

Data-Driven Hierarchical Runge-Kutta Methods For Nonlinear Dynamical Systems

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2025

Overview

- Runge-Kutta 3rd order method implementation
- Adams-Bashforth and Adams-Moulton methods
- Hierarchical data-driven architecture
- Transformer-inspired ODE solver
- Objective-C framework for Apple platforms

Runge-Kutta 3rd Order

Algorithm

$$k_1 = f(t_n, y_n)$$

$$k_2 = f(t_n + h/2, y_n + hk_1/2)$$

$$k_3 = f(t_n + h, y_n - hk_1 + 2hk_2)$$

$$y_{n+1} = y_n + \frac{h}{6}(k_1 + 4k_2 + k_3)$$

- Good balance of accuracy and efficiency
- Suitable for nonlinear systems
- Local truncation error: $O(h^4)$

Adams-Basforth (Predictor)

$$y_{n+1} = y_n + \frac{h}{12}(23f_n - 16f_{n-1} + 5f_{n-2})$$

Adams-Moulton (Corrector)

$$y_{n+1} = y_n + \frac{h}{12}(5f_{n+1} + 8f_n - f_{n-1})$$

- Multi-step methods
- Predictor-corrector scheme
- Higher order accuracy

Hierarchical Architecture

- Transformer-inspired design
- Multiple processing layers
- Attention mechanisms
- Adaptive refinement
- Data-driven learning

Key Features

- Hierarchical state transformations
- Learnable weights and biases
- Self-attention for ODE solutions
- Adaptive step size control

Implementation

Core

- C/C++ implementation
- High performance
- Memory efficient

Framework

- Objective-C wrappers
- Visualization support
- macOS & VisionOS

Applications

- Nonlinear dynamical systems
- Chaotic systems (Lorenz, etc.)
- Engineering simulations
- Scientific computing
- Real-time visualization

Thank You

Questions?

github.com/Sapana-Micro-Software/ddrkam