

## Branches with Algorithms

- Defaults: Mel
- Vision: Mel
- Actions: Nick
- Replay: Brady Y.

## Algorithm Recaps

- Actions
  - JS function uses message system to call action w/ page number
  - Will need to fork to get motion file
  - Use cases:
    - \* Entertainment
    - \* Extending action list
- Defaults
  - Document function prototype
  - Relies on ability to get servo positions. Can this be done?
  - What if we want different default positions?
  - Replay module needs function for default pos too
  - Use Cases:
    - \* Don't want robot to fall on face when thanking from rest pose
    - \* Want robot to go back to init if in the middle of another pose
- Vision
  - Need to take many images of ball
  - Need to pre-process images to only contain ball
  - Create normal distribution of the hsv values
  - Sample from the distribution when looking for ball
  - Lock color when found, re-sample when lost
- Replay
  - Action file or separate files to store recordings?
  - Start/stop for motion follower

## Midterm Presentation

- Everyone must speak
- Each group should speak on its module
- Discuss the algorithm for each module, as well as use cases

## Github Flow

- Will use pull requests
- Will use a dev branch and testing branch for each module, as well as master
- Will make PR from dev to test, Alice will patch from test to master
- Want to add reviewer names to description box for commit

## General Notes

- Need to start putting code locations in documentation
- Light can be different colors
- Primary is person putting most of the code up and documenting
- Secondary mostly in charge of integration testing

## Action Items

- Alice will set up presentation skeleton
- People should add pieces to that when they can
- If you need a repo forked, put it in algorithm file and notify Alice on discord
- Will get 360 reviews next Thursday. Need to take seriously.