

We start from diff. equation: $m\ddot{x} + b\dot{x} + kx = C_0 e^{i\omega_0 t}$

$$\ddot{x} + \frac{b}{m}\dot{x} + \frac{k}{m}x = C_0 e^{i\omega_0 t} \Rightarrow \ddot{x} + 2\gamma\dot{x} + \omega_0^2 x = C' e^{i\omega_0 t}$$

Ansatz $x(t) = A \cdot e^{i\omega_0 t}$, plug in and see

$$A\omega_0^2 e^{i\omega_0 t} + 2\gamma i\omega_0 A_0 e^{i\omega_0 t} + \omega_0^2 A e^{i\omega_0 t} = C' e^{i\omega_0 t}$$

$$-\omega_0^2 A + 2\gamma i\omega_0 A + \omega_0^2 A = C'$$

$$| A = \frac{C'}{\omega_0^2 + 2\gamma i\omega_0 - \omega_0^2} | \checkmark \cdot e^{i\omega_0 t}$$

Now, our driving frequency is cosine function (just imagine)

$$m\ddot{x} + b\dot{x} + kx = F \cos(\omega_0 t)$$

$$\ddot{x} + 2\gamma\dot{x} + \omega_0^2 x = \frac{F}{m} \cos(\omega_0 t) = \frac{F}{2m} (e^{i\omega_0 t} + e^{-i\omega_0 t})$$

So our solution must be a sum of two functions!

preliminary
solution

we have to
eliminate i 's

$$x(t) = \left(\frac{\frac{F}{2m}}{-\omega_0^2 + 2\gamma i\omega_0 + \omega_0^2} \right) e^{i\omega_0 t} + \left(\frac{\frac{F}{2m}}{-\omega_0^2 - 2\gamma i\omega_0 + \omega_0^2} \right) e^{-i\omega_0 t}$$

$$\rightarrow \frac{\left(\frac{F}{2m} \right) (\omega_0^2 - \omega_0^2 - 2\gamma\omega_0 i)}{(\omega_0^2 - \omega_0^2 + 2\gamma\omega_0 i)(\omega_0^2 - \omega_0^2 - 2\gamma\omega_0 i)} = \frac{\frac{F}{2m} (\omega_0^2 - \omega_0^2 - 2\gamma\omega_0 i)}{((\omega_0^2 - \omega_0^2)^2 + 4\gamma^2\omega_0^2)} (\cos(\omega_0 t) + i\sin(\omega_0 t))$$

$$\underbrace{(a+bi)(a-bi)}_{a^2 + b^2} + \frac{\frac{F}{2m} (\omega_0^2 - \omega_0^2 - 2\gamma\omega_0 i)}{((\omega_0^2 - \omega_0^2)^2 + 4\gamma^2\omega_0^2)} (\cos(\omega_0 t) - i\sin(\omega_0 t))$$

$$\sqrt{\frac{F}{2m} \left(a \cos \omega_0 t - b \cancel{\sin \omega_0 t} + \cancel{a} \sin \omega_0 t - b \cancel{i} \cos \omega_0 t + \cancel{a} \cos \omega_0 t + \cancel{b} \sin \omega_0 t - \cancel{a} \cancel{i} \sin \omega_0 t - \cancel{b} \cancel{i} \cos \omega_0 t \right)}$$

$$x(t) = \frac{\frac{F}{m} ((\omega_0^2 - \omega_0^2) \cos \omega_0 t + 2\gamma\omega_0 \sin \omega_0 t)}{((\omega_0^2 - \omega_0^2)^2 + 4\gamma^2\omega_0^2)}$$

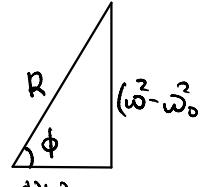
Actually, a really smart move.

$$R^2 = (\omega_0^2 - \omega_0^2)^2 + (2\gamma\omega_0)^2$$

Now, we do some "tricks" define bottom to be R^2 .

$$\text{Then, } \frac{F}{mR} \left(\frac{(\omega_0^2 - \omega_0^2)}{R} \cos \omega_0 t + \frac{2\gamma\omega_0}{R} \sin \omega_0 t \right)$$

Tenepo, uiti nogrotinis neg formuojant $\cos(a-b)$.



$$x(t) = \frac{F}{mR} \left(\cos(\omega_0 t - \phi) \right) \text{ where } \phi = \cos^{-1} \left(\frac{\omega_0^2 - \omega_0^2}{R} \right)$$

btw $0 \leq \phi \leq \pi$, because sin must be positive

We also add our damped solution.

Remember, linearity!

$$x(t) = \frac{F}{mR} \left(\cos(\omega_0 t - \phi) \right) + e^{-\gamma t} (A e^{\gamma t} + B e^{-\gamma t})$$

Resonance $\Rightarrow \omega_0 = \omega$