

# DDRKAM Reference Manual

## Data-Driven Runge-Kutta and Adams Methods

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2025

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# 1 Introduction

This manual provides comprehensive documentation for the DDRKAM (Data-Driven Runge-Kutta and Adams Methods) framework. The framework implements numerical methods for solving ordinary differential equations (ODEs) with support for traditional and hierarchical data-driven approaches.

The framework includes:

- Euler's Method (1st order)
- Data-Driven Euler's Method (DDEuler)
- Runge-Kutta 3rd Order Method (RK3)
- Data-Driven Runge-Kutta 3rd Order (DDRK3)
- Adams Methods (AM)
- Data-Driven Adams Methods (DDAM)

## 2 Euler's Method

### 2.1 Overview

Euler's Method is the simplest numerical method for solving ODEs. It is a first-order explicit method with local truncation error  $O(h^2)$ .

### 2.2 Algorithm

$$y_{n+1} = y_n + h \cdot f(t_n, y_n) \quad (1)$$

where  $h$  is the step size,  $f$  is the ODE function, and  $y_n$  is the state at time  $t_n$ .

### 2.3 API Reference

#### 2.3.1 euler\_step

Performs a single integration step using Euler's method.

```
1 double euler_step(ODEFunction f, double t0, double* y0,
2                     size_t n, double h, void* params);
```

### Parameters:

- **f**: Function pointer to the ODE system
- **t0**: Current time
- **y0**: Current state vector (modified in-place)
- **n**: Dimension of the system
- **h**: Step size
- **params**: User-defined parameters

**Returns:** New time value ( $t_0 + h$ )

#### 2.3.2 euler\_solve

Solves an ODE system over a time interval using Euler's method.

```
1 size_t euler_solve(ODEFunction f, double t0, double
                     t_end,
2                         const double* y0, size_t n, double h,
3                         void* params, double* t_out, double*
                     y_out);
```

## 3 Data-Driven Euler's Method

### 3.1 Overview

Data-Driven Euler's Method (DDEuler) extends standard Euler's method with a hierarchical transformer-inspired architecture that applies adaptive corrections to improve accuracy.

### 3.2 Algorithm

$$y_{n+1} = y_n + h \cdot f(t_n, y_n) + h \cdot \alpha \cdot \text{Attention}(y_n) \quad (2)$$

where  $\alpha$  is a learning rate and  $\text{Attention}(y_n)$  is computed through hierarchical transformer layers.

### 3.3 API Reference

#### 3.3.1 hierarchical\_euler\_init

Initializes a Data-Driven Euler solver.

```
1 int hierarchical_euler_init(HierarchicalEulerSolver*
2           solver,
3           size_t num_layers, size_t
4           state_dim,
5           size_t hidden_dim);
```

#### 3.3.2 hierarchical\_euler\_step

Performs a single integration step using Data-Driven Euler.

```
1 double hierarchical_euler_step(HierarchicalEulerSolver*
2           solver,
3           ODEFunctor f, double t,
4           double* y,
5           double h, void* params);
```

#### 3.3.3 hierarchical\_euler\_solve

Solves an ODE system using Data-Driven Euler over a time interval.

```
1 size_t hierarchical_euler_solve(HierarchicalEulerSolver*
2           solver,
3           ODEFunctor f, double
4           t0, double t_end,
5           const double* y0,
6           double h, void*
7           params,
8           double* t_out, double*
9           y_out);
```

## 4 Runge-Kutta 3rd Order Method

### 4.1 Overview

The Runge-Kutta 3rd order method provides a good balance between accuracy and computational efficiency for solving ODEs.

### 4.2 API Reference

#### 4.2.1 rk3\_step

Performs a single integration step using RK3.

```
1 double rk3_step(ODEFunction f, double t0, double* y0,
2                   size_t n, double h, void* params);
```

##### Parameters:

- **f**: Function pointer to the ODE system
- **t0**: Current time
- **y0**: Current state vector (modified in-place)
- **n**: Dimension of the system
- **h**: Step size
- **params**: User-defined parameters

**Returns:** New time value ( $t_0 + h$ )

#### 4.2.2 rk3\_solve

Solves an ODE system over a time interval.

```
1 size_t rk3_solve(ODEFunction f, double t0, double t_end,
2                   const double* y0, size_t n, double h,
3                   void* params, double* t_out, double*
y_out);
```

##### Parameters:

- **f**: Function pointer to the ODE system

- $t_0$ : Initial time
- $t_{\text{end}}$ : Final time
- $y_0$ : Initial state vector
- $n$ : Dimension of the system
- $h$ : Step size
- $\text{params}$ : User-defined parameters
- $t_{\text{out}}$ : Output time array (allocated by caller)
- $y_{\text{out}}$ : Output state array ( $n \times \text{num\_steps}$ , allocated by caller)

**Returns:** Number of steps taken

### 4.3 Example

```

1 void lorenz(double t, const double* y, double* dydt,
2             void* params) {
3     double* p = (double*)params;
4     double sigma = p[0], rho = p[1], beta = p[2];
5     dydt[0] = sigma * (y[1] - y[0]);
6     dydt[1] = y[0] * (rho - y[2]) - y[1];
7     dydt[2] = y[0] * y[1] - beta * y[2];
8 }
9 double params[3] = {10.0, 28.0, 8.0/3.0};
10 double y0[3] = {1.0, 1.0, 1.0};
11 double t_out[100];
12 double y_out[300];
13 size_t steps = rk3_solve(lorenz, 0.0, 1.0, y0, 3, 0.01,
                           params, t_out, y_out);
14

```

## 5 Adams Methods

### 5.1 Adams-Bashforth 3rd Order

Predictor step for multi-step integration.

```
1 void adams_bashforth3(ODEFunction f, const double* t,
2                         const double* y, size_t n, double
3                         h,
4                         void* params, double* y_pred);
```

## 5.2 Adams-Moulton 3rd Order

Corrector step for multi-step integration.

```
1 void adams_moulton3(ODEFunction f, const double* t,
2                       const double* y, size_t n, double h,
3                       void* params, const double* y_pred,
4                       double* y_corr);
```

# 6 Hierarchical Runge-Kutta Method

## 6.1 Overview

The hierarchical RK method uses a transformer-like architecture with multiple processing layers and attention mechanisms.

## 6.2 API Reference

### 6.2.1 hierarchical\_rk\_init

Initializes a hierarchical RK solver.

```
1 int hierarchical_rk_init(HierarchicalRKSolver* solver,
2                           size_t num_layers, size_t
3                           state_dim,
4                           size_t hidden_dim);
```

**Returns:** 0 on success, -1 on failure

### 6.2.2 hierarchical\_rk\_free

Frees resources allocated by the solver.

```
1 void hierarchical_rk_free(HierarchicalRKSolver* solver);
```

### 6.2.3 hierarchical\_rk\_solve

Solves an ODE using the hierarchical method.

```
1 size_t hierarchical_rk_solve(HierarchicalRKSolver*
2           solver,
3           ODEFunctor f, double t0,
4           double t_end,
5           const double* y0, double h,
6           void* params,
7           double* t_out, double*
8           y_out);
```

## 7 Objective-C Framework

### 7.1 DDRKAMSolver

Main solver class for Objective-C applications.

```
1 DDRKAMSolver* solver = [[DDRKAMSolver alloc]
2                           initWithDimension:3];
3 NSDictionary* result = [solver solveWithFunction:^(
4                           double t,
5                           const
6                           double*
7                           y
8                           ,
9                           double*
10                          dydt
11                          ,
12                          void*
13                          params
14                          )
```

```

7      // ODE definition
8 } startTime:0.0 endTime:1.0
9 initialState:@[@1.0, @1.0, @1.0]
10 stepSize:0.01 params:NULL];
{

```

## 7.2 DDRKAMVisualizer

Visualization component for plotting solutions.

```

1 DDRKAMVisualizer* viz = [[DDRKAMVisualizer alloc] init];
2 NSView* view = [viz createVisualizationViewWithTime:
3                           timeArray
4                           state:
5                           stateArray
6                           dimension:3];
7 [viz exportToCSV:@"/path/to/output.csv"
8          time:timeArray
9          state:stateArray];

```

## 7.3 DDRKAMHierarchicalSolver

Hierarchical solver for Objective-C.

```

1 DDRKAMHierarchicalSolver* solver =
2   [[DDRKAMHierarchicalSolver alloc]
3     initWithDimension:3 numLayers:4 hiddenDim:32];

```

## 8 Platform Support

- macOS 10.13+
- iOS 11.0+
- visionOS 1.0+

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