Robotics lab HW2
Sara Ghavampour
9812762781
spring 2023

[INFO] [1678554271.399552040] [turtlesim_controller]: Received feedback: 0.4540228843688965
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Activities   Terminal ▾   مارس 11 20:36

softblue@rosbox: ~/ros2_ws

softblue@rosbox: ~/ros2_ws   softblue@rosbox: ~/ros2_ws   softblue@rosbox: ~/ros2_ws

[INFO] [1678554366.183588176] [turtlesim_controller]: Received feedback: 1.0870081186294556
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TurtleSim (on rosbox.softblue-13)

Activities   Terminal ▾   مارس 11 20:36

softblue@rosbox: ~/ros2_ws

softblue@rosbox: ~/ros2_ws   softblue@rosbox: ~/ros2_ws   softblue@rosbox: ~/ros2_ws

(base) softblue@rosbox:~/ros2_ws$ ros2 param set turtlesim_controller stop False
2023-03-11 20:34:14.821 [RTPS_TRANSPORT_SHM Error] Failed init_port fastrtps_port7665: open_and_lock_file failed -> Function open_port_internal
Set parameter successful
(base) softblue@rosbox:~/ros2_ws$

TurtleSim (on rosbox.softblue-13)