

Capstone Notes 2/12

- Need to scope down project goals
 - Need Ubuntu for the Gazebo simulator
 - 3 sprints starting term 2
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1. Set up gazebo on machines
 - a. Install ROS
 - b. Install Gazebo
 - c. Install integration packages
 - d. Need Ubuntu 16.04 for ROS Kinetic Kame
 2. Connect to robot

Major Goals for Term 2

1. Balance
2. Balance part 2
3. Vision / Pose