

## Standup

- Brady T.: Obtained photoresistor, etc
- Brady Y.: Made changes to code, testing tonight
- Jordan: Made CMake file required to compile, going to test it
- Mel: Code for defaults is ready to review. Moving to vision.
- Mason: Looked at web code.
- Nick: Worked on studying interface between ball detector and robot

## Announcements/General Notes

- For commits, the title should be the module name, not the repo name anymore
- Webhooks for discord with git are set up
- Next Thursday, Warren will meet with team minus lead. 7pm sounds like best time.
- When moving tar'd repo to robot, move existing dir into /home/ROBOTIS-Old. Remove other copy in this old directory, only keep most recent (just in case tar accident or something)
- Review workflow going forward: no testing branch, just checkout branch, pull master to integration test, stash changes when done, merge to master when PR approved
- Light can be different colors.
- Have 1 checkbox for integration testing
- Have 2 checkboxes for code review
- Use github features for code comments\needs work etc

## Commitments

- Jordan and Brady Y. will come up with the file format to save the captured joint states then working on adding them to external data file.
- Mason will make some buttons in html
- Everyone will list action requirements they are committing to in their module's discord channel
- Mel will consolidate action requirements (AR) from discord

## AR's

- Alice
  - Documentation
  - Clean up kraken
- Jordan
  - create format for saved states and write them to file
- Brady Y
  - create format for saved states and write them to file
- Mason
  - Add web tab for replay with buttons, see how html/js interacts with code to call functions
  - Add some HTML and tighten flossing
- Nick
  - Image gathering system through web interface, gather data
- Brady T
  - present preliminary results of camera noise and hsv interpolation of the data sets. Commit the code to the op3 demo

- Mel
  - Roadmap draft (finalize on Tuesday), Algorithm draft (finalize Tuesday), AR consolidation