



Distance = 27 cm
Distance = 49 cm
Distance = 26 cm
Distance = 23 cm
Distance = 22 cm
Distance = 74 cm
Distance = 23 cm
Distance = 22 cm
Distance = 28 cm
Distance = 26 cm
Distance = 25 cm
Distance = 26 cm
Distance = 23 cm
Distance = 23 cm
Distance = 23 cm

Send

Autoscroll Show timestamp

Newline 9600 baud Clear output

Showing 1 changed file with 25 additions and 0 deletions.

25 sketch_jun15a_ultrasound_ESP32_linux_v1.ino
1 +
2 + //https://lastminuteengineers.com/arduino-sr04-ultrasonic-sensor-tutorial/
3 + // Include NewPing Library
4 + #include "NewPing.h"
5 +
6 + // Hook up HC-SR04 with Trig to Arduino Pin 9, Echo to Arduino pin 10
7 + #define TRIGGER_PIN 32
8 + #define ECHO_PIN 34

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sketch_jun15a_ultrasound_ESP32_linux_v1 | Arduino 1.8.19 (as superuser)

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sketch_jun15a_ultrasound_ESP32_linux_v1

```
//https://lastminuteengineers.com/arduino-sr04-ultrasonic-sensor-tutorial/  
// Include NewPing Library  
#include "NewPing.h"  
  
// Hook up HC-SR04 with Trig to Arduino Pin 9, Echo to Arduino pin 10  
#define TRIGGER_PIN 32  
#define ECHO_PIN 34  
  
// Maximum distance we want to ping for (in centimeters).  
#define MAX_DISTANCE 400  
  
// NewPing setup of pins and maximum distance.  
NewPing sonar(TRIGGER_PIN, ECHO_PIN, MAX_DISTANCE);  
  
void setup() {  
  Serial.begin(9600);  
}  
  
void loop() {  
  Serial.print("Distance = ");  
  Serial.print(sonar.ping_cm());  
  Serial.println(" cm");  
  delay(500);  
}
```

Done uploading.

Writing at 0x00045b48... (88 %)
Writing at 0x0004b007... (100 %)
Wrote 261056 bytes (144683 compressed) at 0x00010000 in 2.3 seconds (effective 12800 bytes/sec)
Hash of data verified.

Leaving...
Hard resetting via RTS pin...

ESP32 (25MB SPIFFS), 240MHz (WiFi/BT), QIO, 80MHz, 4MB (32Mb), 921600, Core 1, Core 1, None, Disabled on /dev