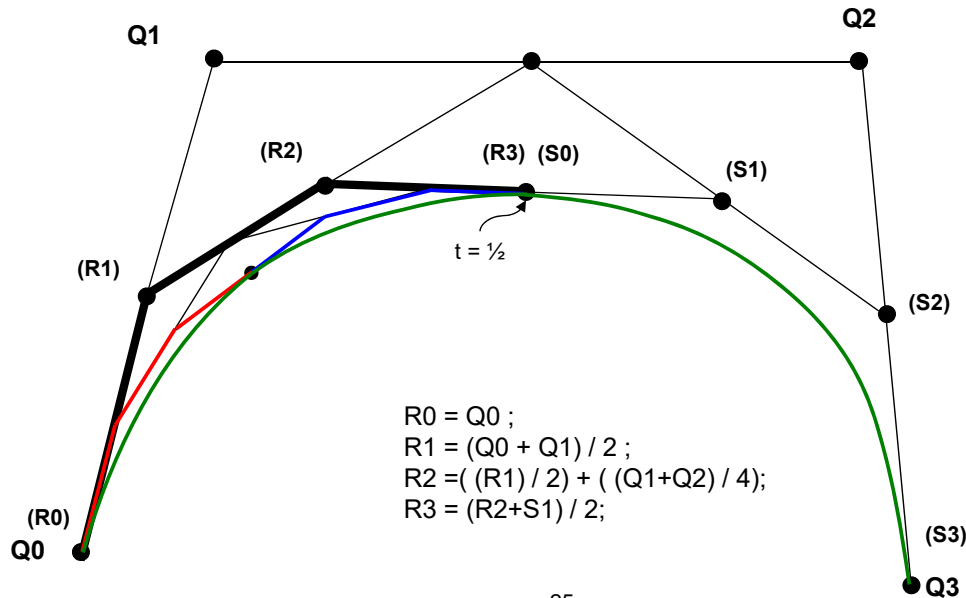
```

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# Control Mesh Subdivision

- Split the control mesh [Q] at  $t=1/2$ 
  - Produces two meshes [R] and [S]



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# Recursive Subdivision

```

/** Draws the (cubic) Bezier curve represented by the (1x4) input Control Point Vector
 * by recursively subdividing the Control Point Vector until the control points are
 * within some tolerance of being colinear, at which time the Control Points are deemed
 * "close enough" to the curve for the 1st and last control points to be used as the
 * ends of a line segment representing a short piece of the actual Bezier curve.
 * Note: This is (Java-like) pseudo code, not real Java code. */

```

```

void drawBezierCurve (ControlPointVector) {
    if ( straightEnough (ControlPointVector))
        Draw Line from 1st Control Point to last Control Point ;
    else {
        subdivideCurve (ControlPointVector, LeftSubVector, RightSubVector) ;
        drawBezierCurve (LeftSubVector) ;
        drawBezierCurve (RightSubVector) ;
    }
}

```

```

/** Splits the input control point vector Q into two control point
 * vectors R and S such that R and S define two Bezier curve segments that
 * together exactly match the Bezier curve defined by Q.
 */

```

```

void subdivideCurve (ControlPointVector Q,R,S) {
    R(0) = Q(0) ;
    R(1) = (Q(0)+Q(1)) / 2.0 ;
    R(2) = (R(1)/2.0) + (Q(1)+Q(2))/4.0 ;
    S(3) = Q(3) ;
    S(2) = (Q(2)+Q(3)) / 2.0 ;
    S(1) = (Q(1)+Q(2))/4.0 + S(2)/2.0 ;
    R(3) = (R(2)+S(1)) / 2.0 ;
    S(0) = R(3) ;
}

```

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# Recursive Subdivision (cont.)

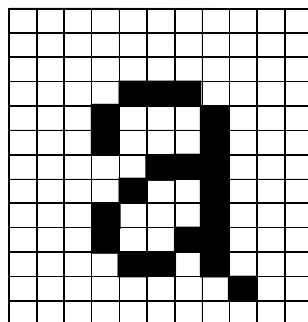
```

/** determines whether the four points Q0,Q1,Q2,Q3 in the input array of Control
 * Points are within some tolerance "epsilon" of being colinear.
 */
boolean straightEnough (ControlPointVector) {
    // find length around control polygon
    d1 = lengthOf(Q0,Q1) + lengthOf(Q1,Q2) + lengthOf(Q2,Q3);
    // find distance directly between first and last control point
    d2 = lengthOf(Q0,Q3) ;
    if ( abs(d1-d2) < epsilon )    // epsilon ("tolerance") = (e.g.) .001
        return true ;
    else
        return false ;
}

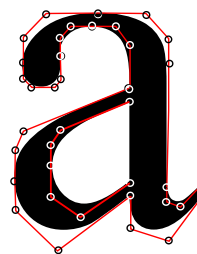
```

# Applications Of Curves

- Two types of “fonts”
  - Bit-mapped
  - Outline



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