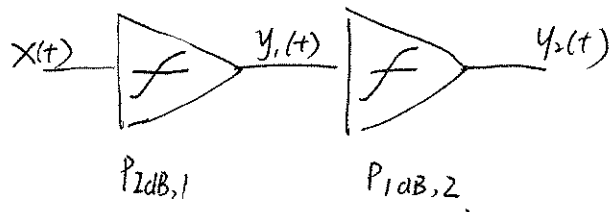




Behzad Razavi - RF Microelectronics Solution (2012)

전자회로I (고려대학교)

2-1 Solu:



$$Y_1(t) = \alpha_1 X(t) + \alpha_2 X^2(t) + \alpha_3 X^3(t)$$

$$Y_2(t) = \beta_1 Y_1(t) + \beta_2 Y_1^2(t) + \beta_3 Y_1^3(t)$$

then.

$$Y_2(t) = \beta_1 [\alpha_1 X(t) + \alpha_2 X^2(t) + \alpha_3 X^3(t)] + \beta_2 [\alpha_1 X(t) + \alpha_2 X^2(t) + \alpha_3 X^3(t)]^2 + \beta_3 [\alpha_1 X(t) + \alpha_2 X^2(t) + \alpha_3 X^3(t)]^3$$

Considering only the first - and third - order terms,

$$Y_2(t) = \alpha_1 \beta_1 X(t) + (\alpha_3 \beta_1 + 2\alpha_1 \alpha_2 \beta_2 + \alpha_1^3 \beta_3) X^3(t) + \dots$$

$$= [\alpha_1 \beta_1 + \frac{3}{4} (\alpha_3 \beta_1 + 2\alpha_1 \alpha_2 \beta_2 + \alpha_1^3 \beta_3) A] X(t) + \dots$$

$$P_{1dB,1} : A_{in,1dB} = \sqrt{0.145 \left| \frac{\alpha_1}{\alpha_3} \right|} ; P_{1dB,2} : A_{in,2dB} = \sqrt{0.145 \left| \frac{\beta_1}{\beta_3} \right|}$$

$$P_{1dB} \Rightarrow 20 \log \left| \alpha_1 \beta_1 + \frac{3}{4} (\alpha_3 \beta_1 + 2\alpha_1 \alpha_2 \beta_2 + \alpha_1^3 \beta_3) A_{in,1dB}^2 \right| = 20 \log |\alpha_1 \beta_1| - 1dB$$

$$A_{in,1dB} = \sqrt{0.145 \left| \frac{\alpha_1 \beta_1}{\alpha_3 \beta_1 + 2\alpha_1 \alpha_2 \beta_2 + \alpha_1^3 \beta_3} \right|}$$

Represented by the P_{1dB} of first and second stage.

$$\frac{1}{A_{in,1dB}^2} = \frac{1}{0.145} \left| \frac{\alpha_3}{\alpha_1} + \frac{2\alpha_2 \beta_2}{\beta_1} + \frac{\alpha_1^2 \beta_3}{\beta_1} \right|$$

$$= \left| \frac{1}{A_{in,1dB}^2} + \frac{2}{0.145} \frac{\alpha_2 \beta_2}{\beta_1} + \frac{\alpha_1^2}{A_{in,2dB}^2} \right|$$

2.2 Solve:

assuming -3 dBm A_1 at 2.42 GHz
 -35 dBm A_2 at 2.43 GHz .

$$\text{IM product} : \frac{3}{4} \gamma_3 A_1^2 A_2$$

$$-3 \text{ dBm} \Rightarrow A_1 = \sqrt{2.50 \cdot 10^{-0.3} \times 10^{-3}} = 223.9 \text{ mV}$$

$$-35 \text{ dBm} \Rightarrow A_2 = \sqrt{2.50 \times 10^{-3.5} \times 10^{-3}} = 5.6 \text{ mV}$$

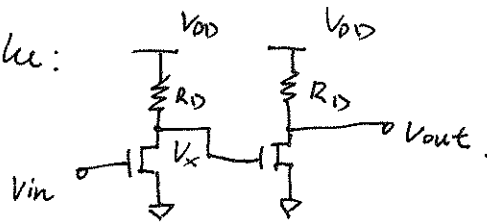
We can write at LNA output:

$$20 \lg |\gamma_1 \cdot A_{\text{sig}}| - 20 \text{ dB} = 20 \lg \left| \frac{3}{4} \gamma_3 A_1^2 A_2 \right|$$

$$\Rightarrow \lg |\gamma_1 \cdot A_{\text{sig}}| = \lg \left| \frac{30}{4} \gamma_3 A_1^2 A_2 \right|$$

$$\begin{aligned} \text{IIP}_3 &= \sqrt{\frac{4}{3} \left| \frac{\gamma_1}{\gamma_3} \right|} = \sqrt{\frac{4}{3} \cdot \frac{30}{4} \cdot \frac{A_1^2 \cdot A_2}{A_{\text{sig}}}} = 9.43 \text{ V}_p \\ &= 29.5 \text{ dBm} \end{aligned}$$

2.3 solve:



$$I_D = K \cdot (V_{GS} - V_T)^2$$

$$V_{out} = V_{DD} - K \cdot R_D (V_x - V_T)^2$$

$$V_x = V_{DD} - K \cdot R_D (V_{in} - V_T)^2$$

$$V_{out} = V_{DD} - K \cdot R_D [V_{DD} - K \cdot R_D (V_{in} - V_T)^2 - V_T]^2$$

$$= V_{DD} - K \cdot R_D [(V_{DD} - V_T) - K \cdot R_D (V_{in} - V_T)^2]^2$$

$$= V_{DD} - K \cdot R_D [(V_{DD} - V_T)^2 + K^2 R_D^2 (V_{in} - V_T)^4 - 2 K R_D (V_{DD} - V_T) (V_{in} - V_T)^2]$$

1st order of V_{in}

$$\Rightarrow [4 \cdot (V_{DD} - V_T) \cdot K \cdot R_D V_T - 4 K^2 R_D^2 V_T^3] \cdot V_{in}$$

3rd order of V_{in}

$$\Rightarrow [-4 K^2 R_D^2 V_T] \cdot V_{in}^3$$

$$A_{IP3} = \sqrt{\frac{4}{3} \cdot \frac{4 \cdot (V_{DD} - V_T) K \cdot R_D V_T - 4 K^2 R_D^2 V_T^3}{4 K^2 R_D^2 V_T}}$$

2.4. Solu.

$$y(t) = \partial_1 x(t) + \partial_2 x^2(t) + \partial_3 x^3(t) + \partial_4 x^4(t) + \partial_5 x^5(t).$$

$$1^\circ \cos^3 \omega t = \frac{3}{4} \cos \omega t + \frac{1}{4} \cos 3\omega t.$$

$$2^\circ \cos^2 \omega t = \frac{1 + \cos 2\omega t}{2}$$

$$3^\circ \cos^4 \omega t = \frac{1 + \cos^2 2\omega t + 2\cos 2\omega t}{2^2}$$

$$4^\circ \cos^5 \omega t = \left(\frac{3}{4} \cos \omega t + \frac{1}{4} \cos 3\omega t \right) \cdot \left(\frac{1 + \cos 2\omega t}{2} \right)$$

$$= \left(\frac{3}{8} \cos \omega t + \frac{1}{8} \cos 3\omega t + \frac{3}{8} \cos \omega t \cdot \cos 2\omega t + \frac{1}{8} \cos 3\omega t \cdot \cos 2\omega t \right)$$

$$\frac{3}{16} [\cos \omega t + \cos 3\omega t] + \frac{1}{16} [\cos \omega t + \cos 5\omega t]$$

1st order $\Rightarrow \partial_1 A + \frac{3}{4} \partial_3 A^3 + \left(\frac{3}{8} + \frac{3}{16} + \frac{1}{16} \right) \partial_5 A^5.$

3rd order

$$\Rightarrow \frac{1}{4} \partial_3 A^3 + \left(\frac{1}{8} + \frac{3}{16} \right) \partial_5 A^5.$$

$$(1) P_{1dB} \Rightarrow 20 \lg |\partial_1 + \frac{3}{4} \partial_3 A^2 + \frac{5}{8} \partial_5 A^4| = 20 \lg |\partial_1| - 1 \text{ dB}.$$

$$\Rightarrow A_{in, 1dB} = \sqrt{\frac{0.8 \cdot (0.5625 \partial_3^2 - 0.27175 \partial_1 \cdot \partial_5) \pm 0.6 \partial_3}{\partial_5}}.$$

(2) IIP_3 doesn't change.

$$A_{IIP3} = \sqrt{\frac{4}{3} \left| \frac{\partial_1}{\partial_3} \right|}.$$

2.5(a) Solu: $A_{sig} = \frac{0.1mV}{\sqrt{0.7943}} \Leftrightarrow -2dB = 10^{-0.1} = 0.7943$

$A_2 = 10mV \times 0.1413 \Leftrightarrow -17dB = 10^{-0.85} = 0.1413$

$A_3 = 10mV \times 0.0141 \Leftrightarrow -37dB = 10^{-1.85} = 0.0141$

at the output of amplifier:

$$20 \log |\sigma_1 \cdot A_{sig}| - 20dB = 20 \log \left| \frac{3}{4} \sigma_3 \cdot A_2^2 \cdot A_3 \right|$$

$$\Rightarrow |\sigma_1 \cdot 0.07943m| = \left| \frac{3}{4} \sigma_3 \cdot 1.413m^2 \cdot 0.141m \right|$$

$$\therefore A_{IP3} = \sqrt{\frac{\frac{3}{4} \cdot 1.413m^2 \cdot 0.141}{0.07943} \cdot \frac{4}{3}} = 5.95mV_p = -34.5dBm$$

Neglect the nonlinearity of BPF.

(b). $y_1(t) = \sigma_1 x(t) + \sigma_3 x^3(t)$

$$y_2(t) = \beta_1 y_1(t) + \beta_3 y_1^3(t)$$

Only considering the first and third order:

$$y_2(t) = \sigma_1 \beta_1 x(t) + (\sigma_3 \beta_1 + \sigma_1^3 \beta_3) x^3(t) + \dots$$

$$\therefore A_{IP3} = \sqrt{\frac{\frac{4}{3} \left| \frac{\sigma_1 \beta_1}{\sigma_3 \beta_1 + \sigma_1^3 \beta_3} \right|}{1}}$$

$$\frac{1}{A_{IP3}^2} = \frac{1}{A_{IP3,1}^2} + \frac{\sigma_1^2}{A_{IP3,2}^2}$$

$$\Rightarrow \frac{1}{A_{IP3}^2} = \frac{1}{500m^2} + \frac{10}{5.95m^2}$$

$$\Rightarrow A_{IP3} = 1.875mV_p$$

2.6 Solu:

Let $x(t)$ be a random signal (wide-sense stationary process)

Auto correlation function: $R_x(\tau) = E[x(t) \cdot x(t+\tau)]$

Let me prove that: $S_x(f) = \int_{-\infty}^{\infty} R_x(\tau) e^{-j2\pi f\tau} d\tau$

$$\text{Proof: } X_T(f) \triangleq \int_{-T/2}^{T/2} x(t) e^{-j2\pi ft} dt$$

$$S_T(f) \triangleq E\left[\frac{1}{T} |X_T(f)|^2\right]$$

$$S_x(f) = \lim_{T \rightarrow \infty} S_T(f)$$

$$\begin{aligned} E[|X_T(f)|^2] &= E\left[\int_{-T/2}^{T/2} x(t) e^{-j2\pi ft} dt \int_{-T/2}^{T/2} x(\tau) e^{-j2\pi f\tau} d\tau\right]^2 \\ &= E\left[\int_{-T/2}^{T/2} x(t) e^{-j2\pi ft} dt \cdot \int_{-T/2}^{T/2} x(\tau) e^{-j2\pi f\tau} d\tau\right] \\ &= E\left[\int_{-T/2}^{T/2} \int_{-T/2}^{T/2} x(t)x(\tau) e^{-j2\pi f(t-\tau)} dt d\tau\right] \\ &= \int_{-T/2}^{T/2} \int_{-T/2}^{T/2} E[x(t)x(\tau)] e^{-j2\pi f(t-\tau)} dt d\tau \\ &= \int_{-T/2}^{T/2} \int_{-T/2}^{T/2} R_x(t-\tau) e^{-j2\pi f(t-\tau)} dt d\tau \\ &= \int_{-T}^T (T-|\tau|) R_x(\tau) e^{-j2\pi f\tau} d\tau \end{aligned}$$

$$E\left[\frac{1}{T} |X_T(f)|^2\right] = \int_{-T}^T \left(1 - \frac{|\tau|}{T}\right) R_x(\tau) e^{-j2\pi f\tau} d\tau$$

$$\text{Therefore: } S_x(f) = \lim_{T \rightarrow \infty} E\left[\frac{1}{T} |X_T(f)|^2\right] = \int_{-\infty}^{\infty} R_x(\tau) e^{-j2\pi f\tau} d\tau$$

2.7. Solu:

Assume $y(t) = \sigma_1 x(t) + \sigma_2 x^2(t) + \sigma_3 x^3(t)$.

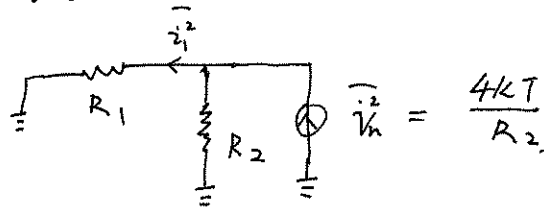
$$x(t) = V_0 \cos \omega_0 t.$$

3rd - harmonic : $\frac{\sigma_3 V_0^3}{4} = V_3$

$$\Rightarrow \sigma_3 = \frac{4V_3}{V_0^3}$$

$$\begin{aligned} A_{in, 1dB} &= \sqrt{0.145 \left| \frac{\sigma_1}{\sigma_3} \right|} \\ &= \sqrt{0.145 \cdot \left| \frac{\sigma_1}{4V_3/V_0^3} \right|} \\ &= \sqrt{\frac{0.145}{4} \left| \frac{\sigma_1 V_0^3}{V_3} \right|}. \end{aligned}$$

2.8 soln:



$$\begin{aligned}
 P_{R_1} &= i_1^2 \cdot R_1 \\
 &= \left(\sqrt{\frac{4kT}{R_2}} \cdot \frac{R_2}{R_1 + R_2} \right)^2 \cdot R_1 \\
 &= \frac{4kT}{(R_1 + R_2)^2} \cdot R_1 R_2
 \end{aligned}$$

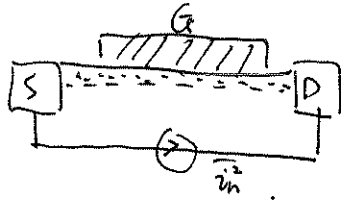
$$\therefore P_{R_1} = P_{R_2}$$

So it proves that the noise power delivered by R_1 to R_2 is equal to that delivered by R_2 to R_2 at the same temperature.

\therefore If it is not the truth, the energy would not be conserved.

2.9 Solu:

Why the channel thermal noise of a MOSFET is model by a current source bw. S & D. rather than G & D.



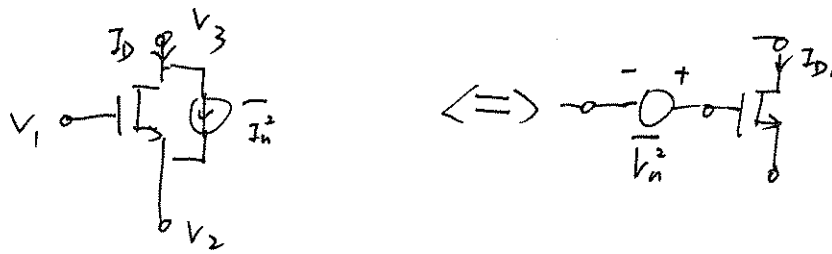
Firstly, from the figure we can find the channel

resistor is between source & drain. As a result, it is reasonable to model the noise by a current source between source and drain.

Secondly, MOSFET has the function of transconductance.

It's easy to transfer the current source from between S & D to the voltage source at the gate.

2.10 Solu:



Proof: transconductance : g_m .

Assume the transistor is in saturation region.

For small-signal analysis, $V_1 = 0$

$$I_D = \sqrt{\bar{I}_n^2} = \sqrt{4KT\gamma g_m}.$$

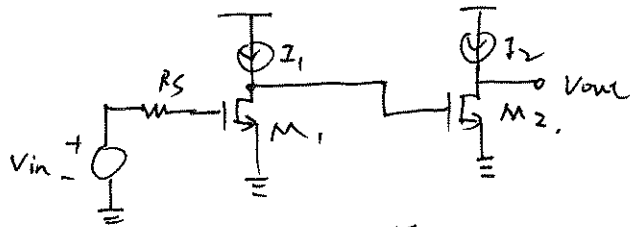
At the same time, for voltage source model.

$$I_D = V_{in} \cdot g_m = \sqrt{4KT\gamma g_m}$$

$$\Rightarrow V_{in} = \sqrt{\frac{4KT\gamma}{g_m}}.$$

$$\Rightarrow \bar{V}_n^2 = \frac{4KT\gamma}{g_m}.$$

2.11 Solu:



$$NF_1 = 1 + \frac{r}{g_{m1}R_S} \quad (2.122)$$

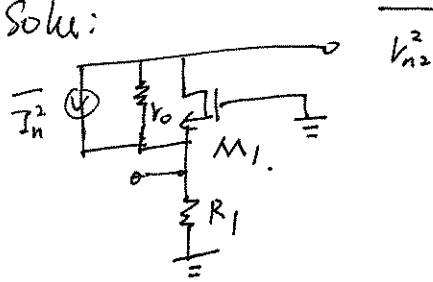
$$NF_2 = 1 + \frac{r}{g_{m2}r_{o1}} \quad ; \quad A_{p1} = \frac{P_{out,av,1}}{P_{in,av,1}} = \frac{V_{in}^2 \cdot A_{v1}^2 \cdot \frac{1}{4r_{o1}}}{V_{in}^2 \cdot \frac{1}{4R_S}}$$

$$\therefore NF_{tot} = 1 + (NF_1 - 1) + \frac{NF_2 - 1}{A_{p1}} = g_{m1}^2 \cdot r_{o1} \cdot R_S$$

$$= 1 + \frac{r}{g_{m1}R_S} + \frac{r}{g_{m2} \cdot r_{o1}} \cdot \frac{1}{g_{m1}^2 r_{o1} R_S}$$

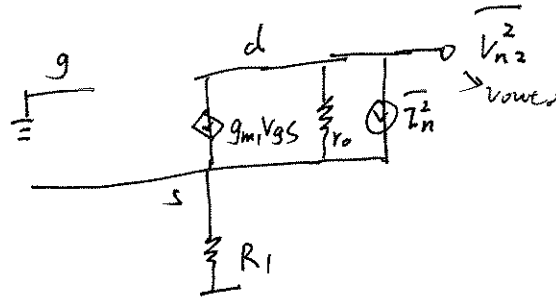
$$= 1 + \frac{r}{g_{m1}R_S} + \frac{r}{g_{m1}^2 r_{o1}^2 g_{m2} \cdot R_S}$$

2.12. Solu:



assume I_n is ideal, and neglect the noise of R_1 .

Proof:



For small-signal analysis,

$$g_m(-V_s) + \frac{V_{out} - V_s}{r_o} + I_n = \frac{V_s}{R_1}$$

Because we cannot find any loop for the current through R_1 ,

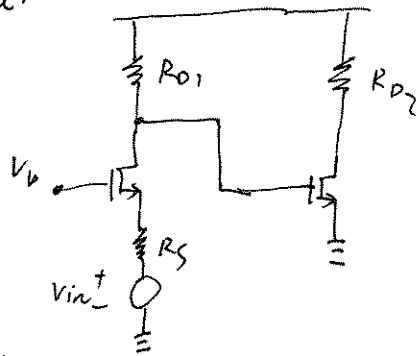
$$V_s = 0$$

$$\Rightarrow \frac{V_{out}}{r_o} = -I_n$$

$$V_{out} = -I_n \cdot r_o$$

$$\therefore \overline{v_{n2}^2} = \overline{I_n^2} \cdot r_o^2$$

2.13. Solu:



Neglect. transistor cap.
flicker noise.
CLM.
body effect.

For 1st stage:

$$R_{in1} = \frac{1}{g_{m1}}, \quad R_{th2} = \infty,$$

$$\overline{V_{n1}^2} = 4kTR_{D1} + \frac{4kT\gamma}{g_{m1}} \left(\frac{R_{D1}}{\frac{1}{g_{m1}} + R_S} \right)^2 \Leftarrow \text{unloaded output noise.}$$

For 2nd stage:

$$\overline{V_{n2}^2} = 4kTR_{D2} + 4kT\gamma \cdot g_{m2} \cdot R_{D2}^2.$$

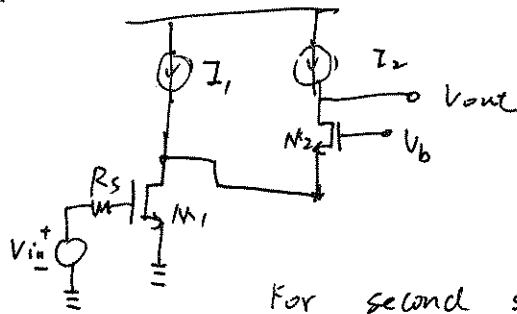
We now substitute these values in Eq. (2.126)

$$NF_{tot} = 1 + \frac{4kTR_{D1} + \frac{4kT\gamma}{g_{m1}} \left(\frac{R_{D1}}{\frac{1}{g_{m1}} + R_S} \right)^2}{\left(\frac{\frac{1}{g_{m1}}}{\frac{1}{g_{m1}} + R_S} \right)^2 (g_{m1} \cdot R_{D1})^2} \cdot \frac{1}{4kTR_S} + \frac{4kTR_{D2} + 4kT\gamma \cdot g_{m2} \cdot R_{D2}^2}{\left(\frac{\frac{1}{g_{m1}}}{\frac{1}{g_{m1}} + R_S} \right)^2 (g_{m1} \cdot R_{D1})^2 \cdot (g_{m2} \cdot R_{D2})^2} \cdot \frac{1}{4kTR_S}.$$

This result is different from the CS + CG configuration because, the first stage's NF and input impedance are different, which affect the NF_{tot} .

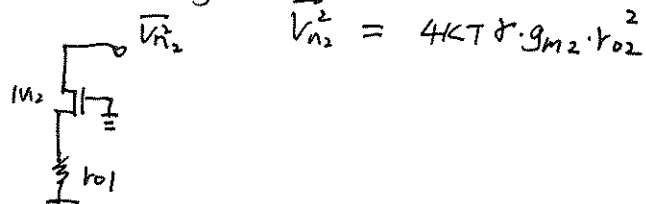
2.14. Solu:

Consider CLM.



$$\begin{aligned}\overline{V_{n1}^2} &= \frac{4KT\gamma}{g_{m1}} \cdot (g_{m1}r_{o1})^2 \\ &= 4KT\gamma \cdot g_{m1}r_{o1}^2\end{aligned}$$

For second stage:

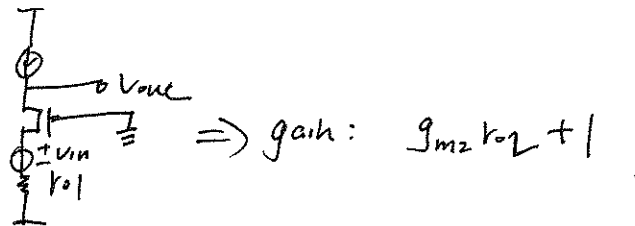


$$\overline{V_{n2}^2} = 4KT\gamma \cdot g_{m2}r_{o2}^2$$

We now substitute these values in Eq. (126).

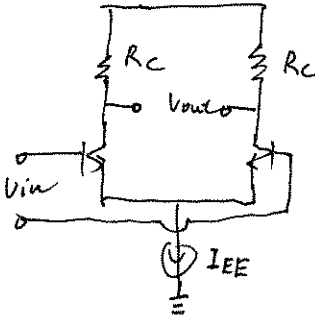
$$\begin{aligned}NF_{tot} &= 1 + \frac{4KT\gamma \cdot g_{m1}r_{o1}^2}{(g_{m1}r_{o1})^2} \cdot \frac{1}{4KTR_S} \\ &\quad + \frac{4KTR_S g_{m2}r_{o2}^2}{(g_{m1}r_{o1})^2 \cdot \left(\frac{1}{\frac{g_{m2}}{g_{m2}+r_{o1}}}\right)^2 \cdot (g_{m2}r_{o2}+1)^2} \cdot \frac{1}{4KTR_S}\end{aligned}$$

Note:



2.15 solve:

IP3.



$$\tanh x = x - \frac{x^3}{3} + \frac{2x^5}{15} - \dots$$

$$V_{out} = -2R_c I_{EE} \tanh \left[\frac{V_{in}}{2V_T} \right]$$

Only consider the first and third order.

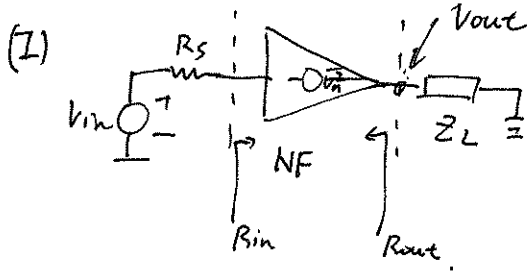
$$V_{out} = -2R_c I_{EE} \left(\frac{V_{in}}{2V_T} - \frac{1}{3} \left(\frac{V_{in}}{2V_T} \right)^3 \right)$$

$$A_{in, IP3} = \sqrt{\frac{4}{3} \left| \frac{\partial^2}{\partial^3} \right|}$$

$$= \sqrt{\frac{4}{3} \cdot \frac{\frac{1}{2V_T}}{\frac{1}{3} \left(\frac{1}{2V_T} \right)^3}}$$

$$= 4V_T = 4 \frac{kT}{q} = 4 \times 26 \text{ mV} = 104 \text{ mV}$$

2.16 Solu:



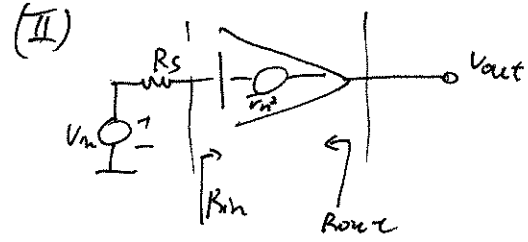
$$\frac{v_{out}}{v_{in}} = A_0 \frac{Z_L}{Z_L + R_{out}}$$

$$\overline{v_{n,out}^2} = \overline{v_n^2} \cdot \left(\frac{Z_L}{Z_L + R_{out}} \right)^2$$

$$NF = 1 + \frac{\overline{v_{n,out}^2}}{\frac{v_{out}}{v_{in}}}$$

$$= 1 + \frac{A_0^2 \overline{v_n^2} \left(\frac{Z_L}{Z_L + R_{out}} \right)^2}{A_0^2 \left(\frac{Z_L}{Z_L + R_{out}} \right)^2} \cdot \frac{1}{4kTR_S}$$

$$= 1 + \frac{\overline{v_n^2}}{A_0^2} \cdot \frac{1}{4kTR_S}$$

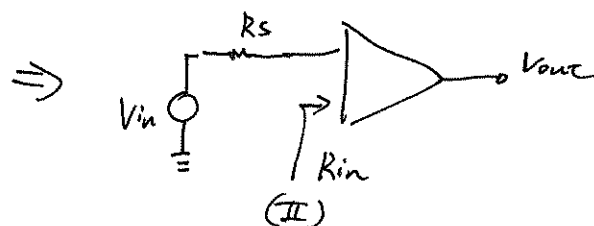
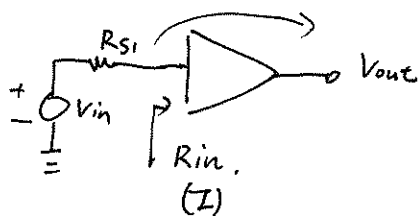


$$NF = 1 + \frac{\overline{v_n^2}}{A_0^2} \times \frac{1}{4kTR_S} \quad \left(\text{unloaded gain} \right)$$

unloaded noise at output.

Compared with (I) and (II), we find noise figures of two situations are the same. i.e. output load doesn't affect the circuit's noise figure.

2.17 Solu: A_v



A_v is unloaded voltage gain from input to output of amplifier.

\therefore In Figure (I),

$$NF_1 = 1 + \frac{\overline{V_n^2}}{\left(\frac{R_{in}}{R_{in} + R_{S1}}\right)^2 \cdot A_v^2} \cdot \frac{1}{4kTR_{S1}} \quad (1)$$

In Figure (II)

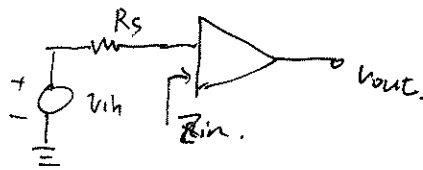
$$NF_2 = 1 + \frac{\overline{V_n^2}}{\left(\frac{R_{in}}{R_{in} + R_{S2}}\right)^2 \cdot A_v^2} \cdot \frac{1}{4kTR_{S2}} \quad (2)$$

$$\frac{(1)}{(2)} \Rightarrow \frac{NF_1 - 1}{NF_2 - 1} = \frac{R_{S2}}{R_{S1}} \cdot \left(\frac{R_{in} + R_{S2}}{R_{in} + R_{S1}}\right)^2$$

So if we know the input impedance and R_{S1} , R_{S2} , it's possible to compute the noise figure for another source impedance R_{S2} .

2.18 soln:

$$NF = \frac{1}{g_m R_s} + 1 \quad \text{Eq. (2.122)}$$



$$\sigma = \frac{Z_{in}}{Z_{in} + R_s} ; \overline{V_{RS}^2} = 4kTR_s$$

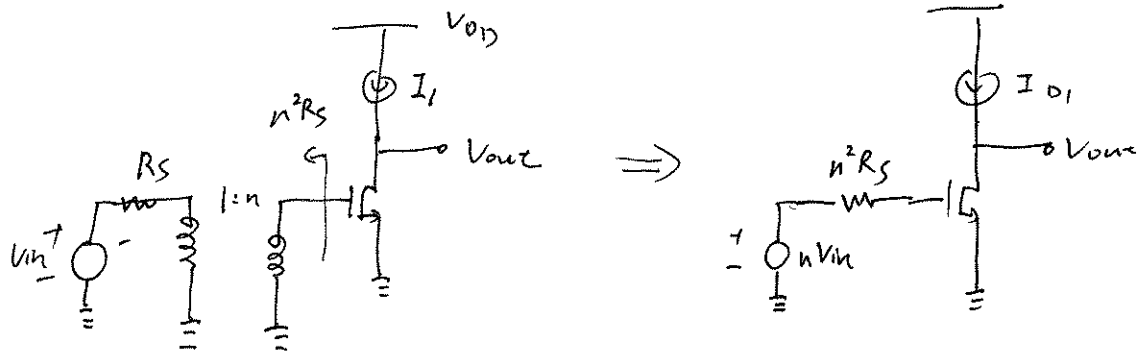
$$SNR_{in} = \frac{V_{in}^2}{\overline{V_{RS}^2}}$$

$$SNR_{out} = \frac{V_{in}^2 |\sigma|^2 A_v^2}{\overline{V_{RS}^2} |\sigma|^2 A_v^2 + \overline{V_n^2}}$$

So, if R_s increases, SNR_{out} will fall.

It seems that the result is contradicted with NF 's falling. Because SNR_{in} will also fall if R_s increases, the ratio of SNR_{in} and SNR_{out} is reasonable.

2.19 Solu:



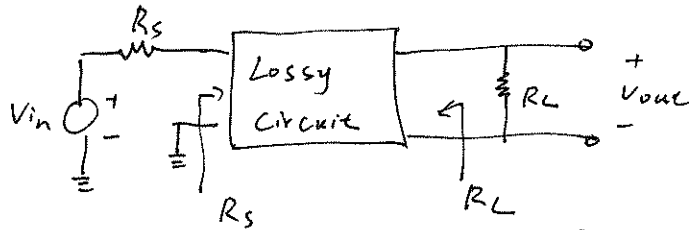
$$\overline{V_n^2} = 4kT \gamma \cdot g_m r_o^2$$

$$A = \frac{V_{out}}{V_{in}} = n \cdot g_m r_o$$

$$\begin{aligned} \therefore NF &= 1 + \frac{4kT \gamma \cdot g_m r_o^2}{(n \cdot g_m r_o)^2} \cdot \frac{1}{4kT n^2 R_S} \\ &= 1 + \frac{1}{n^4 g_m R_S} \end{aligned}$$

From the result, we can find transformer improves the noise performance of Amplifier greatly.

2.20 Solu:



$$\text{Proof: } L = \frac{P_{in}}{P_{out}} = \frac{\frac{V_{in}^2}{4R_s}}{\frac{V_{out}^2}{R_L}} = \frac{V_{in}^2}{4R_s} \cdot \frac{R_L}{V_{out}^2} = \frac{R_L}{4R_s} \cdot \frac{V_{in}^2}{V_{out}^2}$$

Theorem: For a passive (reciprocal) network, the PSD of thermal noise is given by $\overline{V_n^2} = 4KT \operatorname{Re}\{Z_{out}\}$

$$\overline{V_{n,out}^2} = 4KT \cdot R_L \left(\frac{1}{2}\right)^2 \text{ — all the noise} \quad (1)$$

$$A_v = \frac{V_{out}}{V_{in}} \quad (2)$$

$$\begin{aligned} \therefore NF &= \frac{(1)}{(2)^2} = \frac{4KT \cdot R_L \cdot \frac{1}{4}}{\frac{V_{out}^2}{V_{in}^2}} \cdot \frac{1}{4KTR_s} = \frac{R_L}{4R_s} \cdot \frac{V_{in}^2}{V_{out}^2} \\ &= L \end{aligned}$$

2.21. Solu: Neglect CLM & Body effect.

$$(a) \overline{V_{n,out}^2} = \frac{4kT\gamma}{g_{m1}} \left(\frac{g_{m1}}{g_{m2}} \right)^2 + 4kT\gamma \cdot g_{m2}$$

$$\left| \frac{V_{out}}{V_{in}} \right| = \frac{g_{m1}}{g_{m2}}$$

$$NF = 1 + \frac{\overline{V_{n,out}^2}}{\left(\frac{V_{out}}{V_{in}} \right)^2 \cdot 4kTR_S}$$

$$= 1 + 4kT\gamma \left(\frac{1}{g_{m1}} + \frac{g_{m2}^3}{g_{m1}^3} \right) \cdot \frac{1}{4kTR_S}$$

$$(d) \overline{V_{n,out}^2} = \frac{4kT\gamma}{g_{m2}} \left(\frac{g_{m2}}{g_{m3}} \right)^2 + 4kT\gamma \cdot g_{m3} + \frac{4kT\gamma}{g_{m1}} \left(\frac{g_{m1}}{g_{m3}} \right)^2$$

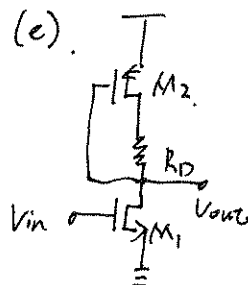
$$\left| \frac{V_{out}}{V_{in}} \right| = \frac{g_{m2}}{g_{m3}}$$

$$NF = 1 + 4kT\gamma \left(\frac{1}{g_{m2}} + \frac{g_{m3}^3}{g_{m2}^3} + \frac{1}{g_{m1}} \cdot \frac{g_{m1}^2}{g_{m2}^2} \right) \cdot \frac{1}{4kTR_S}$$

$$(b) \overline{V_{n,out}^2} = \frac{4kT\gamma}{g_{m1}} \left(\frac{g_{m1}}{g_{m3}} \right)^2 + 4kT\gamma \cdot g_{m3} + \frac{4kT\gamma}{g_{m2}} \left(\frac{g_{m2}}{g_{m3}} \right)^2$$

$$\left| \frac{V_{out}}{V_{in}} \right| = \frac{g_{m1}}{g_{m3}}$$

$$NF = 1 + 4kT\gamma \left(\frac{1}{g_{m1}} + \frac{g_{m3} \cdot g_{m2}^2}{g_{m3}^2} + \frac{1}{g_{m2}} \cdot \frac{g_{m2}^2}{g_{m1}^2} \right) \cdot \frac{1}{4kTR_S}$$



$$\left| \frac{V_{out}}{V_{in}} \right| = \frac{g_{m1}}{g_{m2}}$$

$$\overline{V_{n,out}^2} = \frac{4kT\gamma}{g_{m1}} \left(\frac{g_{m1}}{g_{m2}} \right)^2 + 4kT\gamma R_D$$

$$+ \frac{4kT\gamma}{g_{m2}} \Rightarrow M2's \text{ contribution.}$$

$$(c) \overline{V_{n,out}^2} = \frac{4kT\gamma}{g_{m1}} \left(\frac{g_{m1}}{g_{m3}} \right)^2 + \frac{4kT\gamma}{g_{m2}} \left(\frac{g_{m2}}{g_{m3}} \right)^2 + 4kT\gamma \cdot g_{m3}$$

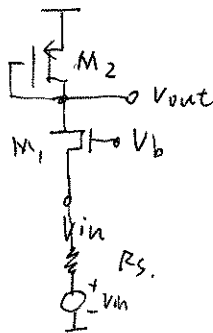
$$\left| \frac{V_{out}}{V_{in}} \right| = \frac{g_{m1}}{g_{m3}}$$

$$NF = 1 + 4kT\gamma \left(\frac{1}{g_{m1}} + \frac{1}{g_{m2}} \cdot \frac{g_{m2}^2}{g_{m1}^2} + \frac{g_{m3}^3}{g_{m1}^3} \right) \cdot \frac{1}{4kTR_S}$$

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2.22 Part 1 Solu:

(a)



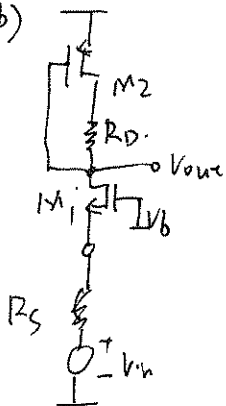
$$\overline{V_{n,out}^2} = 4KT R_S g_{m2} + \frac{4KT \gamma}{g_{m1}} \left(\frac{1}{R_S g_{m2}} \right)^2$$

$$\left| \frac{V_{out}}{V_{in}} \right| = \frac{1}{R_S g_{m2}}$$

$$NF = 1 + 4KT \gamma \left(g_{m2} R_S g_{m2}^2 + \frac{1}{g_{m1}} \right) \cdot \frac{1}{4KT R_S}$$

$$= 1 + \frac{\gamma}{R_S} \left(R_S^2 g_{m2}^3 + \frac{1}{g_{m1}} \right)$$

(b)



noise by M2 :

$$4KT \gamma / g_{m2}$$

noise by RD :

$$4KT R_D$$

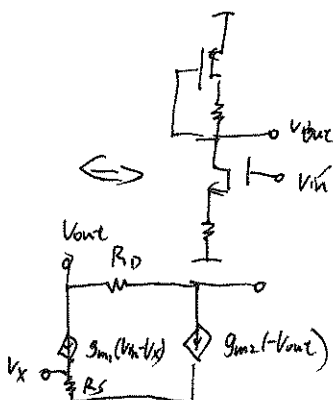
noise by M1 :

$$\frac{V_{out}}{V_{in}} = \frac{g_{m1}}{g_{m2} + g_{m1} g_{m2} R_S}$$

$$\frac{4KT \gamma}{g_{m1}} \left(\frac{V_{out}}{V_{in}} \right)^2$$

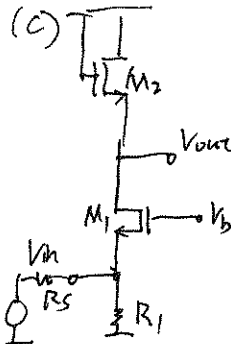
gain of circuit

$$\frac{V_{out}}{V_{in}} = - \frac{g_{m1}}{g_{m2}}$$



$$NF = 1 + 4KT \left[\frac{\gamma}{g_{m2}} + R_D + \frac{\gamma g_{m1}}{(g_{m2} + g_{m1} g_{m2} R_S)^2} \right]$$

$$\times \frac{1}{4KT R_S} \times \frac{g_{m2}^2}{g_{m1}^2}$$



$$\text{noise of } M2 : \frac{4KT \gamma}{g_{m2}} \quad (1)$$

$$\text{noise of } M1 : \frac{4KT \gamma}{g_{m1}} \left(\frac{1}{R_S g_{m2}} \right)^2 \quad (2)$$

noise of R_1 :

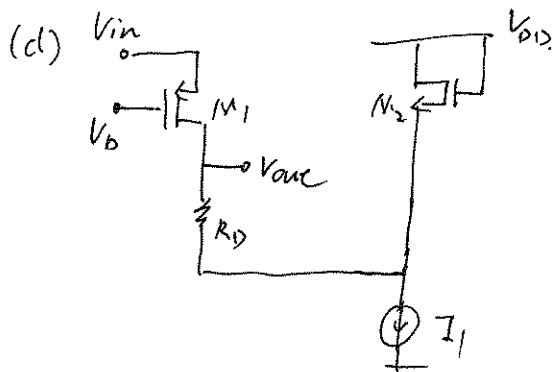
$$4KT R_1 \left(\frac{g_{m1}^{-1}}{R_S + g_{m1}^{-1}} \right)^2 \left(\frac{1}{R_S g_{m2}} \right)^2 \quad (3)$$

$$NF = 1 + \frac{(1) + (2) + (3)}{A_v} \frac{1}{4KT R_S}$$

Note :

$$A_v = \frac{R_1 \parallel \frac{1}{g_{m1}}}{R_S + R_1 \parallel \frac{1}{g_{m1}}} \cdot \frac{1}{R_1 \parallel R_S g_{m2}}$$

2.22 Part 2. Solu:



$$\left| \frac{V_{out}}{V_{in}} \right| = \frac{g_{m1}}{R_D + \frac{1}{g_{m2}}}$$

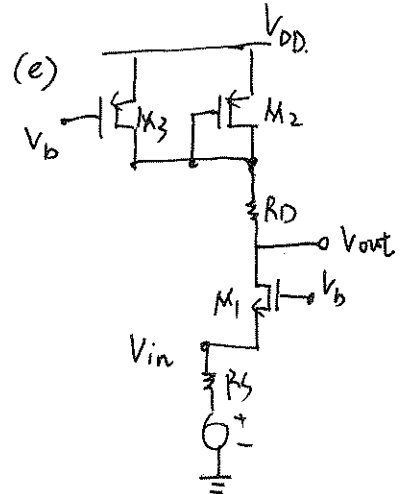
noise of R_D : $4KT R_D$ ①

noise of M_2 : $\frac{4KT\gamma}{g_{m2}}$ ②

noise of M_1 :

$\frac{4KT\gamma}{g_{m1}} \cdot \left(\frac{R_D + \frac{1}{g_{m2}}}{R_S} \right)^2$ ③

$$NF = 1 + \frac{① + ② + ③}{\left| \frac{g_{m1}}{R_D + \frac{1}{g_{m2}}} \right|^2} \times \frac{1}{4KTR_S}$$



$$\left| \frac{V_{out}}{V_{in}} \right| = \frac{R_D + \frac{1}{g_{m2}}}{R_S}$$

noise of R_D : $4KT R_D$ ①

noise of M_1 :

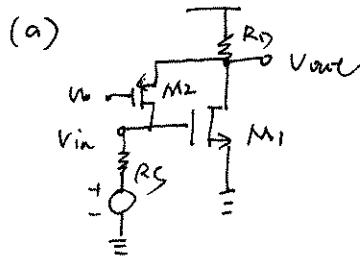
$\frac{4KT\gamma}{g_{m1}} \cdot \left(\frac{R_D + \frac{1}{g_{m2}}}{R_S} \right)^2$ ②

noise of M_2 : $\frac{4KT\gamma}{g_{m2}}$ ③

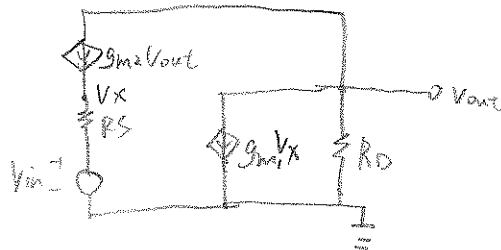
noise of M_3 : $\frac{4KT\gamma}{g_{m3}} \cdot \left(\frac{g_{m3}}{g_{m2}} \right)^2$ ④

$$NF = 1 + \frac{① + ② + ③ + ④}{\left(\frac{R_D + \frac{1}{g_{m2}}}{R_S} \right)^2} \cdot \frac{1}{4KTR_S}$$

part ①
2.23 solu:



Through small-signal analysis,

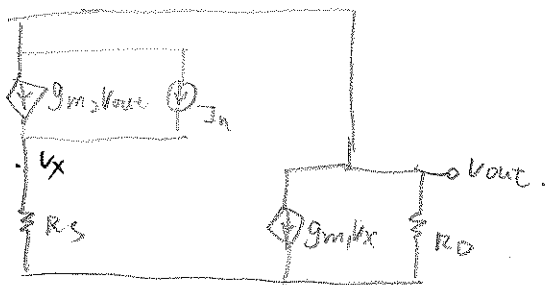


$$\Rightarrow \frac{V_{out}}{V_{in}} = - \frac{g_{m1}}{g_{m2} + \frac{1}{R_D} + g_{m1}g_{m2}R_S}$$

noise from $R_D = 4KT R_D$ ①

noise from M_1 : $\frac{4KT \cdot g_{m1}}{g_{m2} + g_{m1}g_{m2}R_S + \frac{1}{R_D}}$ ②

noise from M_2 :

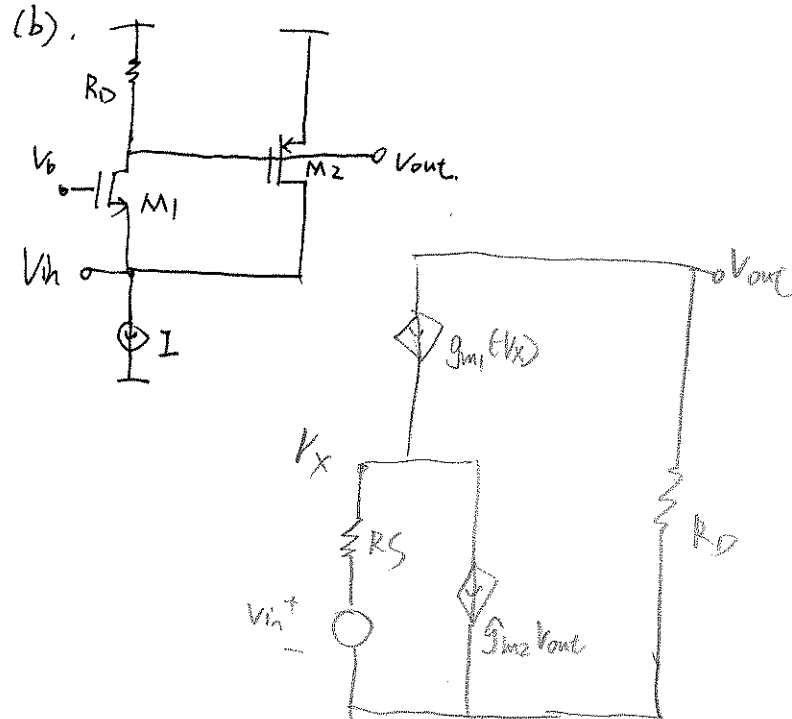


$$g_{m1}V_x + \frac{V_{out}}{R_D} = - \frac{V_x}{R_S} = -(I_n + g_{m2}V_{out})$$

$$\Rightarrow \left| \frac{V_{out}}{I_n} \right| = \frac{g_{m1}R_D + 1}{g_{m2} + \frac{1}{R_D} + g_{m1}g_{m2}R_D}$$

$$\Rightarrow \left| \frac{V_{out}}{I_n} \right|^2 \cdot 4KT \cdot g_{m2}$$
 ③

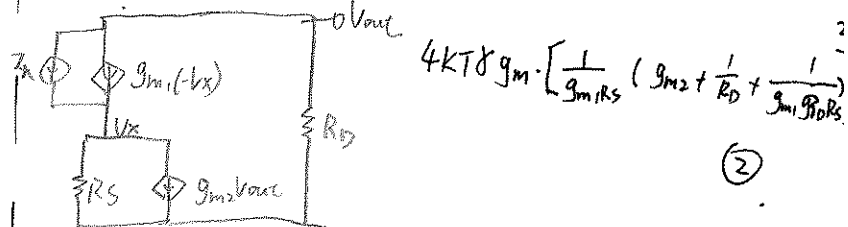
$$NF = 1 + \frac{① + ② + ③}{\left(\frac{g_{m1}}{g_{m2} + \frac{1}{R_D} + g_{m1}g_{m2}R_D} \right)^2} \cdot \frac{1}{4KT \cdot R_S}$$



$$\frac{V_{out}}{V_{in}} = \frac{R_D}{\frac{1}{g_{m1}} + R_S}$$

noise from $R_D = 4KT R_D$ ①

noise from M_1 :



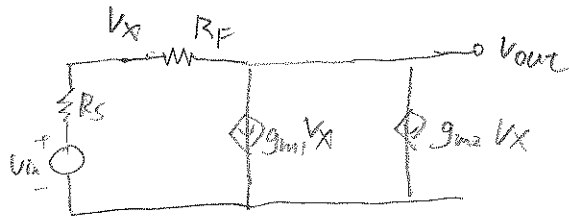
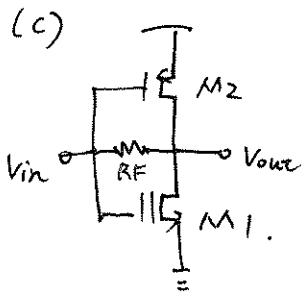
$$4KT \cdot g_{m1} \cdot \left[\frac{1}{g_{m1}R_S} \left(g_{m2} + \frac{1}{R_D} + \frac{1}{g_{m1}R_D R_S} \right) \right]^2$$
 ②

noise from M_2 :

$$4KT \cdot g_{m2} \left[g_{m2} + \frac{1}{R_D} + \frac{1}{g_{m1}R_D R_S} \right]^2$$
 ③

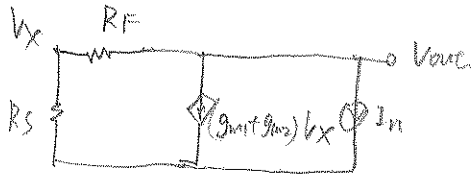
$$NF = 1 + \frac{① + ② + ③}{\left(\frac{R_D}{\frac{1}{g_{m1}} + R_S} \right)^2} \cdot \frac{1}{4KT R_S}$$

2.23 Part ②
Solu:



$$\frac{V_{out}}{V_{in}} = \frac{(g_{m1} + g_{m2}) R_F - 1}{(g_{m1} + g_{m2}) R_S + 1}$$

noise from $M_1 \Rightarrow 4kT \cdot g_{m1} \cdot \left(\frac{R_S + R_F}{(g_{m1} + g_{m2}) R_S + 1} \right)^2$ (1)



noise from $M_2 \Rightarrow 4kT \cdot g_{m2} \cdot \left(\frac{R_S + R_F}{(g_{m1} + g_{m2}) R_S + 1} \right)^2$ (2)

noise from $R_F \Rightarrow 4kT \cdot R_F$ (3)

$$\therefore NF = 1 + \frac{(1) + (2) + (3)}{\left(\frac{(g_{m1} + g_{m2}) R_F - 1}{(g_{m1} + g_{m2}) R_S + 1} \right)^2} \cdot \frac{1}{4kT R_S}$$

3.1 Solu:

$$X_{16QAM}(t) = \sigma_1 A_c \cos(\omega_c t + \Delta\theta) - \sigma_2 A_c (1 + \epsilon) \sin \omega_c t$$

(a) $\Delta\theta \neq 0, \epsilon = 0$

$$\begin{aligned} X_{16QAM}(t) &= \sigma_1 A_c \cos(\omega_c t + \Delta\theta) - \sigma_2 A_c \sin \omega_c t \\ &= \sigma_1 A_c [\cos \omega_c t \cos \Delta\theta - \sin \omega_c t \sin \Delta\theta] - \sigma_2 A_c \sin \omega_c t \\ &= \sigma_1 A_c \cos \Delta\theta \cos \omega_c t - (\sigma_1 A_c \sin \Delta\theta + \sigma_2 A_c) \sin \omega_c t \end{aligned}$$

normalized coefficient: $\sigma_1 \cos \Delta\theta, -(\sigma_1 \sin \Delta\theta + \sigma_2)$

$$\beta_1 = \cos \Delta\theta, \beta_2 = -\sin \Delta\theta + 1; \quad \beta_1 = \cos \Delta\theta, \beta_2 = -\sin \Delta\theta + 2;$$

$$\beta_1 = \cos \Delta\theta, \beta_2 = -\sin \Delta\theta - 1; \quad \beta_1 = \cos \Delta\theta, \beta_2 = -\sin \Delta\theta - 2;$$

$$\beta_1 = -\cos \Delta\theta, \beta_2 = \sin \Delta\theta + 1; \quad \beta_1 = -\cos \Delta\theta, \beta_2 = \sin \Delta\theta + 2;$$

$$\beta_1 = -\cos \Delta\theta, \beta_2 = \sin \Delta\theta - 1; \quad \beta_1 = -\cos \Delta\theta, \beta_2 = \sin \Delta\theta - 2;$$

$$\beta_1 = 2\cos \Delta\theta, \beta_2 = -2\sin \Delta\theta + 1; \quad \beta_1 = 2\cos \Delta\theta, \beta_2 = -2\sin \Delta\theta + 2;$$

$$\beta_1 = 2\cos \Delta\theta, \beta_2 = -2\sin \Delta\theta - 1; \quad \beta_1 = 2\cos \Delta\theta, \beta_2 = -2\sin \Delta\theta - 2;$$

$$\beta_1 = -2\cos \Delta\theta, \beta_2 = 2\sin \Delta\theta + 1; \quad \beta_1 = -2\cos \Delta\theta, \beta_2 = 2\sin \Delta\theta + 2;$$

$$\beta_1 = -2\cos \Delta\theta, \beta_2 = 2\sin \Delta\theta - 1; \quad \beta_1 = -2\cos \Delta\theta, \beta_2 = 2\sin \Delta\theta - 2;$$

(b) $\Delta\theta = 0, \epsilon \neq 0$

$$X_{16QAM}(t) = \sigma_1 A_c \cos \omega_c t - \sigma_2 A_c (1 + \epsilon) \sin \omega_c t$$

normalized coefficient: $(\sigma_1, -\sigma_2(1 + \epsilon))$

Similar to (a), there are 16 different combinations

3.2 Solu:

If $NF < 10 \text{ dB}$.

$$NF = \frac{\text{Noise, out}}{A_0^2 \cdot P_{RS}}$$

$$\frac{\text{Noise, out}}{A_0^2} = \text{Noise, in} = NF \cdot P_{RS}$$

$$\begin{aligned} \therefore \text{Noise, in} \cdot B &= NF_{\text{dB}} + 174 \text{ dB/Hz} + 10 \log B \\ &= (10 - 174 + 53) \text{ dBm} \\ &= -111 \text{ dBm}. \end{aligned}$$

$$\text{If } NF < 10 \text{ dB} \Rightarrow \text{Noise, in} \cdot B < -111 \text{ dBm}.$$

$$IIP_3 = P_{in} + \frac{P_{in} - P_{IM, in}}{2}$$

Since the maximum tolerable noise is -108 dBm ,
the IM can contribute more than 3 dB .

$$\text{So } P_{IM, in} > -111 \text{ dBm}$$

$$\Rightarrow IIP_3 < -18 \text{ dBm}.$$

It demonstrates that if the RX contributes less noise,
the receiver's linearity requirement can be loose.

3.3 solve:

For WCDMA.

Receiver sensitivity : -104 dBm .

B : 5 MHz .

Assum: $NF = 3 \text{ dB}$

$$\begin{aligned} \text{Noise}_{in,B} &= -174 \text{ dBm} + 3 + 10 \log(3.84 \text{ MHz}) \\ &= -115 \text{ dBm}. \end{aligned}$$

For an acceptable BER, SNR of 9 dB is required.
i.e. the total noise in the desired channel must remain below -113 dBm .

\Rightarrow The intermodulation can contribute at most 2 dB

i.e. $P_{IM, in} = -117 \text{ dBm}$.

$$\begin{aligned} IIP_3 &= \frac{-46 \text{ dBm} - (-117 \text{ dBm})}{2} + (-46 \text{ dBm}) \\ &= -10.5 \text{ dBm}. \end{aligned}$$

3.4 Solu:

IMX2000. maximum tolerable relative noise floor.

In DCS1800 RX Band 1805 ~ 1880 MHz.

TX Power remain below -71 dBm, in 100-KHz bandwidth.

of DCS1800.

$$-71 \text{ dBm} - 10 \log 10 \text{ kHz} = -121 \text{ dBm / Hz}.$$

Tx outpower : 24 dBm.

⇒ The Max Tolerable relative noise floor :

$$-145 \text{ dBc / Hz}.$$

3.5
Solu:

This problem is the same as Problem 3.3.

3.6 Solu:

$$SNR = 17 \text{ dB}$$

That means the total noise should remain below -81 dBm .

Let me assume $NF = 10 \text{ dB}$.

$$B = 1 \text{ MHz.}$$

$$\begin{aligned} \text{Noise by Rx} &= -174 \text{ dBm/Hz} + 10 \lg B + NF. \\ &= -104 \text{ dBm.} \end{aligned}$$

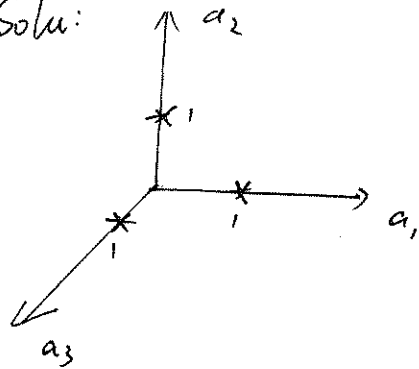
So IM can contribute maximum 23 dB .

$$\Rightarrow -81.02 \text{ dBm.}$$

$$IIP_3 = \frac{(-39) - (-81.02)}{2} \text{ dB} + (-39 \text{ dBm})$$

$$= -18 \text{ dBm.}$$

3.7 Solu:

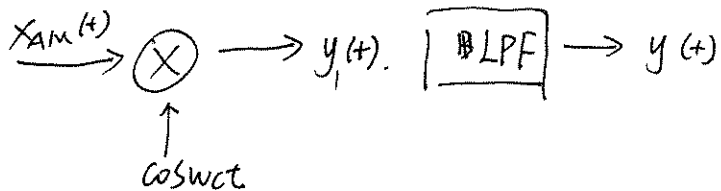


the constellation of $X_{FSK}(t) = a_1 \cos \omega_1 t + a_2 \cos \omega_2 t + a_3 \cos \omega_3 t$.

3.8 sdu:

Demodulation of AM

$$x_{AM}(t) = A_c [1 + m x_{BB}(t)] \cdot \cos \omega_c t$$



$$y_1(t) = A_c [1 + m x_{BB}(t)] \cos^2 \omega_c t$$

$$= A_c [1 + m x_{BB}(t)] \frac{1 + \cos 2\theta}{2}$$

$$y(t) = \text{LPF} [y_1(t)]$$

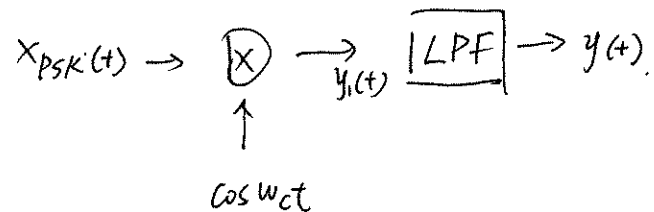
$$= \frac{1}{2} A_c [1 + m x_{BB}(t)]$$

From the equation of $y(t)$, we can easily find the original information $x_{BB}(t)$.

3.9 soln:

Demodulation of PSK

$$x_{PSK}(t) = a_n \cos \omega_c t$$



$$y_1(t) = a_n \cos \omega_c t \cdot \cos \omega_c t$$

$$= \frac{1}{2} a_n (1 + \cos 2\omega_c t)$$

\Downarrow

$$y(t) = \text{LPF}[y_1(t)]$$

$$= \frac{1}{2} a_n$$

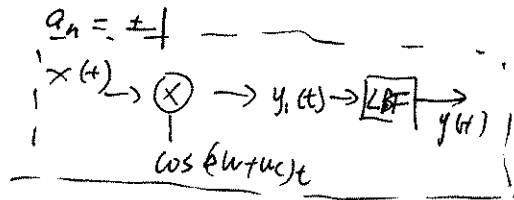
From the result of $y(t)$, we can easily find the original binary sequence a_n .

3.6 Solu:

$$x_{\text{BPSK}}(t) = a_n \cos \omega_c t$$

Proof:

$$y_1(t) = x_{\text{BPSK}} \cdot \cos(\omega_c + \omega_w)t$$

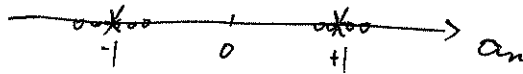


$$= a_n \cos \omega_c t \cdot \cos(\omega_c + \omega_w)t$$

$$= \frac{1}{2} a_n [\cos(2\omega_c + \omega_w)t + \cos \omega_w t]$$

$$y(t) \xrightarrow{\text{LPF}} [y_1(t)]$$

$$= \frac{1}{2} a_n \cos \omega_w t$$



4.1 Solu:

(a). If input RF range is from f_1 to f_2 .

$$\therefore \left[\frac{4}{5}f_1, \frac{4}{5}f_2 \right] \text{ — LO freq. range.}$$

Suppose input band is partitioned into N channels

$$\frac{f_2 - f_1}{N} = \Delta f.$$

$$\text{The first channel} \Rightarrow f_{LO} = \frac{4}{5} \left(f_1 + \frac{\Delta f}{2} \right)$$

$$\text{The second channel} \Rightarrow f_{LO} = \frac{4}{5} \left(f_1 + \frac{3}{2}\Delta f \right).$$

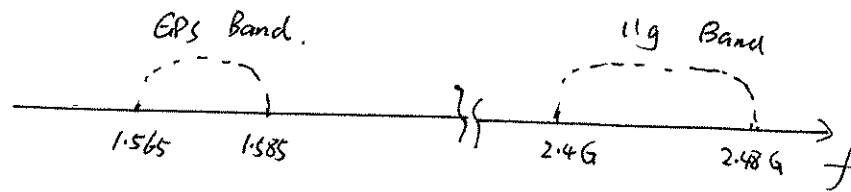
$$\therefore \text{LO increments in steps of } \frac{4}{5}\Delta f.$$

(b). Image range.

$$\text{For } f_{LO} = \frac{4}{5}f_1, \text{ the image lies at } 2f_{LO} - f_{in} = \frac{3}{5}f_1$$

$$\Rightarrow \text{Image Freq. Range} = \left[\frac{3}{5}f_1, \frac{3}{5}f_2 \right]$$

4.2 soln:



For Fig 4.26 Sliding-IF Receiver,

$$f_{LO1} = \frac{2}{3} f_{in}$$

$$Image = 2f_{LO1} - f_{in}$$

$$= \frac{1}{3} f_{in}$$

$$\in [0.8 \text{ GHz}, 0.827 \text{ GHz}]$$

Image Range : 27 MHz.

GPS Band : 20 MHz.

So, it's not possible to design an 11g receiver whose image is confined to GPS Band.

4.3 Solu:

$$f_{L01} = \frac{2}{3} f_{in}$$

$$f_{L02} = \frac{1}{3} f_{in}$$

$$f_{in} - \frac{2}{3} f_{in} - \frac{1}{3} f_{in} = 0$$

$$W_{int} \pm m W_{L01} \pm n W_{L02} = 0$$

$$W_{int} = \pm m W_{L01} \pm n W_{L02}$$

$$\begin{aligned} \text{i.e. } f_{int} &= \pm m f_{L01} \pm n f_{L02} \\ &= (\pm 2m \pm n) \frac{f_{in}}{3} \end{aligned}$$

\Rightarrow mixing spurs. (m, n are integers)

4.4. Solu:

(a) assume the second IF is zero.

$$f_{in} - \frac{1}{2}f_{LO} - f_{LO} = 0.$$

$$f_{LO} = \frac{2}{3}f_{in}.$$

If the input RF Range is $[f_1, f_2]$, the LO: freq.

Range is $[\frac{2}{3}f_1, \frac{2}{3}f_2]$

$$(b) \quad 2 \cdot (\frac{1}{2}f_{LO}) - f_{in} = f_{image}.$$

$$\Rightarrow f_{image} = -\frac{1}{3}f_{in}.$$

The Range of image freq. is $[-\frac{1}{3}f_2, -\frac{1}{3}f_1]$.

(c) No.

Because the image freq. range doesn't change.

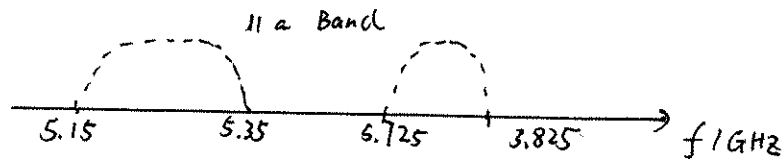
And the I/Q mixer's operate at much higher frequency \Rightarrow difficult to design.

4.5
Solu :

Mixing spurs :

$$\begin{aligned} f_{\text{int}} &= \pm m f_{L01} \pm n f_{L02} \\ &= \left(\pm \frac{m}{2} \pm n \right) \cdot \frac{2}{3} f_{\text{in}} \end{aligned}$$

4.6.
(a).



assume the second IF is zero

$$f_{in} - f_{LO1} - \frac{1}{8} f_{LO1} = 0$$

$$f_{LO1} = \frac{8}{9} f_{in}$$

$$f_{image} = 2f_{LO1} - f_{in}$$

$$= \frac{7}{9} f_{in} \Rightarrow \text{Image band:}$$

$$= [4.01 \text{ GHz}, 4.16 \text{ GHz}] \cup [4.45 \text{ GHz}, 4.53 \text{ GHz}]$$

(b). Mixed with 3rd harmonic of the first LO.

$$f_{int} - 3f_{LO1} - m \frac{1}{8} f_{LO1} = 0$$

$$f_{int} = 3f_{LO1} + \frac{m}{8} f_{LO1} = (3 + \frac{m}{8}) f_{LO1}$$

Mixed with 3rd harmonic of the second LO

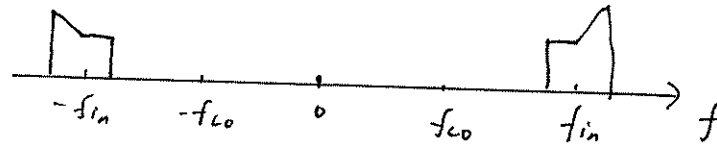
$$f_{int} - n \cdot f_{LO1} - \frac{3}{8} f_{LO1} = 0$$

$$f_{int} = n \cdot f_{LO1} + \frac{3}{8} f_{LO1} = (n + \frac{3}{8}) f_{LO1}$$

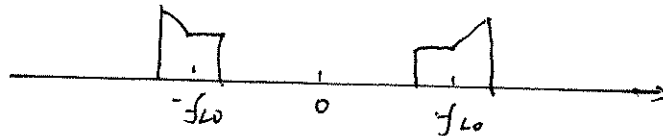
4.7. Solu:

$$f_{LO} = \frac{f_{in}}{2}$$

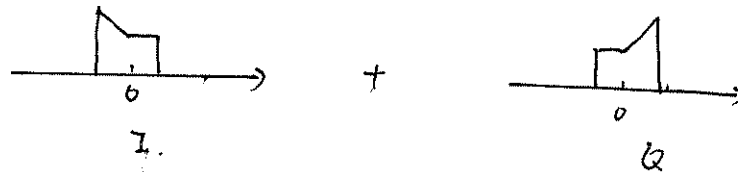
(a)



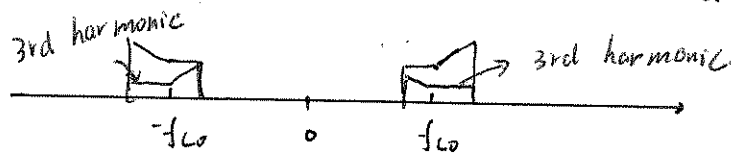
↓



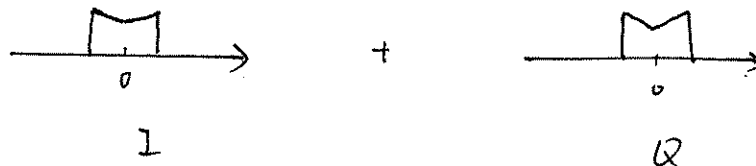
⇓



(b)



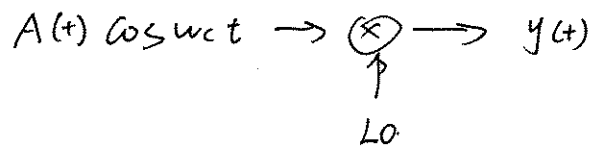
⇓



(c)

Because the second IF is zero, while the flicker noise has a huge component at low frequency.

4.8 Solu:



(a). $A(t) \cdot \cos \omega_c t \cdot \cos \omega_c t$.

$$= A(t) \frac{(1 + \cos 2\omega_c t)}{2}$$

After LPF, baseband signal: $\frac{A(t)}{2}$.

(b) $A(t) \cdot \cos \omega_c t \cdot \sin(\omega_c t)$.

$$= \frac{1}{2} A(t) \sin(2\omega_c t)$$

After LPF, baseband signal is nothing.

A signal modulated by $\cos \omega_c t$ should be demodulated by $\cos \omega_c t$.
Vice Versa. If a signal modulated by $\cos(\omega_c t + \phi)$, ϕ is phase mismatch, the quadrature downconversion is necessary.

4.9 Solu:

$$V_0 \cos \omega_{LO} t + V_{int}(t) \cos \omega_{int} t$$

(a). components near carrier.

assume LNA : $y(t) = \alpha_1 x(t) + \alpha_2 x^2(t) + \alpha_3 x^3(t)$.

$$\begin{aligned} & \frac{3}{4} \alpha_3 V_0^2 V_{int}(t) \cos(2\omega_{LO} - \omega_{int}) \\ & + \frac{3}{4} \alpha_3 V_{int}^2 \cdot V_0 \cos(2\omega_{int} - \omega_{LO}) . \end{aligned}$$

(b). baseband component.

$$\left(\alpha_1 V_0 + \frac{3}{4} \alpha_3 V_0^3 + \frac{3}{2} \alpha_3 V_0 \cdot V_{int}^2(t) \right) \cdot \cos \omega_{LO} t$$

They will corrupt the desired signal surely.

4.10 Solu:

A higher from-end gain directly arise Sth. in
Fig. 4.44.

$$\frac{P_{n1}}{P_{n2}} = \frac{8.2 f_c}{100 \text{ KHz.}}$$

$$\frac{\delta}{f_c} = \text{Sth.}$$

$$f_{c \text{ new}} = \frac{\delta}{\text{Sth.}} \cdot \frac{1}{A} = f_c \cdot \frac{1}{A}.$$

$$\therefore \frac{P_{n1}}{P_{n2}} = \frac{8.2}{100 \text{ K}} \cdot \frac{200 \text{ K}}{A} < 10$$

$$\Rightarrow A > 1.64.$$

So that the penalty remains below 1 dB.

4.11 Solu:

$$\frac{P_{n1}}{P_{n1}} = \frac{8.2 f_c}{100K} < 10$$

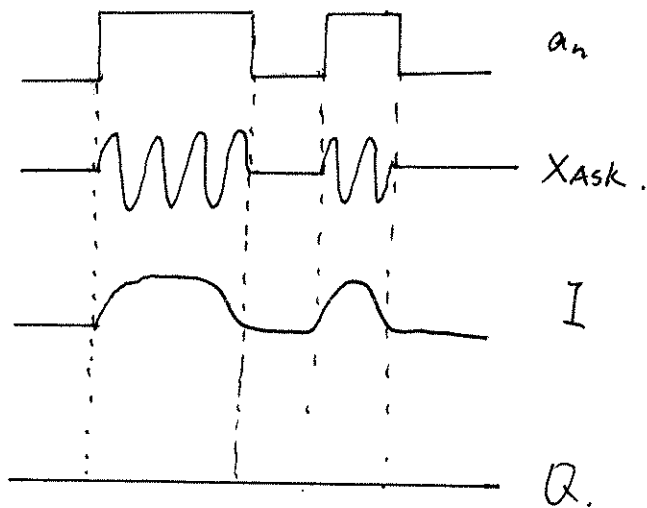
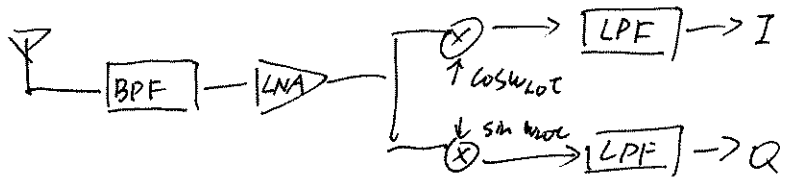
$$f_c < 122 \text{ KHz}.$$

If the penalty must remain below 1 dB,
the flicker noise corner frequency should
be smaller than 122 kHz.

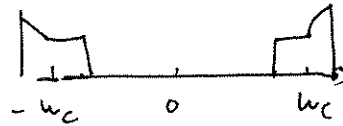
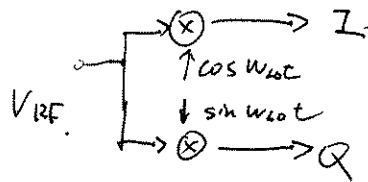
4.12 Solu:

$$x_{ASK}(t) = a_n \cos \omega_c t$$

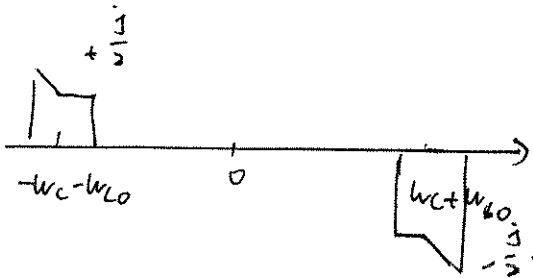
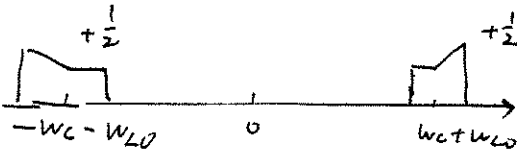
$(a_n = 1 \text{ or } 0)$



4.13 Solu:



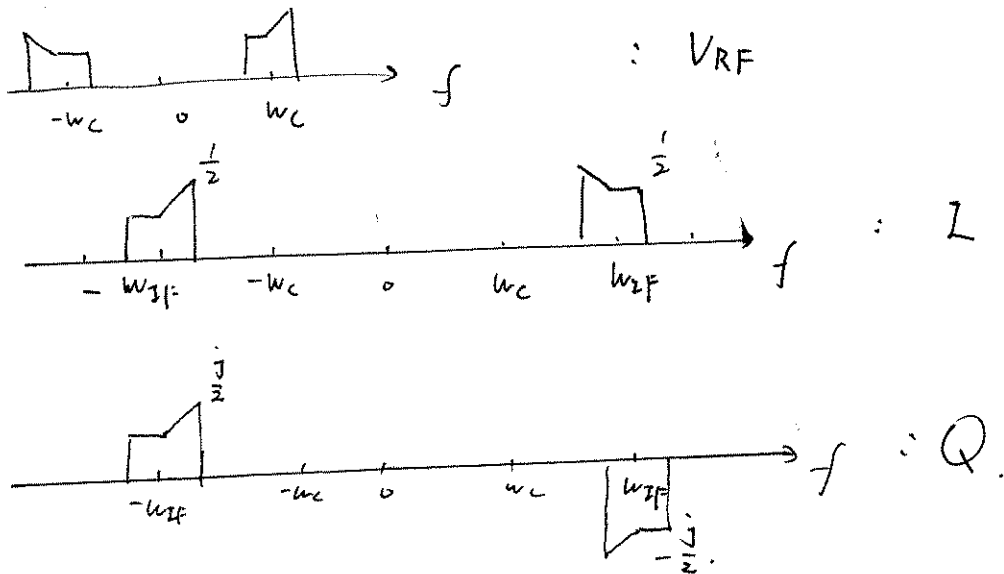
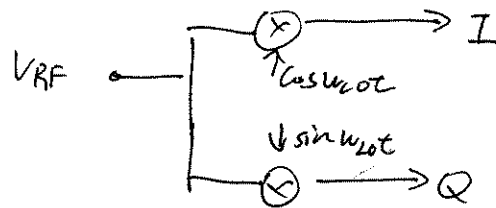
I : up converted output



Q : up converted output.

Fig 4.59(a) performs a Hilbert Transform when if the up converted are considered.

4.14. Solu: If $\omega_{IF} > \omega_c$.



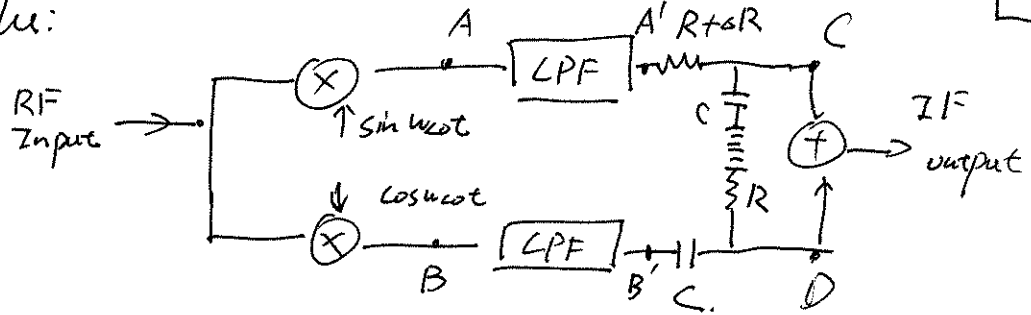
The result is the same as original analysis.

4.15 Solu:

Yes. Hartley architecture can cancel the image if the IF Low-pass filters are replaced with high-pass filters.

As the analysis of problem 4.13, the upconverted components can be used successfully, just like the downconverted components.

4.16 Solu:



$$X_{A(t)} = -\frac{A_{sig}}{2} \sin[(\omega_c - \omega_{LO})t + \phi_{sig}] - \frac{A_{im}}{2} \sin[(\omega_{im} - \omega_{LO})t + \phi_{im}]$$

$$X_{B(t)} = \frac{A_{sig}}{2} \cos[(\omega_c - \omega_{LO})t + \phi_{sig}] + \frac{A_{im}}{2} \cos[(\omega_{im} - \omega_{LO})t + \phi_{im}]$$

$$\arctan(RC \cdot \frac{1}{RC}) = 45^\circ$$

$$\arctan((R + \Delta R) \cdot C - \frac{1}{RC}) = \arctan(1 + \frac{\Delta R}{R})$$

$$\Delta\theta = \arctan(1 + \frac{\Delta R}{R}) - \arctan(1)$$

$$= \arctan\left(\frac{\Delta R}{1 + 1 + \frac{\Delta R}{R}}\right)$$

$$= \arctan\left(\frac{\Delta R}{2 + \frac{\Delta R}{R}}\right)$$

$$\therefore \cos(\arctan(x))$$

$$= \frac{1}{\sqrt{x^2 + 1}}$$

$$IRR = \frac{2 + 2\cos\Delta\theta}{2 - 2\cos\Delta\theta} = \frac{1 + \cos\Delta\theta}{1 - \cos\Delta\theta}$$

$$= \frac{1 + \frac{1}{\sqrt{\left(\frac{2 + \frac{\Delta R}{R}}{\Delta R + R}\right)^2 + 1}}}{1 - \frac{1}{\sqrt{\left(\frac{2 + \frac{\Delta R}{R}}{\Delta R + R}\right)^2 + 1}}}$$

$$= \frac{2\sqrt{\left(\frac{\Delta R \cdot R}{2R + \Delta R}\right)^2 + 1} + 2}{\left(\frac{\Delta R \cdot R}{2R + \Delta R}\right)^2 + 1}$$

4.17 solve:

$$w_{IF} = (R_1 C_1)^{-1}.$$

$$\Delta\theta = 2 \arctan(R_1 C_1 (w_{IF} + \Delta w)) - \frac{\pi}{2}.$$

$$IRR = \frac{1 + \cos \Delta\theta}{1 - \cos \Delta\theta}.$$

$$= \frac{1 + \sin \left(2 \arctan \left(1 + \frac{\Delta w}{w_{IF}} \right) \right)}{1 - \sin \left(2 \arctan \left(1 + \frac{\Delta w}{w_{IF}} \right) \right)}.$$

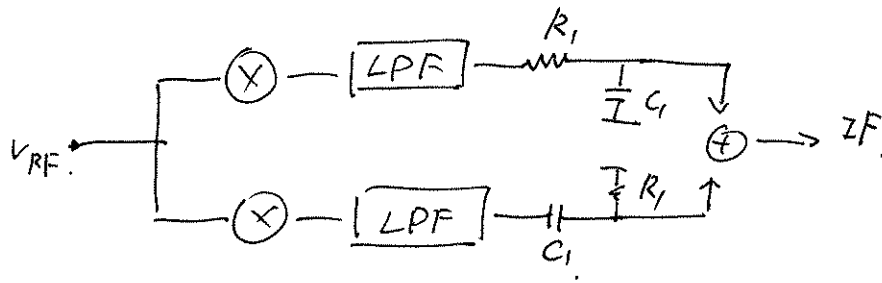
$$= \left(\frac{\frac{\Delta w}{w_{IF}} + 1}{\frac{\Delta w}{w_{IF}}} \right)^2.$$

$$\therefore \Delta w \ll w_{IF}$$

$$\therefore IRR \approx \left(\frac{w_{IF}}{\Delta w} \right)^2.$$

$$\begin{aligned} & \sinh(\arctan(x)) \\ &= \frac{x}{\sqrt{x^2 + 1}} \end{aligned}$$

4.18. Solu:



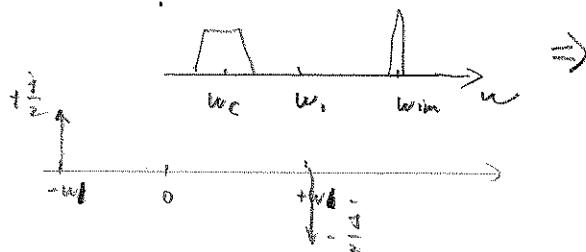
assume mixers, and LPF and adder are free of noise.

$$NF = 1 + \frac{2 \cdot 4kT \cdot R_1}{A_1^2} \cdot \frac{1}{4kT \cdot R_D}$$

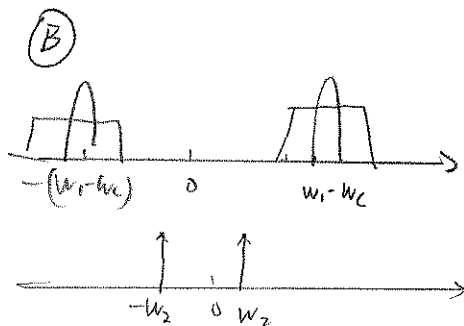
$$= 1 + \frac{2R_1}{R_D} \cdot \frac{1}{A_1^2}$$

4.19 Solu:

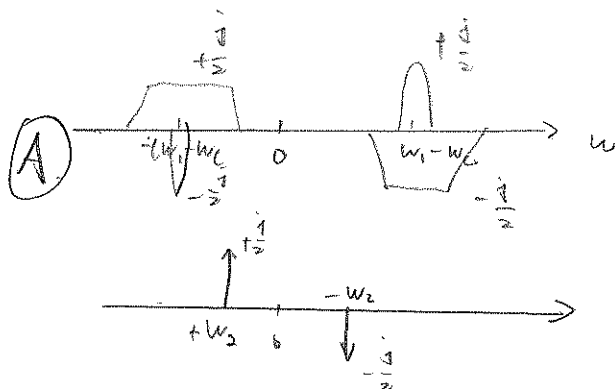
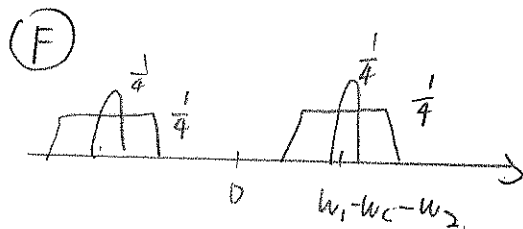
(I) high-side, low-side.



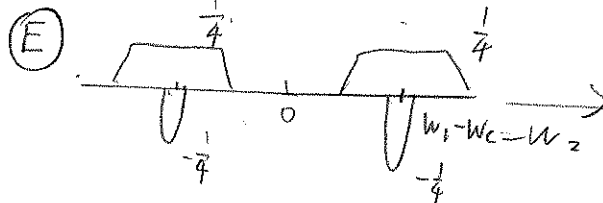
⇓



⇓



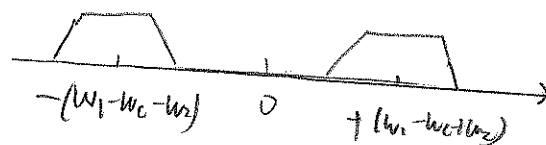
⇓



⇓

(E) + (F)

⇓



For high-side, low-side configuration,

E should be added to F. In order to
cancel the image component.

(II) high-side, high-side

similar analysis to (I).

(III) low-side, high-side

4.20 Solu:

(a). It cannot reject the image.

LO are not quadrature.

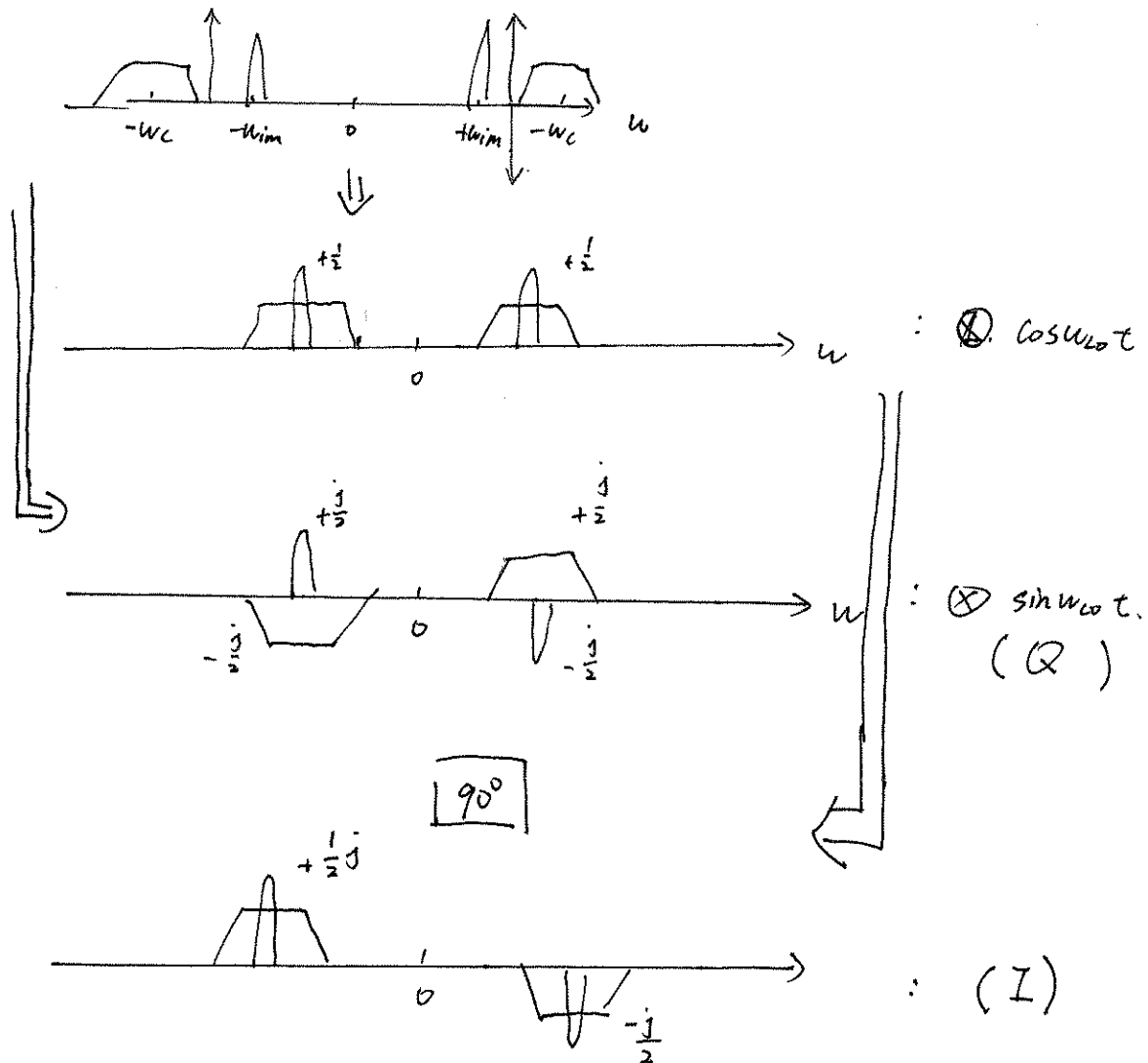
(b). It can reject the image.

The structure is similar to the original one.

(c) It cannot reject the image.

LO are not quadrature. So it is not possible to provide $\pm j$ factor, which can cancel the image by proper operations.

4.21. Solu:



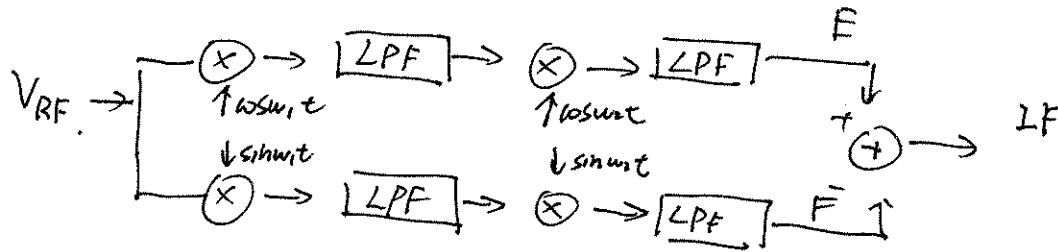
I - Q operation can cancel the image.

So the answer is Yes, $\sin \omega_c t$ & $\cos \omega_c t$ can be suppressed.

The only thing needs to be considered is that I should be subtracted by Q.

4.22 Solu:

In Weaver architecture.



The answer is the same as the previous

problem 4.21. Yes. It can cancel the image.

Which needs to be paid more attention is that

the last operation on E and F.

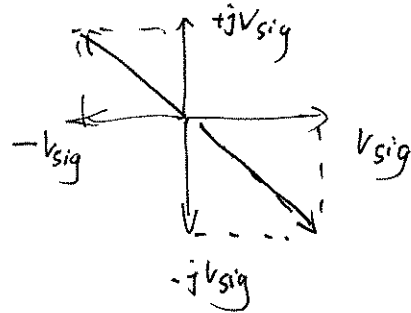
4.23. Solu:

IRR at the output is.

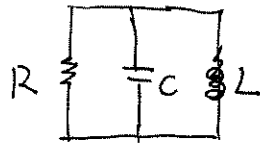
$$\frac{P_{im}}{P_{sig}} = \frac{|v_{im}|^2 \cdot \frac{(RC\omega)^2}{2}}{|v_{sig}|^2 (2\sqrt{2})^2}$$

assum $|v_{im}| = |v_{sig}|$

$$IRR = \frac{(RC\omega)^2}{16}$$



4.24.
Solve:



$$1^\circ 3\omega_0 = \frac{1}{\sqrt{LC}}$$

$$2^\circ Q = R \cdot C \cdot 3\omega_0$$

Proof: $Y_{in} = \frac{1}{R} + \frac{1}{j\omega L} + j\omega C$

when $\omega = \omega_0$

$$Y_{in, \omega_0} = \frac{1}{R} + \frac{1}{j\omega_0 L} + j\omega_0 C$$

$$= \frac{1}{R} + j\left(\omega_0 C - \frac{1}{\omega_0 L}\right)$$

$$Y_{in, 3\omega_0} = \frac{1}{R}$$

$$\frac{|Y_{in, \omega_0}|}{|Y_{in, 3\omega_0}|} = \sqrt{\left(\frac{1}{R}\right)^2 + \left(\omega_0 C - \frac{1}{\omega_0 L}\right)^2} \cdot R$$

$$= \sqrt{1 + \omega_0^2 C^2 R^2 + \frac{R^2}{\omega_0^2 L^2} - 2 \cdot \frac{C}{L} \cdot R^2}$$

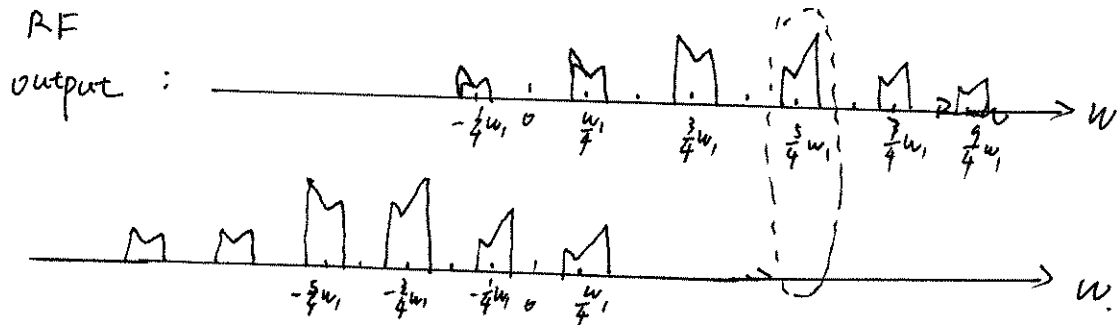
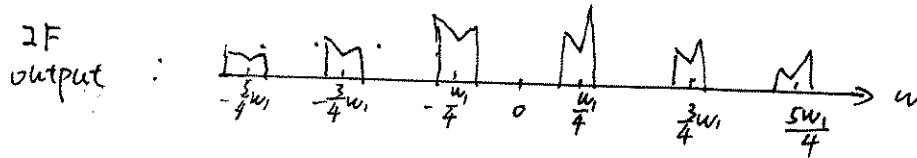
$$= \sqrt{1 + \frac{Q^2}{9} + 9Q^2 - 2Q^2}$$

$$= \sqrt{1 + \frac{64}{9}Q^2} \quad (\text{assume } Q \gg 1)$$

$$\approx \frac{8}{3}Q$$

4.25 Soln: $\frac{1}{4}\omega_1$ and ω_1 . output $\frac{5}{4}\omega_1$

1^o Consider the first LO.



The unwanted signal at $\frac{1}{4}\omega_1$, $\frac{3}{4}\omega_1$, $\frac{7}{4}\omega_1$, $\frac{9}{4}\omega_1$ must be suppressed by RF bandpass filter.

2^o Consider the second LO.

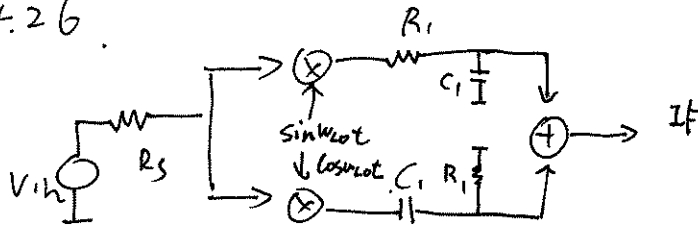
IF should be mixed not only ω , but $3\omega_1$ and $5\omega_1$.

⊗ $3\omega_1 \Rightarrow -\frac{5}{4}\omega_1$ will be translated to $\frac{7}{4}\omega_1$
 $-\frac{3}{4}\omega_1$ will be translated to $\frac{9}{4}\omega_1$

⊗ $5\omega_1 \Rightarrow -\frac{3}{4}\omega_1$ will be translated to $\frac{15}{4}\omega_1$.

So in the band of $+\frac{5}{4}\omega_1$, the wanted spectrum is alone.

4.26.



1° Noise, out = $4kTR_1 \cdot 2$.

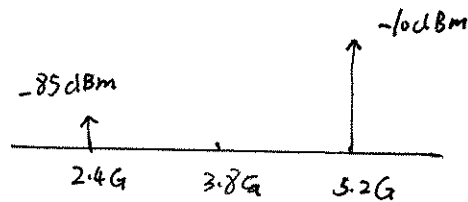
2° find the gain.

only up-branch $\Rightarrow A_{mix} \times \frac{1}{2} \times \frac{1}{2}$
 only up-branch $\Rightarrow A_{mix} \times \frac{1}{2} \times \frac{1}{2}$ } $\times 2 \Rightarrow \frac{1}{2} A_{mix}$.

3° $NF = 1 + \frac{4kT \cdot R_1 \cdot 2}{(\frac{1}{2} \cdot A_{mix})^2} \cdot \frac{1}{4kTR_S}$
 $= 1 + \frac{8 \cdot R_1}{R_S} \cdot \frac{1}{A_{mix}^2}$.

4.2] Solu:

(a).



$$IRR = 45 \text{ dB}$$

Neglect the noise and nonlinearity of RX.

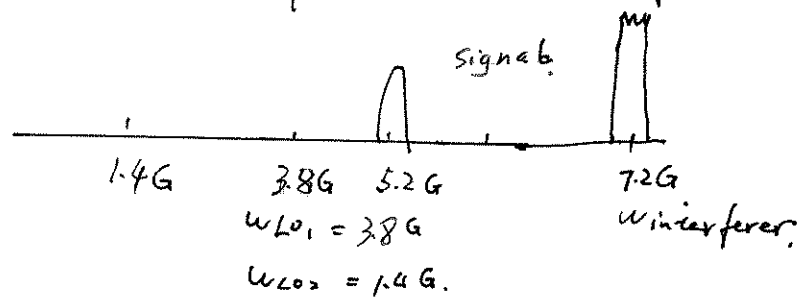
$$SNR = 20 \text{ dB} \quad V_{RF} = -85 \text{ dBm}$$

$$\Rightarrow \text{Noise, in} \leftarrow -65 \text{ dBm.}$$

$$-10 \text{ dBm} - 45 \text{ dB} = -55 \text{ dBm.}$$

So BPF. need provide 10 dB rejection at 5.2 GHz.

(b).



$$3w_{L01} = 11.4 \text{ G.}$$

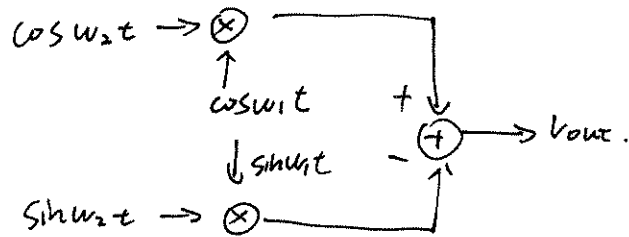
$$3w_{L02} = 4.2 \text{ G}$$

$$W_{\text{interferer}} - 3w_{L01} - 3w_{L02} = 0. \text{ baseband.}$$

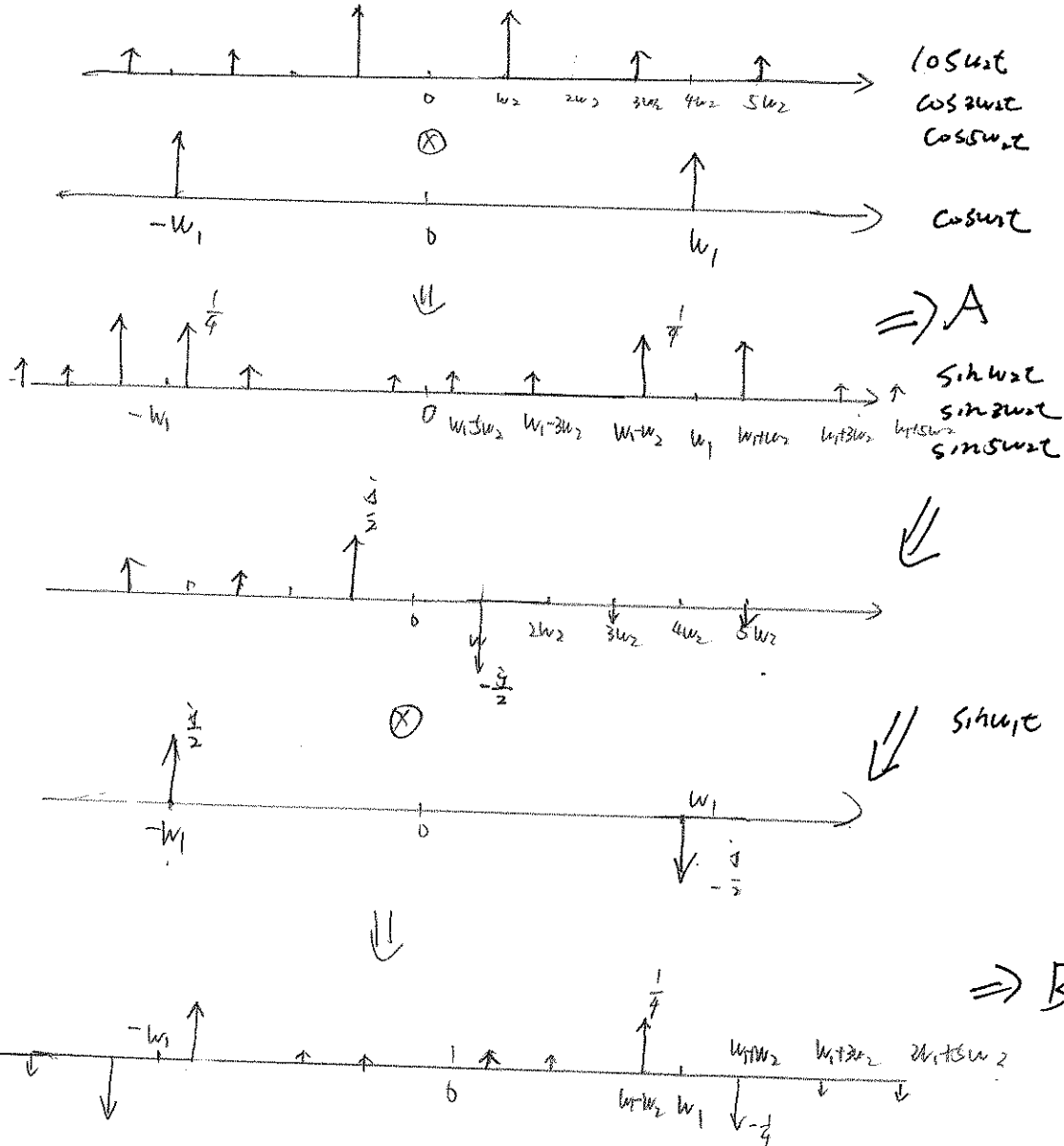
Yes. The Weaver Architecture can prohibit this phenomenon. Because the 5.2GHz. band circuit is design for high-side injection. Ant the 7.2G Interferer can be mixed to baseband. This only happens for low-side injection.

part ①.

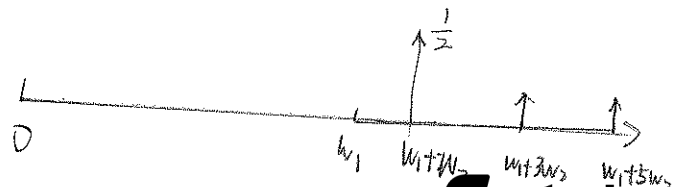
4.28. Solu:



(a) $w_1 > 3w_2$

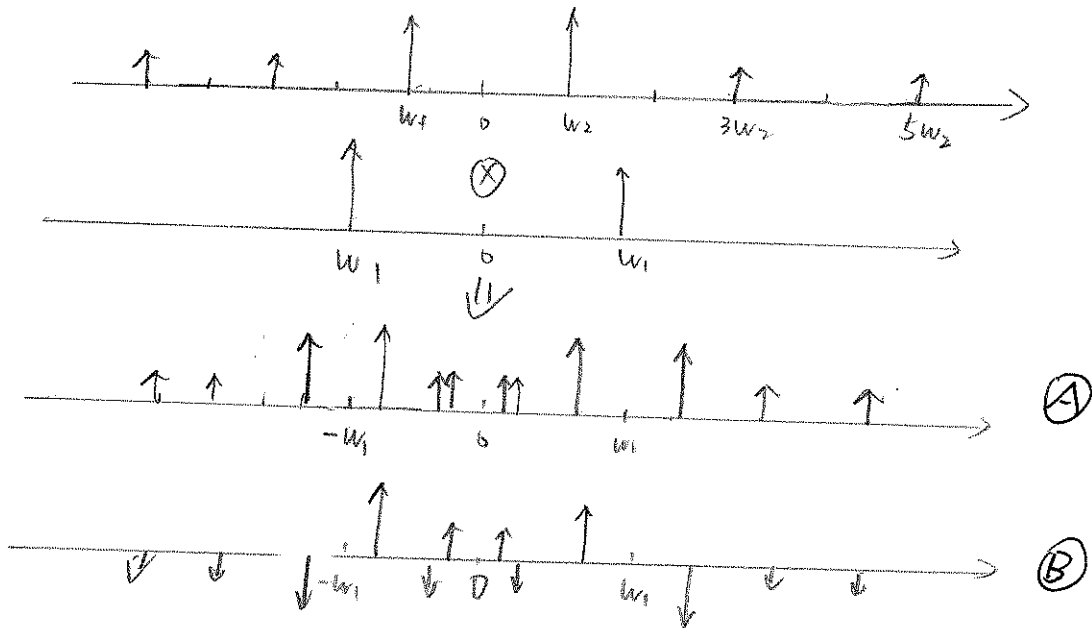


① - ②

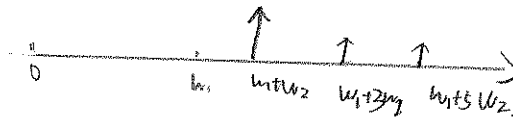


4.28 part ②

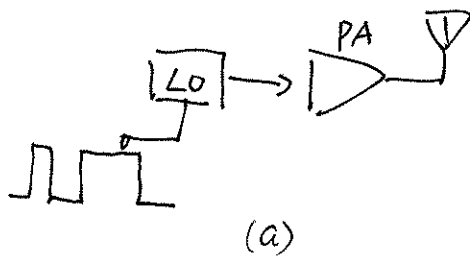
(b) $w_1 < 3w_2$.



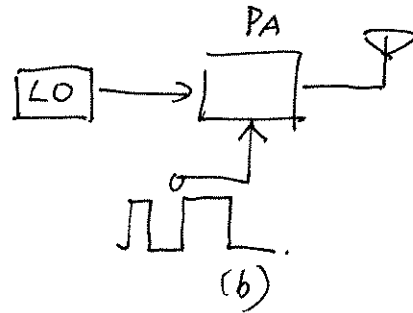
(A) - (B).



4.29 solu:



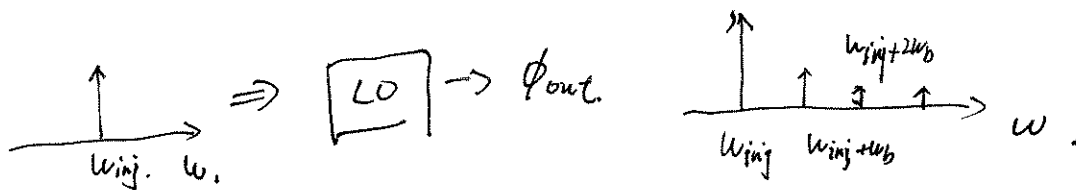
V.S.



study the injection pulling.

In The archeticture (b), PA is controlled to turn on & off.

The output spectrum of LO changes a lot in this situation.



5.1 Soln:

$$\Gamma = \left| \frac{x+jy - R_s}{x+jy + R_s} \right|^2$$

$$\Gamma = \frac{(x-R_s)^2 + y^2}{(x+R_s)^2 + y^2}$$

$$\Gamma(x^2 + R_s^2 + 2R_s x) + \Gamma y^2 = (x+R_s)^2 + y^2$$

$$(\Gamma-1)x^2 + 2R_s[\Gamma+1]x + (\Gamma-1)R_s^2 + (\Gamma-1)y^2 = 0$$

$$x^2 + 2R_s \frac{\Gamma+1}{\Gamma-1} x + R_s^2 + y^2 = 0$$

$$x^2 + 2R_s \frac{\Gamma+1}{\Gamma-1} x + \left(R_s \frac{\Gamma+1}{\Gamma-1}\right)^2 + y^2 = -R_s^2 + R_s^2 \left(\frac{\Gamma+1}{\Gamma-1}\right)^2$$

$$\left(x - \frac{1+\Gamma}{1-\Gamma} R_s\right)^2 + y^2 = \frac{4\Gamma \cdot R_s^2}{(\Gamma-1)^2}$$

\Rightarrow This is a circle with $\left(\frac{1+\Gamma}{1-\Gamma} R_s, 0\right)$ as center,

with $\sqrt{\frac{4\Gamma \cdot R_s^2}{(\Gamma-1)^2}}$ as radius.

5.2 Solu:

Eq. (5.18)

$$NF = 1 + \frac{R_S}{R_P} + \frac{\gamma R_S}{g_m (R_S \parallel R_P)^2} + \boxed{\frac{R_S}{g_m^2 (R_S \parallel R_P)^2 R_D}} \quad \text{neglect.}$$

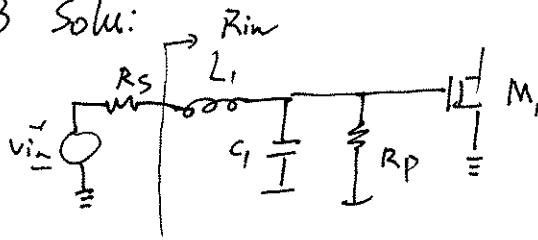
If $R_S = R_P$ $g_m R_S \approx 1$.

$$NF = 1 + 1 + \frac{\gamma}{g_m \cdot \frac{1}{4}} = 2 + \frac{4\gamma}{g_m} = 3.5 \text{ dB}$$

$$\Rightarrow 2 + \frac{4\gamma}{g_m} = 10^{0.35}$$

$$\Rightarrow g_m = 16.76 \text{ S}$$

5.3 Solu:



$$R_{in} = j\omega L_1 + (R_P \parallel \frac{1}{j\omega C_1})$$

$$= j\omega L_1 + \frac{R_P}{j\omega R_P C_1 + 1}$$

$$= \frac{R_P}{1 + (R_P C_1 \omega)^2} + j \left(\omega L_1 - \frac{R_P C_1 \omega}{1 + (R_P C_1 \omega)^2} \right)$$

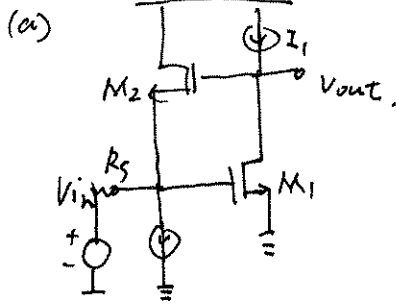
$$= R_S \quad \quad \quad = 0$$

R_P cannot choose arbitrary because ω & C_1 depend on system requirements and technology.

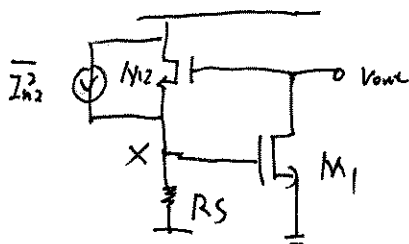
So this topology is not different from Fig. 5.9 (a).

As a result, it's impossible to achieve a noise figure less than 3 dB.

5.4. Solu - Part ①.



1^o noise of M_2



For M_1 , there is no ac pass

$$\Rightarrow V_X = 0.$$

$$g_{m2} \cdot V_{out} = I_{n2}$$

$$V_{out} = \frac{I_{n2}}{g_{m2}}$$

$$\overline{V_{n,M2}^2} = \frac{4KT\delta}{g_{m2}}$$

noise of M_1

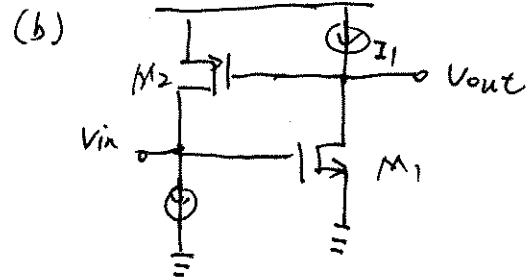
$$\overline{V_{n,M1}^2} = 4KT\delta \cdot g_{m1} \cdot \left(\frac{g_{m1} \cdot g_{m2}}{\frac{1}{R_S} + g_{m2}} \right)^2$$

$$2^o \frac{V_{out}}{V_{in}}$$

$$= - \frac{1}{R_S g_{m2}}$$

$$3^o NF = 1 + \frac{\frac{1}{g_{m2}} + \frac{1}{g_{m1}} \left(\frac{g_{m1} \cdot g_{m2}}{\frac{1}{R_S} + g_{m2}} \right)^2}{\frac{1}{R_S^2 g_{m2}^2}} \cdot \frac{1}{R_S}$$

$$= 1 + \frac{1}{R_S g_{m2}} + \frac{1}{g_{m1} R_S g_{m2}} \left(\frac{g_{m1} \cdot g_{m2}}{\frac{1}{R_S} + g_{m2}} \right)^2$$



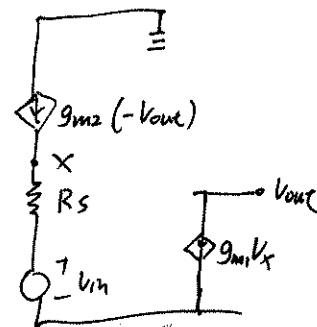
1^o noise of M_2

$$\overline{V_{n,M2}^2} = \frac{4KT\delta}{g_{m2}}$$

noise of M_1

$$\overline{V_{n,M1}^2} = \frac{4KT\delta \cdot g_{m1}}{g_{m1}^2 R_S^2 \cdot g_{m2}^2}$$

$$2^o \frac{V_{out}}{V_{in}} = ?$$



$$g_{m2}(-V_{out}) = \frac{V_X - V_{in}}{R_S}$$

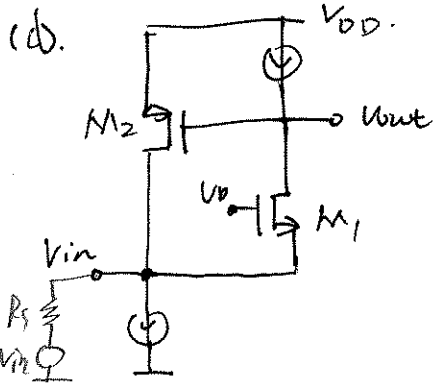
$$\frac{V_{out}}{V_{in}} = \frac{1}{g_{m2} R_S}$$

3^o NF

$$= 1 + \frac{\frac{1}{g_{m2}} + \frac{1}{g_{m1}} \left(\frac{g_{m1} \cdot g_{m2}}{\frac{1}{R_S} + g_{m2}} \right)^2}{\frac{1}{g_{m2}^2 R_S^2}} \cdot \frac{1}{R_S}$$

$$= 1 + \frac{1}{R_S g_{m2}} + \frac{1}{g_{m1} R_S g_{m2}} \left(\frac{g_{m1} \cdot g_{m2}}{\frac{1}{R_S} + g_{m2}} \right)^2$$

5.4 Solu: Part 2



1° noise of M_2

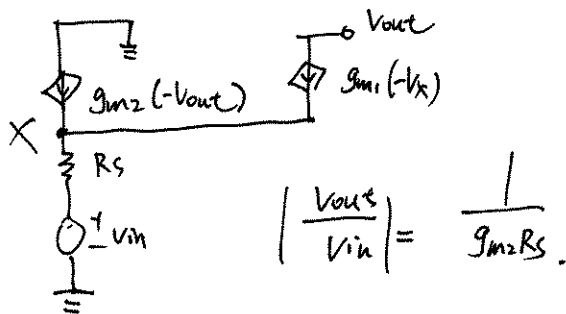
$$g_{m2}(-V_{out}) = I_{n2}$$

$$\overline{V_{n,M2}^2} = \frac{4kTR}{g_{m2}}$$

noise of M_1

$$\overline{V_{n,M1}^2} = \frac{4kTR}{g_{m1}g_{m2}R_s^2}$$

2° $\frac{V_{out}}{V_{in}} = ?$

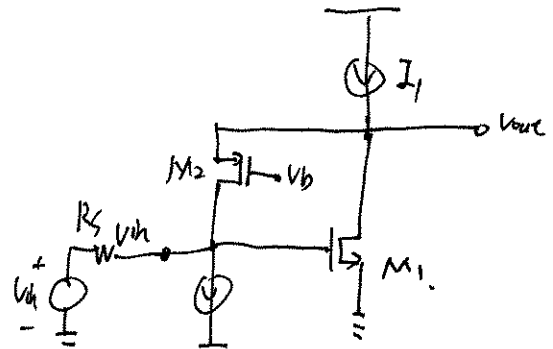


3° HF

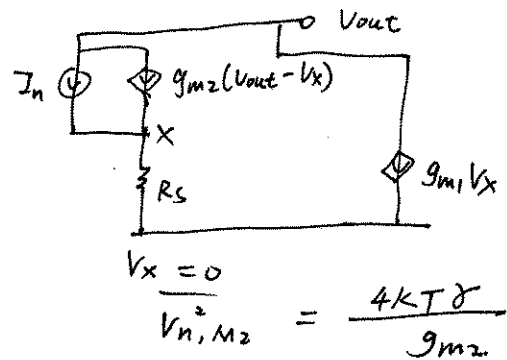
$$= 1 + \frac{\frac{1}{g_{m2}} + \frac{1}{g_{m1}g_{m2}R_s^2}}{\frac{1}{g_{m2}R_s}} \cdot \frac{1}{R_s}$$

$$= 1 + \frac{1}{g_{m2}R_s} + \frac{1}{g_{m1}R_s}$$

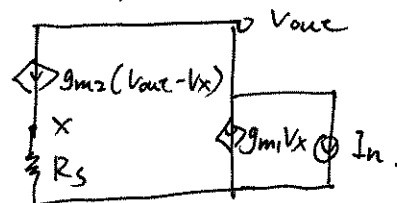
(c)



1° noise of M_2



noise of M_1



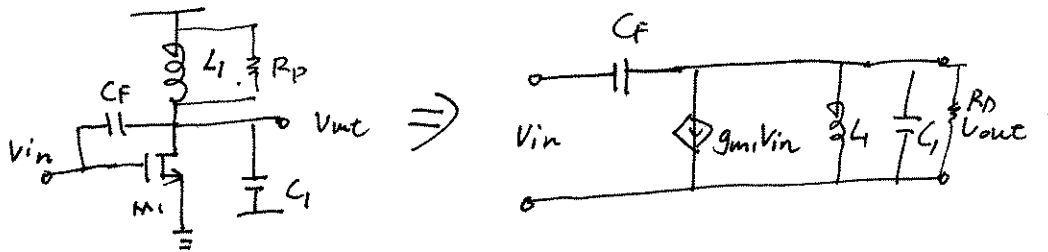
$$\begin{cases} g_{m1}V_x + I_{n1} + g_{m2}(V_{out} - V_x) = 0 \\ g_{m2}(V_{out} - V_x) = \frac{V_x}{R_s} \end{cases}$$

$$\Rightarrow \overline{V_{n,M1}^2} = 4kTR \cdot g_{m1} \left[\frac{g_{m2} + \frac{1}{R_s}}{g_{m2}(g_{m1} + 2g_{m2} + \frac{1}{R_s})} \right]^2$$

2° $\left| \frac{V_{out}}{V_{in}} \right| = \frac{1}{g_{m2}R_s - (g_{m2}R_s + 1) \cdot \frac{g_{m2}}{g_{m2} - g_{m1}}}$

3° NF = $1 + \frac{\text{①} + \text{②}}{\left| \frac{V_{out}}{V_{in}} \right|^2} \cdot \frac{1}{4kTR_s}$

5.5 solu:



at $\omega_0 = \frac{1}{\sqrt{L_1(C_1 + C_F)}}$ $|jC_1\omega_0| \ll g_m$.

$$\frac{V_{in} - V_{out}}{C_F s} = g_{m1} V_{in} + \frac{V_{out}}{L s} + \frac{V_{out}}{\frac{1}{C_1 s}} + \frac{V_{out}}{R_P}$$

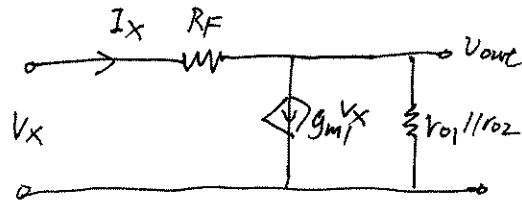
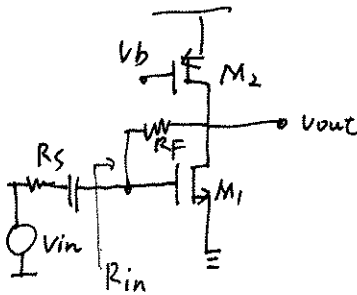
$$\frac{V_{out}}{V_{in}} = \frac{C_F s - g_{m1}}{(C_1 + C_F)s + \frac{1}{L s} + R_P}$$

(R_P is the model of loss).

at ω_0

$$\frac{V_{out}}{V_{in}}(\omega_0) = \frac{j\omega_0 C_F - g_{m1}}{R_P} \approx -\frac{g_{m1}}{R_P}$$

5.6 solu:



1° $R_{in} = ?$

$$\frac{V_x - I_x \cdot R_F}{r_{o1} \parallel r_{o2}} + g_{m1} V_x = I_x$$

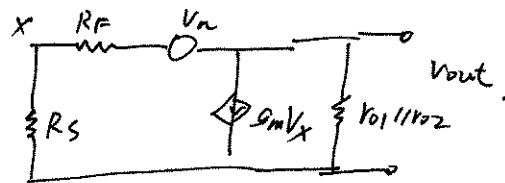
$$\Rightarrow \frac{V_x}{I_x} = \frac{R_F + r_{o1} \parallel r_{o2}}{1 + g_{m1} r_{o1} \parallel r_{o2}} = R_S$$

2°

$$\begin{aligned} \frac{V_{out}}{V_x} &= 1 - \frac{1 + g_{m1} (r_{o1} \parallel r_{o2})}{R_F + r_{o1} \parallel r_{o2}} \cdot R_F \\ &= 1 - \frac{R_F}{R_S} \end{aligned}$$

$$\frac{V_{out}}{V_{in}} = \frac{1}{2} \left(1 - \frac{R_F}{R_S} \right)$$

3° noise of R_F .



$$\overline{V_{n, RF}^2} = 4kTR_F \left(\frac{1 - g_{m1} R_F}{1 - g_{m1} R_S - \frac{R_F + R_S}{r_o}} \right)^2 \approx 4kTR_F$$

4° noise of M_1, M_2

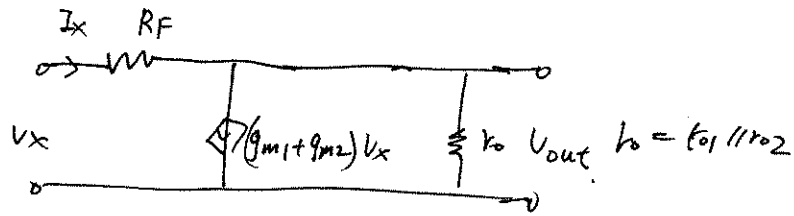
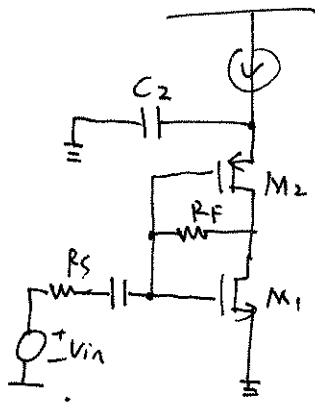
$$R_{out} = \frac{R_F + R_S}{\frac{R_F + R_S}{r_o} + R_F g_{m1} + 1} \quad (r_o = r_{o1} \parallel r_{o2})$$

$$\overline{V_{n, M_1 \& M_2}^2} = 4kT \gamma (g_{m1} + g_{m2}) R_{out}^2$$

5° NF

$$= 1 + \frac{4kTR_F + 4kTR_{out}^2 (g_{m1} + g_{m2})}{\left(\frac{1}{2} \left(1 - \frac{R_F}{R_S} \right) \right)^2} \cdot \frac{1}{4kTR_S}$$

S.7 Solu:



1° $R_{in} = ?$

$$I_x = (g_{m1} + g_{m2}) V_x + \frac{V_x - I_x R_F}{r_o}$$

$$\Rightarrow \frac{V_x}{I_x} = R_{in} = \frac{r_o + R_F}{(g_{m1} + g_{m2}) r_o + 1} = R_S$$

2° $\frac{V_{out}}{V_x} = 1 - \frac{R_F}{R_S}$

$$\frac{V_{out}}{V_{in}} = \frac{1}{2} \left(1 - \frac{R_F}{R_S} \right)$$

3° noise of R_F .

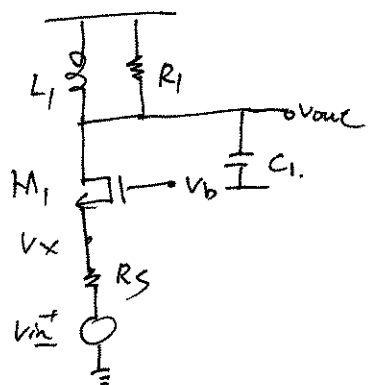
$$\overline{V_{n, R_F}^2} = 4kTR_F \left(\frac{1 - (g_{m1} + g_{m2}) R_F}{1 - (g_{m1} + g_{m2}) R_F - \frac{R_F + R_S}{r_o}} \right)^2$$

4° noise of M_1, M_2

$$\overline{V_{n, M_1 \& M_2}^2} = 4KT \gamma (g_{m1} + g_{m2}) \cdot \frac{R_F + R_S}{\frac{R_F + R_S}{r_o} + R_F (g_{m1} + g_{m2}) + 1}$$

$$5^\circ \text{ NF} = 1 + \frac{\overline{V_{n, R_F}^2} + \overline{V_{n, M_1 \& M_2}^2}}{\left[\frac{1}{2} \left(1 - \frac{R_F}{R_S} \right) \right]^2} \cdot \frac{1}{4kTR_S}$$

5.8 Solu:



$$1^{\circ} \frac{V_{out}}{V_x} = g_m \cdot R_1$$

$$\frac{V_{out}}{V_{in}} = \frac{\frac{1}{g_m}}{R_s + \frac{1}{g_m}} \cdot g_m \cdot R_1$$

$$= \frac{R_1}{R_s + \frac{1}{g_m}}$$

2^o noise of M_1

$$\overline{V_{n,M_1}^2} = \frac{4kT\gamma}{g_m} \left(\frac{R_1}{R_s + \frac{1}{g_m}} \right)^2$$

3^o noise of R_1

$$\overline{V_{n,R_1}^2} = 4kTR_1$$

$$4^{\circ} NF = 1 + \frac{1}{g_m R_s} + \frac{R_1}{R_s} \left(\frac{R_s + \frac{1}{g_m}}{R_1} \right)^2$$

$$= 1 + \frac{1}{g_m R_s} + \frac{1}{R_1 R_s} \left(R_s + \frac{1}{g_m} \right)^2$$

$$= 1 + \frac{1}{g_m R_s} + \frac{R_s}{R_1} \left(1 + \frac{1}{g_m R_s} \right)^2$$

$$NF < 1 + \frac{1}{g_m R_s} + 4 \frac{R_s}{R_1}$$

$$\Rightarrow g_m \cdot R_s > 1$$

$$\text{i.e. } g_m > \frac{1}{R_s}$$

5.9 Solu:

$$(1) \quad NF = 1 + \frac{\overline{V_{n,out}^2}}{A_v^2} \cdot \frac{1}{4kTR_S}$$

where $\overline{V_{n,out}^2}$ is not due to R_S .

$$\therefore NF = 1 + \frac{\overline{V_{n,in}^2}}{4kTR_S} = 3 \text{ dB.}$$

$$\therefore \overline{V_{n,in}^2} = 4kTR_S$$

$$\Rightarrow 50\%$$

$$(2) \quad NF = 1 \text{ dB} = 10^{0.1} = 1.26.$$

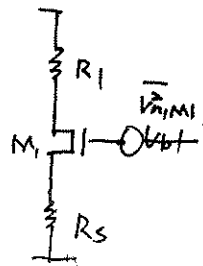
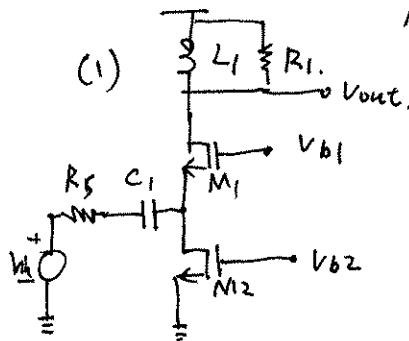
$$NF = 1 + \frac{\overline{V_{n,in}^2}}{4kTR_S} = 1.26$$

$$\overline{V_{n,in}^2} = 0.26 \cdot 4kTR_S$$

$$\Rightarrow 1 - \frac{0.26}{1.26} = -20.6\% = 79.4\%$$

...5.10 Solu:

Neglect channel-length modulation & body effect.



$$\Rightarrow \overline{v_{n, out M1}^2} = \frac{4KT}{g_m} \left(\frac{R_1}{R_S + \frac{1}{g_m}} \right)^2$$

$$= \frac{KT}{g_m} \frac{R_1^2}{R_S}$$

$$\Rightarrow \overline{v_{n, out M2}^2} = 4KT \cdot g_{m2} \cdot R_1^2$$

$$\Rightarrow \overline{v_{n, out R1}^2} = 4KT R_1$$

If input is matched. $\frac{v_{out}}{v_{in}} = \frac{R_1}{2R_S}$

$$NF = 1 + \frac{1}{g_{m1}R_S} + 4 \frac{R_S}{R_1} + 4R_S \cdot g_{m2}$$

(2).

If M_2 is replaced by R_B

$$\overline{v_{n, out, RB}^2} = \frac{4KT}{R_B} \cdot R_1^2$$

$$NF = 1 + \frac{1}{g_{m1}R_S} + 4 \frac{R_S}{R_1} + 4 \frac{R_S}{R_B}$$

5.11 Solu:

$$(R_1 C_X)^{-1} < \omega < \frac{g_{m2}}{C_{GS2} + C_X}$$

$$\frac{1}{R_1 C_X} \ll \frac{g_{m2}}{C_{GS2} + C_X}$$

$$\Rightarrow \frac{1}{R_1 C_X} \ll \frac{g_{m2}}{2 C_X}$$

$$\Rightarrow g_{m2} R_1 \gg 2$$

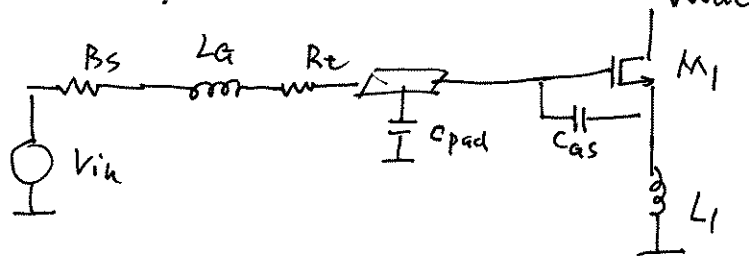
$$\Rightarrow g_{m1} R_1 \gg 2$$

gain of LNA is after 15 ~ 20 dB

$$\text{i.e. } g_{m1} R_1 = 32 \sim 100 \gg 2$$

\therefore Such a frequency range does exist.

Solu: 5.12. neglect. CLM, body-effect, C_{GD} & C_{pad} .



From. (5.89) Eq.

$$\Rightarrow V_{in} = I_{out} \left(j\omega L_1 + \frac{j(R_S + R_t)C_{GS}\omega}{g_m} \right) - I_{in} \frac{j(R_S + R_t)C_{GS}\omega}{g_m}$$

1° Transconductance gain:

$$\left| \frac{I_{out}}{V_{in}} \right| = \frac{1}{\omega_0 \left(L_1 + \frac{(R_S + R_t)C_{GS}}{g_m} \right)} = \frac{\omega_T}{(2R_S + R_t)\omega_0}$$

$$|I_{n,out}|_{M_1} = |I_n| \frac{(R_S + R_t)C_{GS}}{g_m L_1 + (R_S + R_t)C_{GS}} \approx \frac{|I_n|}{2 + \frac{R_t}{R_S}}$$

$$2^\circ \overline{|I_{n,out}|}_{M_1}^2 = 4KT \gamma g_m \cdot \frac{1}{\left(2 + \frac{R_t}{R_S}\right)^2}$$

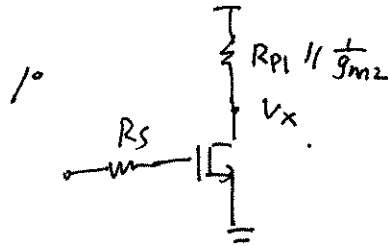
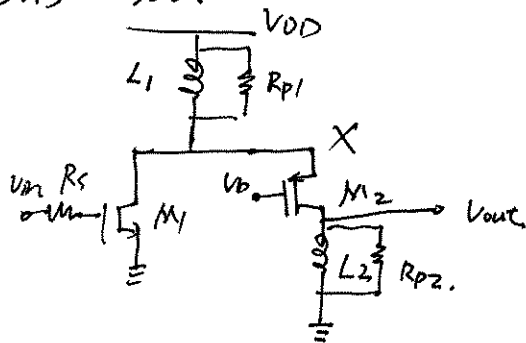
3° noise of R_t .

$$\overline{|I_{n,out}|}_{R_t}^2 = 4KT R_t \left[\frac{\omega_T}{(2R_S + R_t)\omega_0} \right]^2$$

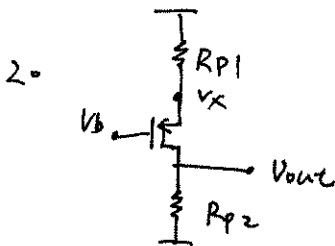
$$4^\circ NF = 1 + \frac{\overline{|I_{n,out}|}_{M_1}^2 + \overline{|I_{n,out}|}_{R_t}^2}{\left| \frac{I_{out}}{V_{in}} \right|^2} \cdot \frac{1}{4KTR_S}$$

$$= 1 + \frac{R_t}{R_S} + \gamma \cdot g_m R_S \left(\frac{\omega_0}{\omega_T} \right)^2$$

5.13 Solu:



$$\frac{V_x}{V_{in}} = g_{m1} \cdot (R_{p1} \parallel \frac{1}{g_{m2}})$$



$$\frac{V_{out}}{V_x} = \frac{g_{m2}}{1 + g_{m2} R_{p1}} \cdot R_{p2}$$

$$\therefore \frac{V_{out}}{V_{in}} = \frac{g_{m1} \cdot g_{m2} R_{p1} \cdot R_{p2}}{(1 + g_{m2} R_{p1})^2}$$

3° $\overline{V_{n,M1}^2} = \frac{4KT\gamma}{g_{m1}} \cdot \left| \frac{V_{out}}{V_{in}} \right|^2$

4° noise of M2

$$\overline{V_{n,M2}^2} = 4KT\gamma g_{m2} \cdot R_{p2}^2$$

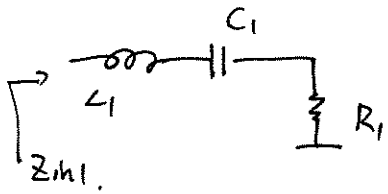
5° noise of Rp1

$$\overline{V_{n,Rp1}^2} = 4KT R_{p1} \cdot \left| \frac{V_{out}}{V_x} \right|^2$$

$$6° NF = 1 + \frac{\frac{4KT\gamma}{g_{m1}} \left| \frac{V_{out}}{V_{in}} \right|^2 + 4KT\gamma g_{m2} R_{p2}^2 + 4KT R_{p1} \left| \frac{V_{out}}{V_x} \right|^2}{\left| \frac{V_{out}}{V_{in}} \right|^2} \cdot \frac{1}{4KT R_s}$$

$$= 1 + \frac{\gamma}{g_{m1} R_s} + \frac{R_{p1}}{R_s} \left(\frac{1 + g_{m2} R_{p1}}{g_{m1} R_{p1}} \right)^2 + \frac{\gamma g_{m2} R_{p2}^2}{R_s} \cdot \left| \frac{V_{out}}{V_{in}} \right|^2$$

5.14 Solu:

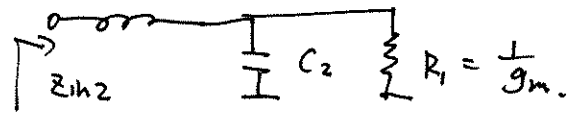


$$\begin{aligned} \operatorname{Re}\{Z_{in}\} &= R_1 \\ \operatorname{Im}\{Z_{in}\} &= \frac{L_1 C_1 \omega^2 - 1}{C_1 \omega} \\ &\approx 2L_1 \Delta\omega \frac{L_1 \Delta\omega}{\omega_0} \end{aligned}$$

$$S_{11} = \frac{j 2L_1 \Delta\omega \frac{L_1 \Delta\omega}{\omega_0}}{2R_1 + j 2L_1 \Delta\omega \frac{L_1 \Delta\omega}{\omega_0}}$$

$$\frac{2L_1 \Delta\omega \frac{L_1 \Delta\omega}{\omega_0}}{\sqrt{4R_1^2 + \left(2L_1 \Delta\omega \frac{L_1 \Delta\omega}{\omega_0}\right)^2}} \leq 0.1$$

\Rightarrow solve $\Delta\omega_{\max}$



$$\operatorname{Re}\{Z_{in2}\} \approx R_1$$

$$\begin{aligned} \operatorname{Im}\{Z_{in2}\} &= (L_2 - R_1^2 C_2) \omega \\ &\approx (L_2 - R_1^2 C_2) (\omega_0 + \Delta\omega) \end{aligned}$$

$$S_{11} = \frac{j (L_2 - R_1^2 C_2) (\omega_0 + \Delta\omega)}{2R_1 + j (L_2 - R_1^2 C_2) (\omega_0 + \Delta\omega)}$$

$$\frac{(L_2 - R_1^2 C_2) (\omega_0 + \Delta\omega)}{\sqrt{4R_1^2 + (L_2 - R_1^2 C_2) (\omega_0 + \Delta\omega)^2}} \leq 0.1$$

\Rightarrow solve $\Delta\omega_{\max}$

5.15 Solu:

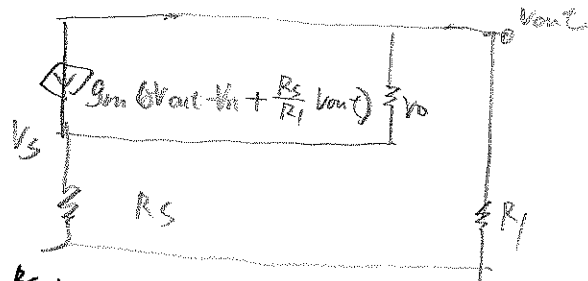
$$1^{\circ} \quad Z_{in} = \frac{\frac{1}{g_m} \parallel r_o}{(1 + g_m(R_1 \parallel r_o)\alpha)} = R_S$$

$$= \left(\frac{1}{g_m} \parallel r_o\right) \cdot (1 + g_m(R_1 \parallel r_o)\alpha)$$

$$= \frac{1}{g_m} \parallel r_o + \frac{r_o g_m^2 \alpha}{1 + r_o g_m} (R_1 \parallel r_o)$$

$$\frac{V_{out}}{V_{in}} = \frac{1}{2} \cdot \frac{g_m(R_1 \parallel r_o)}{1 + \alpha g_m(R_1 \parallel r_o)}$$

2^o noise of M_1 .



$$\frac{V_{out}}{R_1} + \frac{V_{out} + \frac{R_S}{R_1} V_{out}}{r_o} + g_m \left(\alpha V_{out} - V_{in} + \frac{R_S}{R_1} V_{out} \right) = 0$$

$$\Rightarrow \left. \frac{V_{out}}{V_{n1}} \right|_{M_1} = \frac{g_m}{\frac{1}{R_1} + g_m \left(\alpha + \frac{R_S}{R_1} \right) + \frac{1}{r_o} + \frac{R_S}{R_1 r_o}}$$

$$\overline{V_{n,M_1}^2} = \frac{4KT\alpha}{g_m} \cdot \left| \left. \frac{V_{out}}{V_{n1}} \right|_{M_1} \right|^2$$

3^o noise of R_1

$$R_{out} = R_1 \parallel r_o \parallel (1 + g_m R_S / (\alpha g_m))$$

$$\overline{V_{n,R_1}^2} = \frac{4KT}{R_1} R_{out}^2$$

$$4^{\circ} \quad NF = 1 + \frac{\overline{V_{n,M_1}^2} + \overline{V_{n,R_1}^2}}{\left| \frac{V_{out}}{V_{in}} \right|^2} \cdot \frac{1}{4KTR_S}$$

5.16 Solu:

From 4.15 Problem, we can find the gain from the gate of M to v_{out} is $\left| \frac{v_{out}}{v_{in}} \right|_{M1}$. So is $\overline{V_{n,F}^2}$.

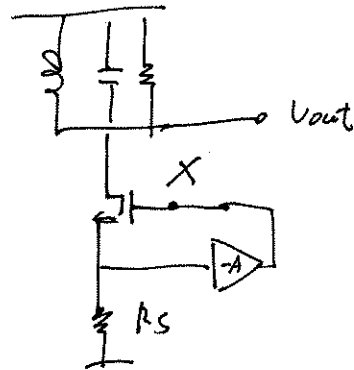
$$\overline{V_{n,F}^2}_{out} = \overline{V_{n,F}^2} \cdot \left| \frac{v_{out}}{v_{in}} \right|_{M1}^2$$

$$\therefore NF = 1 + \frac{\overline{V_{n,F}^2} + \overline{V_{n,R1}^2} + \overline{V_{n,M1}^2}}{\left| \frac{v_{out}}{v_{in}} \right|^2} \cdot \frac{1}{4kTR_S}$$

$$= NF_{\text{Problem 4.15}} + \frac{\overline{V_{n,F}^2}}{\left| \frac{v_{out}}{v_{in}} \right|^2} \cdot \frac{1}{4kTR_S}$$

5.17. Solu:

Proof:



$$\frac{v_{out}}{v_x} = - \frac{g_m R_L}{(1+A) g_m R_S + 1} \quad (\text{Eq. 5.122})$$

$$\frac{v_{out}}{v_{in}} = \frac{1}{2} (1+A) g_m R_L \quad (\text{matched})$$

The fourth term in Eq. (5.124)

$$= \frac{\overline{V_{nA}^2} \cdot A^2 \cdot \left(\frac{v_{out}}{v_x}\right)^2}{\left|\frac{v_{out}}{v_{in}}\right|^2} \cdot \frac{1}{4KTR_S}$$

$$= \frac{\overline{V_{nA}^2} \cdot A^2 \cdot \frac{g_m^2 R_L^2}{[(1+A) g_m R_S + 1]^2}}{\frac{1}{4} [(1+A) g_m R_S]^2} \cdot \frac{1}{4KTR_S}$$

$R_S = R_{in} \text{ (matched)}$

$$\approx \frac{\overline{V_{nA}^2} \cdot A^2 \cdot \frac{g_m^2 R_L^2}{4}}{\frac{1}{4} [(1+A) g_m R_L]^2} \cdot \frac{1}{4KTR_S}$$

$$= \frac{\overline{V_{nA}^2} \cdot A^2}{4KTR_S \cdot (1+A)^2}$$

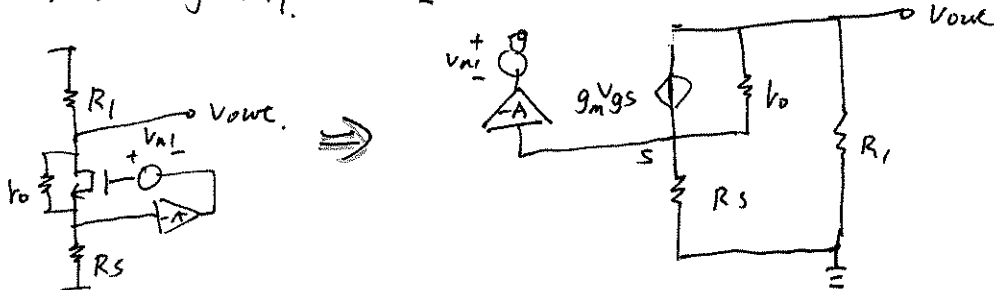
5.18 Solu:

$$1^{\circ} R_{in-original} = \frac{R_1 + r_o}{1 + g_m r_o}$$

$$R_{in} = \frac{R_1 + r_o}{1 + g_m(1+A)r_o} = R_S \text{ (matched)}$$

$$A_v = \frac{V_{out}}{V_{in}} = \frac{1}{1} \cdot \frac{(1+A)g_m r_o + 1}{r_o + R_S + (1+A)g_m r_o R_1} \cdot R_1 \text{ (matched)}$$

$$2^{\circ} \text{ noise of } M_1 = \frac{R_1}{2R_S}$$



$$\begin{cases} \frac{V_{out}}{R_1} + \frac{V_{out} - V_S}{r_o} + g_m(-A V_S + V_{n1} - V_S) = 0 \\ \frac{V_{out}}{R_1} + \frac{V_S}{R_S} = 0 \end{cases}$$

$$\Rightarrow \frac{V_{out, noise, M_1}}{V_{n1}} = \frac{-g_m V_{n1}}{\left(\frac{1}{R_1} + \frac{1}{r_o} + \frac{R_S}{R_1 r_o} + g_m(A+1)\frac{R_S}{R_1}\right)}$$

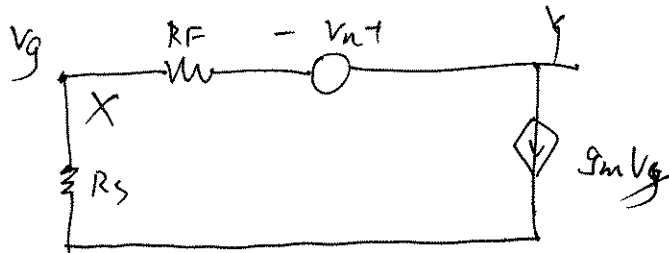
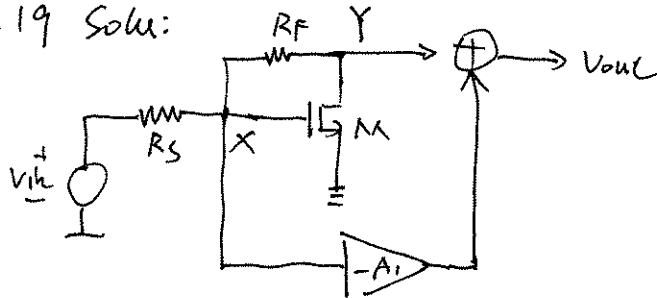
$$\text{(matched)} = \frac{-R_1 r_o g_m}{2(R_1 + r_o)}$$

3^o. noise of R_1

$$R_{out} = \frac{2R_1 r_o + R_1^2}{2(R_1 + r_o)} \quad \overline{V_{n,R_1}^2} = \frac{4kT}{R_1} \cdot R_{out}$$

$$4^{\circ} NF = 1 + \frac{\frac{4kT}{R_1} R_{out}^2 + \frac{4kT}{g_m} \left(\frac{R_1 r_o g_m}{2(R_1 + r_o)}\right)^2}{\left(\frac{R_1}{2R_S}\right)^2} \cdot \frac{1}{4kT R_S}$$

5.19 Solu:



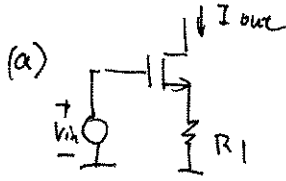
$$\frac{V_Y - V_X}{R_F + R_S} = -g_m v_g = \frac{V_Y - V_X - V_n}{R_F}$$

$$\Rightarrow \begin{cases} V_Y = V_n \\ V_X = 0 \end{cases}$$

The noise voltage of R_F produces V_n at node Y, but produces zero at node X.

\Rightarrow So the architecture cannot cancel the noise of R_F .

5.20 Solu:



$$I_{out} = K (V_{in} - I_{out} R_1 - V_{th})^2$$

$$\frac{\partial I_{out}}{\partial V_{in}} = K \cdot 2 \cdot (V_{in} - I_{out} R_1 - V_{th}) \left(1 - R_1 \frac{\partial I_{out}}{\partial V_{in}}\right)$$

$$\Rightarrow d_1 = \left. \frac{\partial I_{out}}{\partial V_{in}} \right|_{V_0, I_0} = \frac{2K (V_0 - I_0 R_1 - V_{th})}{1 + 2R_1 K (V_0 - I_0 R_1 - V_{th})} = \frac{g_m}{1 + g_m R_1}$$

(b).

$$\frac{\partial^2 I_{out}}{\partial V_{in}^2} = 2K \left(1 - R_1 \frac{\partial I_{out}}{\partial V_{in}}\right)^2 + 2K (V_{in} - R_1 I_{out} - V_{th}) \times \left(-R_1 \frac{\partial^2 I_{out}}{\partial V_{in}^2}\right)$$

$$\Rightarrow \left. \frac{\partial^2 I_{out}}{\partial V_{in}^2} \right|_{V_0, I_0} = 2\sigma_2 = \frac{2K}{(1 + g_m R_1)^3} = \frac{g_m^2}{2I_0 (1 + g_m R_1)^3}$$

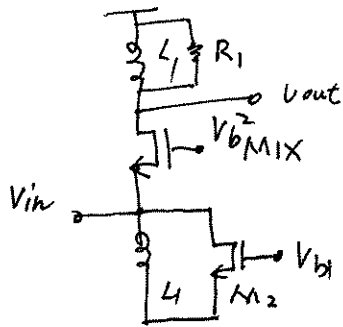
(c).

$$\begin{aligned} y &= a_1 x + \sigma_2 x^2 \\ &= a_1 \cos \omega t + \sigma_2 \frac{1 + \cos 2\omega t}{2} \\ &= a_1 \cos \omega t + \frac{1}{2} \sigma_2 \cos 2\omega t + \frac{\sigma_2}{2} \end{aligned}$$

$$|a_1 A_{1P2}| = \left| \frac{1}{2} \sigma_2 \cdot A_{2P2}^2 \right|$$

$$\begin{aligned} \therefore A_{1P2} &= 2 \cdot \frac{\sigma_1}{\sigma_2} = 2 \cdot \frac{\frac{g_m}{1 + g_m R_1}}{\frac{g_m^2}{2 \cdot 2I_0 (1 + g_m R_1)^3}} \\ &= \frac{8 I_0 (1 + g_m R_1)^2}{g_m} \end{aligned}$$

5.21. Solu:



$$\therefore g_m = \mu_n C_{ox} \frac{W}{L} (V_{GS} - V_{th}) \approx W,$$

$$g_{mix} = \frac{g_m}{\sqrt{2}}$$

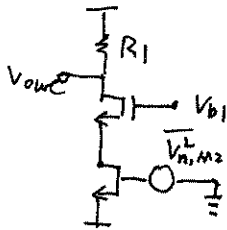
$$R_{out2} = \frac{\sqrt{2}}{\sqrt{2}-1} R_S \quad (\text{input matched}).$$

1° $\frac{V_{out}}{V_{in}} = \frac{g_m R_1}{\sqrt{2}}$

2° noise of MIX.

$$\overline{V_{n-out, mix}^2} = 4KT \frac{g_m}{\sqrt{2}} R_1^2$$

3° noise of M2



$$\overline{V_{n-out, M2}^2} = \frac{4KT}{g_{m2}} \left(g_{m2} \cdot \frac{\sqrt{2}}{g_m} \right)^2$$

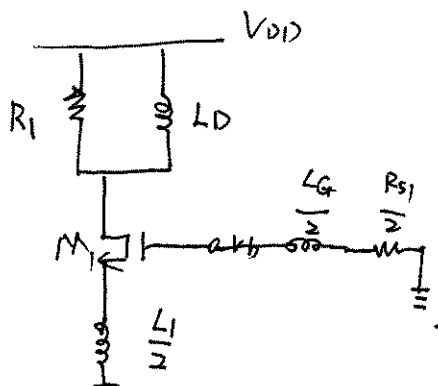
4° noise of R_1

$$\overline{V_{n-out, R1}^2} = 4KT \cdot R_1$$

5° $NF = 1 + \frac{\sqrt{2}}{g_m R_S} + \frac{4 \left(\frac{g_{m2}}{g_m} \right)^2}{(g_m R_S)^2 R_S} + \frac{2 R_1}{(g_m R_1)^2 R_S}$

5.22 Solu:

(a).



If the input is matched.

$$\frac{L_1}{2} \cdot \frac{g_{m1}}{C_{gs1}} = \frac{R_{S1}}{2}$$

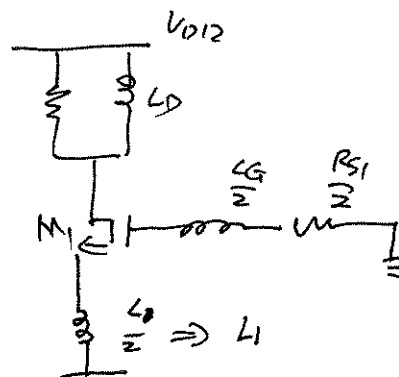
$$g_{m1} = \frac{R_{S1} C_{gs1}}{L_1} = \frac{2I_D}{V_{GS} - V_{th}}$$

$$= \sqrt{2I_D \mu n C_{ox} \frac{W}{L}}$$

$$\text{Power}_{\text{diff}} = \frac{g_{m1}^2}{2K} \cdot V_{DD} \cdot 2 = \frac{V_{DD} \cdot g_{m1}^2}{K}$$

$$\text{Power}_{\text{sig}} = \frac{g_{m1}^2}{2K} \cdot V_{DD} = \frac{1}{2} \text{Power}_{\text{diff}}$$

(b)



If we need NF is the same as signal-ended one.

$$A_v = \frac{W_1}{W_0} \frac{R_1}{2 \cdot \frac{R_{S1}}{2}} \text{ unchanged}$$

If only consider the noise of

MOS.

$$\overline{V_{n,M1}^2} = 2 \times K T \cdot g_{m1} \cdot R_1^2$$

So if g_{m1} changes to $g_{m1}/2$.

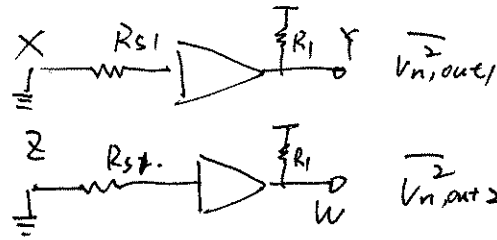
the M1's contribution in noise figure is unchanged.

$$\text{Power}_{\text{diff}} = \frac{\left(\frac{g_{m1}}{2}\right)^2}{2K} \cdot V_{DD} \cdot 2 = \frac{1}{4} \frac{V_{DD} \cdot g_{m1}^2}{K}$$

$$\text{Power}_{\text{sig}} = \frac{g_{m1}^2}{2K} \cdot V_{DD} = 2 \cdot \text{Power}_{\text{diff}}$$

5.23 solu:

if 1 to 2 balun is used,



gain from X to Y
is $\frac{R_L}{2R_{S1}}$

$$\overline{V_{n,out1}^2} = 4kTR_L + 4kTR_{S1} \left(\frac{R_L}{2R_{S1}} \right)^2 + kT \gamma \cdot \frac{R_L^2}{R_{S1}}$$

$$A_v = \frac{R_L}{2 \cdot R_{S1}} \cdot 2$$

$$\therefore NF = \frac{\overline{2V_{n,out}^2}}{2^2 \left(\frac{R_L}{2R_{S1}} \right)^2} \cdot \frac{1}{4kTR_{S1}}$$

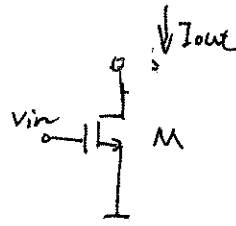
$$= \frac{2}{4} \left(\frac{R_L}{R_{S1}} \frac{4R_{S1}^2}{R_L^2} + 1 + \frac{\gamma}{4} \right)$$

$$= \frac{1}{2} + \frac{\gamma}{2} + \frac{2R_{S1}}{R_L}$$

From the result compared with 1 to 1 balun, NF is much smaller.

5.24 Solu:

$$(a) \quad I_{out} = K (V_{GS} - V_{th})^2 \\ = K (V_{in} - V_{th})^2$$



$$\frac{\partial I_{out}}{\partial V_{in}} = 2K (V_{in} - V_{th}) = \partial_1$$

$$\frac{\partial^2 I_{out}}{\partial V_{in}^2} = 2K = 2\partial_2 \Rightarrow \partial_3 = 0$$

$$\frac{\partial^3 I_{out}}{\partial V_{in}^3} = 0 = 6\partial_3 \Rightarrow \begin{cases} P_{1dB} = \infty \\ \omega_{P3} = \infty \end{cases}$$

$$(b) \quad I_{out} = \frac{1}{2} \mu_0 C_{ox} \frac{W}{L} \frac{(V_{in} - V_{th})^2}{1 + \left(\frac{\mu_0}{2V_{sat}L} + \theta \right) (V_{in} - V_{th})}$$

From (5.186) (5.187) Eq.

$$\partial_1 = K [2 - 3a(V_{GS} - V_{th})] (V_{GS} - V_{th})$$

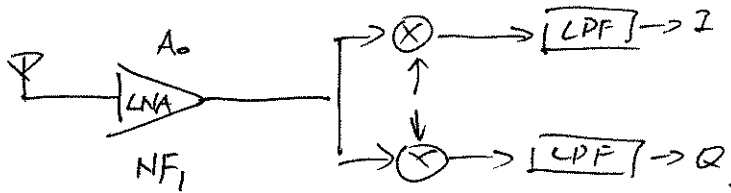
$$\partial_3 = -Ka$$

$$\text{where } K = \frac{1}{2} \mu_0 C_{ox} \frac{W}{L}, \quad a = \mu_0 / (2V_{sat}L) + \theta$$

$$A_{IIP3} = \sqrt{\frac{4}{3} \times \frac{2 - 3a(V_{GS} - V_{th})}{a} (V_{GS} - V_{th})}$$

$$A_{1dB} = \sqrt{0.145 \cdot \frac{2 - 3a(V_{GS} - V_{th})}{a} (V_{GS} - V_{th})}$$

6.1 soln:



assuming the conversion gain of mixers is unity.

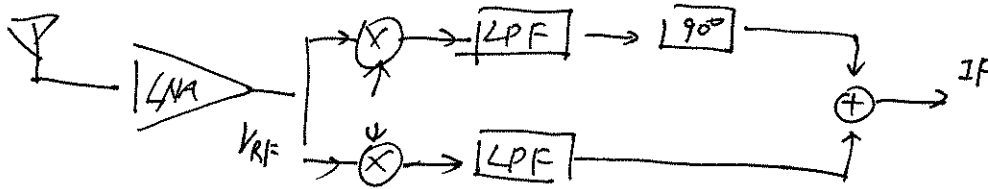
$$\therefore NF_1 = 1 + \frac{\overline{V_{n,out,LNA}^2}}{A_0^2} \cdot \frac{1}{4kTR_S}$$

$$\Rightarrow \overline{V_{n,out,LNA}^2} = (NF_1 - 1) \cdot A_0^2 \cdot 4kTR_S$$

$$\overline{V_{n,out}^2} = \overline{V_{n,out,LNA}^2} + 1 \cdot \overline{V_{n,in,mixer I or Q}^2} \cdot 2$$

$$\Rightarrow NF_{tot} = 1 + \frac{(NF_1 - 1)A_0^2 \cdot 4kTR_S + 2\overline{V_{n,in,mixer I or Q}^2}}{A_0^2} \cdot \frac{1}{4kTR_S}$$

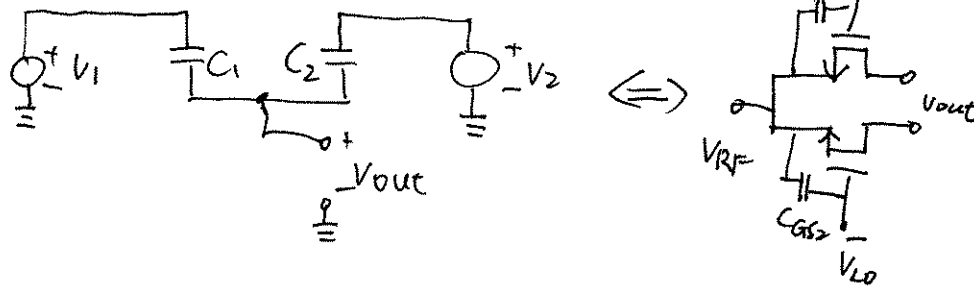
6.2 Solu:



the same as the 6.1's analysis.

$$NF_{tot} = 1 + \frac{1}{4kTR_S} \frac{(NF_{LNA} - 1) A_0^2 \cdot 4kTR_S + 2 \overline{V_{n,th,max I or Q}^2}}{A_0^2}$$

6.3 solu:



(a) $C_1 = C_2 = C_0 (1 + \delta_1 V)$

$$V_{out} @ \text{ RF input port}$$

$$= V_1 \cdot \frac{C_1}{C_1 + C_2} + V_2 \cdot \frac{C_2}{C_1 + C_2}$$

$$= V_0 \cos \omega_{LO} t \cdot \frac{C_1 - C_2}{C_1 + C_2}$$

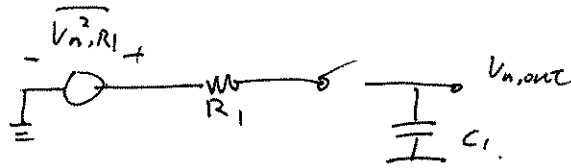
$$= 0$$

\therefore So for single-balanced mixer like Fig 6.5(b),
the LO-RF feedthrough at ω_{LO} vanishes if.

the circuit is symmetric.

(b). the result is the same as (a)
because of symmetry.

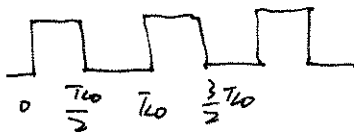
Soln: 6.4



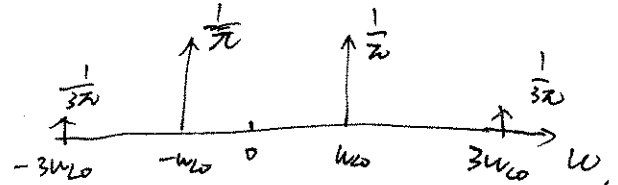
the $V_{n1}(t)$ is the product of $V_{n,LPF}(t)$ and a square wave between 0 and 1

Assume. $\frac{1}{R_1 C_1} \ll 3\omega_{LO}$.

$$\overline{V_{n,LPF}^2} = \overline{V_{nR_1}^2} \frac{1}{1 + (R_1 C_1 \omega)^2}$$



\Leftrightarrow



$$V_{n1}(f) = V_{n,LPF}(f) * \text{Square}(f)$$

$$= V_{n,LPF}(f) * \left[\frac{1}{j\omega} (1 - e^{-j\omega T_{LO}/2}) \frac{1}{T_{LO}} \sum_{k=-3}^{+3} \delta(f - \frac{k}{T_{LO}}) \right]$$

$$= V_{n,LPF}(f) * \left[\frac{1}{j\pi} \delta(f - \frac{1}{T_{LO}}) + \frac{1}{j\pi} \delta(f + \frac{1}{T_{LO}}) \right]$$

$$+ \frac{1}{j3\pi} \delta(f - \frac{3}{T_{LO}}) + \frac{1}{j3\pi} \delta(f - \frac{3}{T_{LO}})]$$

$$= V_{n,LPF}(f - \frac{1}{T_{LO}}) \cdot \frac{1}{j\pi} + V_{n,LPF}(f) (f + \frac{1}{T_{LO}}) \cdot \frac{1}{j\pi}$$

$$+ V_{n,LPF}(f - \frac{3}{T_{LO}}) \cdot \frac{1}{j3\pi} + V_{n,LPF}(f) (f + \frac{3}{T_{LO}}) \cdot \frac{1}{j3\pi}$$

$$\therefore \overline{V_{n1}^2}(f) = 2 \times \left(\frac{1}{\pi^2} + \frac{1}{9\pi^2} \right) \frac{2kTR_1}{1 + (2\pi R_1 C_1 f)^2}$$

6.5 Solu:

Eq. (6.54)

$$I_{IF}(t) = \frac{2}{\pi} \cdot \frac{\sin \pi d}{2d} \cdot I_{RF0} \cos \omega_{ZF} t$$

$$V_{IF}(t) = \frac{2}{\pi} \cdot \frac{\sin \pi d}{2d} \cdot I_{RF0} \cdot \cos \omega_{ZF}(t) \times \underbrace{2 \times Z_{BB}}_{\text{by differential output.}} \cdot V_{RF0}$$

So \Rightarrow voltage conversion gain

$$= \frac{2}{\pi} \cdot \frac{\sin \pi d}{2d} \cdot 2$$

where d stands for duty cycle.

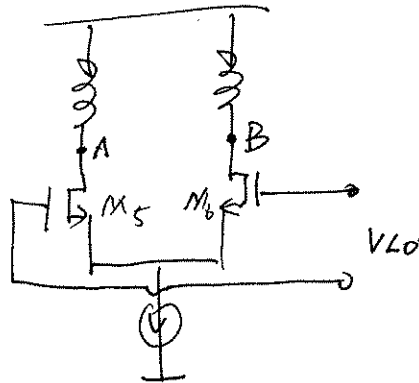
$$\lim_{d \rightarrow 0} \frac{2}{\pi} \cdot \frac{\sin \pi d}{2d} \cdot 2 = 2$$

So voltage conversion gain

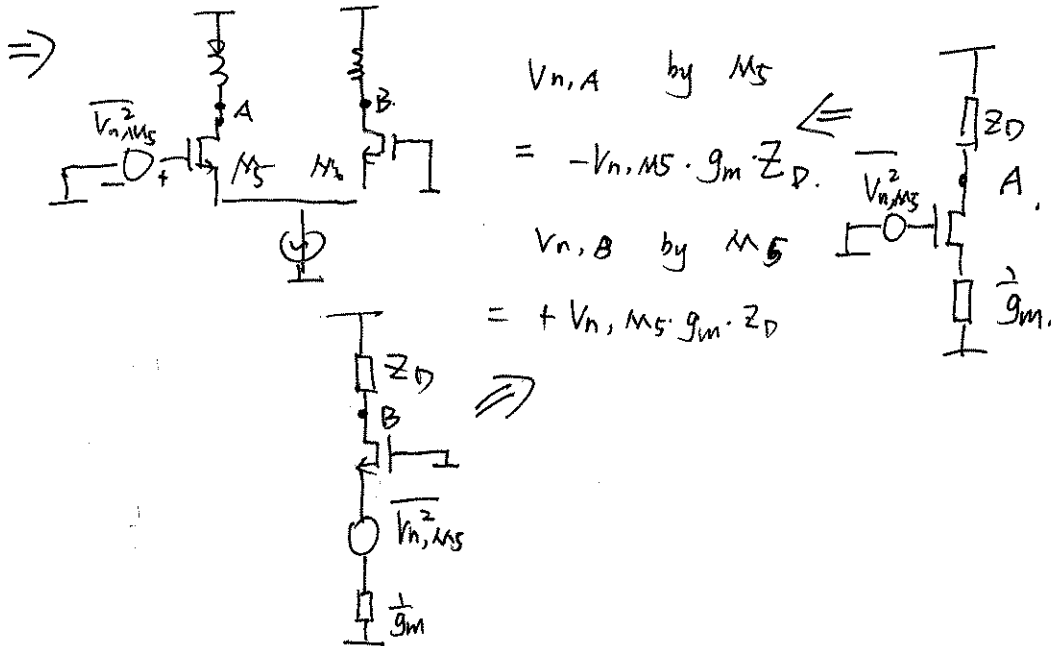
$$= 20 \log_{10}(2)$$

$$= 6 \text{ dB}$$

6.6 Solu:



Assume the buffer's MOS are in saturation region.
and the M_5 and M_6 are the same.

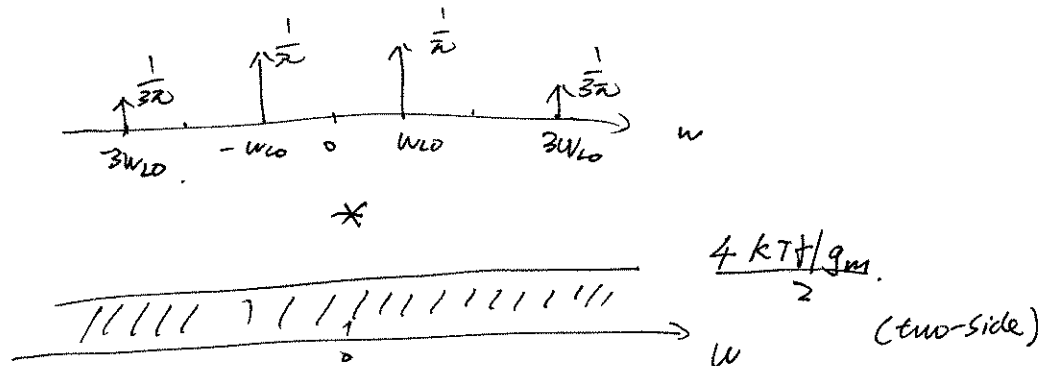


the situation of M_6 's noise is the same.

So we can easily say that. the noise of M_5 & M_6
appears differentially at nodes A & B.

6.7 solve:

LO: 50% duty cycle.

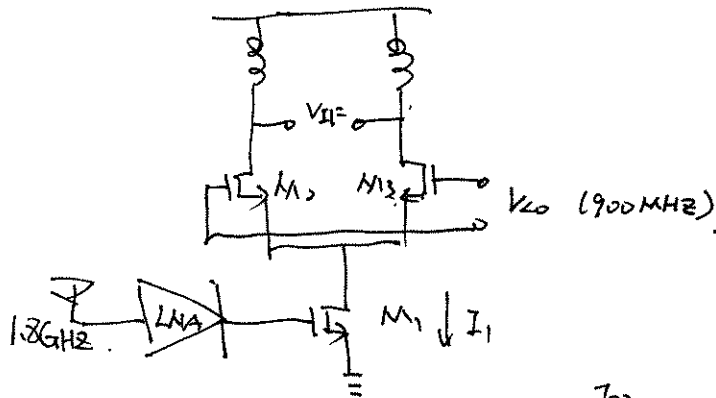


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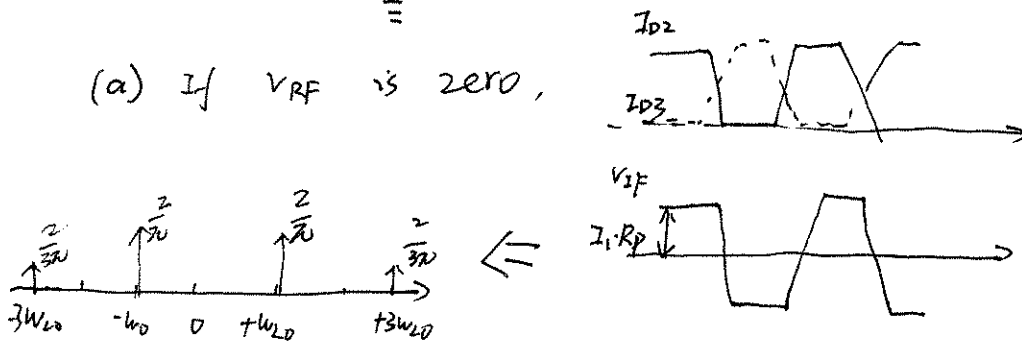
$$\begin{aligned} & \frac{4kT/g_m}{2} \left[\frac{1}{\pi^2} + \frac{1}{(3\pi)^2} + \frac{1}{(5\pi)^2} + \dots \right] \times 2 \\ &= 4kT/g_m \cdot \frac{1}{\pi^2} \cdot \frac{\pi^2}{8} \quad (\text{two side}) \end{aligned}$$

$$\Rightarrow \frac{4kT}{g_m} \cdot \frac{1}{\pi^2} \cdot \left[\frac{\pi^2}{4} \right]$$

6.9 Solu:



(a) If V_{RF} is zero,



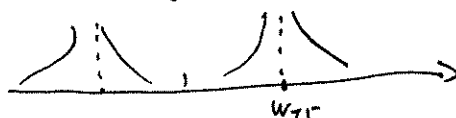
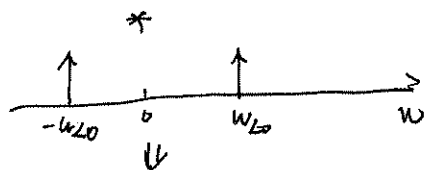
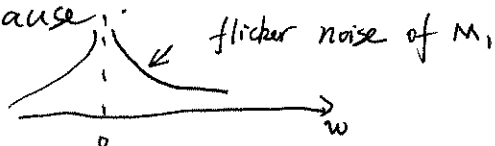
LO-IF feed through

$$= I_1 \cdot R_p \cdot \frac{4}{\pi} \quad \left(\frac{R_p}{\omega_0 L_1} = Q \right)$$

$$= I_1 \omega_0 L_1 Q \cdot \frac{4}{\pi}$$

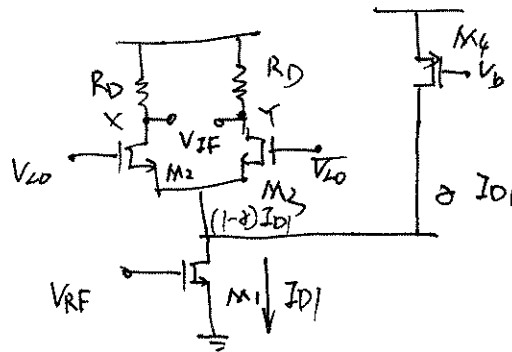
(b) flicker noise of M_1 is critical.

because:



we notice that flicker noise is transferred to IF band.

6.10 Solu:



$$I_2 = I_3 = \frac{1-\delta}{2} I_{D1} = \frac{1}{2} I'_{2,org} = \frac{1}{2} I'_{3,org}$$

$$\Rightarrow \delta = \frac{1}{2}$$

$$V_{n,out,org}(f) = \left(\frac{I_{D1} \cdot R_D}{\pi C_{p,Lo}} \right) \cdot V_{n2}(f)$$

$\Rightarrow R_D$ & gain hence can be doubled.

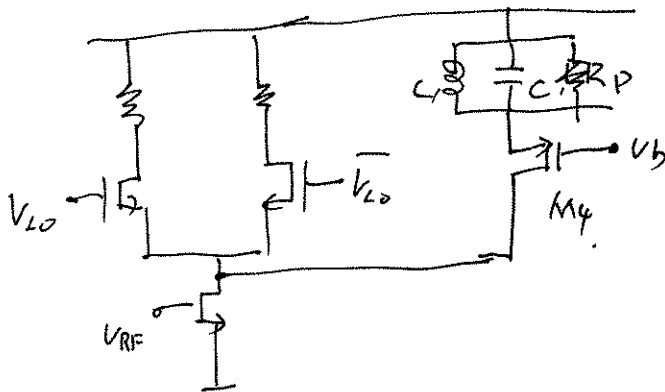
$$\therefore \overline{V_{n,out}^2} = \frac{1}{4} \overline{V_{n,out,org}^2}$$

$$\text{gain} = 2 \text{ gain}_{org}$$

$$\therefore \overline{V_{n,in}^2} = \frac{\overline{V_{n,out}^2}}{\text{gain}} = \frac{1}{16} \cdot \overline{V_{n,in,org}^2}$$

So, the input-referred flicker noise falls to sixteenth of original one.

6.11 Solu:



Let me analyse the noise current we saw from

V_{RF} MOS drain.

$$\frac{g_{m4}}{1 + g_{m4}R_P} \approx \frac{1}{R_P} \quad (g_{m4}R_P \gg 1)$$

$$\overline{I_{n,out}^2} = \frac{4kT\gamma}{g_{m4}} \left(\frac{1}{R_P} \right)^2 + 4kTR_P \left(\frac{1}{R_P} \right)^2$$

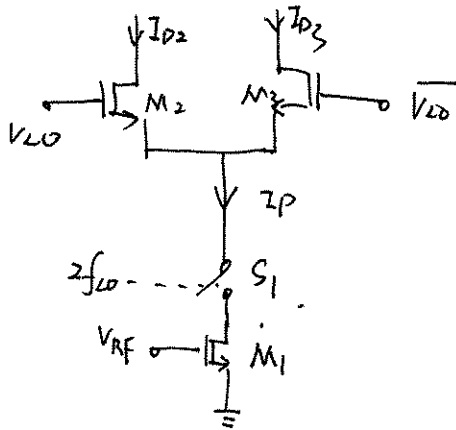
$$= \frac{4kT\gamma}{g_{m4}R_P^2} + \frac{4kT}{R_P}$$

So Eq. (6.116) should be re-written as

$$\overline{I_{n,M1}^2} + \overline{I_{n,M4}^2} + \overline{I_{n,RP}^2}$$

$$= 4kT\gamma \frac{2I_{D1}}{(V_{GS} - V_{th})_1} + \frac{4kT\gamma}{R_P^2} \frac{|V_{GS} - V_{th}|_4}{2I_{D1}} + \frac{4kT}{R_P}$$

6.12 Solu:



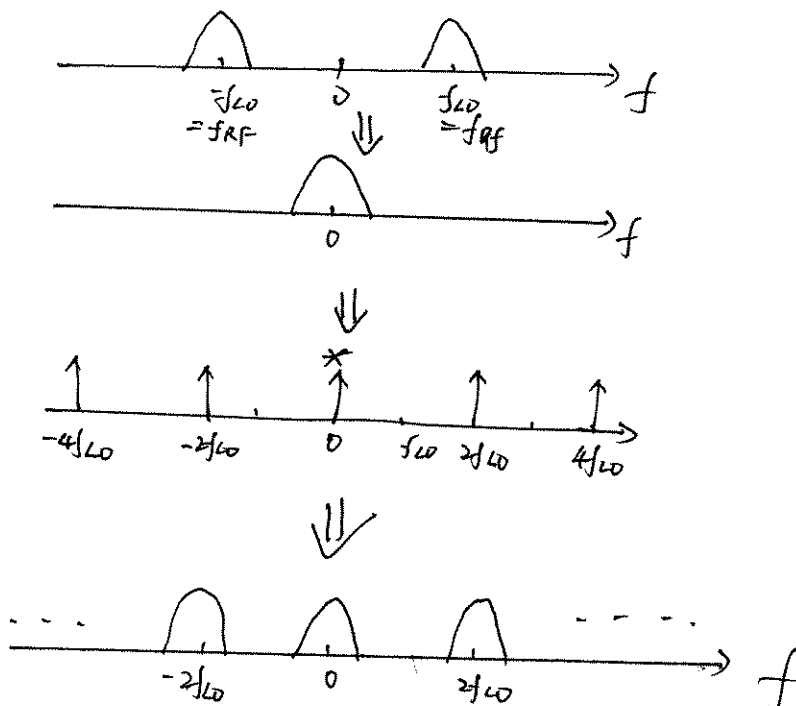
Yes, we can view this scheme as a differential pair whose tail current is modulated at a rate of $2f_{L0}$.

$$I_{D2} - I_{D3}(t) = \sum_{k=-\infty}^{+\infty} g_m \cdot V_{RF}(t) \cos(\omega_{L0} t) \cdot \delta(t - k \cdot \frac{T_{L0}}{2})$$

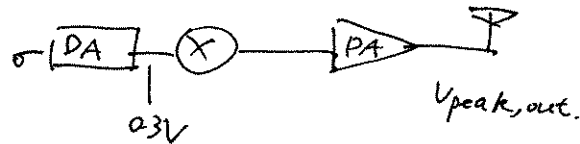
F.T.

$$I_{D2} - I_{D3}(f) = \sum_{k=-\infty}^{+\infty} g_m V_{RF}(f) * \delta(f - f_{L0}) \cdot \delta(t - 2kf_{L0})$$

We can appreciate from spectrum.



6.13 soln:



1^o gain

assume 50Ω antenna system.

$$V_{peak,out} = \sqrt{1W \cdot 50\Omega \cdot 2}$$

$$= 10V.$$

$$gain = \frac{V_{peak,out}}{V_{peak,in}} = \frac{10}{0.3} = 33.3.$$

2^o. noise power = -155 dBm.

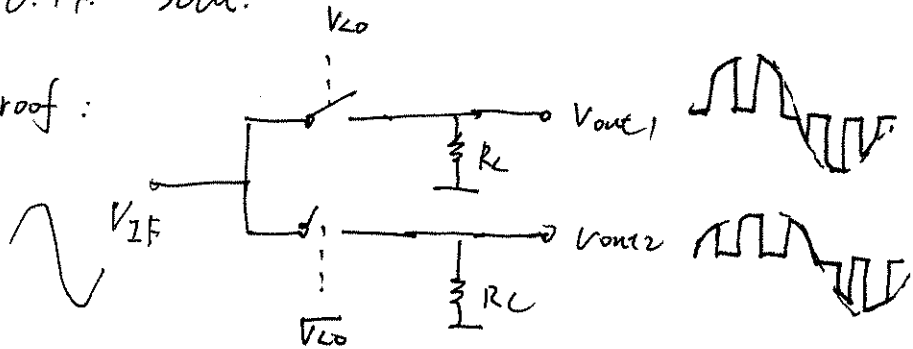
$$\Rightarrow 10^{-15.5} mW = 3.16 \times 10^{-16} mW.$$

$$V_{noise,rms,out} = 3.98 nV.$$

$$3^o \Rightarrow \overline{V_{noise,rms,in}^2} = \frac{(3.98 nV)^2}{gain^2} = 1.43 \times 10^{-20} V^2/Hz.$$

6.14. Solu:

Proof:



$$V_{out1}(t) = V_{IF}(t) \cdot \text{Square}(t)$$

$$V_{out2}(t) = V_{IF}(t) \cdot \text{Square}\left(t - \frac{T_{L0}}{2}\right)$$

only consider the fundamental freq.

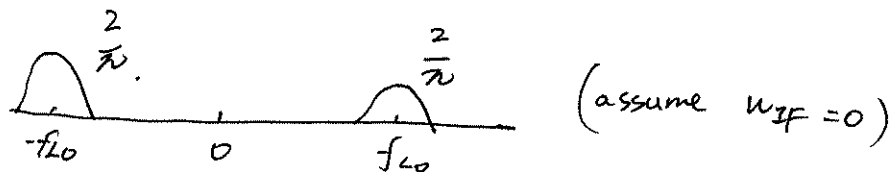
$$V_{out1}(t) \approx V_{IF}(t) \cdot \frac{2}{\pi} \cos \omega_{L0} t$$

$$V_{out2}(t) \approx -V_{IF}(t) \cdot \frac{2}{\pi} \cos \omega_{L0} t$$

$$\therefore V_{out}(t) = (V_{out1} - V_{out2})(t)$$

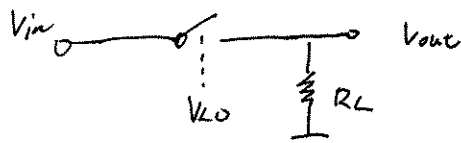
$$\text{F.T.} = V_{IF}(t) \frac{4}{\pi} \cos \omega_{L0} t$$

$$V_{out}(f) = \frac{2}{\pi} V_{IF}(f) * [\delta(f + f_{L0}) + \delta(f - f_{L0})]$$



\therefore voltage conversion gain of a single-balanced return-to-zero mixer is equal to $\frac{2}{\pi}$.

6.15 Solu:



Let's study the affect on the spectrum of V_{L0} about duty cycle's distortion.

$$V_{L0}(t) = \sum_{k=-\infty}^{+\infty} \text{rec}(\sigma t) \cdot \delta(t - k \cdot T_{L0})$$

where $\text{rec}(\sigma t) \Rightarrow$

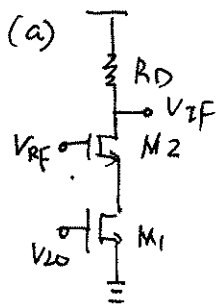
So duty cycle = $\frac{a}{T_{L0}}$.

That means, if T_{L0} is unchangeable, duty cycle distortion is equivalent to a 's distortion.

$$V_{L0}(f) = \frac{1}{T_{L0}} \cdot \sum_{k=-\infty}^{+\infty} \text{sinc}\left(\frac{f}{a}\right) \cdot \frac{1}{|a|} * \delta(f - k \cdot f_{L0})$$

From the above equation, we can find. duty cycle only affect the gain of mixer, but doesn't produce any feedthrough. at the output.

6.16 Solu:



$$V_{out}(t) = I_{RF}(t) \cdot R_D \frac{2}{\pi} \cos \omega_{LO} t + \dots$$

$$I_{RF}(t) = \frac{g_{m2}}{1 + g_{m2} R_{on1}} R_D V_{RF} \cdot \cos \omega_{RF}(t)$$

$$V_{ZF}(t) = \frac{1}{\pi} \cdot \frac{g_{m2}}{1 + g_{m2} R_{on1}} R_D V_{RF} \cdot \cos(\omega_{RF} - \omega_{LO})t$$

$$\therefore \frac{V_{ZF,P}}{V_{RF,P}} = \frac{1}{\pi} \cdot \frac{g_{m2}}{1 + g_{m2} R_{on1}} \cdot R_D$$

(b). If $R_{on} \ll \frac{1}{g_{m1}}$

$$\therefore \text{gain} = \frac{1}{\pi} \cdot g_{m2} \cdot R_D$$

$$V_{RF} = V_m \cos \omega_1 t + V_m \cos \omega_2 t + V_{BS0}$$

$$I_{DM2} = \frac{1}{2} \mu_n C_{ox} \frac{W}{L} V_m^2 \cdot \cos(\omega_1 - \omega_2)t$$

$$\frac{1}{2} \mu_n C_{ox} \frac{W}{L} V_{HP2}^2 R_D = \frac{1}{\pi} \cdot g_{m2} \cdot R_D \cdot V_{ZP2}$$

$$\Rightarrow V_{HP2} = \frac{2}{\pi} (V_{BS0} - V_{th})_2$$

7.1 Solu:

N -turn spirals.

$$\begin{aligned} L_{tot} = & L_1 + L_2 + \dots + L_N \\ & + M_{12} + M_{13} + M_{14} + \dots + M_{1N} \\ & + M_{23} + M_{24} + \dots + M_{2N} \\ & + M_{34} + \dots \\ & \vdots \\ & + M_{N-1N} \end{aligned} \left. \vphantom{\begin{aligned} L_{tot} = & L_1 + L_2 + \dots + L_N \\ & + M_{12} + M_{13} + M_{14} + \dots + M_{1N} \\ & + M_{23} + M_{24} + \dots + M_{2N} \\ & + M_{34} + \dots \\ & \vdots \\ & + M_{N-1N} \end{aligned}} \right\} C_N^2 \cdot M_{ij}.$$

$$C_N^2 = \frac{N(N-1)}{2} \quad \text{terms for mutual inductance.}$$

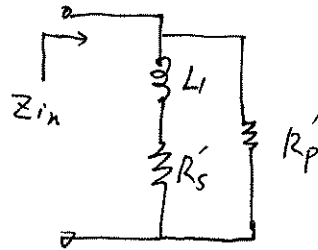
Total terms Number

$$= N + \frac{N(N-1)}{2}$$

$$= \frac{N^2 - N + 2N}{2} = \frac{N(N+1)}{2}.$$

7.2 Solu.

Proof:



$$Z_{in}(s) = (sL_1 + R_s') \parallel R_p'$$

$$= \frac{sL_1 R_p' + R_s' R_p'}{sL_1 + R_s' + R_p'}$$

$$Z_{in}(j\omega) = \frac{R_s' R_p' + j\omega L_1 R_p'}{R_s' + R_p' + j\omega L_1} = \frac{(R_s' R_p' + j\omega L_1 R_p')(R_s' + R_p' - j\omega L_1)}{(R_s' + R_p')^2 - \omega^2 L_1^2}$$

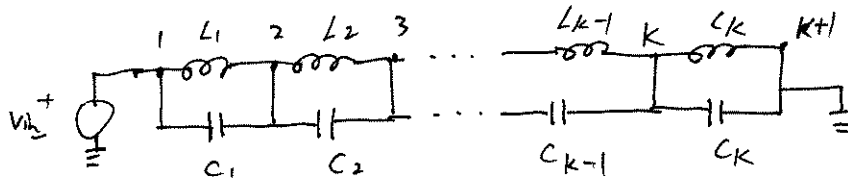
$$Q \triangleq \frac{\text{Im}(Z_{in})}{\text{Re}(Z_{in})} = \frac{\omega L_1 R_p' (R_s' + R_p') - \omega L_1 (R_s' R_p')}{R_s'^2 R_p' + R_p'^2 R_s' + \omega^2 L_1^2 R_p'}$$

$$= \frac{\omega L_1 R_p'^2}{L_1^2 \omega^2 R_p' + R_s' R_p' (R_s' + R_p')}$$

$$= \frac{L_1 \omega}{L_1^2 \omega^2 + R_s' (R_s' + R_p')}$$

7.3 Solu:

Proof. model of interwinding capacitance

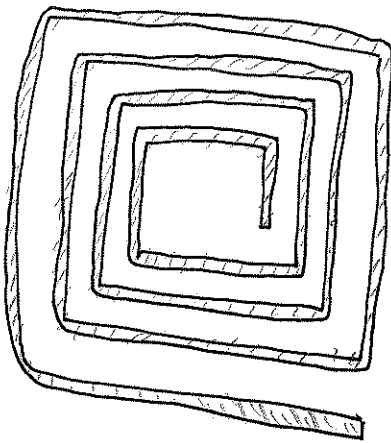


For N -turn spiral inductor.

the equivalent interwinding capacitance

is

$$C_{eq} = \frac{C_1 + C_2 + \dots + C_{4(N-1)}}{[4(N-1)]^2}$$



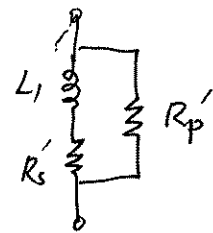
For example: 4-turn spiral inductor.

$$K = 4(N-1)$$

$$C_{eq} = \frac{C_1 + C_2 + \dots + C_{4(N-1)}}{[4(N-1)]^2}$$

7.4 Solu:

Eq. (7.62) $Q = \frac{L_1 \omega R_p'}{L_1^2 \omega^2 + R_s'(R_s' + R_p')}$ \Leftarrow



For Fig. 7.37 (b) $Q_1 = \frac{L \omega R_1}{L \omega^2 + R_s(R_s + R_1)}$

For Fig. 7.37 (d)

$$Q_2 = \frac{\frac{L}{2} \omega \cdot R_1}{\frac{L}{2} \omega^2 + \frac{R_s}{2} \left(\frac{R_s}{2} + R_1 \right)}$$

$$= \frac{L \omega R_1}{L \omega^2 + R_s \left(\frac{R_s}{2} + R_1 \right)}$$

We can find the differences between Q_1 & Q_2
 the denominator of Q_2 is smaller than
 that of Q_1 .

7.5 Solu:

For Fig. 7.41 (a).

Using the right-hand rule, we observe that

the magnetic field due to L_1 points into page.

So does the magnetic field due to L_2 ,
(at far-from point)

On the other hand, for Fig. 7.41 (b)

Using the right-hand rule, we also observe

that the magnetic field due to L_1 points out of the
page but that due to L_2 points into the page
(at far-from point).

So Fig 7.41 (b)'s topology can cancel the magnetic field
at a point far from the circuit. and has

the less net magnetic field.

7.6 soln:

$$L = 5 \text{ nH}, \quad W = 5 \mu\text{m}, \quad S = 0.5 \mu\text{m}, \quad N = 4.$$

$$R_0 = 22 \text{ m}\Omega/\square$$

$$f_{\text{crit}} \approx \frac{3.1}{2\pi\mu} \cdot \frac{W+S}{W^2} \cdot R_0$$

$$= \frac{3.1}{2\pi \cdot 4\pi \times 10^{-7}} \cdot \frac{5 \mu + 0.5 \mu}{(5 \mu)^2} \cdot 22 \text{ m}\Omega/\square$$

$$= 1.9 \text{ GHz}.$$

$$R_{\text{eff}} = R_0 \left[1 + \frac{1}{16} \left(\frac{900 \text{ M}}{1.9 \text{ G}} \right)^2 \right] = 1.0224 R_0 = 16 \text{ }\Omega.$$

$$(\text{For } R_0 = 15.75 \text{ }\Omega \Leftarrow L = 5 \text{ nH}).$$

From Eq. (7/5) we can calculate the length.

So with length, width, space and no. of turn,
the outer diameter is determinate.

7.7 Solu:

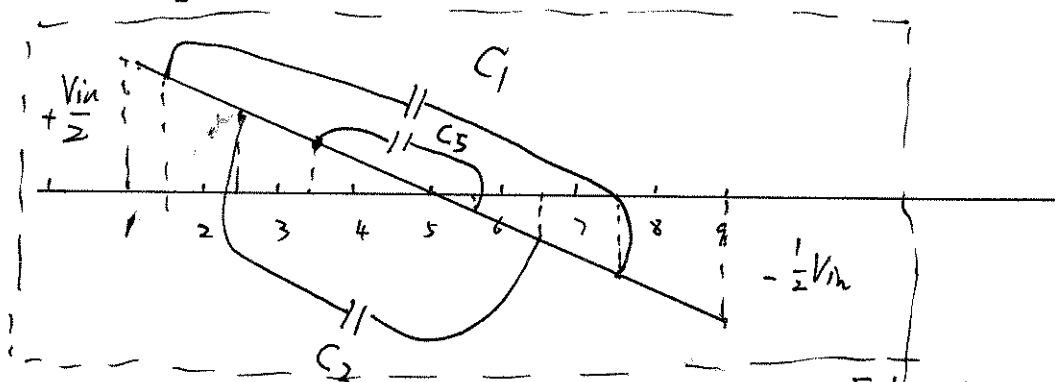
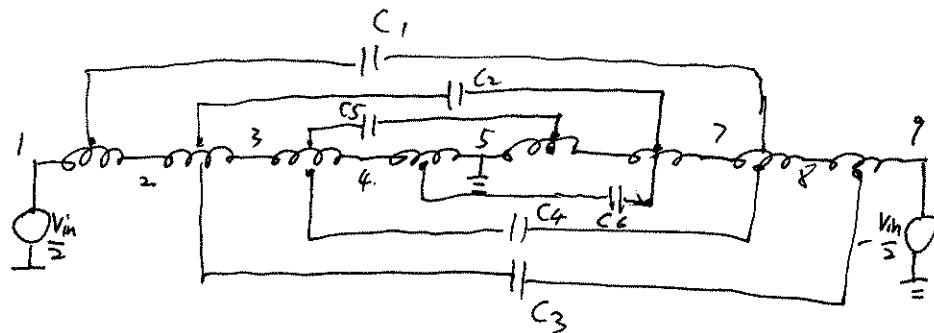
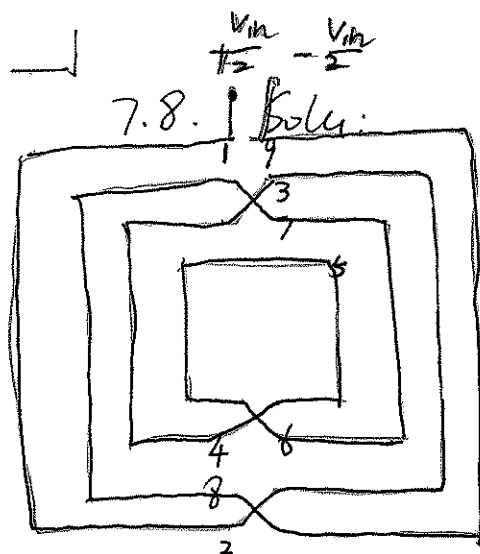
$$Y_{11}(s) = \frac{I_{in}(s)}{V_{in}(s)} = \frac{R_{sub} + L_2 s}{L_1 R_{sub} s + (L_1 L_2 - M^2) s^2}$$

$$Y_{11}(j\omega) = \frac{R_{sub} + jL_2\omega}{jL_1 R_{sub}\omega + (M^2 - L_1 L_2)\omega^2}$$

$$= \frac{(R_{sub} + jL_2\omega)[(M^2 - L_1 L_2)\omega^2 - jL_1 R_{sub}\omega]}{[(M^2 - L_1 L_2)\omega^2]^2 + L_1^2 R_{sub}^2 \omega^2}$$

$$= \underbrace{\frac{R(M^2 - L_1 L_2)\omega^2 + L_1 L_2 R_{sub}}{(M^2 - L_1 L_2)\omega^2 + L_1^2 R_{sub}^2}}_{\frac{1}{R_P'}} + \underbrace{\frac{1}{j\omega} \left(\frac{L_1 R_{sub}^2 - L_2 (M^2 - L_1 L_2)\omega^2}{L_1^2 R_{sub}^2 + (M^2 - L_1 L_2)^2 \omega^2} \right)}_{\frac{1}{j\omega L'}}$$

We can find that the result is not the same
at that shown in Eq. (7.55).



$C_1 \& C_3$ sustains $\frac{6}{8} V_{in}$

$C_2 \& C_4$ sustains $\frac{4}{8} V_{in}$

$C_5 \& C_6$ sustains $\frac{2}{8} V_{in}$

$$E_{tot} = 2 \cdot \left[\frac{1}{2} C \left(\frac{6}{8} V_{in} \right)^2 + \frac{1}{2} C \left(\frac{4}{8} V_{in} \right)^2 + \frac{1}{2} C \left(\frac{2}{8} V_{in} \right)^2 \right]$$

$$= \frac{7}{8} \cdot C \cdot V_{in}^2$$

$$\therefore C_1 + C_2 + \dots + C_6 = C_{tot} \Rightarrow C = \frac{C_{tot}}{8}$$

$$\therefore E_{tot} = \frac{7}{8} \cdot \frac{C_{tot}}{8} \cdot V_{in}^2$$

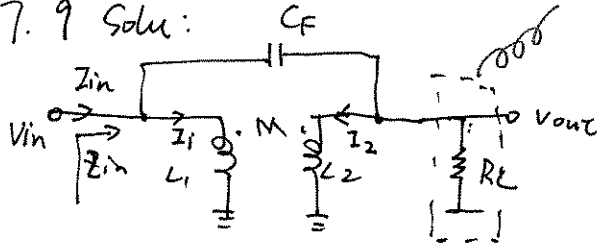
$$\Rightarrow C_{eq} = \frac{7}{24} C_{tot}$$

For N -turn $\Rightarrow E_{tot} = 2 \cdot \frac{1}{2} \cdot \frac{C_{tot}}{2(N-1)} V_{in}^2 \cdot \left[\left(\frac{N-1}{N} \right)^2 + \left(\frac{N-2}{N} \right)^2 + \left(\frac{N-3}{N} \right)^2 + \dots + \left(\frac{1}{N} \right)^2 \right]$

$$C_{eq} = \frac{2N-1}{6N} \cdot C_{tot} \Leftarrow = \frac{C_{tot} \cdot V_{in}^2}{2(N-1)} \cdot \frac{1}{N^2} \cdot \frac{(N-1)N(2N-1)}{6}$$

$$= \frac{C_{tot}}{12} \cdot V_{in}^2 \cdot \frac{2N-1}{N}$$

7.9 Solu:



$$\begin{cases} V_{in} = L_1 s I_1 + M s I_2 \\ V_{out} = L_2 s I_2 + M s I_1 \\ I_{in} = I_1 + (V_{in} - V_{out}) s C_F \end{cases} \Rightarrow \begin{cases} I_1 = V_{in} \frac{1 - \frac{s^2 M C_F (L_1 - \frac{M^2}{L_1})}{1 + L_2 s^2 C_F - \frac{M^2}{L_1} s^2 C_F}}{L_1 s} \\ I_2 = \frac{V_{in} s C_F (L_1 - \frac{M^2}{L_1})}{1 + L_2 s^2 C_F - \frac{M^2}{L_1} s^2 C_F} \end{cases}$$

$$(V_{in} - V_{out}) s C_F = I_2$$

$$\Rightarrow Z_{in}(s) = \frac{V_{in}(s)}{I_{in}(s)} = \frac{L_1 s I_1 + M s I_2}{I_1 + (V_{in} - L_2 s I_2 - M s I_1) s C_F}$$

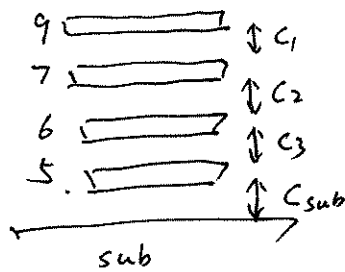
Substitute I_1, I_2 into $Z_{in}(s)$. then we can get

the result.

$$Z_{in}(s) = \frac{L_1 s - \frac{M \cdot C_F (L_1 - M) s^3}{1 + s^2 C_F (L_2 - M)}}{1 + s^2 C_F (L_1 - M) - \frac{s^4 C_F^2 (L_2 - M) (L_1 - M)}{1 + s^2 C_F (L_2 - M)}}$$

Solu: 7.10.

Assume we choose to use Metal 9, metal 7,
metal 6 and metal 5.



each spiral must provide

an inductance of $\frac{4.96 \text{ nH}}{16} = 0.31 \text{ nH}$.

choose $N = 3$, $w = 4 \text{ } \mu\text{m}$, $s = 0.5 \text{ } \mu\text{m}$.

From Eq. (7.15), yields

$$l_{\text{tot}} \approx 167 \text{ } \mu\text{m}$$

$$D_{\text{out}} = \frac{l_{\text{tot}}}{4N} + w + (N-1)(w+s)$$

each spiral has an area of $167 \text{ } \mu\text{m} \times 4 \text{ } \mu\text{m} = 667 \text{ } \mu\text{m}^2$

$$\therefore C_1 = 167 \times 667 \times 10^{-18} = 10.7 \text{ fF}$$

$$C_2 = 88 \times 667 \times 10^{-18} = 58.7 \text{ fF} \quad C_{\text{sub}} = 5.7 \text{ fF}$$

$$C_3 = 88 \times 667 \times 10^{-18} = 58.7 \text{ fF}$$

$$\therefore C_{\text{eq}} = \frac{4 \cdot (C_1 + C_2 + C_3) + C_{\text{sub}}}{3 \cdot 4^2} = 10.8 \text{ fF}$$

7.11. Solu:

For pn-junction varactor.



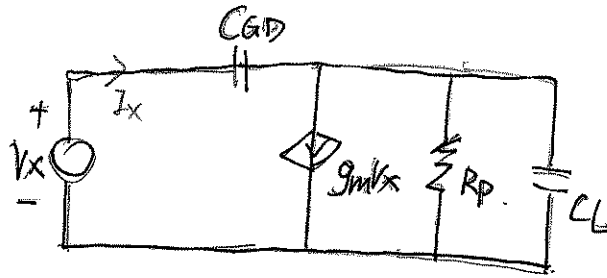
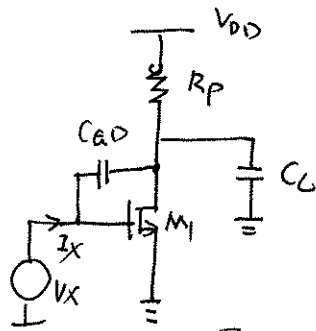
$$C_j = \frac{C_{j0}}{\left(1 + \frac{V_D}{V_0}\right)^m}$$

Range of control voltage:

$$V_D \in [0, V_{DD}]$$

the output swing should be as much as the supply voltage, however the actual output swing depends on the LC VCO design.

8.1. Solu:



$$I_X = g_m V_X + \frac{V_X - I_X \cdot \frac{1}{sC_{GD}}}{R_P \parallel \frac{1}{sC_L}}$$

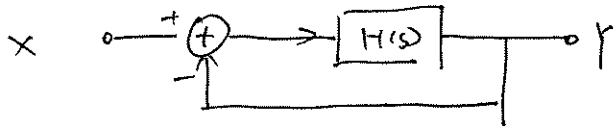
$$\begin{aligned} \Rightarrow \frac{I_X}{V_X} = Y_{in} &= \frac{g_m + \frac{1}{R_P \parallel \frac{1}{sC_L}}}{1 + \frac{1}{sC_{GD}} \cdot \frac{1}{R_P \parallel \frac{1}{sC_L}}} \\ &= \frac{(R_P \parallel \frac{1}{sC_L}) g_m + 1}{(R_P \parallel \frac{1}{sC_L}) + \frac{1}{sC_{GD}}} \\ &= \frac{s^2 C_L C_{GD} R_P + (R_P g_m + 1) C_{GD} \cdot s}{1 + s R_P (C_{GD} + C_L)} \end{aligned}$$

$$s = j\omega$$

$$Y_{in}(j\omega) = \frac{-\omega^2 C_L C_{GD} R_P + j\omega C_{GD} (R_P g_m + 1)}{1 + j\omega R_P (C_{GD} + C_L)}$$

$$\begin{aligned} \therefore \text{Re}[Y_{in}(j\omega)] &= \frac{\omega^2 C_{GD} R_P (R_P g_m + 1) (C_{GD} + C_L) - \omega^2 C_L C_{GD} R_P}{1 + \omega^2 R_P^2 (C_{GD} + C_L)^2} \\ &= \frac{\omega^2 R_P C_{GD} [(R_P g_m + 1) C_{GD} + R_P g_m C_L]}{1 + \omega^2 R_P^2 (C_{GD} + C_L)^2} \end{aligned}$$

8.2 Solu:



$$|H(j\omega_1)| = 1$$

$$\angle H(j\omega_1) = 170^\circ$$

$$\frac{Y}{X}(s) = \frac{H(s)}{1 + H(s)}$$

$$\left| \frac{Y}{X}(j\omega_1) \right| = \frac{1}{|1 + e^{j\frac{170}{180}\pi}|} = 1/0.174 = 5.73$$

$$\angle \frac{Y}{X}(j\omega_1) = \frac{170}{180}\pi - \angle(1 + H(j\omega_1))$$

$$= \frac{17}{18}\pi - 1.4835 = 1.4835 \Rightarrow 85^\circ$$

So if $x(t)$ is a sinusoidal signal at ω_1 ,
the amplitude ^{of output} will be multiplied by $1/0.174$ & the phase
 $= 5.73$
will change by 85° .

8.3 Solu:

$$|H(j\omega_1)| = A > 1$$

$$\angle H(j\omega_1) = 180^\circ$$

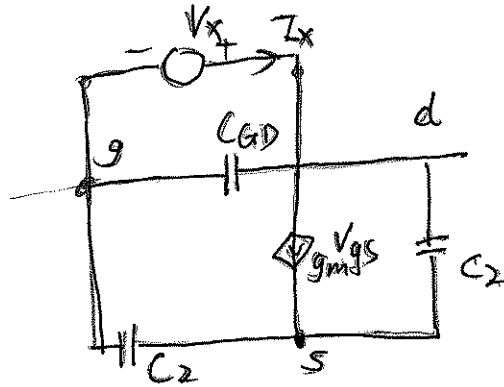
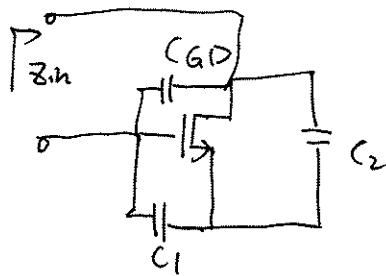
$$\therefore H(j\omega_1) = A \cdot e^{j\pi} = -A.$$

$$\left| \frac{Y}{X}(j\omega_1) \right| = \frac{A}{-(1-A)} = \frac{A}{A-1} > 1.$$

$$\angle \frac{Y}{X}(j\omega_1) = \pi - \pi = 0.$$

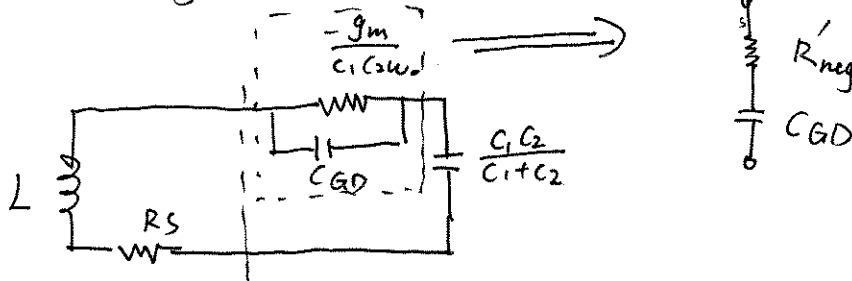
So if the input of the system is a sinusoidal signal at ω_1 ,
the amplitude of output will be multiplied by $\frac{A}{A-1}$ and
the phase of output will not change, compared with input.

8.4. Solu:



$$Z_{in} = \frac{1}{sC_{GD}} \parallel -\frac{g_m}{C_1 C_2 \omega^2}$$

So the Fig. 8.15 will change to



So the $\omega_{osc} = \frac{1}{\sqrt{L_1 \cdot \frac{C_1 C_2 C_{GD}}{C_1 + C_2} / \left(-\frac{C_1 C_2}{C_1 + C_2} + C_{GD} \right)}}$

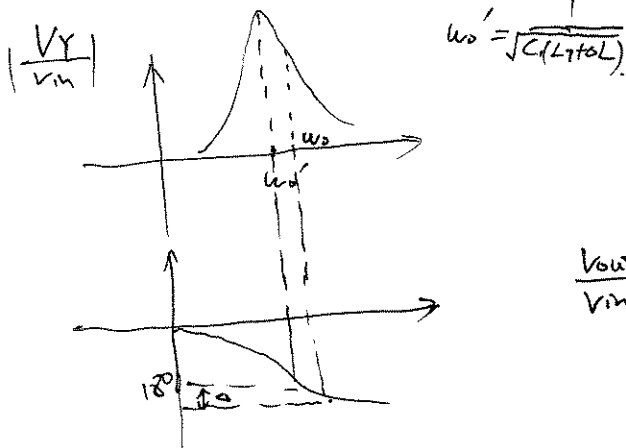
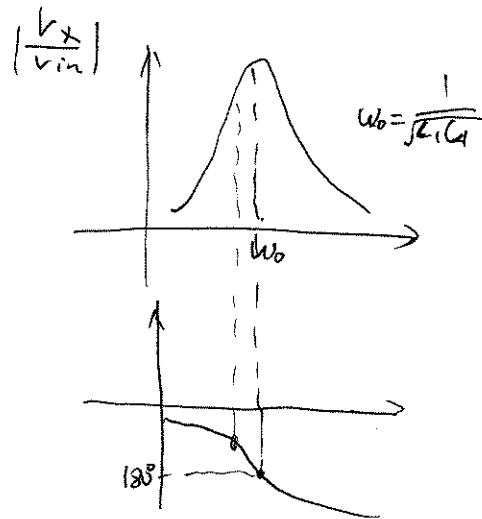
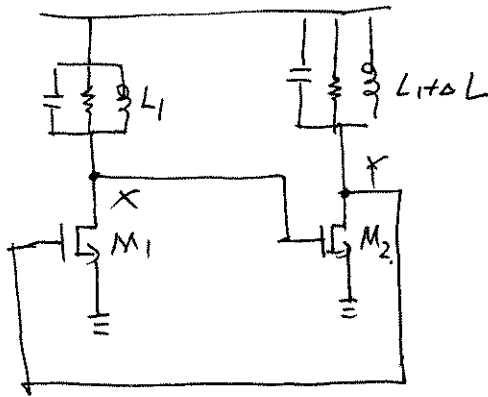
8.5 Solu:

Yes. Any feedback oscillator that employs a lossy resonator be viewed as one-port system of 8.13(c) Figure.

Only in this way, the feedback system can satisfy

the Barkhausen's Criteria $|H(s=j\omega)| = 1$ at resonance
 $\angle H(s=j\omega) = -180^\circ$ freq.

8.6 solu:



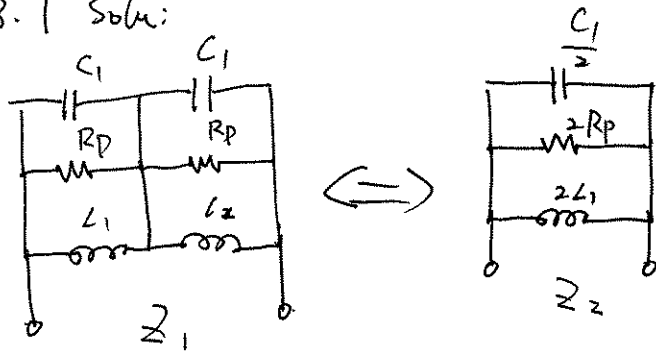
$$\begin{aligned} \frac{V_{out}}{V_{in}} &= (-g_m) (R_p \parallel \frac{1}{C_1 s} \parallel s L_1) \cdot (-g_m) \left[R_p \parallel \frac{1}{C_1 s} \parallel s (L_1 + \Delta L) \right] \\ &= g_m^2 \underbrace{\left(R_p \parallel \frac{1}{C_1 s} \parallel s L_1 \right)}_{(1)} \underbrace{\left(R_p \parallel \frac{1}{C_1 s} \parallel s (L_1 + \Delta L) \right)}_{(2)} \end{aligned}$$

phase contribution by ① & ②

$$\pi - \left[\arctan \frac{\omega L_1}{R_p (1 - L_1 C_1 \omega^2)} + \arctan \frac{\omega C_1 (L_1 + \Delta L)}{R_p (1 - \omega^2 (L_1 + \Delta L) C_1)} \right] = 0$$

⇒ Solve the ω .

8.7 Solu:



Proof: $Z_1 = 2 \cdot \frac{1}{sC_1} \parallel R_p \parallel L_1 s$

$$= 2 \cdot \frac{L_1 R_p s}{L_1 s + R_p (1 + s^2 L_1 C_1)}$$

For $Z_2 = \frac{1}{\frac{sC_1}{2}} \parallel 2R_p \parallel 2L_1 s$

$$= \frac{2 L_1^2 R_p s}{2 L_1 s + 2 R_p (1 + s^2 L_1 C_1)}$$

$$= \frac{2 L_1 R_p s}{L_1 s + R_p (1 + s^2 L_1 C_1)}$$

$\therefore Z_1 = Z_2.$

8.8 solve:

If C_b is placed at node P & Q.

$$1/C_{var} = 1/C_{var} + 1/C_b$$

$$C_{var} = \frac{C_{var} C_b}{C_{var} + C_b}$$

Without C_s & C_b . Eq. (8.73) shows

$$\Delta W_{osc} \approx \frac{1}{\sqrt{L_1 C_1}} \cdot \frac{0.5 C_{max}}{2 C_1}$$

For this range to reach 10% of centre freq.

$$C_{max} = \frac{2}{5} C_1$$

With effect of C_s & C_b . From Eq. 8.69)

$$\Delta W_{osc} = \frac{1}{\sqrt{L_1 C_1}} \cdot \frac{1}{2 C_1} \cdot \frac{C_s^2 \left(\frac{C_{max} C_b}{C_{max} + C_b} - \frac{C_{min} C_b}{C_{min} + C_b} \right)}{\left(C_s + \frac{C_{max} C_b}{C_{max} + C_b} \right) \left(C_s + \frac{C_{min} C_b}{C_{min} + C_b} \right)}$$

$$C_s = 10 C_{max}$$

$$C_b = 0.5 C_{max}$$

$$C_{min} = \frac{1}{2} C_{max}$$

$$= \frac{1}{\sqrt{L_1 C_1}} \cdot \frac{100 C_{max}^2 \left(\frac{0.5 C_{max}^2}{1.5 C_{max}} - \frac{0.25 C_{max}^2}{1 C_{max}} \right)}{\left(10 C_{max} + \frac{1}{3} C_{max} \right) \left(70 C_{max} - \frac{1}{4} C_{max} \right)} \cdot \frac{1}{2 C_1}$$

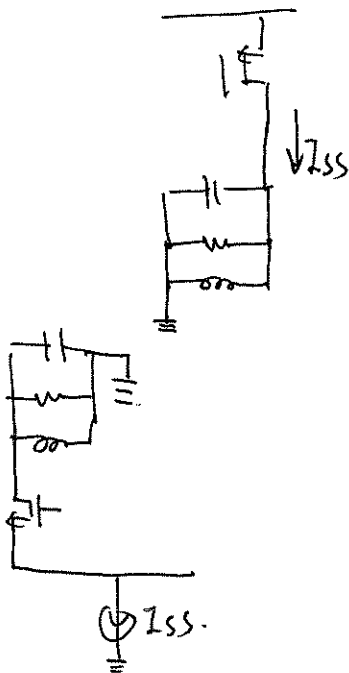
$$= \frac{1}{\sqrt{L_1 C_1}} \cdot \frac{100}{31.39 \cdot 2} \cdot \frac{C_{max}}{C_1}$$

$$= \frac{100 / (39.3 / 2) \cdot \frac{2}{5}}{1} \cdot W_0$$

$$= 1.65 \% W_0$$

So the tuning range there falls to 1.65% around $(44)^{1/2}$.

8.9. Solu:



Why do the PMOS devices in Fig 8.36 carry a current of I_{SS} ?

Because we know the ground in the middle is only ac ground.

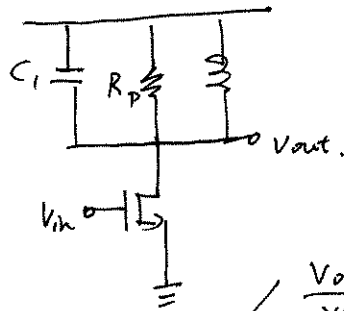
The dc path at this time is the right PMOS & the left NMOS.

That's why PMOS carries I_{SS} .

Solu: 8.10.

Proof: For a CS stage loaded by a second-order parallel RLC tank, prove that.

$$\frac{R_p}{L\omega_0} = \frac{\omega_0}{2} \left| \frac{d\phi}{d\omega} \right|.$$



$$\frac{v_{out}}{v_{in}}(j\omega) = - \frac{jg_m R_p L \omega}{R_p(1 - L C_1 \omega^2) + jL\omega}.$$

$$\angle \frac{v_{out}}{v_{in}}(j\omega) = \left[-\frac{\pi}{2} - \tan^{-1} \frac{L\omega}{R_p(1 - L C_1 \omega^2)} \right].$$

$$\frac{d}{d\omega} \angle \frac{v_{out}}{v_{in}}(j\omega) = - \frac{1}{1 + \left[\frac{L\omega}{R_p(1 - L C_1 \omega^2)} \right]^2} \left[\frac{L}{R_p(1 - L C_1 \omega^2)} + \frac{L\omega R_p(-1) \cdot (-2L C_1 \omega)}{R_p^2(1 - L C_1 \omega^2)^2} \right]$$

$$= - \frac{1}{1 + \left[\frac{L\omega}{R_p(1 - L C_1 \omega^2)} \right]^2} \left[\frac{L}{R_p(1 - L C_1 \omega^2)} + \frac{2L^2 C_1 \omega R_p}{R_p^2(1 - L C_1 \omega^2)^2} \right]$$

$$= - \frac{L R_p(1 - L C_1 \omega^2) + 2L^2 C_1 \omega^2 R_p}{[R_p(1 - L C_1 \omega^2)]^2 + (L\omega)^2}$$

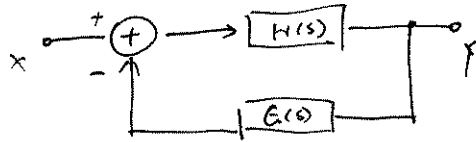
$$\left| \frac{\omega_0}{2} \frac{d \angle \frac{v_{out}}{v_{in}}(j\omega)}{d\omega} \right|_{\omega=\omega_0} = \frac{\omega_0^2}{2} \frac{2C_1 R_p \omega_0^2}{\omega_0^4} = \omega_0^2 C_1 R_p$$

$$= \frac{1}{\sqrt{C_1 L}} R_p$$

$$= \frac{R_p}{L\omega_0}.$$

$$\text{So } \frac{R_p}{L\omega_0} = \frac{\omega_0}{2} \left| \frac{d\phi}{d\omega} \right|.$$

8.11 Solu:



$$[X(s) - Y(s)G(s)] \cdot H(s) = Y(s)$$

$$\frac{Y(s)}{X(s)} = \frac{H(s)}{1 + G(s)H(s)}$$

$$H(s) \Rightarrow H(j\omega_0 + \Delta\omega) \approx H(j\omega_0) + \Delta\omega \frac{dH}{d\omega}$$

$$G(s) \Rightarrow G(j\omega_0 + \Delta\omega) \approx G(j\omega_0) + \Delta\omega \frac{dG}{d\omega}$$

$$\frac{Y}{X}(j\omega_0 + j\Delta\omega) \approx \frac{-1 + \Delta\omega \frac{dH}{d\omega}}{1 + G(j\omega_0)H(j\omega_0) + \Delta\omega \frac{d(GH)}{d\omega}}$$

$$\approx \frac{-1}{1 + G(j\omega_0)H(j\omega_0) + \Delta\omega \frac{d(GH)}{d\omega}}$$

$$\approx -\frac{1}{\Delta\omega \frac{d(GH)}{d\omega}} \quad (\text{assume } G(j\omega_0)H(j\omega_0) \approx -1)$$

$$\left| \frac{d(GH)}{d\omega} \right|^2 = \left| \frac{d|GH|}{d\omega} \right|^2 + \left| \frac{d\angle GH}{d\omega} \right|^2 |GH|^2$$

$$\begin{aligned} \therefore \left| \frac{Y}{X}(j\omega_0 + j\Delta\omega) \right|^2 &= \frac{1}{\Delta\omega^2} \cdot \frac{1}{\left| \frac{d\angle GH}{d\omega} \right|^2 + |G(j\omega_0)|^2} \\ &= \frac{1}{4 \left(\frac{\omega_0}{2} \right)^2 \left| \frac{d\angle GH}{d\omega} \right|^2} \cdot \frac{4 \left(\frac{\omega_0}{2} \right)^2}{\Delta\omega^2} \cdot \frac{1}{|G(j\omega_0)|^2} \end{aligned}$$

$$= \frac{1}{4 \cdot Q^2} \cdot \left(\frac{\omega_0}{\Delta\omega} \right)^2 \cdot \frac{1}{|G(j\omega_0)|^2}$$

$$\text{Where } Q = \frac{\omega_0}{2} \cdot \left| \frac{d\angle GH}{d\omega} \right|$$

8.12 Solu:

$$x(t) = A \cos \omega_0 t + n_1(t) \cos \omega_0 t - n_2(t) \sin \omega_0 t.$$

$$x(t) = \sqrt{[A + n_1(t)]^2 + n_2^2(t)} \cos \left[\omega_0 t + \tan^{-1} \frac{n_2(t)}{A + n_1(t)} \right]$$

$$\approx \sqrt{[A + n_1(t)]^2 + n_2^2(t)} \cos \left[\omega_0 t + \frac{n_2(t)}{A} \right]$$

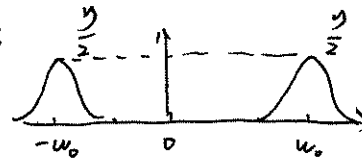
For PM,

$$x_1(t) = A \cos \left(\omega_0 t + \frac{n_2(t)}{A} \right)$$

$$\approx A \cos \omega_0 t - n_2(t) \cdot \sin \omega_0 t.$$

Noise Power in PM sidebands

$$= n_2(t) \cdot \sin \omega_0 t.$$



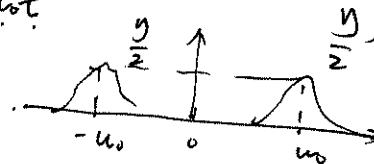
For AM,

$$x_2(t) = \sqrt{[A + n_1(t)]^2 + n_2^2(t)} \cos \omega_0 t.$$

Noise Power in AM sidebands

$$x_2(t) \approx A \left[1 + \frac{1}{2A} [n_1(t) + n_2(t)] \right] \cdot \cos \omega_0 t.$$

$$\Rightarrow n_1(t) \cdot \cos \omega_0 t.$$



So, the power carried by AM sidebands is equal to that carried by the PM sidebands and equal to the half power of $n(t)$.

8.13 Solu: Part II

(b) (continue). If the definition of C_{avg} is above mentioned, the result is meaningless. That require us, to compute the average value in the $\frac{2\pi}{\omega_0}$.

So. C_{avg} is revised to

$$\Rightarrow C_{avg} = C_0 + \left(\frac{4}{\pi} R_p\right)^2 \left[I_{ss} \cdot I_m \cos \omega_m t + \frac{1}{4} I_m^2 \cdot \cos 2\omega_m t \right]$$

(c). Compute ^{PM.} ~~the noise~~ because of tank freq. modulation.

From the reference paper [13],

the conversion coefficient

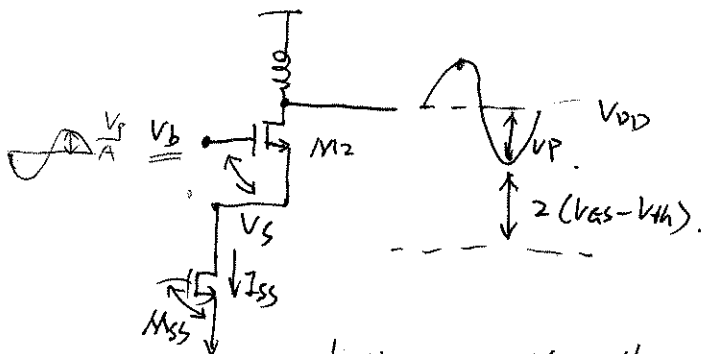
$$K_{AM/PM} = \left| \frac{\partial \omega}{\partial A} \right| \frac{A}{\sigma}.$$

$$\begin{cases} A \text{ is amplitude} \Rightarrow \frac{4}{\pi} I_{ss} R_p; \\ \omega \text{ is } \omega_m; \\ \omega \text{ is oscillation freq;} \end{cases}$$

8.14 Solu.

In Fig. 8.86 (b).

the peak drain voltage swing \max .



Let's consider the critical point, which let M_{SS} & M_2 are on the edge of triode region.

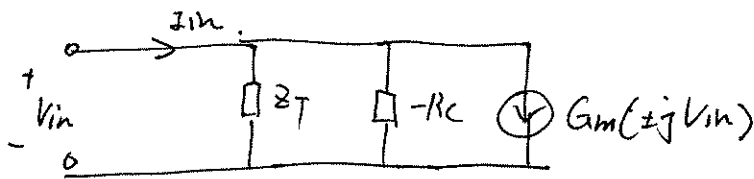
In this situation, the peak drain voltage swing is maximized as $V_{DD} - 2(V_{GS} - V_{th})$.

In this situation, V_b , the gate voltage, cannot change too much, that's because when the M_2 is on the edge of triode region, $V_{DS2} = V_b - V_s - V_{th}$.

$$V_{DS1} = V_b - V_s - V_{th} \quad (V_s = V_{GS} - V_{th}) \quad \text{where } V_b = V_G + \frac{V_p}{A}$$

If $\frac{V_p}{A}$ is too large, the stress for M_{SS} will be too large.

8.5 Solu:



$$Z_T = (L_1 s) \parallel (C_1 s)^{-1} \parallel R_p.$$

$$\text{assume } \begin{cases} G_{m1} = G_{m2} = G_m. \\ V_x = \pm V_x \end{cases}$$

$$V_{in} = [\cancel{I_{in}} \cdot [Z_T \parallel (-R_C)]] \cdot [I_{in} - G_m(\pm j V_{in})]$$

$$V_{in} (1 + G_m(\pm j)(-R_C) \parallel Z_T) = I_{in} \cdot (Z_T \parallel (-R_C))$$

$$\frac{I_{in}}{V_{in}} = \frac{1 \pm j G_m (Z_T \parallel (-R_C))}{Z_T \parallel (-R_C)}$$

$$= \frac{1}{Z_T \parallel (-R_C)} + j G_m.$$

$$= \frac{1}{j\omega_0 L_1} + j\omega_0 C_1 + \frac{1}{R_p} - \frac{1}{R_C} \pm G_m.$$

So. $\frac{I_{in}}{V_{in}}$ can be zero even $\frac{1}{R_p} - \frac{1}{R_C} \neq 0$.

\Rightarrow Because of each oscillator receiving energy from each other, the start-up condition need not to be as stringent.

$$\text{as } Z_T(s=\omega_0) = R_C.$$

8.16 Solu:

$$\Delta W = \frac{W_0}{2Q_{\text{tank}}} \tan^{-1} \frac{g_{m3}}{g_{m1}}$$

$$g_{m3} = \sqrt{2\mu_n C_{ox} \left(\frac{W}{L}\right)_3 \cdot (I_{T1} + I_{n1}) / 2}$$

Assume $K = \mu_n C_{ox} \left(\frac{W}{L}\right)_3$

$$g_{m3} = \sqrt{K(I_{T1} + I_{n1})} \simeq \sqrt{K I_{T1}} + 2\sqrt{\frac{K}{I_{T1}}} \cdot I_{n1}$$

$$\begin{aligned} \tan^{-1} \frac{g_{m1}}{g_{m3}} &\simeq \tan^{-1} \left(\sqrt{K I_{T1}} + 2\sqrt{\frac{K}{I_{T1}}} \cdot I_{n1} \right) \\ &\simeq \tan^{-1}(\sqrt{K I_{T1}}) + \frac{2\sqrt{\frac{K}{I_{T1}}}}{1 + K I_{T1}} \cdot I_{n1} \end{aligned}$$

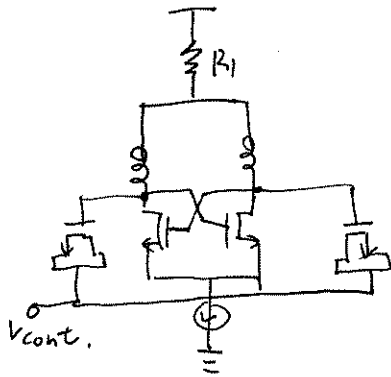
The approximation is done according to Taylor

Series, we choose the first and second terms.

Note:

$$f(x) \simeq f(a) + f'(a) \cdot (x-a)$$

8.17 Solu:



$$(a) \quad \omega_{out} = \frac{1}{\sqrt{L_1 C_0 (1 + \delta V_{var})}}$$

V_{var} is the average voltage across the varactor.

$$V_{var} = V_{DD} - R_1 I_{SS} - V_{cont.}$$

$$\begin{aligned} \omega_{out} &= \frac{1}{\sqrt{L_1 C_0 [1 + \delta (V_{DD} - R_1 I_{SS} - V_{cont.})]}} \\ &\approx \frac{1}{\sqrt{L_1 C_0 [1 + \delta (V_{DD} - V_{cont.})]}} + \frac{-L_1 C_0 \delta R_1}{2 \sqrt{L_1 C_0 [1 + \delta (V_{DD} - V_{cont.})]}} \cdot I_{SS} \end{aligned}$$

\Rightarrow the "gain" from I_{SS} to ω_{out}

$$= - \frac{L_1 C_0 \delta R_1}{2 \sqrt{L_1 C_0 [1 + \delta (V_{DD} - V_{cont.})]}}$$

$$(b) \quad \omega_{out} = \omega_0 + \frac{L_1 C_0 \delta R_1}{2 \sqrt{L_1 C_0 [1 + \delta (V_{DD} - V_{cont.})]}} \cdot I_n \cos \omega_{mt}$$

The frequency is modulated by $I_n \cos \omega_{mt}$.

Using narrowband FM approximation.

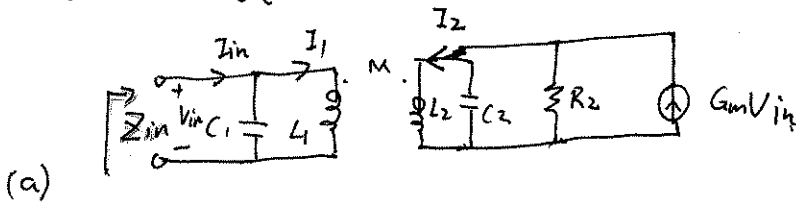
$$\Rightarrow X(t) = A \cos(\omega_0 t + B(t)) \quad B(t) = I_n \cos \omega_{mt}$$

$$\approx A \cos \omega_0 t - A \cdot B(t) \cdot \sin \omega_0 t$$

$$\approx A \cos \omega_0 t - A I_n \cos \omega_{mt} \cdot \sin \omega_0 t$$

\therefore the sidebands relative magnitude is $\frac{I_n}{2}$.

8.18 Solu:



$$\begin{cases} V_{in} = I_1 L_1 s + I_2 M s & (1) \end{cases}$$

$$\begin{cases} I_1 = I_{in} - V_{in} \cdot s C_1 & (2) \end{cases}$$

$$\begin{cases} I_2 + \frac{(I_2 L_2 s + I_1 M s)}{R_2} = G_m V_{in} & (3) \end{cases}$$

$$V_{in} = (I_{in} - V_{in} \cdot s C_1) L_1 s + I_2 M s$$

$$\Rightarrow I_2 = \frac{V_{in} (1 + s^2 L_1 C_1) - I_{in} L_1 s}{M s} \quad (4)$$

substitute I_1, I_2 into (3).

$$V_{in} \frac{1 + s^2 L_1 C_1}{M s} - I_{in} \frac{L_1}{M} + \left[V_{in} \frac{L_2 (1 + s^2 L_1 C_1)}{M} - I_{in} \frac{L_1 L_2 s}{M} + I_{in} M s - V_{in} s^2 C_1 M \right] \frac{s R_2 C_2 + 1}{R_2} = G_m V_{in}$$

$$V_{in} \left(\frac{1 + s^2 L_1 C_1}{M} + \frac{L_2 (1 + s^2 L_1 C_1)}{M} \cdot \frac{s R_2 C_2 + 1}{R_2} - s^2 C_1 M \frac{s R_2 C_2 + 1}{R_2} - G_m \right)$$

$$= I_{in} \left(\frac{L_1}{M} + \frac{L_1 L_2 s}{M} - M s \right)$$

$$Z_{in} = \frac{V_{in}}{I_{in}}$$

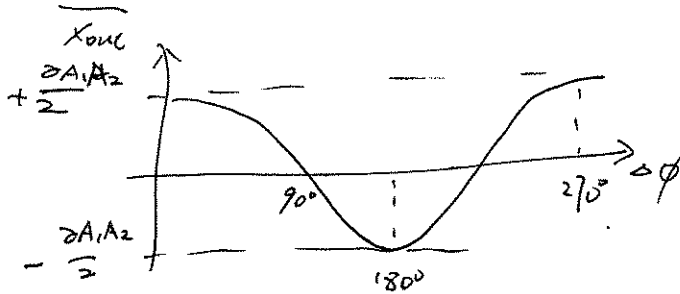
(b). when $\frac{1 + s^2 L_1 C_1}{M} + \frac{L_2 (1 + s^2 L_1 C_1)}{M} \cdot \frac{s R_2 C_2 + 1}{R_2} - s^2 C_1 M \frac{s R_2 C_2 + 1}{R_2} - G_m = 0$ $|_{s=j\omega}$

$$\Rightarrow \omega_1 = \sqrt{\frac{R_2 + L_2 - G_m M R_2}{L_1 R_2 + L_1 L_2 C_1 - C_1 M^2}}$$

$$\omega_2 = \sqrt{\frac{L_1}{L_1 L_2 C_1 - C_1 M^2}}$$

9.1 Solu:

$$\overline{x_{out}(t)} = \frac{\sigma A_1 A_2}{2} \cos \Delta\phi$$



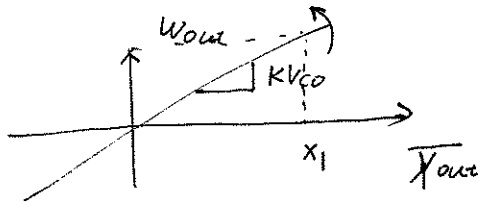
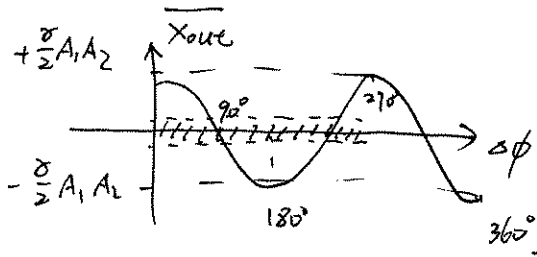
The 'gain' should be defined carefully in Phase Detector.

The zero gain at $\Delta\phi = 180^\circ$ & 0° , only means when $\Delta\phi$ is very near to 0° or 180° , the average of x_{out} will not

change or change very slowly. However, with the

accumulation of $\Delta\phi$, the gain cannot remain zero.

9.2 Solu:



$$\omega_{out} = \omega_0 + KV_{CO} \cdot \overline{X_{out}}$$

$\therefore KV_{CO}$ is very high

$\therefore \overline{X_{out}}$ is very small.

From the Figure about,

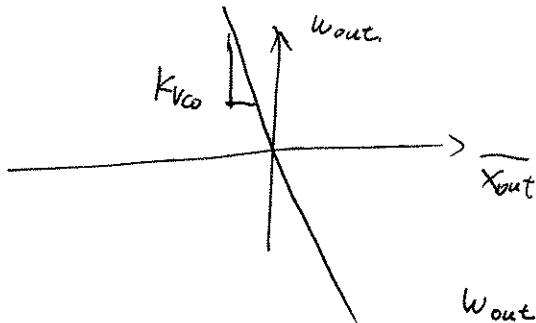
we can find $\Delta\phi$ should be near $90^\circ + 180^\circ k$ ($k=0, 1, 2, \dots$)

$$\Rightarrow \Delta\phi \approx 90^\circ + 180^\circ \times k$$

$$(k = 0, 1, 2, \dots).$$

9.3 soln:

For Problem 2, if the K_{VCO} 's sign is change.
the ω_{out} v.s. \bar{x}_{out} diagram should be



$$\omega_{out} = \omega_0 + K_{VCO} \cdot \bar{x}_{out}$$

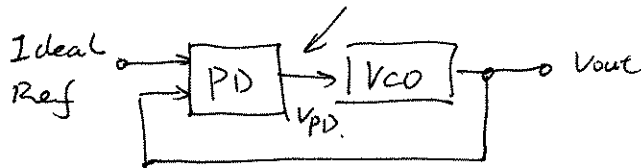
\bar{x}_{out} will be also changing its sign.

However, our result won't change.

$$\Delta\phi \approx 90^\circ + 180^\circ \cdot k$$

$$(k=0, 1, 2, \dots)$$

9.4. Solu:



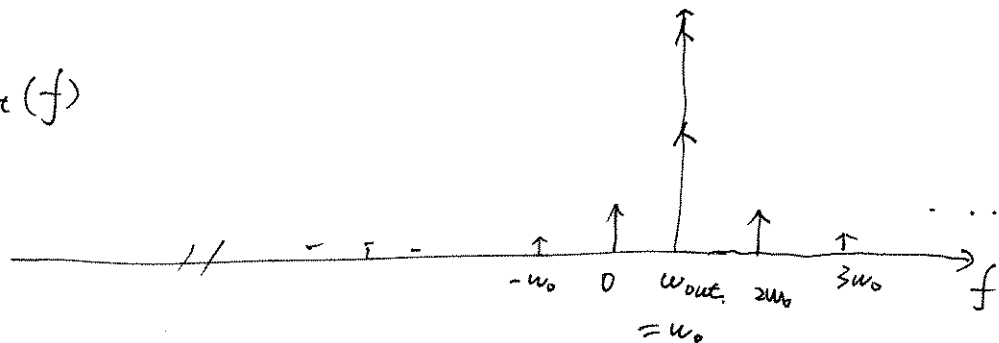
$$V_{CO} \Rightarrow V_{out}$$

$$\omega_{out} = \omega_0 + V_{PD} K_{VCO}$$

$$V_{out} = V_0 \cos \left[\omega_0 t + K_{VCO} \int V_{PD}(t) dt \right]$$

$$\approx V_0 \cos \omega_0 t - \frac{V_0 \cdot \int V_{PD}(t) dt K_{VCO} \cdot \sin \omega_0 t}{1}$$

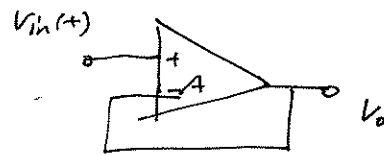
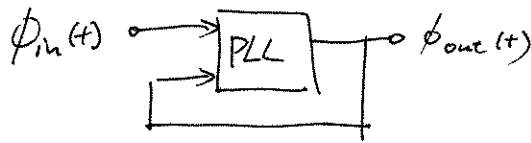
$V_{out}(f)$



\Rightarrow So,

output sidebands are located as the figure above.

9.5. Solu:



$$\therefore \frac{d\phi_{out}}{dt} = \frac{d\phi_{in}}{dt}$$

$$\Rightarrow \Delta \phi_{out} = \Delta \phi_{in}.$$

$$\Delta V_{out} = \Delta V_{in}$$

$$\Delta V_{out} = \frac{\Delta V_{in}}{A_o + 1}$$

The statement of ^{unity} buffer is not correct.

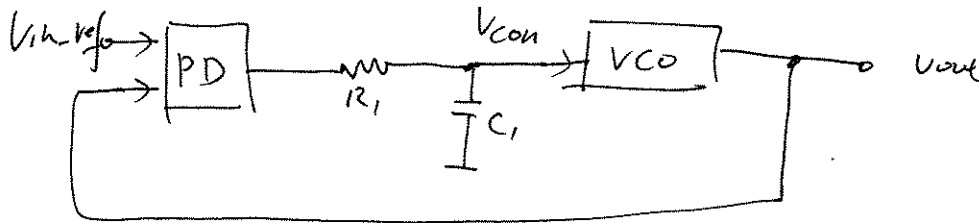
We can compute the transfer function of unity-gain buffer.

$$H(s) = \frac{A(s)}{1 + A(s)}$$

$$s \approx 0 \text{ 时 } H(s) = \frac{A_o}{1 + A_o} \approx 1$$

$$s_o \quad \Delta V_{in} \Rightarrow \Delta V_{out} = \Delta V_{in}.$$

9.6 Solu:



(I) VCO noiseless

If we break the R_1 ,

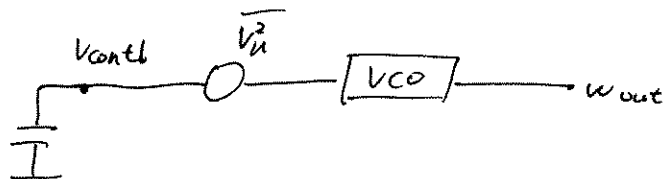
V_{con} won't change because the charge is conserved on capacitor C_1 .

So the wave will also be stable.

(II) VCO noisy.

If we break the R_1 ,

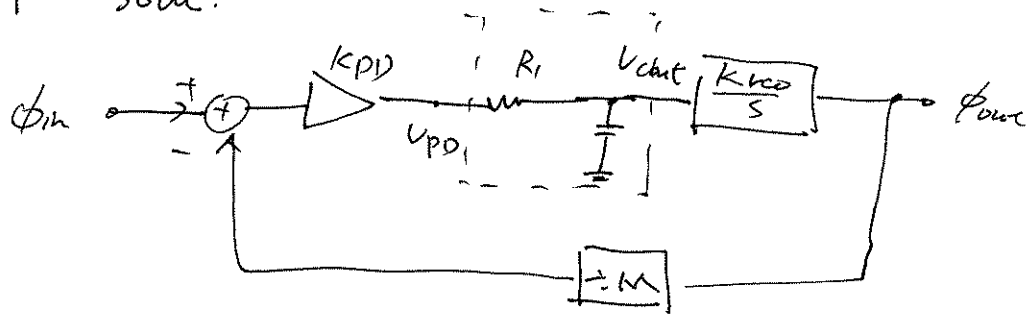
V_{con} on C_1 will be in series with a input-referred noise source.



So, the wave will be modulated by $\overline{V_n^2}$.

$$H_1(s) = \frac{\frac{1}{sC_1}}{\frac{1}{sC_1} + R_1} = \frac{1}{sR_1C_1 + 1}$$

9.7 solu:



$$\left(\phi_{in} - \frac{\phi_{out}}{M}\right) \cdot K_{PD} \cdot \frac{1}{sR_1C_1 + 1} \cdot \frac{KV_{CO}}{s} = \phi_{out}$$

$$\phi_{in} \cdot \frac{K_{PD} \cdot K_{VCO}}{s(sR_1C_1 + 1)} = \phi_{out} \left[1 + \frac{K_{PD} \cdot K_{VCO}}{s(sR_1C_1 + 1)M} \right]$$

$$\frac{\phi_{out}}{\phi_{in}}(s) = \frac{K_{PD} \cdot K_{VCO} M}{s(sR_1C_1 + 1)M + K_{PD} \cdot K_{VCO}}$$

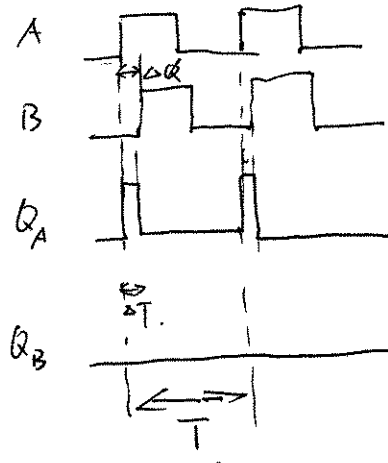
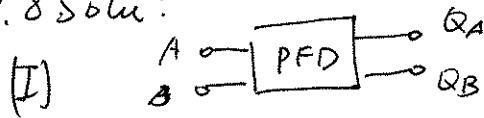
$$= \frac{K_{PD} \cdot K_{VCO} \cdot M}{s^2 R_1 C_1 M + sM + K_{PD} \cdot K_{VCO}}$$

$$= \frac{K_{PD} \cdot K_{VCO} \cdot M / R_1 C_1 M}{s^2 + \frac{M}{R_1 C_1 M} s + \frac{K_{PD} \cdot K_{VCO}}{R_1 C_1 M}}$$

$$\omega_n = \sqrt{K_{PD} \cdot K_{VCO} \cdot \omega_{LPF} / M} \quad (\omega_{LPF} = \frac{1}{R_1 C_1})$$

$$\zeta = \frac{1}{2} \sqrt{\frac{\omega_{LPF} M}{K_{PD} \cdot K_{VCO}}}$$

9.8 Solu:

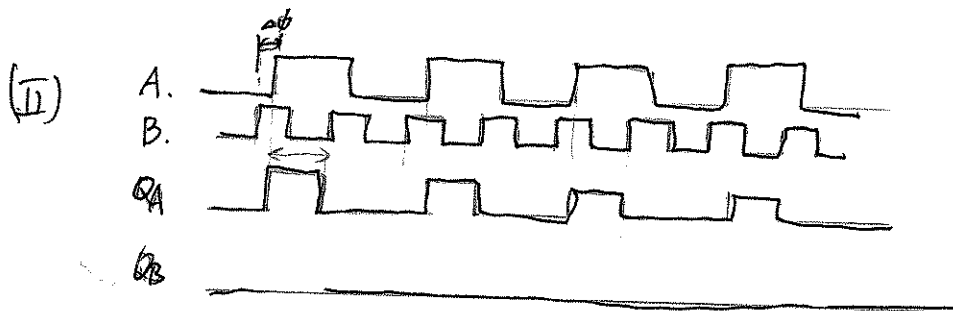


assume the magnitude of
all signal
will be 1.

$$\frac{\Delta\phi_{AB}}{2\pi} \cdot T = \Delta T$$

$$\overline{Q_A - Q_B} = \frac{\Delta T \cdot 1}{T} = \frac{\Delta\phi_{AB}}{2\pi}$$

$\Rightarrow \overline{Q_A - Q_B}$ is a linear function of input phase error.



assume $f_B = 2f_A$. $Q_A = f_A$.

$$\overline{Q_A - Q_B} = \frac{\pi - \Delta\phi}{2\pi} \cdot \frac{1}{f_A} \cdot \frac{1}{f_A} = \frac{\pi - \Delta\phi}{2\pi}$$

$\Rightarrow \overline{Q_A - Q_B}$ is a linear function of input freq. difference.

(It's a special case to demonstrate, but not

9.9. Solu.

Eq. (9.19)

$$H(s) = \frac{\frac{I_p \cdot K_{VCO}}{2\pi C_1} \cdot (R_1 C_1 s + 1)}{s^2 + \frac{I_p}{2\pi} K_{VCO} R_1 s + \frac{I_p}{2\pi} K_{VCO}}$$

$$= \frac{\frac{I_p \cdot K_{VCO} R_1}{2\pi} \left(s + \frac{\omega_n}{2\zeta} \right)}{s^2 + 2\zeta \omega_n s + \omega_n^2}$$

peak is at ω_n .

$$\begin{aligned} |H(j\omega_n)| &= \frac{I_p \cdot K_{VCO} \cdot R_1}{2\pi} \left| \frac{j\omega_n + \frac{\omega_n}{2\zeta}}{-\omega_n^2 + \omega_n^2 + 2\zeta \omega_n^2 j} \right| \\ &= 2\zeta \omega_n \left| \frac{\sqrt{\omega_n^2 + \frac{\omega_n^2}{4\zeta^2}}}{2\zeta \omega_n^2} \right| \\ &= 2\zeta \omega_n \sqrt{1 + \frac{1}{4\zeta^2}} \\ &= \sqrt{4\zeta^2 + 1} \end{aligned}$$

9.10 Solu:

$$\therefore f = \frac{R_1}{2} \sqrt{\frac{I_p C_1 K_{VCO}}{2\pi}}$$

$$\omega_n = \sqrt{\frac{I_p K_{VCO}}{2\pi C_1}}$$

$$f = 1$$

time constant

$$= 1/f \cdot \omega_n = \frac{25}{\omega_n}$$

$$\omega_n = \frac{\omega_{in}}{25}$$

$$K_{VCO}(V_{conmax} - V_{conmin}) = 10\% \cdot \omega_{in}$$

$$K_{VCO} \cdot V_{DD} = 0.1 \cdot \omega_{in}$$

$$\Rightarrow \omega_n = \frac{R_1}{2} \cdot \frac{I_p \cdot K_{VCO}}{2\pi}$$

$$\Rightarrow \omega_n = \frac{R_1}{2} \cdot \frac{I_p}{2\pi} \cdot \frac{0.1 \cdot \omega_{in}}{V_{DD}}$$

$$\Rightarrow \frac{\omega_{in}}{25} = R_1 \cdot I_p \cdot \frac{0.1}{4\pi} \cdot \frac{\omega_{in}}{V_{DD}}$$

$$\Rightarrow R_1 \cdot I_p = \frac{1/25}{4\pi} \cdot V_{DD}$$

$$= 1.6\pi V_{DD}$$

9.11. Solu:

$$M_1 = 1000$$

(a) If output freq. remain

$$M_2 = 500$$

$$\frac{A_{\text{side}}}{A_{\text{carrier}}} = \frac{1}{2\pi} \cdot \frac{\Delta T \cdot I_p}{C_2} T_{\text{res}} \cdot K_{\text{VCO}}$$

the ration doesn't change.

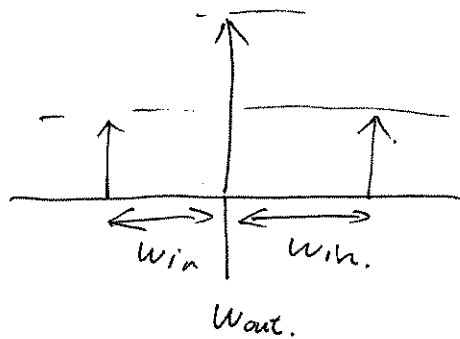
(b) If output freq. doubled, K_{VCO} doubled.

$$M_2 = 1000$$

$$\frac{A_{\text{side}}}{A_{\text{carrier}}} = \frac{1}{2\pi} \cdot \frac{\Delta T \cdot I_p}{C_2} T_{\text{res}} \cdot K_{\text{VCO}} \cdot 2$$

The ration also doubles.

9.12 Solu:

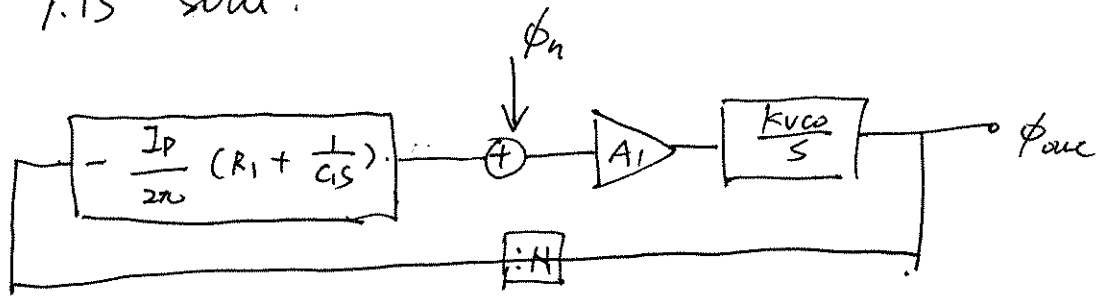


loop bandwidth $\ll w_{in}$ to ensure the continuous-time approximation's validity.

So the sidebands is located at w_{in} away from w_{out} . PLL cannot suppress high-frequency noise.

\Rightarrow That's why PLL suppress VCO phase noise but not the sidebands due to ripple.

9.13 Solu:



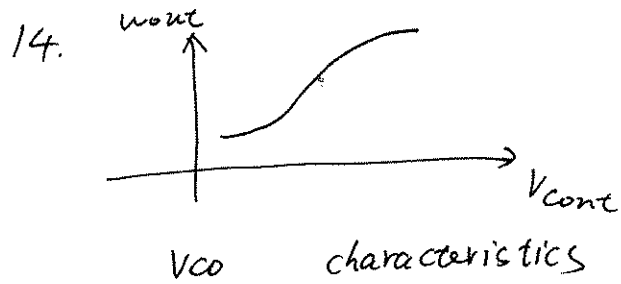
$$\left[\frac{\phi_{out}}{N} \left(-\frac{I_p}{2\pi} \left(R_1 + \frac{1}{C_1 s} \right) \right) + \phi_n \right] \cdot A_1 \cdot \frac{K_{vco}}{s} = \phi_{out}$$

$$\left[1 + \frac{I_p}{2\pi} \left(R_1 + \frac{1}{C_1 s} \right) \frac{A_1 K_{vco}}{N s} \right] \phi_{out} = A_1 \cdot \frac{K_{vco}}{s} \cdot \phi_n$$

$$\phi_{out} = \frac{\frac{A_1 \cdot K_{vco}}{s}}{1 + \frac{I_p}{2\pi} \left(R_1 + \frac{1}{C_1 s} \right) \frac{A_1 K_{vco}}{N s}} \phi_n$$

$$\phi_{out, n}^2 = \frac{(A_1 K_{vco})^2}{\sqrt{\left(\frac{I_p A_1 K_{vco}}{2\pi N C_1} - \omega^2 \right)^2 + \left(\frac{I_p A_1 K_{vco} R_1}{2\pi N} \right)^2}} \cdot \frac{\sigma^2}{f^2}$$

9.14. Solve;

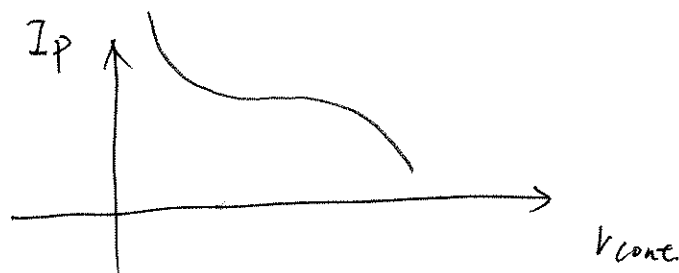


characteristic equation :

$$: s^2 + \frac{I_p}{2\alpha} k_{VCO} R_1 s + \frac{I_p}{2\alpha C} k_{VCO} = 0.$$

$I_p \cdot k_{VCO}$ should be constant.

$$\Rightarrow I_p \propto \frac{1}{k_{VCO}}, \quad \left(k_{VCO} = \frac{dw_{out}}{dv_{cont}} \right).$$



9.15 Solu:

(a) PFD now make half as many phase comparisons per second.
pumping half as much as charge into the loop filter.
Thus, loop is less stable.

Not correct.
Because of unchangeable all loop parameters,
the stability is unchanged.

(b). Equation $\zeta = \frac{R_p}{2} \sqrt{\frac{I_p K_{vco} C_p}{2\pi}}$ indicates that ζ remains
constant and the loop is as stable as before.

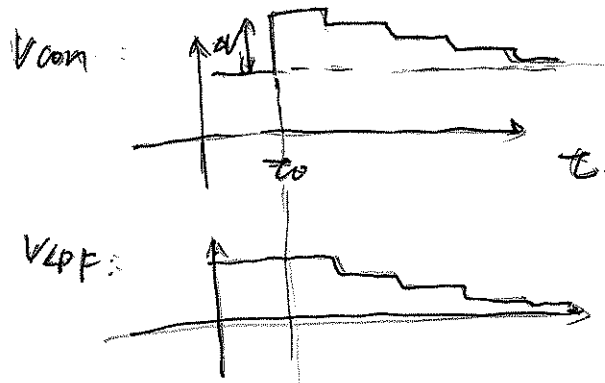
Correct.

$$H(s) = \frac{2\zeta\omega_n \left(s + \frac{\omega_n}{2\zeta}\right)}{s^2 + 2\zeta\omega_n s + \omega_n^2} \quad \text{is unchanged.}$$

So ζ is poles & zero. That means the Phase

Margin of this loop is unchanged. Only operation
point is different.

9.16 Solu:



assume non-idealities
are all neglected.

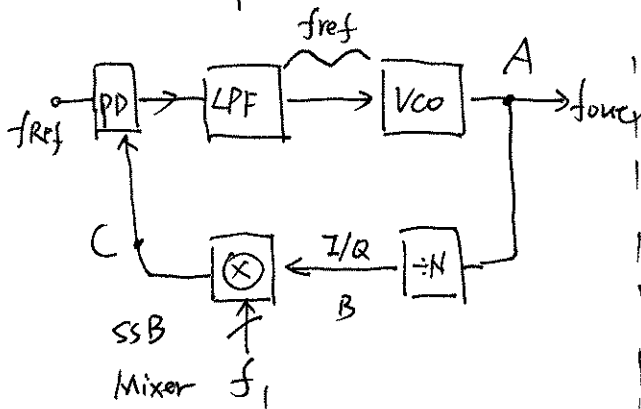
V_{com} total change should be zero.

V_{LPF} total change should be $-\Delta V$.

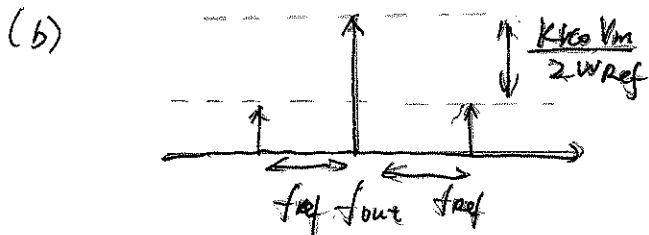
out put frequency won't change. when phase-locked.

The input & output phase difference :

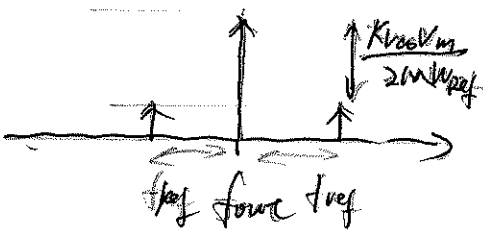
9.17 Solu:



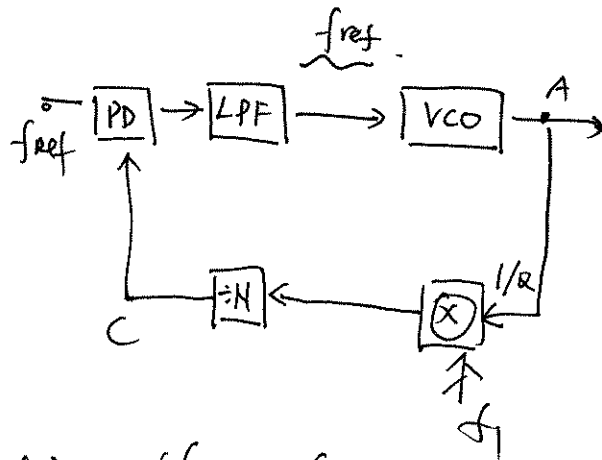
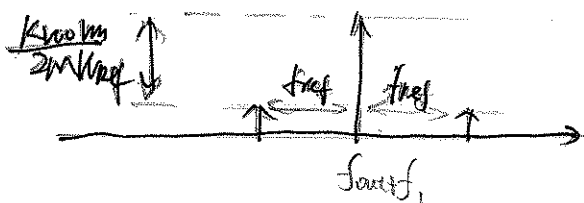
(a) $\frac{f_{out}}{N} + f_1 = f_{ref}$
 $f_{out} = N(f_{ref} - f_1)$



(c) ② B mode

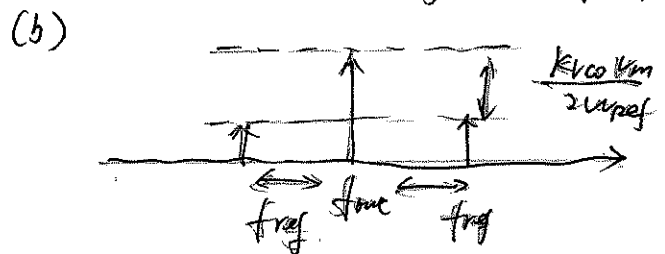


② C mode

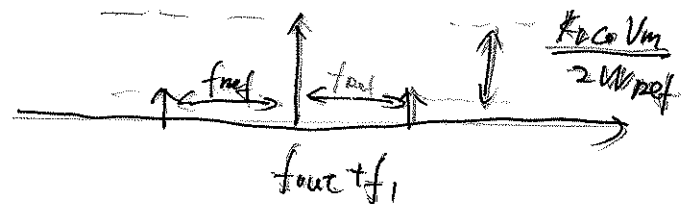


(a) $\frac{f_{out} + f_1}{N} = f_{ref}$

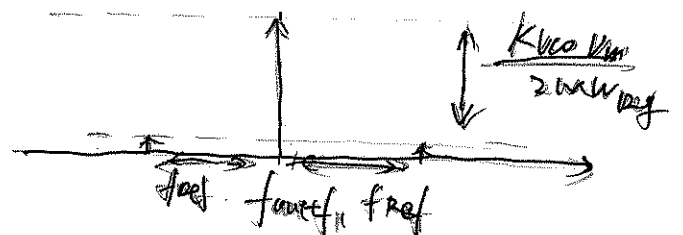
$f_{out} = N \cdot f_{ref} - f_1$
 * (V_m is the magnitude of ripple).



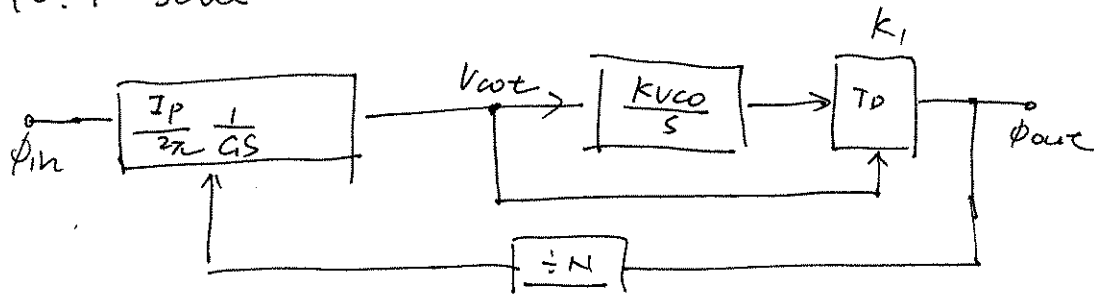
(c) ② B mode



② C mode



10.1 Solu:

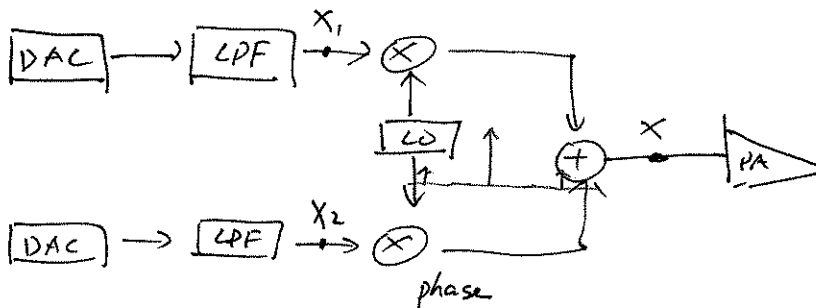


$$H_{open}(s) = \frac{I_p}{2\pi C_1 s} \left(\frac{K_{VCO}}{s} + K_1 \right)$$

$$\begin{aligned} H_{close}(s) &= \frac{H_{open}(s)}{1 + 1/N \cdot H_{open}(s)} \\ &= \frac{\frac{I_p}{2\pi C_1 s} \left(\frac{K_{VCO}}{s} + K_1 \right)}{1 + \frac{1/N I_p}{2\pi C_1 s} \left(\frac{K_{VCO}}{s} + K_1 \right)} \\ &= \frac{\frac{I_p K_{VCO}}{2\pi C_1} + \frac{I_p K_1}{2\pi C_1} s}{s^2 + \frac{1/N I_p K_1}{2\pi C_1} s + \frac{1/N I_p K_{VCO}}{2\pi C_1}} \end{aligned}$$

$$\begin{cases} \frac{1/N I_p K_1}{2\pi C_1} = 2\zeta \omega_n \\ \omega_n^2 = \frac{1/N I_p K_{VCO}}{2\pi C_1} \end{cases} \Rightarrow \begin{cases} \omega_n = \sqrt{\frac{I_p K_{VCO}}{2\pi C_1 N}} \\ \zeta = \frac{K_1}{2} \sqrt{\frac{I_p}{2\pi C_1 K_{VCO} N}} \end{cases}$$

10.2 soln:



Prove that far-out ^{phase} noise of LO, also appears as noise in RX band.

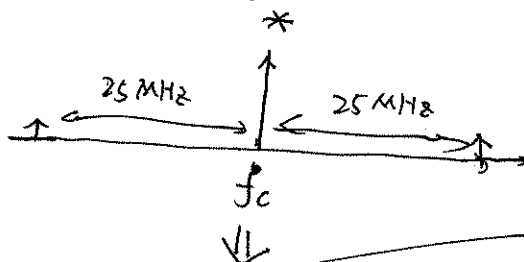
Determine the phase noise @ 25 MHz offset for GSM.

Model the ^{far-out} phase of LO as impulse.

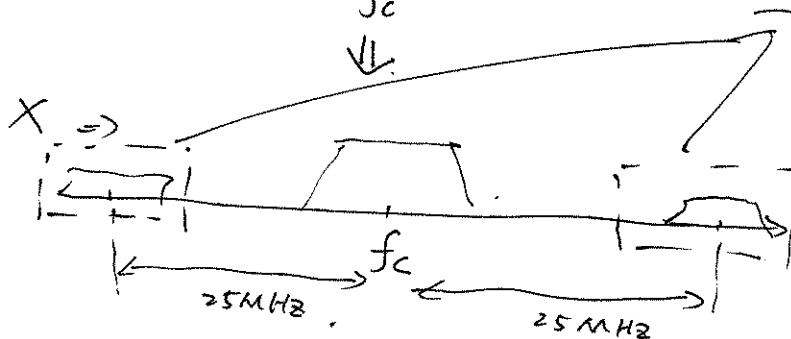
X_1 & $X_2 \Rightarrow$



LO \Rightarrow

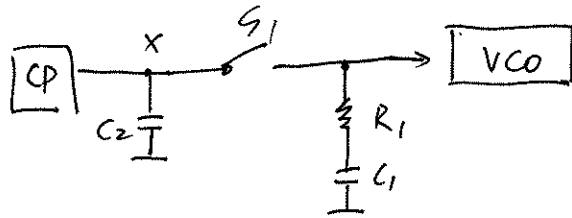


$X \Rightarrow$



will appear in the RX band.

10.3 Solu:



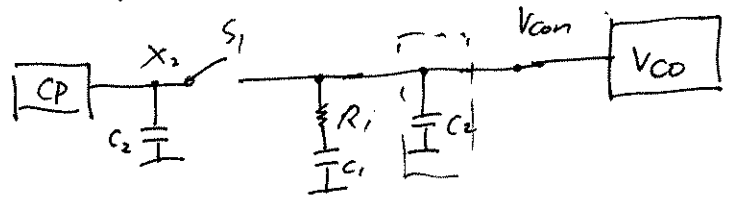
No. the sampling filter cannot remove the effect of the mismatch between the up & down current.

When there is an $\Delta I = I_{up} - I_{down}$, duration time ΔT

~~this~~ $Q = \Delta I \cdot \Delta T$, this amount of charge will be stored in capacitor C_2 when S_1 is off.

When S_1 is on, $Q = \Delta I \cdot \Delta T$ will share between C_1 and C_2 , which will affect the V_{con} .

Soln 10.4.

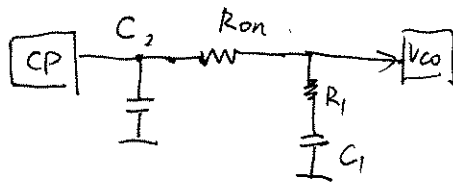


We still need a C_2 at the node of V_{con} .

because, the switch S_1 truly helps us to remove the most of ripple by PFD/CP circuit, but, it also brings charge injection and clock feed through to the node of V_{con} .

The purpose of C_2 tied to V_{con} is to suppress the charge injection and clock feedthrough of S_1 .

10.5 soln:



This R_{on} suppress the ripple at node V_{cont} ,
However, it degrades the Phase Margin of the
loop.

From Eq. (9.42) and Appendix (Z).

we know.

$$PM \approx \tan^{-1}(4\beta^2) - \tan^{-1}\left(4\beta^2 \frac{R_{on} \omega_2}{R_1 C_1}\right)$$

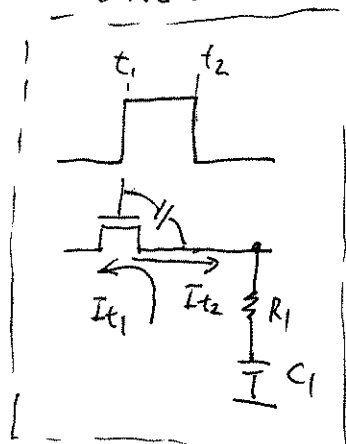
which means $(R_{on} \omega_2)^{-1}$ must remain 5 to 10 times
higher than ω_2 . So R_{on} cannot be too large.

10.6 Solu:

Sure. Even when the PLL is Locked, the charge injection and clock feedthrough of S_1 still produce ripple on the V_{cont} . (Even Neglect the CP/PFD nonideality)

Because. when the switch is on I_{t1} discharges and I_{t2} charges the C_1 , which will affect

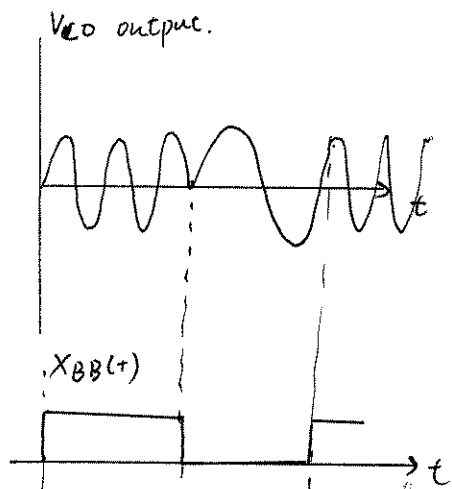
the V_{cont} .



10.7. Solu:

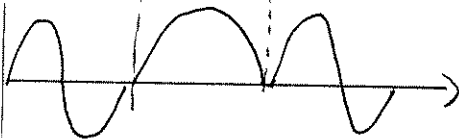
(I) The base band bit period
much shorter than
loop time constant.

(a). output of VCO.



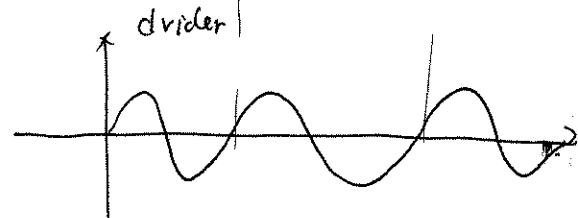
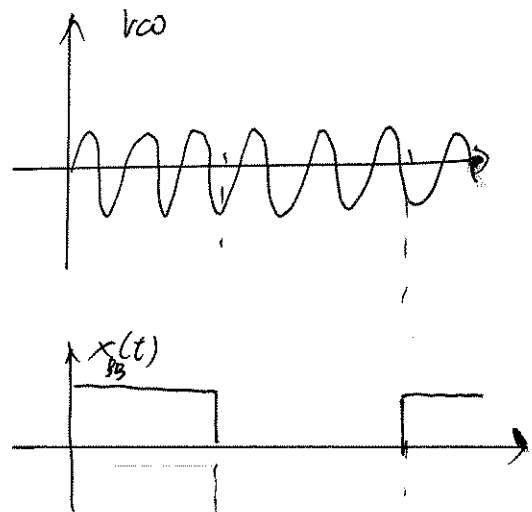
(b)

divider $N=2$



(II) The base band bit period
much longer than
the loop time constant

(a) output of VCO



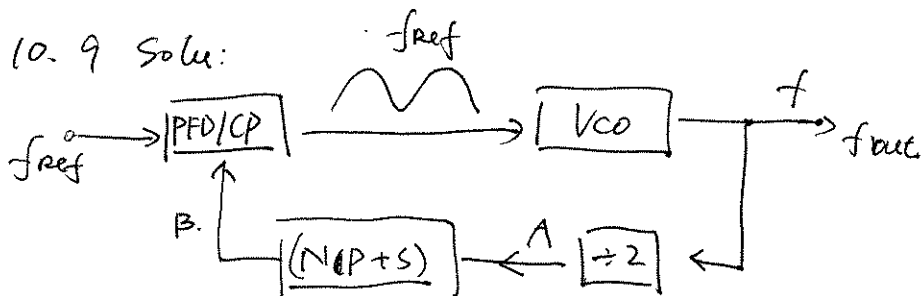
10.8 Soln:

If the modulus control of the prescaler.
assume the change happens at prescaler is m ($< N$)
at the beginning.

Ideally, the modulus should be $N+1$, now it changes
to N .

$$N S + (N+1)(P-S) \\ = (N+1)P.$$

So the result is that the modulus of the
overall ^{slow} divider is change to $(N+1)P$.
pulse

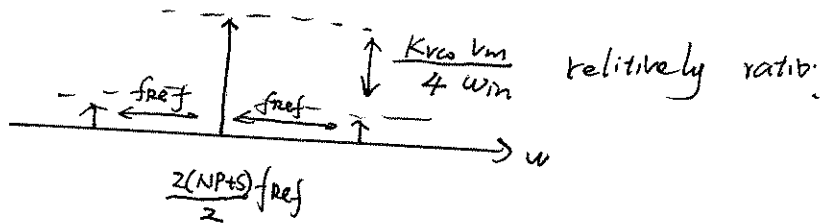


$$f_{out} = 2 \cdot (NP+S) f_{ref} + K_{vco} \sin f_{ref} \cdot 2\pi \cdot t.$$

② node A.

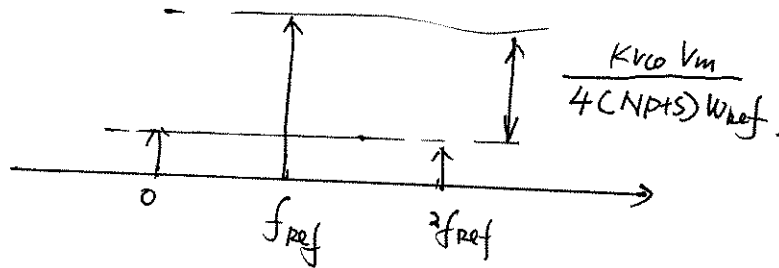
$$V_A = V_o \cos \left[\frac{1}{2} f_{out} \cdot 2\pi \cdot t + \frac{K_{vco}}{2} \int V_m \cdot \sin f_{ref} \cdot 2\pi \cdot t \right]$$

$$\approx V_o \cos \left[2\pi \cdot \frac{f_{out}}{2} \cdot t \right] - \frac{K_{vco} V_m}{2 \cdot 2 \cdot \omega_{in}} V_o \cos \left(\frac{\omega_{out}}{2} + \omega_{in} \right) t \quad \frac{K_{vco} V_m}{2 \cdot \omega_{in}} V_o \cos \left(\frac{\omega_{out}}{2} - \omega_{in} \right)$$

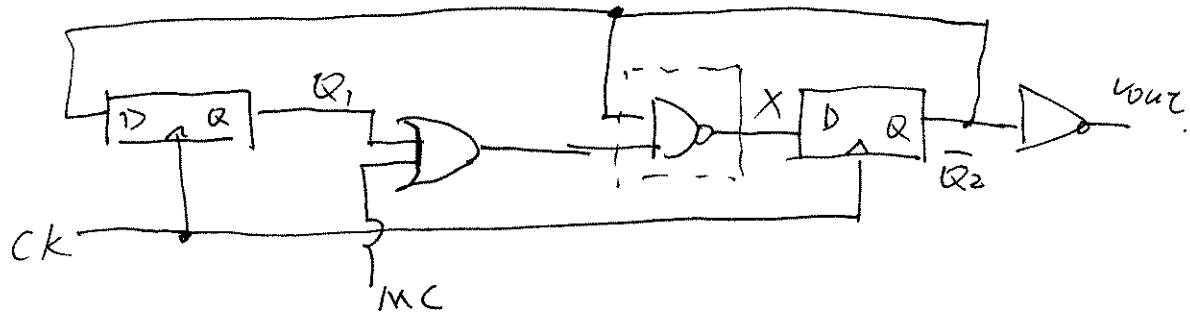


② node B.

V_B :



10.10. Solu:



If G_1 is the NAND Gate,

When $MC = 1$, X is always 0.

So the $\div 2$ divider cannot work correctly

When $MC = 0$,

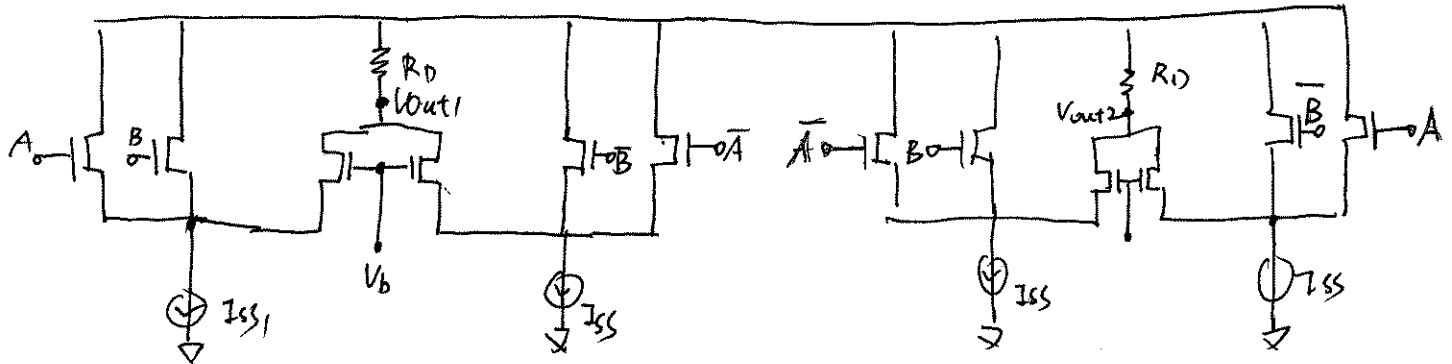
Q_1	Q_2	\bar{Q}_2	X	V_{out}
0	0	1	0	0
1	0	1	0	0
1	0	0	0	0

X is always 0 also.

So the $\div 3$ divider can't work correctly too.

10.11. Solu:

Modify Fig. 10.42 to provide differential outputs.



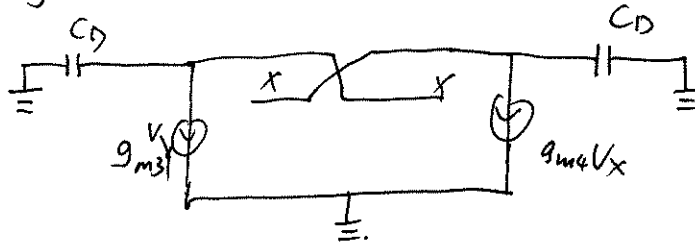
$$\therefore V_{out1} = \overline{AB} + \overline{A\bar{B}} ;$$

$$\begin{aligned} \overline{V_{out1}} &= \overline{\overline{AB} + \overline{A\bar{B}}} = (A + \bar{B}) \cdot (\bar{A} + B) \\ &= A \cdot B + \bar{B} \cdot \bar{A} \end{aligned}$$

$$\therefore \underline{V_{out2} = A \cdot B + \bar{A} \cdot \bar{B}}$$

10.12 Solu:

If Fig 10.44 (a) changes into



$$C_D \cdot \frac{dV_X}{dt} + g_{m3,4}V_Y = 0$$

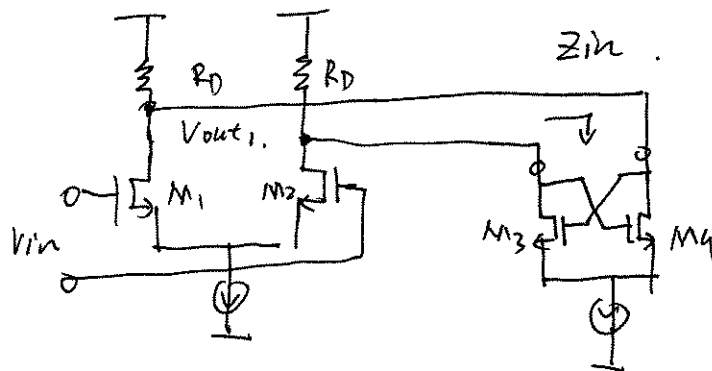
$$C_D \cdot \frac{dV_Y}{dt} + g_{m3,4}V_X = 0$$

$$C_D \left(\frac{d(V_X - V_Y)}{dt} \right) = + (g_{m3,4})(V_X - V_Y)$$

$$\Rightarrow V_{XY} = V_{XY0} \exp \left(\frac{g_{m3,4}}{C_D} \cdot t \right)$$

$$\Rightarrow \tau = \frac{C_D}{g_{m3,4}} \therefore$$

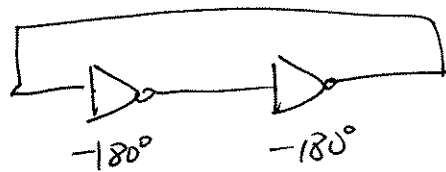
10.13 Solu:



$$Z_{in} = -\frac{2}{g_{m3,4}}$$

From stage 1 operation, we can find that there are 180° phase shift., and also produces some gain.

So for two-stage consideration, we can model this as



So Barkhausen condition is satisfied.

10.14. Solu:

From example 10.18.

$$T_{reg} = \frac{R_D C_D}{g_{m3,4} R_D - 1} \quad \text{Equation (10.44)}$$

$$\text{If } g_{m3,4} R_D \gg 1 \Rightarrow T_{reg} = \frac{C_D}{g_{m3,4}}$$

independent of R_D .

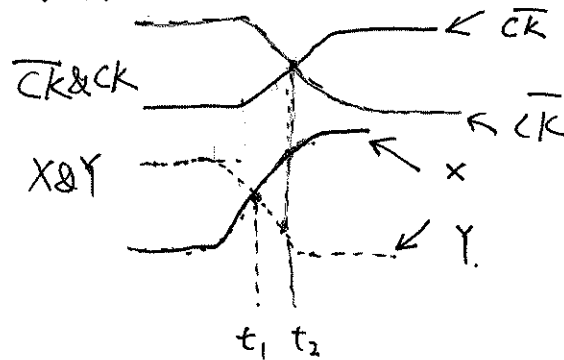
When R_D is very large, the current generated by M_3 & M_4 will mainly charge the capacitor C_D . That means the current flowing into R_D is neglected.

So T_{reg} is ~~dep~~ determined by the C_D and $g_{m3,4}$.

10.15 Solu:

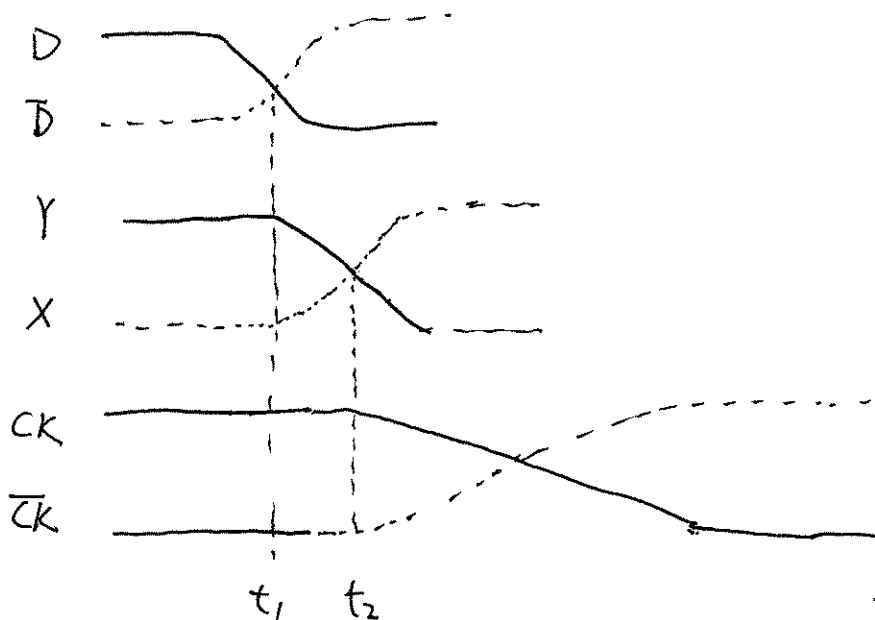
In Fig. 10.43.

(a) clock transition time on the X, Y constant. ^{order of} _{time}



From the above figure, when clock transition time is on the order of X, Y time constant, the D latch can be working correctly.

(b) clock transition time is much longer.



From the above, figure, we know that even the clock transition is much longer, the operation will be still correct.

10.16. Solu:

Fig. 10.68.

loop gain = mixer conversion gain * amplif.

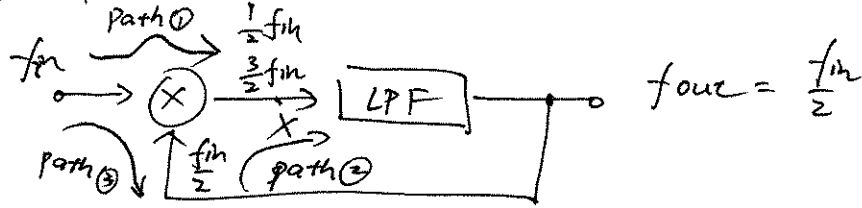
$$= \frac{4}{\pi} \cdot g_{m5,6} \cdot \left| R_p \parallel \left(-\frac{2}{g_{m7,8}} \right) \right|$$

$$= \frac{4}{\pi} \cdot g_{m5,6} \cdot \left| \frac{R_p \cdot \frac{2}{g_{m7,8}}}{\frac{2}{g_{m7,8}} - R_p} \right|$$

$$= \frac{8}{\pi} \frac{g_{m5,6}}{g_{m7,8}} \cdot \left| \frac{g_{m7,8} \cdot R_p}{2 - R_p \cdot g_{m7,8}} \right|$$

$$= \frac{4 \cdot g_{m5,6} R_p}{\pi |2 - R_p \cdot g_{m7,8}|}$$

10.17 Solu:



Path ① f_{in} to \times node, will be attenuated by LPF.

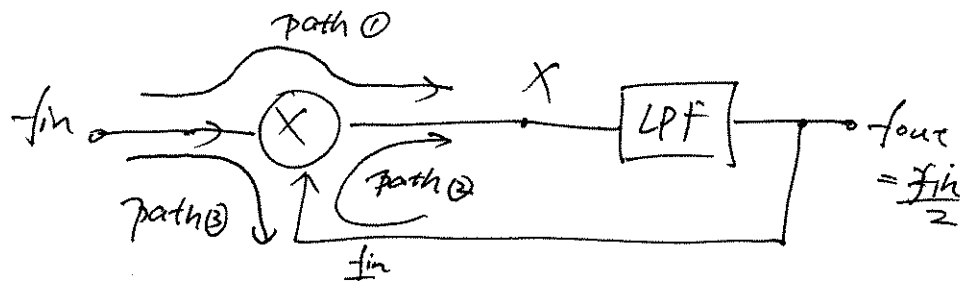
path ②. the frequency is f_{out} itself, which doesn't contribute spurs.

Path ③.

Feed through f_{in} signal with mixer with the input f_{in} signal, which results at output is just DC signal.

In summary, even if the mixer suffers from port to port feed throughs, there are no spurs at output.

10.18 Solu:



Assume node nonlinearity by $y(x) = ax + bx^2 + cx^3$;
 path ① at X node.

$\Rightarrow f_{in}, 2f_{in}, 3f_{in}$ components.

path ② at X node

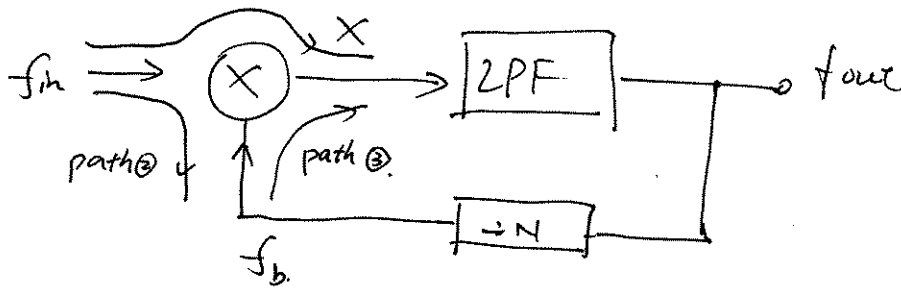
$\Rightarrow \frac{f_{in}}{2}, f_{in}, \frac{3}{2}f_{in}$ components.

path ③ at X node.

$\Rightarrow 0, f_{in}, 2f_{in}$ components.

In summary, if the Lowpass filter has enough orders to attenuate the component at f_{in} , then the results are the same with the previous problem.

10. 19 Solu: path ①



$$f_{out} = \frac{N}{N+1} f_{in}, \quad f_b = \frac{1}{N+1} f_{in}.$$

(a) port-to-port feed through.

path ① \Rightarrow ② X node.

$$f_{in}, \quad f_{in} + \frac{1}{N+1} f_{in}, \quad f_{in} - \frac{1}{N+1} f_{in}$$

path ③ \Rightarrow ③ X node

DC,

path ③ \Rightarrow ② X node

$$\frac{1}{N+1} f_{in}$$

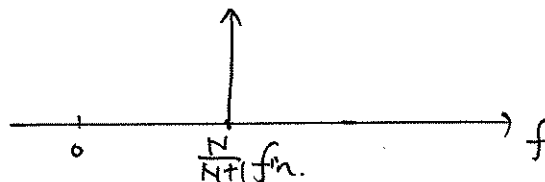
In sum, there are three spurs.

(b) port nonlinearity

③ X node. -

$$f_{in} + \frac{1}{N+1} f_{in}, \quad \frac{N}{N+1} f_{in}, \quad \frac{2N}{N+1} f_{in}, \quad \dots$$

output spectrum.



port linearity can produce high-order harmonics of $\frac{N}{N+1} f_{in}$.

However, they can be filtered by LPF.

10.20 Solu:

Which mixer topologies are suited to the Miller Divider?

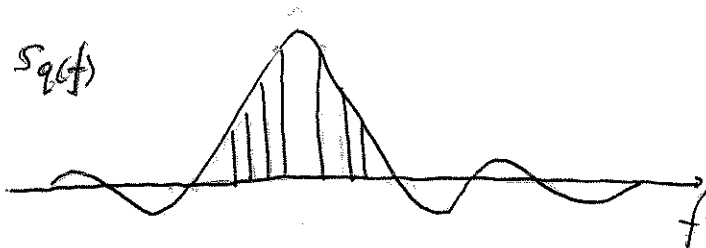
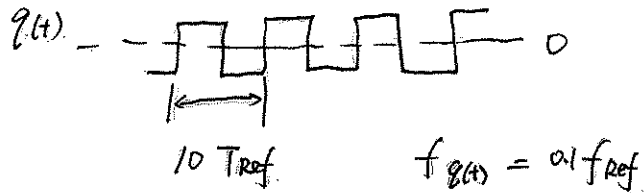
In order to achieve more gain, I'd like to choose active mixer. Because ^{before} steady state the loop need enough loop gain to startup.

If passive mixer must be used, some gain enhancement technique should be used like Fig. 10.68. a coupled pair M7 & M8.

11.1 Solu:

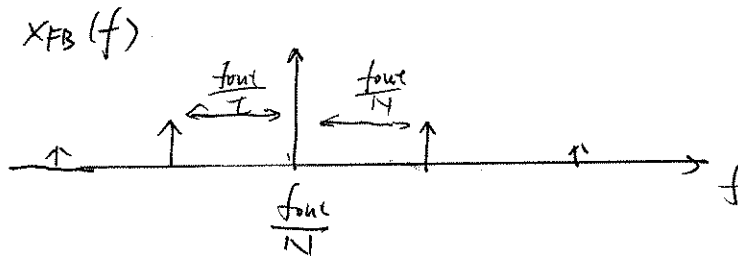
$$f_{FB}(t) = \frac{f_{out}}{N + b(t)} \approx \frac{f_{out}}{N} \left(1 - \frac{b(t)}{N}\right)$$

$$b(t) = a + q(t), \quad \alpha = 0.1, \quad \text{periodic.}$$



$$X_{FB}(t) = V_0 \cos \left(\frac{f_{out}}{N} \left(1 - \frac{b(t)}{N}\right) t \right)$$

With narrowband FM approximation



11.2 Solu:

$$f_{FB}(t) \approx \frac{f_{out}}{N} \left(1 - \frac{b(t)}{N}\right)$$

$$\phi_{out}(t) = \frac{f_{out}}{N} t + \phi_0$$

$$= \frac{f_{FB}^{(t)} N}{1 - \frac{b(t)}{N}} t + \phi_0$$

$$= \frac{f_{FB}(t) N^2}{N - b(t)} t + \phi_0$$

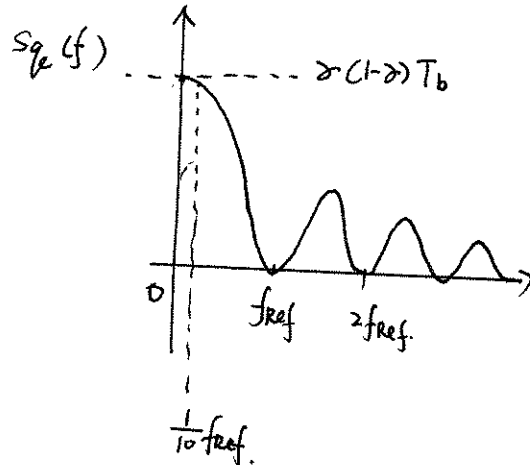
From the equation above, we can conclude that $f_{FB}(t)$ and $b(t)$ are periodic $\Rightarrow \frac{f_{FB}(t) N^2}{N - b(t)}$ are also periodic.

$$\phi_{out}(t) = A(t) \cdot t + \phi_0$$

$$\frac{d\phi_{out}(t)}{dt} = A(t) + A'(t) \cdot t$$

Solu 11.3.

If $T_0 = T_{ref}$.



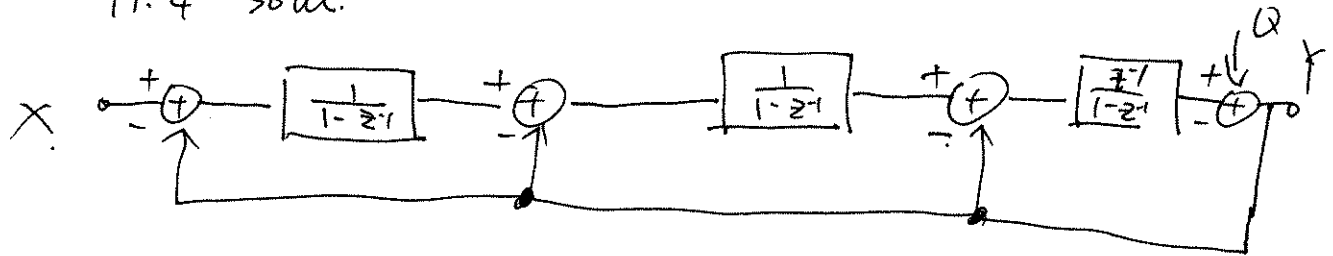
It implies that the low-frequency part ($f < \frac{1}{10} f_{ref}$) of $S_g(f)$ can be suppressed by PLL. The components with higher frequencies will be the critical part of $S_g(f)$

$$S_g\left(\frac{1}{10} f_{ref}\right) = 2(1-2) \cdot f_{ref} \left(\frac{\sin \pi \frac{f}{f_{ref}}}{\pi f} \right) \bigg|_{f = \frac{1}{10} f_{ref}}$$

$$= 2(1-2) f_{ref} \frac{\sin \pi \frac{1}{10}}{\pi \cdot \frac{1}{10} f_{ref}}$$

$$= 0.98 \cdot 2(1-2)$$

11.4 Solu:



assume $X = 0$.

$$\left\{ \left[\left[0 - Y(z) \right] \frac{1}{1-z^{-1}} - Y(z) \right] \frac{1}{1-z^{-1}} - Y(z) \right\} \frac{z^{-1}}{1-z^{-1}} + Y = Y(z)$$

$$\Rightarrow \frac{Y}{Q}(z) = (1-z^{-1})^3$$

$$\Rightarrow S_y(f) = S_q(f) |2 \sin(\pi f T_{ck})|^6$$

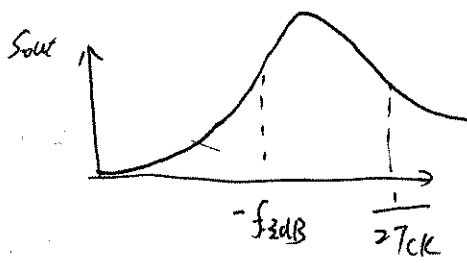
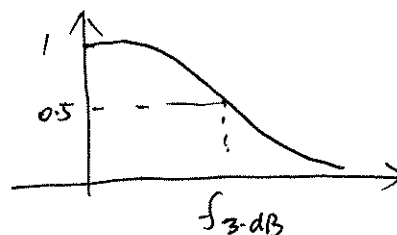
$$\therefore \phi(z) = Y(z) / (1-z^{-1})$$

$$\therefore \phi(z) = (1-z^{-1})^2 Q(z)$$

$$\therefore S_\phi(f) = |1-z^{-1}|^4 S_q(f)$$

$$= |2 \sin \pi f T_{ck}|^4 S_q(f)$$

$$\therefore S_{out}(f) = S_\phi(f) \cdot N^2 \frac{4 \gamma^2 \omega_n^2 \omega^2 + \omega_n^2}{(\omega^2 - \omega_n^2)^2 + 4 \gamma^2 \omega_n^2 \omega^2}$$



11.5 soln:

For a second order :

$$S_y(f) = S_g(f) |2 \sin(\pi f T_{ck})|^2$$

For a fourth-order :

$$S_y(f) = S_g(f) |2 \sin(\pi f T_{ck})|^4$$

$|H_{PLL}(f)|^2$ is the same.

For 2nd order

$$S_{out}(f)_{2nd} = S_g(f) |2 \sin \pi f T_{ck}|^2 |H_{PLL}(f)|^2$$

For 4th order

$$S_{out}(f)_{4th} = S_g(f) |2 \sin \pi f T_{ck}|^4 |H_{PLL}(f)|^2$$

$$\frac{f_{ref}}{10} \approx f \ll f_{ck}$$

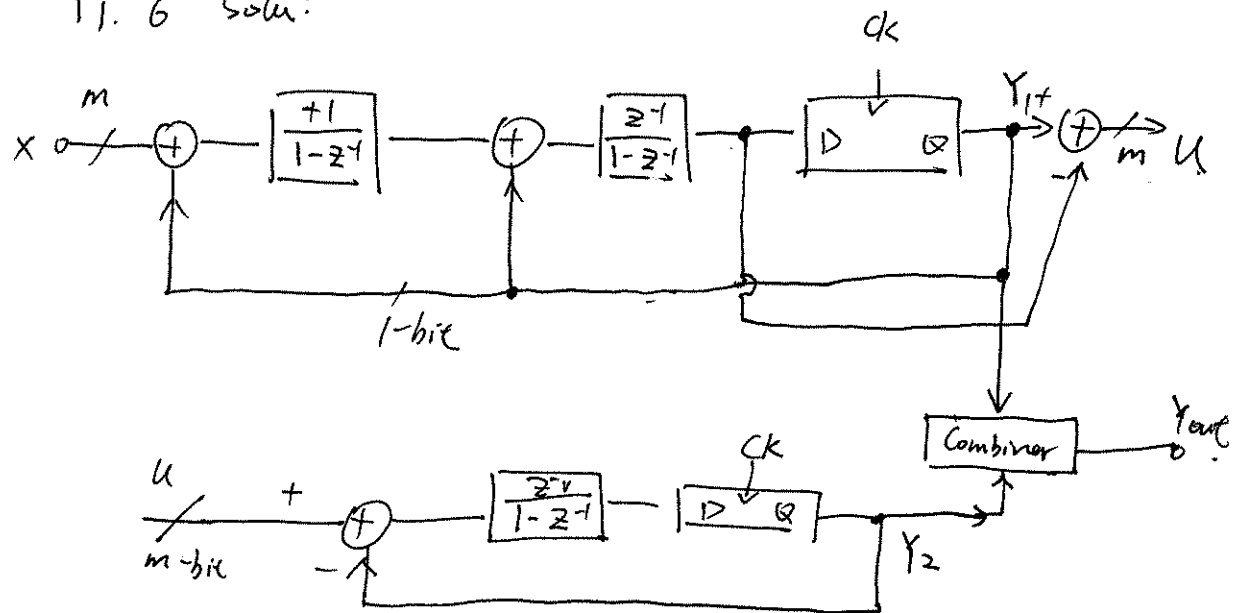
$$\therefore \frac{S_{out}(f)_{4th}}{S_{out}(f)_{2nd}} = |2 \sin \pi f T_{ck}|^4 \approx 16 f^4 (\pi T_{ck})^4$$

$$\text{assume } f = \frac{f_{ck}}{10}$$

$$10 \lg \left(16 \frac{f_{ck}^4}{10^4} \cdot \pi^4 \frac{1}{f_{ck}^4} \right) = 10 \lg_{10} \left(\frac{16 \pi^4}{10^4} \right)$$

$$= 8.1 \text{ dB}$$

11.6 Solu:



$$Y_1(z) = (1 - z^{-1})^2 Q(z)$$

$$Y_2(z) = z^{-1} Q(z) + (1 - z^{-1}) Q'(z)$$

$$Y_{out}(z) = Y_1(z) \cdot z^{-1} - (1 - z^{-1})^2 Y_2(z)$$

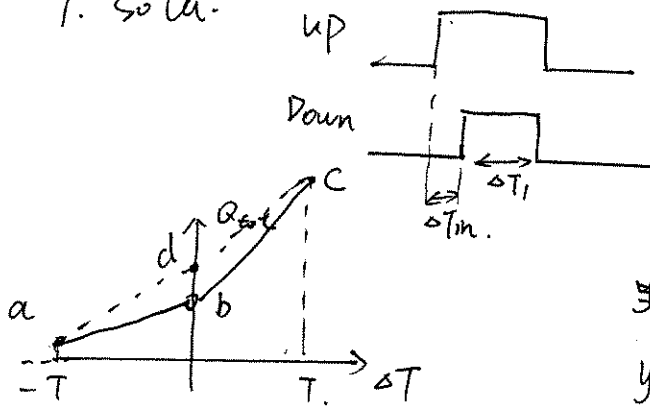
$$= z^{-1} (1 - z^{-1})^2 Q(z) - z^{-1} (1 - z^{-1})^2 Q(z) - (1 - z^{-1})^3 Q'(z)$$

$$= -(1 - z^{-1})^3 Q'(z)$$

//

This is what combiner should do.

7. Solu:



assume $(I_1 - I_2) \Delta T_1 = A$

\neq

$$\frac{y - I_1 T - (I_1 - I_2) \Delta T_1}{x - T} = \frac{I_1 + I_2}{2}$$

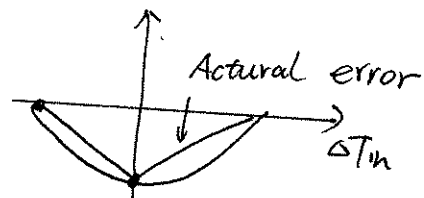
$$\boxed{y = \frac{I_1 + I_2}{2} x + \frac{I_1 - I_2}{2} T + A}$$

$$-b + \frac{I_1 - I_2}{2} T + A = A$$

$$\Rightarrow b = \frac{I_1 - I_2}{2} T$$

$$a \Delta T_{in}^2 - b = 0$$

$$\Rightarrow \Delta T_{in} = \pm \sqrt{\frac{a}{b}}$$



Actual error:

$$\text{Error} = \frac{I_1 - I_2}{2} \Delta T_{in} - \frac{I_1 - I_2}{2} T = 0$$

$$\Rightarrow \Delta T_{in} = T$$

$$\therefore \sqrt{\frac{a}{b}} = T$$

$$\Rightarrow a = T^2 b = T^3 \frac{I_1 - I_2}{2} = 2.5\% T^3$$

11.8 Solu:

(a) unequal Up and Down pulse widths.

Unequal up and down pulse widths are equivalent to the I_1 and I_2 mismatch in CP. So it's noise folding behavior can be modeled as the same as Fig. 11.30.

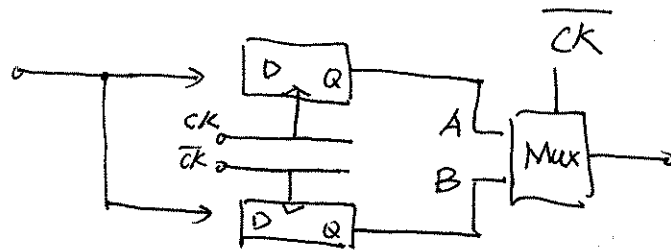
(b) charge injection mismatch between up & Down switch in CP.

For charge injection mismatch, it contributes to the $(I_1 - I_2)$ mismatch every cycle. That means.

In equation $Q_{\text{ave}} \approx I_{\text{avg}} \Delta T_m + a \Delta T_m^2 - b$, a will be larger.

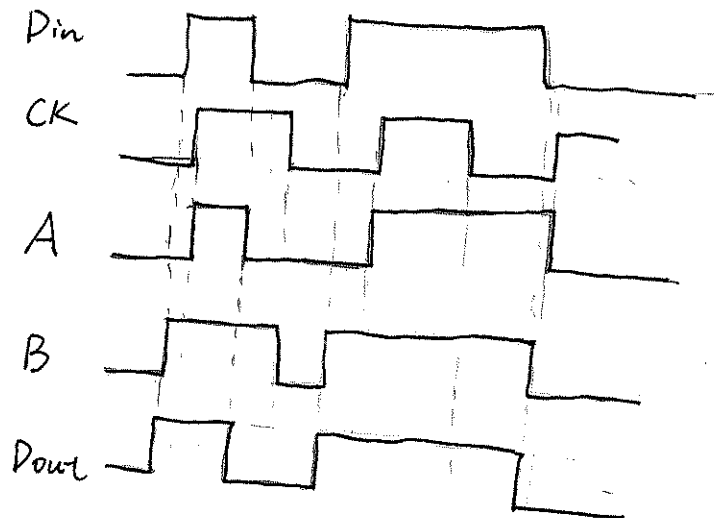
So the mismatch makes noise folding worse.

11.9 soln:



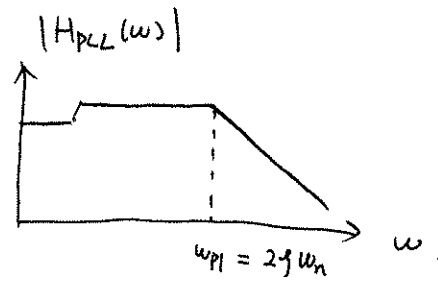
Previously, when CK is high B is selected.

Now, when CK is high. A is selected.



11.10 Solu:

PLL



Model as one-pole system.

$$H_{PLL}(s) = \frac{2\xi\omega_n}{s + 2\xi\omega_n}$$

$$= \frac{0.1 \cdot \frac{2\pi}{T_1}}{s + 0.1 \cdot \frac{2\pi}{T_1}}$$

$$\therefore |H_{PLL}(j\omega)| = \left| \frac{0.1}{j\frac{\omega}{f_1} + 0.1} \right| \quad \left(f_1 = \frac{1}{T_1} \right)$$

$$= \frac{0.1}{\sqrt{0.1^2 + \frac{\omega^2}{f_1^2}}}$$

$$|H_{PLL}(j2\pi \frac{f_1}{2})| = \frac{0.1}{\sqrt{0.1^2 + 5^2}} = 0.02$$

$$= -16.9 \text{ dB}$$

If $f_{out} = N \cdot f_{in}$. (assume, ω_n, ξ remain the same).

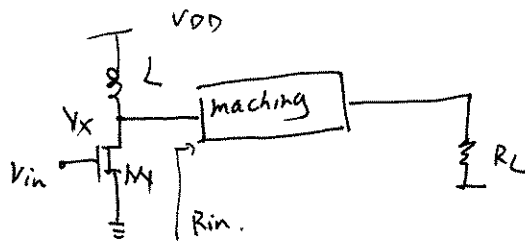
$$\xi = \frac{R_1}{2} \sqrt{\frac{Z_p C K_{VCO}}{2\pi M}}; \quad \omega_n = \sqrt{\frac{Z_p K_{VCO}}{2\pi M}}$$

If ξ, ω_n is the same, then $Z_p \cdot K_{VCO}$ will be change to N times larger.

So the attenuation is not changed, but

the circuit design is more difficult.

12.1 Solu:



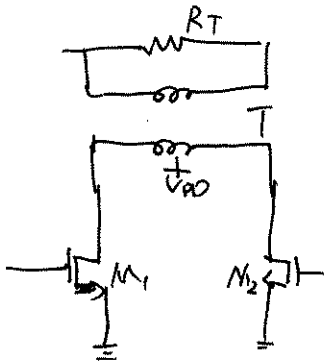
$$\begin{aligned}
 v_x(t) &= V_{DD} (1 + \cos \omega t) \\
 i_d(t) &= \frac{V_{DD}}{R_{in}} (1 + \cos \omega t)
 \end{aligned}
 \left[\begin{array}{l} \text{assume accurate bias} \\ = \frac{V_{DD}}{R_{in}} \\ \text{only on this condition} \\ \eta = 50\% \end{array} \right]$$

P_{FET}

$$\begin{aligned}
 &= \frac{1}{2T} \int_0^T v_x(t) \cdot i_d(t) dt \\
 &= \frac{1}{2T} \int_0^T \cdot \frac{V_{DD}^2}{R_{in}} (1 + 2\cos \omega t + \cos^2 \omega t) dt \\
 &= \frac{V_{DD}^2}{2R_{in}}
 \end{aligned}$$

\therefore The other 50% of supply power is dissipated by M_1 itself.

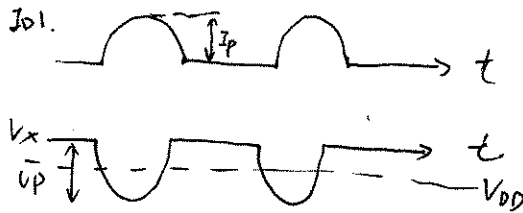
12.2 solu:



This class B amplifier seems very symmetric like differential structure. However, when it works, M_1 , M_2 is ~~sepa~~ separately operating just like single-end. structure.

So it's still sensitive to bond wire inductance in series with V_{DD} .

12.3 Solu:



$$I_{D1} = I_p \sin \omega_0 t \quad (0 < t < \frac{\pi}{\omega_0})$$

$$\frac{1}{T} \left(\int_0^T (V_x - V_p \sin \omega_0 t) dt + \int_0^T V_x dt \right) = V_{DD}$$

$$\Rightarrow V_x = V_{DD} + \frac{V_p}{\pi}$$

The voltage swing above V_{DD} is:

$$V_x - V_{DD} = \frac{V_p}{\pi} \approx 0.32 V_p$$

The voltage swing below V_{DD} is:

$$V_p - \frac{V_p}{\pi} = V_p \left(1 - \frac{1}{\pi}\right) \approx 0.68 V_p$$

So the swing above V_{DD} is approx. half that below V_{DD} .

12.4 solve:

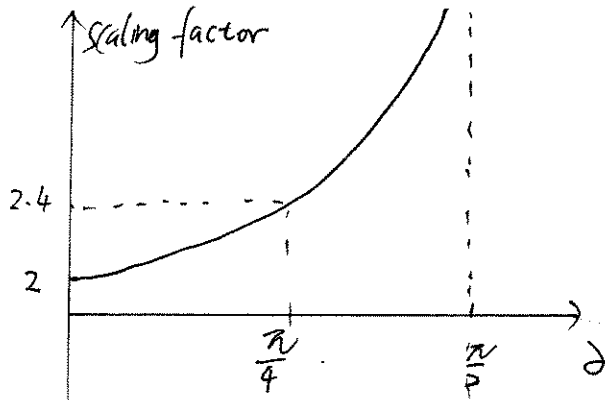
From Eq. 12.39 & Eq. 12.40.

$$a_1 = I_p \frac{\pi - 2\theta}{2\pi} + \frac{I_p}{2\pi} \sin 2\theta.$$

$$(\theta \in (0, \frac{\pi}{2})).$$

scaling factor

$$= \frac{1}{a_1/I_p} = \frac{1}{\frac{\pi - 2\theta}{2\pi} + \frac{\sin 2\theta}{2\pi}}$$



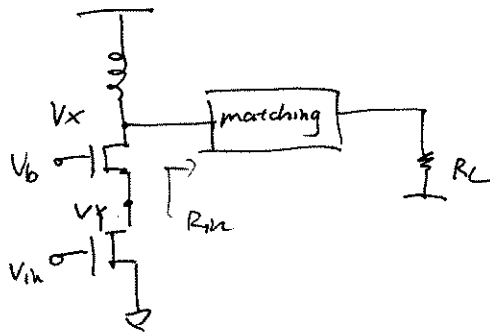
From the figure above, we can conclude that.

only when the transistor is infinitely large, the efficiency

can be 100% on the condition of providing

an comparable output power to that of A class.

12.5 solu:



when V_x reaches to $2V_{DD}$ and nearly zero.

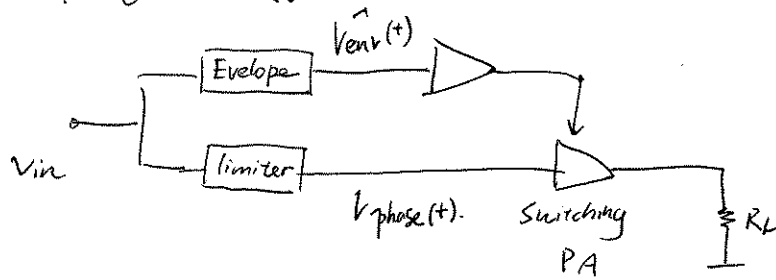
$$P_L = \left(\frac{2V_{DD}}{2}\right)^2 / 2R_{in}.$$

$$\text{The } I_D = \frac{V_{DD}}{R_{in}}.$$

$$\therefore \eta_{\max} = \frac{P_L}{I_D \cdot V_{DD}} = \frac{V_{DD}^2 / 2R_{in}}{V_{DD}^2 / R_{in}} = 50\%$$

In sum, the efficiency is the same
as class A PA.

12-6 Solu:



$$V_{in} = V_{env}(t) \cos(\omega_0 t + \phi(t))$$

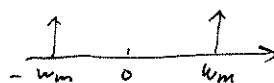
$$\begin{cases} \hat{V}_{env}(t) = V_{env}(t) + \frac{1}{3} V_{env}^3(t) \\ V_{phase}(t) = V_0 \cos(\omega_0 t + \phi(t)) \end{cases}$$

$$V_{out} = \hat{V}_{env}(t) \cdot V_{phase}(t)$$

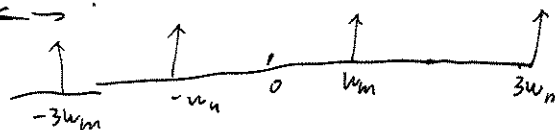
$$= V_0 V_{env}(t) \cos(\omega_0 t + \phi(t)) + \frac{1}{3} V_0 V_{env}^3(t) \cos(\omega_0 t + \phi(t))$$

Assume

$$V_0 V_{env}(t) \xleftrightarrow{\text{Fourier}}$$



$$V_{env}^3(t) \xleftrightarrow{\text{Fourier}}$$



This part of spectrum will also convert to the vicinity of ω_0 .

So the output spectrum exhibits growth in the adjacent channels.

12.7 soln:

Assuming the phase signal experiences a delay mismatch of ΔT .

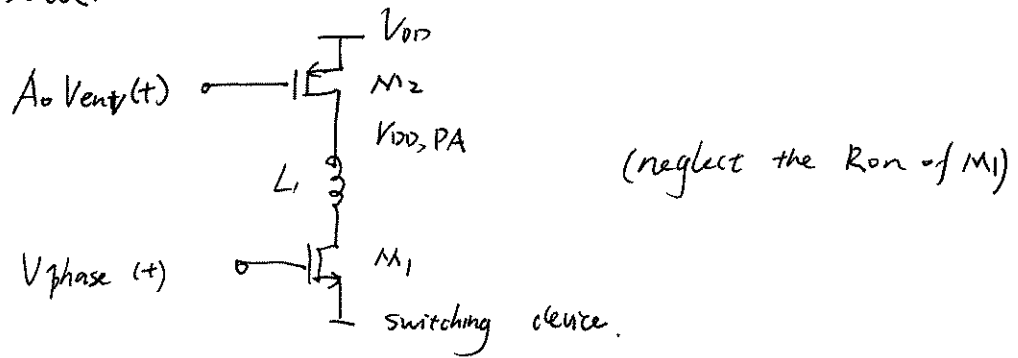
$$\begin{aligned} V_{out} &= A_0 V_{env}(t) \cos [\omega_0 (t - \Delta T) + \phi(t - \Delta T)] \\ &\approx A_0 V_{env}(t) \cos \left[\omega_0 t - \omega_0 \Delta T + \phi(t) - \Delta T \frac{d\phi(t)}{dt} \right] \\ &\approx A_0 V_{env}(t) \cos [\omega_0 t + \phi(t)] \cos \left[\left(\omega_0 + \frac{d\phi(t)}{dt} \right) \Delta T \right] \\ &\quad + A_0 V_{env}(t) \sin [\omega_0 t + \phi(t)] \sin \left[\left(\omega_0 + \frac{d\phi(t)}{dt} \right) \Delta T \right] \end{aligned}$$

$$\text{assume } \Delta T \ll \frac{1}{\omega_0 + \frac{d\phi(t)}{dt}}$$

$$V_{out} \approx A_0 V_{env}(t) \cos [\omega_0 t + \phi(t)] + \underbrace{\Delta T \left(\omega_0 + \frac{d\phi(t)}{dt} \right) A_0 V_{env}(t) \sin [\omega_0 t + \phi(t)]}_{\downarrow}$$

From the second term, we can also conclude that this mismatch ΔT leads to substantial spectral regrowth.

12.8 solu:



In this stage, L_1 ~~does~~ not consume power, neither M_1 .
So the only dissipated power is consumed by M_2 .

$$\text{efficiency} = 1 - \frac{I_0 V_0}{I_0 \cdot V_{DD}}$$

$$= 1 - \frac{V_0}{V_{DD}}$$

12.9 Solu:

$V_1(t)$ $V_2(t)$ are defined by Eq (12.109) (12.110)

$$V_1(t) + V_2(t)$$

$$= \left(\frac{V_0}{2} + \Delta V \right) \sin [\omega_0 t + \phi(t) + \theta(t) + \Delta\theta] - \frac{V_0}{2} \sin [\omega_0 t + \phi(t) - \theta(t)]$$

$$= \frac{V_0}{2} \left\{ \sin [\omega_0 t + \phi(t) + \theta(t) + \Delta\theta] - \sin [\omega_0 t + \phi(t) - \theta(t)] \right\}$$

$$+ \Delta V \sin [\omega_0 t + \phi(t) + \theta(t) + \Delta\theta]$$

$$= \frac{V_0}{2} \left\{ \sin [\omega_0 t + \phi(t) + \theta(t)] \cdot \cos \Delta\theta - \sin [\omega_0 t + \phi(t) - \theta(t)] \right\}$$

$$+ \frac{V_0}{2} \sin \Delta\theta \cos [\omega_0 t + \phi(t) + \theta(t)] + \Delta V \left\{ \sin [\omega_0 t + \phi(t) + \theta(t)] \cos \Delta\theta \right.$$

$$\left. + \cos [\omega_0 t + \phi(t) + \theta(t)] \cdot \sin \Delta\theta \right\}$$

$$\approx \frac{V_0}{2} \cdot 2 \cdot \cos [\omega_0 t + \phi(t)] \sin \theta(t) + \Delta V \sin [\omega_0 t + \phi(t) + \theta(t)]$$

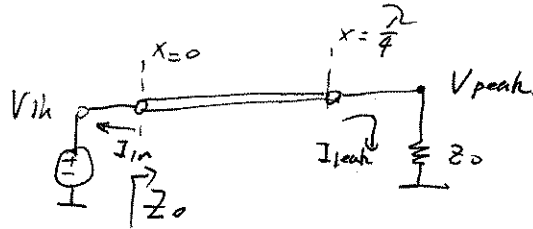
$$+ \left(\frac{V_0}{2} + 1 \right) \Delta\theta \cos [\omega_0 t + \phi(t) + \theta(t)]$$

$$\approx \frac{V_0}{V_a} V_{env}(t) \cdot \cos [\omega_0 t + \phi(t)] + \Delta V \sin [\omega_0 t + \phi(t) + \theta(t)]$$

$$+ \left(\frac{V_0}{2} + 1 \right) \Delta\theta \cos [\omega_0 t + \phi(t) + \theta(t)]$$

12.10 Solu:

If the input is driven by an ideal voltage source.



$$V(t, x) = V^+ \cos(\omega t - \beta x) + V^- \cos(\omega t + \beta x)$$

$$I(t, x) = \frac{V^+}{Z_0} \cos(\omega t - \beta x) - \frac{V^-}{Z_0} \cos(\omega t + \beta x)$$

$$V(t, 0) = (V^+ + V^-) \cos \omega t = V_{in}$$

$$I(t, 0) = \left(\frac{V^+}{Z_0} - \frac{V^-}{Z_0} \right) \cos \omega t = I_{in}$$

$$V(t, \frac{\lambda}{4}) = (-V^+ + V^-) \sin \omega t = V_{peak}$$

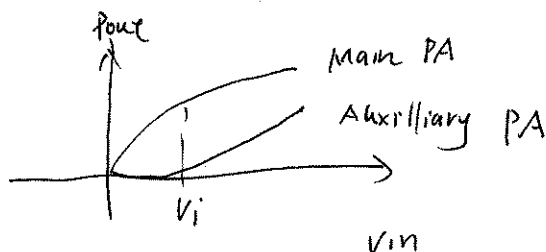
$$I(t, \frac{\lambda}{4}) = \left(-\frac{V^+}{Z_0} - \frac{V^-}{Z_0} \right) \sin \omega t = I_{peak}$$

$$\frac{V_{peak}}{Z_0} = I(t, \frac{\lambda}{4})$$

$$\frac{(-V^+ + V^-) \sin \omega t}{Z_0} = \left(-\frac{V^+}{Z_0} - \frac{V^-}{Z_0} \right) \sin \omega t \Rightarrow -V^+ + V^- = -(V^+ + V^-)$$

$$\frac{V_{in}}{I_{in}} = \frac{V^+ + V^-}{V^+ - V^-} \cdot Z_0 = Z_0$$

The inputs of peaking PA and carrier PA are the exactly same. So it cannot satisfy the figure below.

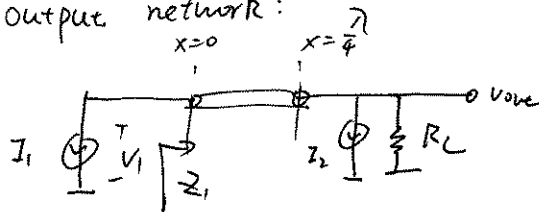


12.11. Solu:

$\delta = 0.5$. The waveform at $x=0$ & $x = \lambda/4$.

$$Z_0 = R_L$$

output network:



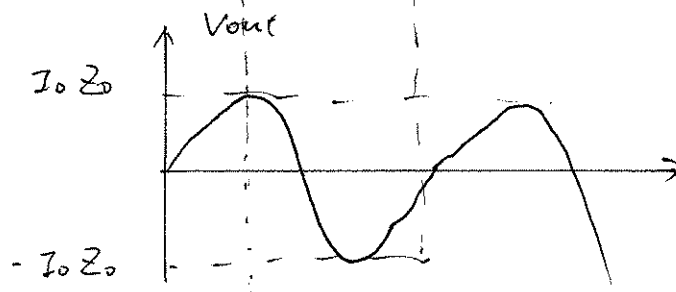
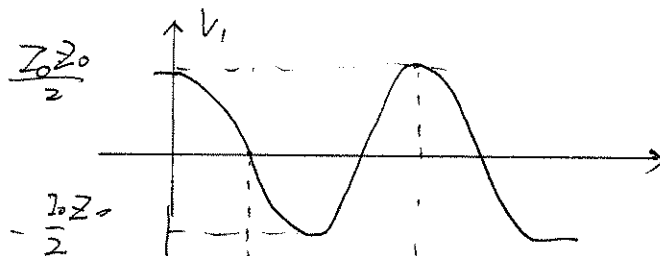
$$Z_1 = Z_0 \left(\frac{Z_0}{R_L} - \delta \right) = \frac{Z_0}{2}$$

assume $I_1 = -I_0 \cos \omega t$.

$$V_1 = I_0 \cos \omega t \cdot \frac{Z_0}{2}$$

$$V_{out} = 2 \cdot I_0 \cos \left(\omega t + \frac{\pi}{2} \right) \cdot \frac{Z_0}{2} \quad I(t, \frac{\lambda}{4}) = -I_0 \frac{Z_0}{2} \sin \omega t$$

$$V(t, \frac{\lambda}{4}) = I_0 Z_0 \sin \omega t$$



13.1. Soln:

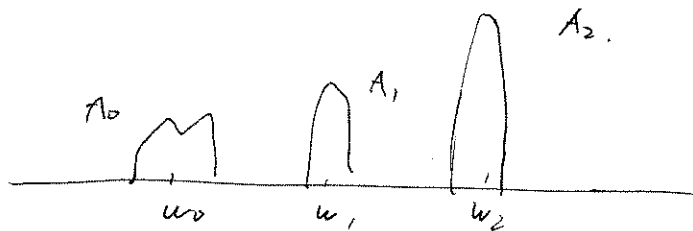
$$\text{data rate} = 54 \text{ Mb/s}$$

sensitivity of -65 dBm .

desired signal : $A_0 \cos \omega_0 t$

adjacent : $A_1 \cos \omega_1 t$

alternate : $A_2 \cos \omega_2 t$



$$20 \log A_0 = -62 \text{ dBm}$$

$$20 \log A_1 = -46 \text{ dBm}$$

$$20 \log A_2 = -30 \text{ dBm}$$

$$20 \log \left| \frac{303}{401} \right| = -15 \text{ dB} - 40 \log A_1 - 20 \log A_2 + 20 \log A_0$$

$$= (-15 + 92 + 60 - \frac{124}{2}) \text{ dBm}$$

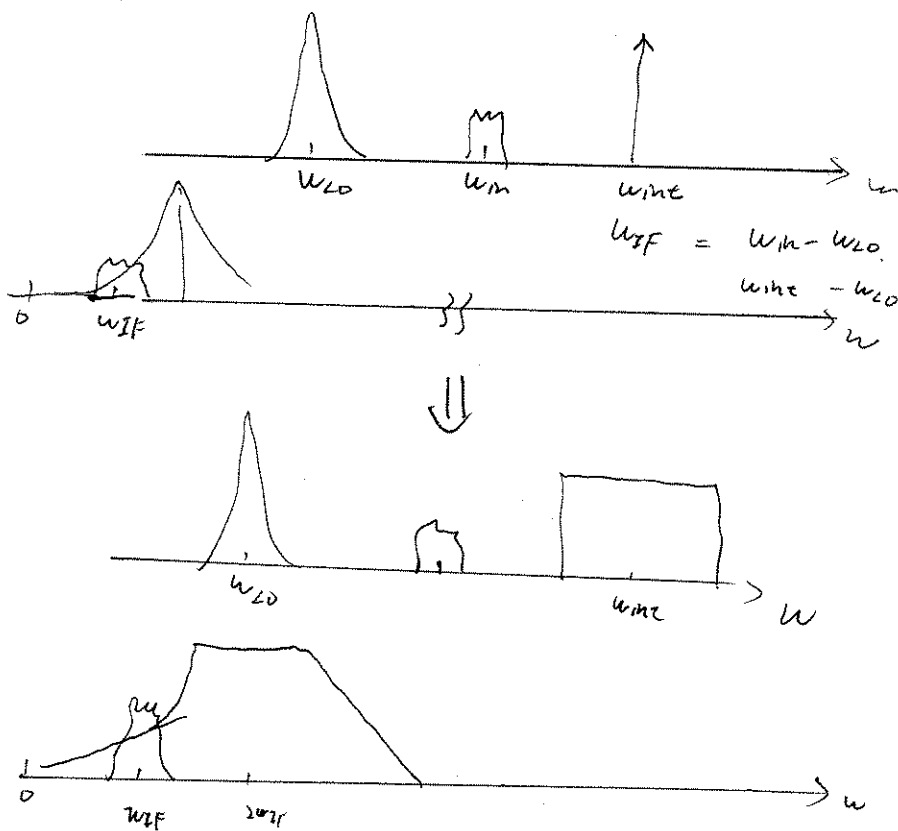
$$= +75 \text{ dBm}$$

$$\text{IIP}_3 \text{ dBm} = 20 \log \sqrt{\frac{481}{393}} = -37.5 \text{ dBm}$$

13.2 Soln:

If interferers are not approximated by narrow-band sig. signal,

The corruption due to reciprocal mixing is larger.



13.3 Solu:

desired input -65 dBm

~~SRI~~ SNR = -35 dB

desired input = -62 dBm

adjacent signal = -46 dBm

alternative : = -30 dBm .

$$\frac{P_{PN, \text{tot}}}{P_{\text{sig}}} = a_1 \delta \left(\frac{1}{f_1} - \frac{1}{f_2} \right) + a_2 \delta \left(\frac{1}{f_3} - \frac{1}{f_4} \right)$$

$$= 39.8 \delta \left(\frac{1}{10\text{M}} - \frac{1}{30\text{M}} \right) + 1585 \delta \left(\frac{1}{30\text{M}} - \frac{1}{50\text{M}} \right)$$

$$= -35 \text{ dB}$$

$$\boxed{-35 = 10 \log_{10} \frac{P_{N, \text{tot}}}{P_{\text{sig}}}}$$

$$\Rightarrow 10^{-6} \cdot 2.3787 \delta = 10^{-\frac{35}{10}}$$

$$\delta \approx 13.3$$

$$\therefore S_n(f) = \frac{13.3}{f^2}$$

13.4 solu:

from Eq (6.51)

$$Z_{in, SB} = \frac{1}{2} \left[R_1 + \frac{1}{\frac{jC_1 \omega}{2} + 2f_G} \right] \quad \omega \approx \omega_{20}$$

$\left\{ \begin{array}{l} R_1 : \text{on resistance of switch} \\ C_1 : \text{the load of the switch. capacitance.} \end{array} \right.$

In the Fig. 13.19.

$$C_1 \approx \frac{2}{3} W L C_{ox} = 130 \text{ fF}$$

$$R_1 \approx 100 \Omega$$

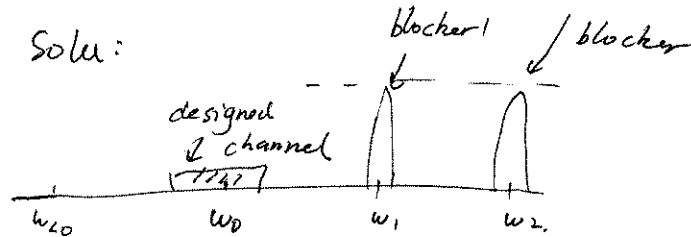
Ⓐ 2.4 G

$$\begin{aligned}
 Z_{in, SB} &= \frac{1}{2} \left(100 + \frac{1}{4.8 \text{ G} \cdot 130 \text{ f} + j \frac{\pi \cdot 2.4 \text{ G} \cdot 130 \text{ f}}{2}} \right) \\
 &= \frac{1}{2} \left(100 + \frac{1}{4.8 \cdot 130 \times 10^{-6} + j \pi \cdot 24 \cdot 130 \cdot 10^{-6}} \right) \\
 &= 459 e^{-j0.91}
 \end{aligned}$$

Ⓑ 6 G

$$Z_{in, SB} = 203.4 e^{-j0.795}$$

13.5 Solu:



$$S_n(f) = \frac{\sigma}{f^2}$$

assume -100 dBc/Hz @ 1 MHz .

$$10 \log \frac{\sigma}{f^2} = -100 \quad \frac{\sigma}{10^{12}} = 10^{-5 \times 2} \Rightarrow \sigma = 100$$

$$\frac{P_{NN, \text{tot}}}{P_{\text{sig}}} = a \cdot 100 \left(\frac{1}{f_1} - \frac{1}{f_2} \right) + a \cdot 100 \left(\frac{1}{f_3} - \frac{1}{f_4} \right)$$

$$100 a \left(\frac{1}{10\text{M}} - \frac{1}{30\text{M}} + \frac{1}{30\text{M}} - \frac{1}{50\text{M}} \right)$$

$$= \frac{8a}{10^6}$$

$$10 \log \frac{8a}{10^6} = -30$$

$$\frac{8a}{10^6} = 10^{-3}$$

$$a = 125$$

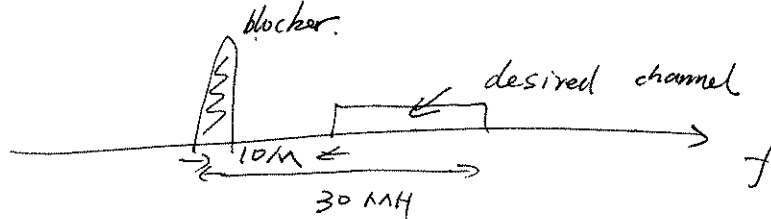
$$10 \log a = 21 \text{ dB}$$

So the highest blocker can be stronger than designed signal than 21 dB.

13.6 Solve:

If only one blocker is located in the adjacent channel.

$\alpha = 100$ (from previous problem)



$$\begin{aligned}\frac{P_{PN}}{P_{sig}} &= a \int_{f_1}^{f_2} \frac{a}{f^2} df \\ &= a \alpha \left(\frac{1}{f_1} - \frac{1}{f_2} \right) = -30\text{ dB} \\ &= 100 a \cdot \left(\frac{1}{10\text{ MHz}} - \frac{1}{30\text{ MHz}} \right) = 10^{-3} \\ 6.67 a \times 10^{-6} &= 10^{-3}\end{aligned}$$

$$a = 150$$

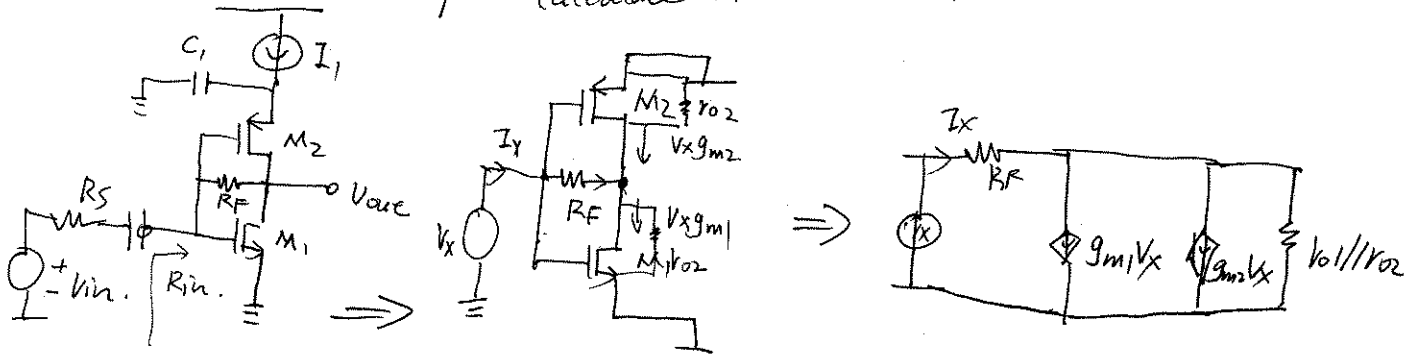
$$\Rightarrow 10 \log_{10} a = 21.76\text{ dB}$$

Compared with the result of Problem 5, 21 dB,

We can conclude that the main effect is because of the blocker in the adjacent channel.

13.7 solu:

1^o calculate R_{in}



$$\frac{V_x - I_x R_F}{r_{o1} || r_{o2}} + g_{m1} V_x + g_{m2} V_x - I_x = 0$$

$$\Rightarrow R_{in} = \frac{V_x}{I_x} = \boxed{\frac{r_{o1} || r_{o2} + R_F}{1 + (g_{m1} + g_{m2})(r_{o1} || r_{o2})}}$$

2^o calculate $\frac{V_{out}}{V_{in}}$

$$\frac{V_{out}}{V_x} = \frac{(r_{o1} || r_{o2}) [1 - (g_{m1} + g_{m2}) R_F]}{R_F + (r_{o1} || r_{o2})}$$

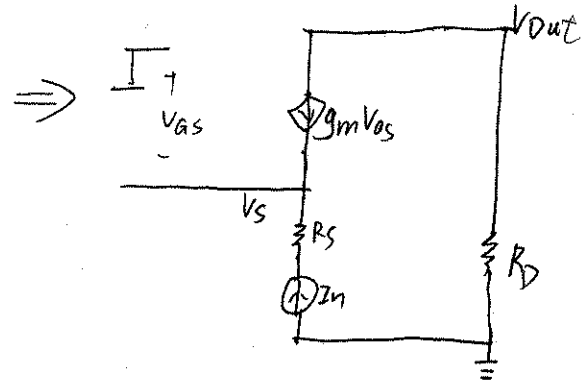
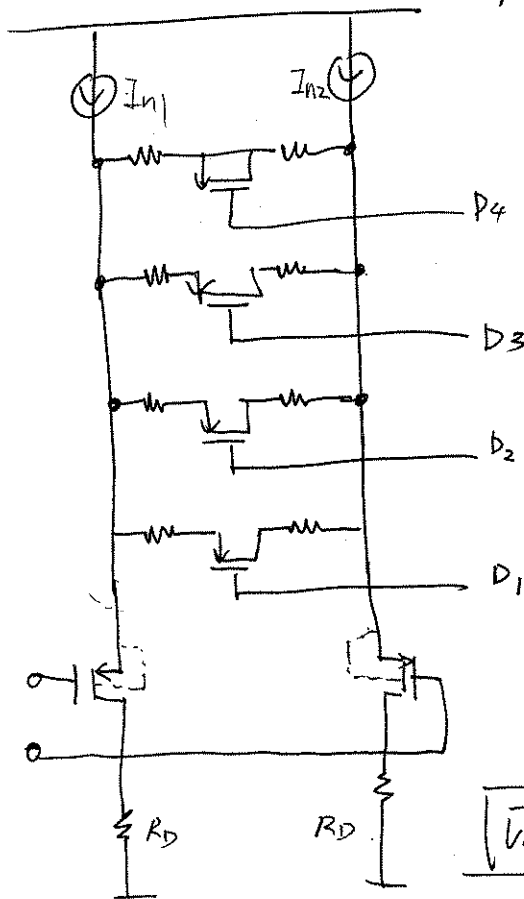
$$\frac{R_{in}}{R_S + R_{in}} = \frac{(r_{o1} || r_{o2}) + R_F}{[1 + (g_{m1} + g_{m2})(r_{o1} || r_{o2})] R_S + r_{o1} || r_{o2} + R_F}$$

$$\therefore \frac{V_{out}}{V_{in}} = \frac{R_{in}}{R_S + R_{in}} \cdot \frac{V_{out}}{V_x}$$

$$= \boxed{\frac{[1 - (g_{m1} + g_{m2}) R_F] \cdot (r_{o1} || r_{o2})}{[1 + (g_{m1} + g_{m2}) R_S] (r_{o1} || r_{o2}) + R_F + R_S}}$$

13.8 solu:

neglect on-resistance of switch,
channel-length modulation,
body effect.



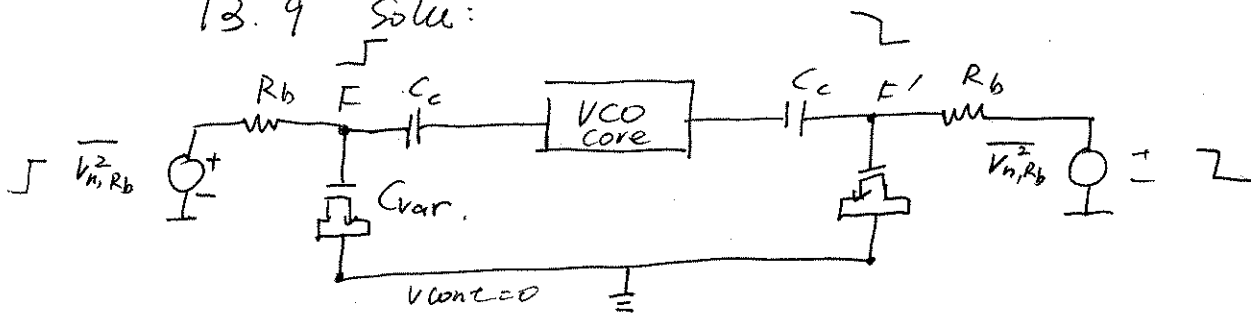
$$\frac{V_{out}}{R_D} = I_n$$

$$V_{out} = I_n \cdot R_D$$

$$\overline{V_{out}^2} = (\overline{I_{n1}^2} + \overline{I_{n2}^2}) R_D^2$$

So the I_{n1} and I_{n2} contribute the output directly,
which is very bad.

13.9 Solu:



$$\Delta V_{con} \cdot K_{VCO} = \Delta \omega.$$

The noise of R_b directly modulates the varactor, as if it were in series with V_{con} , offset freq. below $\omega_{-3dB} \approx \frac{1}{R_b C_c}$
 $C_c \gg C_{var}$, $\omega \approx \frac{1}{R_b C_c}$

$$\Delta V_F = \frac{\frac{1}{C_{var} s}}{R_b + \frac{1}{C_{var} s}} \cdot V_{n,Rb}$$

$$= \frac{1}{R_b C_{var} s + 1} \cdot V_{n,Rb}$$

$$\approx V_{n,Rb}$$

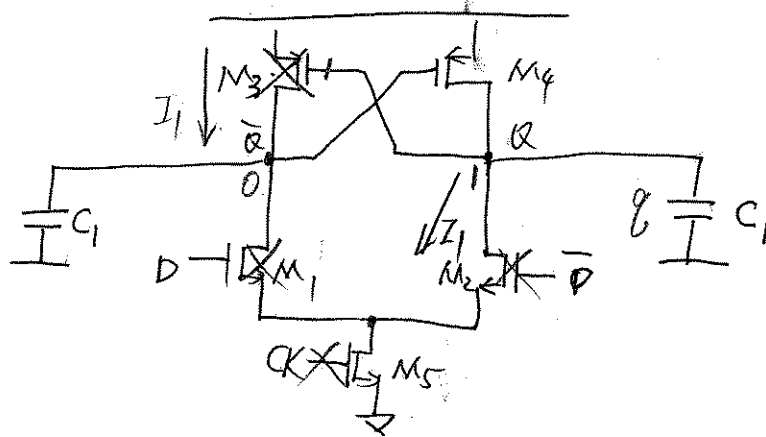
$$\Delta V_{F'} \approx V_{n,Rb}.$$

$$\Delta V_{con} \approx \Delta V_F = V_{n,Rb}.$$

$$\therefore \Delta \omega = V_{n,Rb} \cdot K_{VCO}.$$

\Rightarrow the gain from the noise voltage of each resistor to VCO output frequency is equal to K_{VCO} .

13.10 Solu:



Assume last state is $Q = 1$, M_3 is off, M_4 is on, C_1 in the ^{right} hand have q_e charge in it. (M_3 is off).

And \bar{Q} node has a leakage from M_3 , which can charge the C_1 in the left hand. \bar{Q} node has a leakage I_1 through M_3 & M_5 .

When the voltage $V_Q < V_{\bar{Q}}$, the state will be corrupted.

$$\text{Estimate Time} \Rightarrow \frac{I_1 \cdot t}{C_1} > \frac{q_e - I_1 t}{C_1}$$

$$\text{Critical Time} \Rightarrow t = \frac{q_e}{2I_1}$$

$$q_e = V_{DD} \cdot C_1$$

$$\Rightarrow t = \frac{V_{DD} \cdot C_1}{2I_1}$$