

# Design Iterations on Self-Folding Neuroelectrodes

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## Background

- Peripheral nerve interfacing offers a targeted therapeutic approach for metabolic disorders but requires mechanically compliant electrode designs that enable highly selective stimulation of relevant nerves.
- Conventional cuff electrodes provide stable nerve contact but can be difficult to handle at small scales.
- A prior self-folding flexible cuff design improved implantability but were limited to single-site interfacing.
- To support more precise neuromodulation, there is a clear need for multi-channel interfaces capable of engaging multiple nerves simultaneously.
- This project builds on the self-folding cuff concept by [1] to create a multi-channel flexible electrode designed for the peripheral nerves innervating brown adipose tissue in mice.

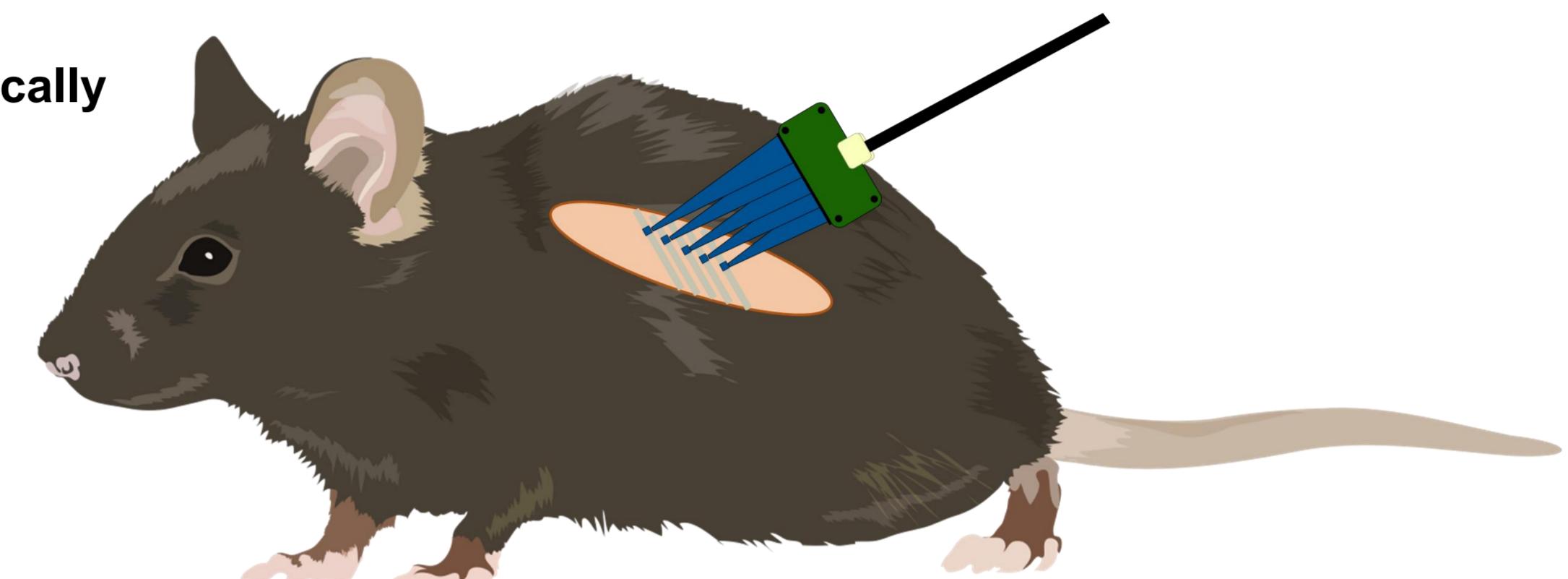
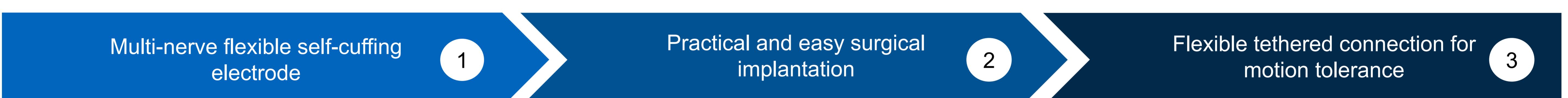


Fig. 1: Conceptual schematic of the multi-cuff electrode system targeting mouse adipose-tissue-associated nerves.

**Research Objective:** Re-design an existing flexible neuroelectrode to reliably interface multiple nerves in freely moving animals while maintaining relative ease of surgical implantation.



## 1 Designing a flexible self-cuffing electrode for the simultaneous interfacing of multiple nerves

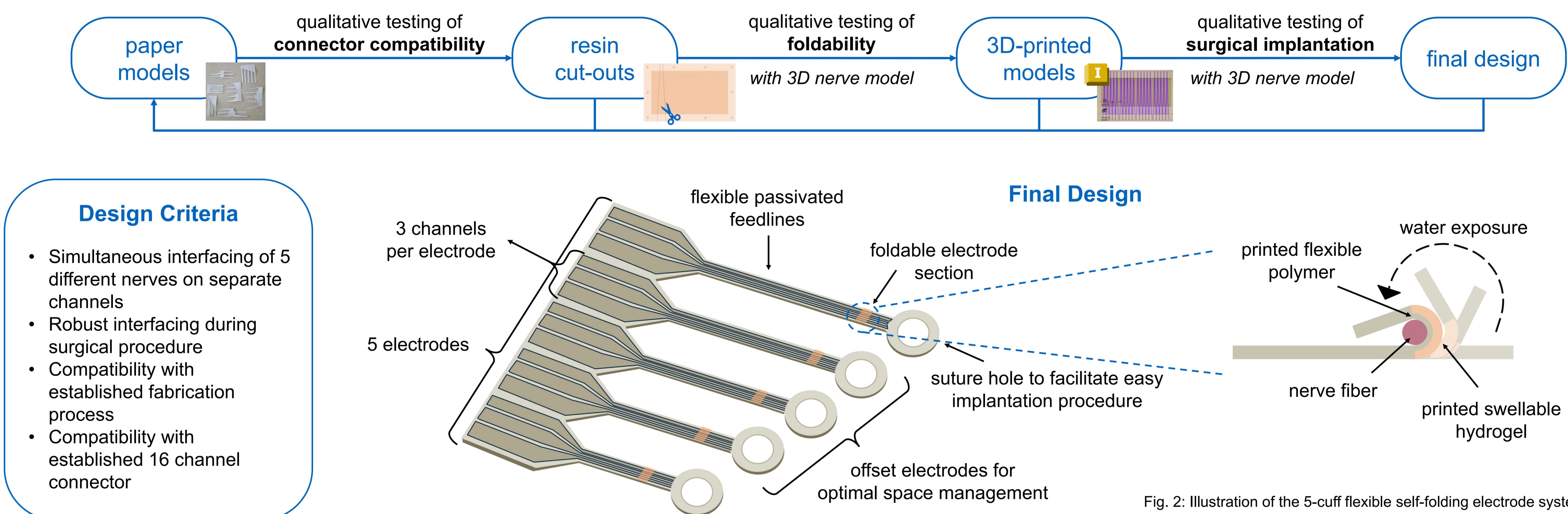


Fig. 2: Illustration of the 5-cuff flexible self-folding electrode system.

## 2 Designing easy surgical implantation

- Individual electrode placement is challenging; self-folding alone proved unreliable during multi-electrode implantation.
- A scaled 3D-printed nerve model with wire "nerves" was used to refine the procedure.
- A custom applicator was designed to hold electrodes under the nerves and enable sutured cuffing before self-folding and removal.

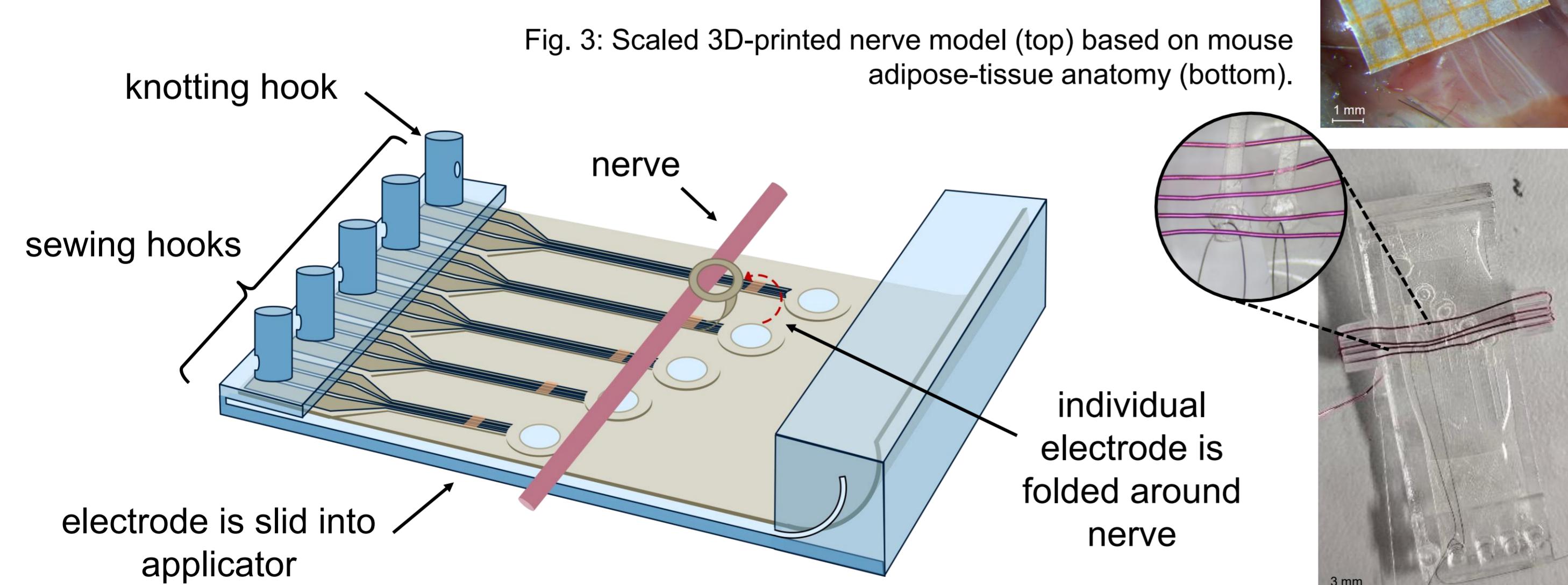


Fig. 4: Illustration of the applicator used for guiding and securing individual cuff electrodes during the implantation procedure (left). Fixation of individual electrodes via sutures (right).

## 3 Designing a motion-tolerant tether

- Rigid FPC connectors routed signals to external wiring for real-time recording.
- Flexible PCBs designed in KiCad provided strain relief between the electrode and external connector.
- Three geometries were qualitatively evaluated for maximizing the animal's range of motion.
- In vivo testing in locusts indicated that the spiral design provided the greatest flexibility with minimal stress on the electrode system.

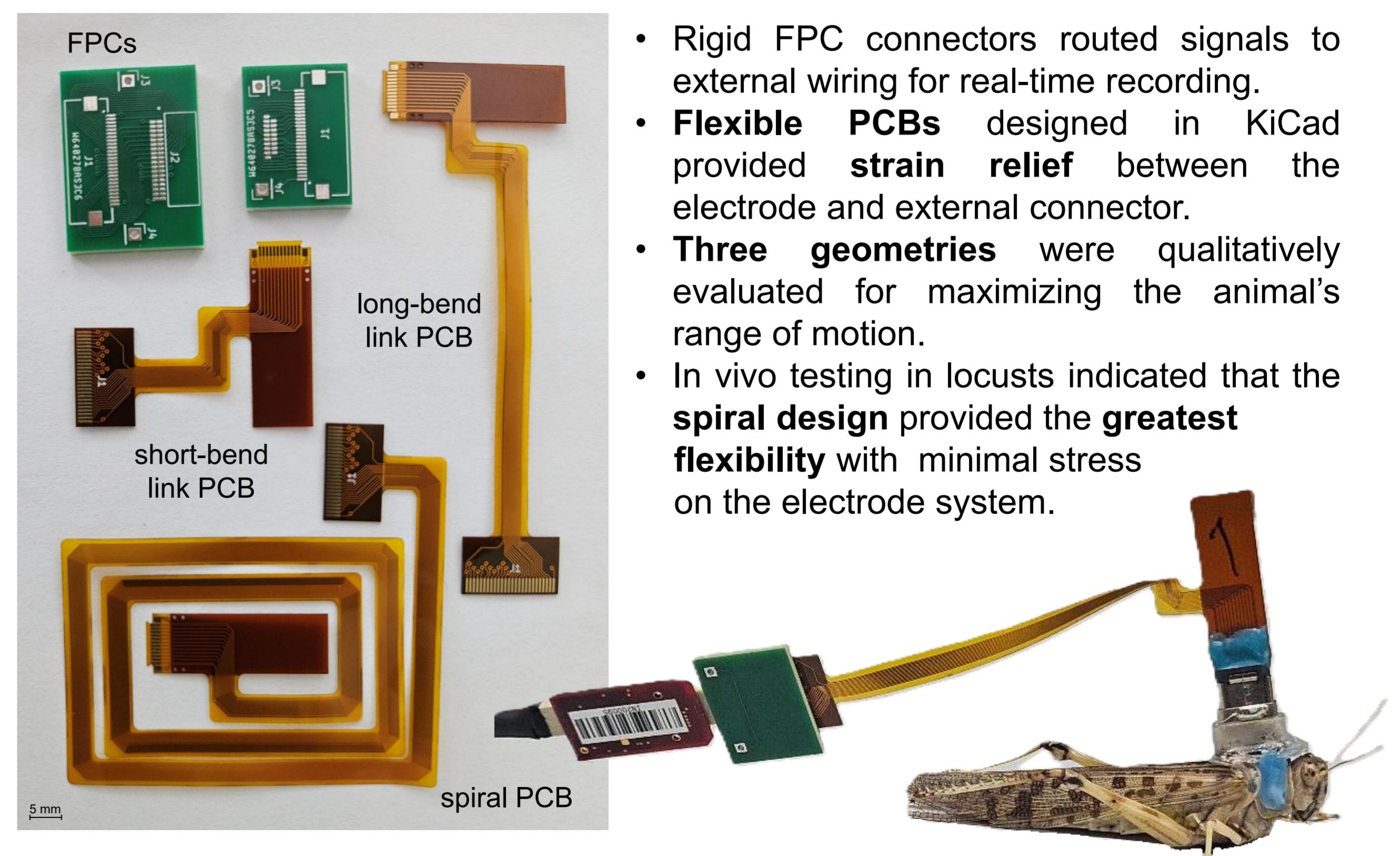


Fig. 5: Printed flexible PCBs and FPC connectors developed for the motion system (left), shown alongside the long bent flexible PCB implemented in a live locust for qualitative in vivo evaluation (right).

## Limitations and Outlook

The current evaluation of the redesigned electrode system was primarily qualitative, and quantitative metrics – such as stimulation thresholds, impedance spectra, and signal-to-noise ratios – have not yet been obtained. Comprehensive electrochemical characterization and in vivo testing will be essential to assess long-term stability, selectivity, and functional performance. Additionally, the mechanical behavior of the multi-channel design under chronic motion and its reliability during repeated implantation procedures remain to be validated. Future work should focus on these assessments and on refining the geometry and connector system to further enhance usability and multi-site interfacing capability.