

# **5COSC001W - Object Oriented Programming, Week 1**

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# Contents

This module:

- ▶ introduces the concepts of objects and classes;
- ▶ teaches applications of object oriented analysis and design in tackling programming problems;
- ▶ aims to extend your programming skills from year 1.

Since C++ is our language of choice, we will also:

- ▶ address topics specific to it, such as multiple inheritance.

# Contents

- ▶ Classes and objects.
- ▶ Object oriented principles and characteristics.
- ▶ Inheritance, polymorphism, abstraction, encapsulation.
- ▶ How to design classes. Introduction to UML.
- ▶ Concurrency and multithreading.
- ▶ Design patterns and principles.

# Assessment

- ▶ One coursework, one exam
- ▶ 50% of mark each
- ▶ Need to score 30% in each and 40% overall
- ▶ Coursework spec will be published in week 3, deadline is in week 10
- ▶ Exam is in January, date yet to be determined

# Books and Resources

## Books:

- ▶ Programming: Principle and Practice Using C++, Bjarne Stroustrup, 2nd Edition

## Further reading and resources:

- ▶ C++. The Complete Reference, Herbert Schildt
- ▶ The Object Oriented Thought Process, 4th Edition, M. Weisfeld
- ▶ Design Patterns: Elements of Reusable Object-Oriented Software, Gemma, Helm, Johnson, Vlissides
- ▶ [www.hackerrank.com](http://www.hackerrank.com)  
(Programming challenges to practise what you have learned)

# Recap: C++ basics

- ▶ **Variables** contain values of various **types**:
  - ▶ Basic types (`int`, `bool`, ...)
  - ▶ Arrays: `int numbers[10][10];`
  - ▶ Pointers: `int *numPointer;`
  - ▶ Also references, enums, structs, ...
- ▶ Basic operations:
  - ▶ Declaration introduces a new variable
  - ▶ Assignment sets a variable's value: `myNumber = 5;`
  - ▶ Other operations like comparisons (`myNumber <= 7`)

# Recap: C++ basics

- ▶ Program structure:
  - ▶ branching: `if`, `switch`
  - ▶ loops: `while`, `for`
  - ▶ functions: `bool compare(int x, int y);` declares a function `compare` with two arguments of type `int` and return type `bool`
- ▶ Functional decomposition:
  - ▶ Break the code down into reasonably small functions
  - ▶ Candidates are
    - ▶ Pieces of code which are used in multiple places
    - ▶ Pieces of code which have a clearly defined purpose
- ▶ Object orientation allows us to further structure code and data

# So What is "Object Oriented" About?

- ▶ Programs typically create models of part of the “real” world
- ▶ The parts of the model are objects, which can be
  - ▶ something tangible (a person, a vehicle, ...)
  - ▶ something more abstract (a point in time, a quest, ...)
  - ▶ auxiliary objects (e.g. a **factory** for creating other objects)

Often a good starting point: **nouns** in the specification

- ▶ Objects are categorised into types called **classes**

---

```
class Quest{ /* details of the class go here */ };
```

---

- ▶ Objects belonging to a class (**instances** of the class) share the same **characteristics** and **behaviors**.

---

```
Quest q1, q2; // Creates two instances of the Quest class
```

---



# Properties of Classes

For each class we need to decide:

- ▶ its **attributes**, given by **variables** of various types
  - ▶ Example: Class **Robot** may have attributes
    - ▶ **xPosition**, **yPosition** of type **int**
    - ▶ **tool** of type **Tool**, which is another class
  - ▶ The current values of these attributes in an instance define its **state**, including relations with other objects.
- ▶ its **operations** (functions or **methods**), defining instances' possible behaviours and ways of changing state
  - ▶ Example: Class **Robot** may have a method  
**void moveTo(int newX, int newY)**  
to change position
- ▶ its **constructors**, for initialising new instances
- ▶ its **destructor**, for disposing of an instance

These are collectively known as **members** of the class.

# Choosing classes: example

Consider this snippet from a fictional game description:

## DigBots game

The player controls a number of bots which move around on a grid. Each bot has a tool with a power level (...)

- ▶ The **nouns** (or noun phrases) in this excerpt are: **player, number, bot(s), grid, tool, power level.**
- ▶ Not all of these represent in-game objects or entities:
  - ▶ The **player** is outside the game (but some games will have related classes like **player characters** or **profiles**)
  - ▶ The **number** in "a number of bots" is not itself an entity.
  - ▶ The **power level** is going to be just a number, an **attribute** of the Tool class.
- ▶ This leaves us with classes **Bot, Grid, Tool.**

# Example: Tool class

Header files contain **declarations**; in **tool.h**:

---

```
class Tool{
    private:
        int powerLevel = 1; // Attribute and initial value
    public:
        Tool();           // Default constructor
        Tool(int p);      // Constructor with given power level
        void setPowerLevel(int p); // Setter method
        int getPowerLevel(); // Getter method
};
```

---

- ▶ The attribute is defined as **private** and cannot be directly accessed from outside the class
- ▶ The constructors and methods are **public**, i.e. accessible from the outside
- ▶ Constructors are declared similarly to methods, but
  - ▶ they have no return type
  - ▶ their name must equal the class name

# Example: Tool class

Source files contain **definitions**; in **tool.cpp**:

---

```
#include "tool.h"

Tool::Tool() {}

Tool::Tool(int p):powerLevel(p) {}

void Tool::setPowerLevel(int p) {
    powerLevel = p;
}

int Tool::getPowerLevel() {
    return powerLevel;
}
```

---

- ▶ Note the **Tool::** prefixes: We are outside the class declaration and need to specify which scope these members belong to.
- ▶ The second constructor uses an **initializer list**, about which more in a bit

# Overloading and Defaults

- ▶ The `Tool` class has several **overloaded** constructors with different parameters.
  - ▶ The constructor used will be chosen based on the parameters provided

---

```
class Tool{
    /* ... */
    Tool();           // Default constructor
    Tool(int p);      // Constructor with given power level
};

Tool tool1;          // No parameters provided, uses the default constructor
Tool tool2(15);      // in parameter provided, uses the other constructor
```

---

- ▶ The same can be done with methods.
- ▶ In this case, the same effect can be achieved using **default parameters**:

---

```
class Tool
{
    /* ... */
    Tool(int p = 1);  // Uses parameter p if provided, default 1 otherwise
};
```

---

# Example: Bot class

## In bot.h:

---

```
#include "tool.h" // Need definition of Tool

class Bot{
private:    // Attributes defining the state
    int xPosition, yPosition;
    Tool *tool; // Pointer to an instance of the Tool class
public:
    Bot(int x, int y);
    ~Bot();    // Destructor
    void move(int dx, int dy);
};
```

---

## In bot.cpp:

---

```
#include "bot.h"

Bot::Bot(int x, int y):xPosition(x),yPosition(y){
    tool = new Tool();
}

Bot::~Bot(){ // Delete our tool to prevent memory leak
    delete tool;
}

void Bot::move(int dx, int dy){
    xPosition += dx;
    yPosition += dy;
}
```

---

# Object construction

- ▶ The attributes are initialized in the order in which they are declared, using these steps for each:
  1. If it occurs in the initializer list, this initialization is used
  2. Otherwise, if its declaration comes with an in-class initializer (as in `int powerLevel = 1;`), this value is usedExample, in `tool.h`:

---

```
class Tool{  
    private:  
        int powerLevel = 1; // value 1 is used unless overridden by initializer list  
    / ... /  
};
```

---

3. Otherwise, it gets default-initialized if possible  
For example, we could modify the `Bot` class like this:

---

```
class Bot{  
    /* ... */  
    Tool tool; // Will be initialized using default constructor Tool::Tool()  
    public:  
        Bot(int x, int y);  
};
```

---

4. The constructor body may then do additional operations.

# Reminder: Object Lifetimes

- ▶ A variable only exists in the scope in which it is declared

---

```
void shortProject() {  
    Robot scrappy;  
    /* do stuff with scrappy */  
} /* scrappy gets deleted at the end of the project*/
```

---

- ▶ But:

---

```
void badProject() {  
    Robot* scrapPtr = new Robot();  
    /* do stuff with scrapPtr */  
} /* scrapPtr gets deleted, object still on the heap! */
```

---

- ▶ This is OK if the object is still needed – but make sure to
  - ▶ keep it accessible (e.g. by returning or storing the pointer)
  - ▶ **delete** it when no longer needed
  - ▶ Otherwise, you get memory leaks.
- ▶ As of C++11, there are **smart pointers** which help with this. We will see them in a later lecture.



# Objects as Parameters

- ▶ Objects can be parameters to a method
- ▶ But note that the method receives a **copy**:

---

```
class Bot{  
    /* ... */  
    void disarm(Bot victim) {  
        victim.tool = nullptr;  
    }  
};  
Bot marvin;  
Bot mephisto;  
mephisto.disarm(marvin); // disarms a copy, marvin is still armed
```

---

- ▶ If this is not wanted:
  - ▶ either make the parameter a pointer:

---

```
void Robot::disarm(Robot *victim){ victim->tool = null; }
```

---

- ▶ or pass the object is **by reference**:

---

```
void Robot::disarm(Robot &victim){ victim.tool = null; }
```

---

# Encapsulation

- ▶ Each member in a class has an access modifier
- ▶ **public**: accessible outside the class
- ▶ **private**: accessible only within the class itself
- ▶ Defined by blocks (preceded by “**private**:” and “**public**:” keywords)  
Default (if not preceded by either keyword) is **private**
- ▶ Often attributes will be private, and methods and constructors will be public
  - ▶ indirect/restricted access to attributes through methods
  - ▶ this facilitates **encapsulation (data hiding)** between classes

# Encapsulation

- ▶ Idea: wrap the data (attributes) and code acting on the data (methods) together as a single unit.
- ▶ Attributes of a class will be hidden from other classes, to be accessed only through methods.
- ▶ This allows us to:
  - ▶ limit how they can be changed
  - ▶ keep track of changes
  - ▶ modify class internals without breaking other code.
- ▶ In the Robot example:
  - ▶ limit movement to possible speeds, empty terrain, . . .
  - ▶ maintain a list of visited locations
  - ▶ change internal representation of coordinates.

# Encapsulation: Example

---

```
class Robot{
    // ...
    // list of visited locations
    std::list<std::pair<int, int>> visited;

    bool move(int dx, int dy){
        // cannot move too fast
        if(dx < -1 || dx > 1 || dy < -1 || dy > 1)
            return false;
        xPosition += dx;
        yPosition += dy;
        visited.push_back(pair<int, int>(xPosition, yPosition));
        return true;
    }
};
```

---

- ▶ Position cannot be changed directly
- ▶ Method ensures speed limit and proper history tracking

# Summary – What you should know so far

- ▶ Objects and Classes
- ▶ Class declaration
- ▶ Objects as instances of a class
- ▶ Constructors, initializer lists
- ▶ Destructors
- ▶ Encapsulation