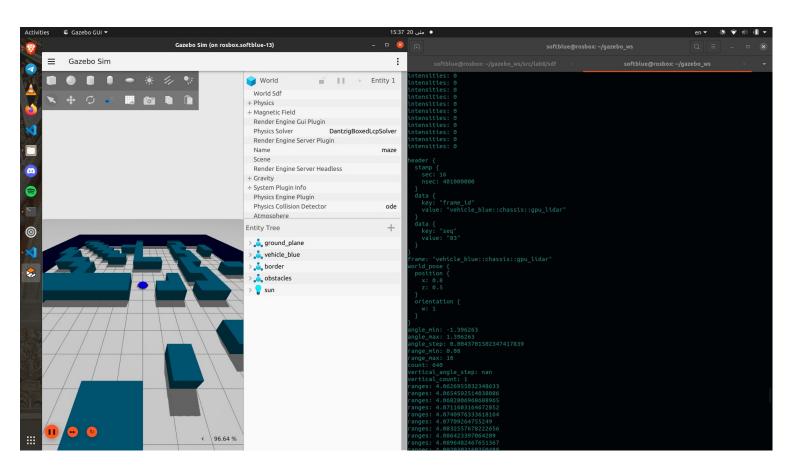
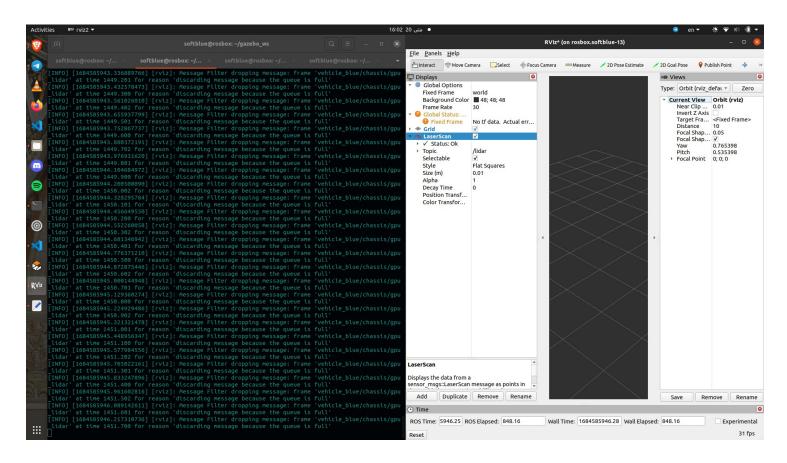
## **Introduction to Robotics**

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```
(base) softblue@rosbox:~/gazebo_ws$ ros2 run tf2_ros static_transform_publisher "0" "0" "0" "0" "0" "0"
" "world" "vehicle_blue/chassis/gpu_lidar"
[WARN] [1684586286.919449079] []: Old-style arguments are deprecated; see --help for new-style arguments
[INFO] [1684586286.941044741] [static_transform_publisher_xnQuSjcFeSw7GzEi]: Spinning until stopped -
publishing transform
translation: ('0.0000000', '0.0000000')
rotation: ('0.0000000', '0.0000000', '1.0000000')
from 'world' to 'vehicle_blue/chassis/gpu_lidar'
```