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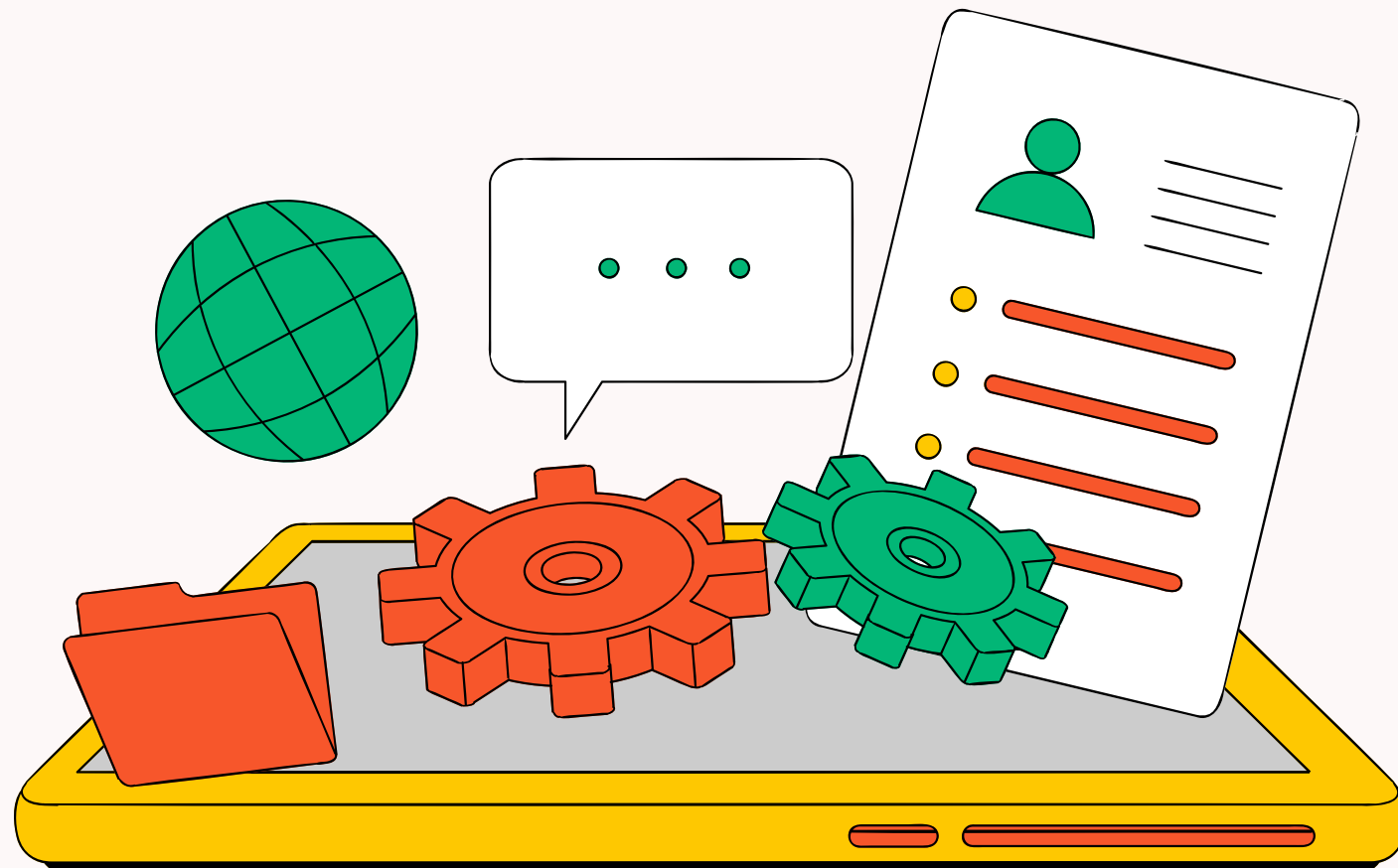
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# PRESENTATION OUTLINE



**Introduction**

**Objectives**

**Tools & Technologies**

**Project Demonstration**

**Algorithm Integration**

**Testing**

**Future Implementation**

**Conclusion**



# INTRODUCTION

This project is a Pathfinding Visualizer, an interactive tool designed to demonstrate how various pathfinding algorithms work in real time. It helps users understand and compare algorithms by visualizing their step-by-step process of exploring nodes and finding the shortest path.

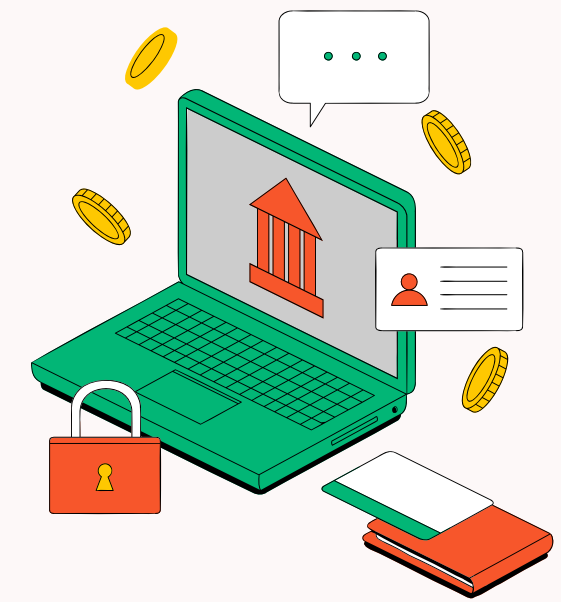


# OBJECTIVES

- **An interactive tool to visualize how pathfinding algorithms work in real-time.**
- **Helps users understand and compare the behavior of different algorithms.**
- **Built using Python and Pygame for smooth graphical interface and animation.**



# TOOLS & TECHNOLOGIES



## FRONTEND

- Pygame Library
- GUI for mouse interaction

## BACKEND

- Python

## DEVELOPMENT TOOLS

- VS Code



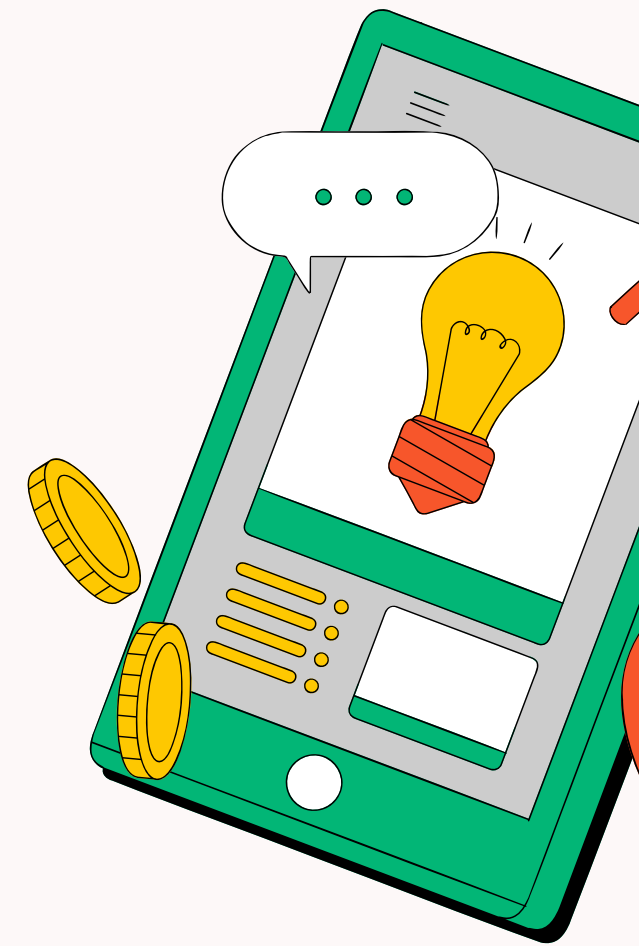
# PROJECT DEMONSTRATION

**Algorithm  
Selection**

**Grid  
Manipulation**

**Step-by-  
Step  
Visualization**

**Perfomance  
metrics**



# ALGORITHM INTEGRATION

01

**GREEDY BEST  
FIRST SEARCH**

02

**DEPTH FIRST  
SEARCH**

03

**A\* SEARCH**





# ALGORITHM INTEGRATION

04

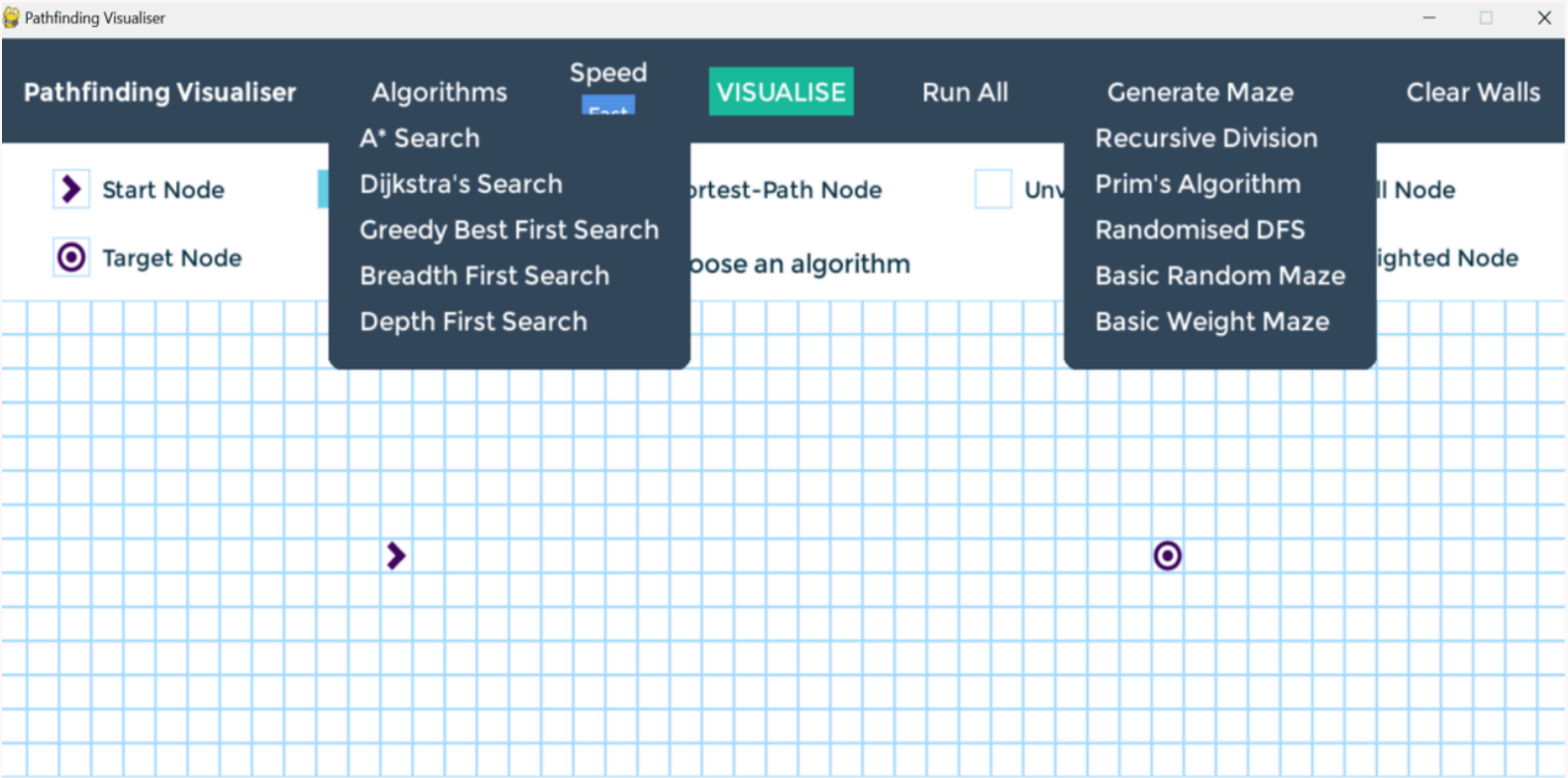
**BREADTH FIRST  
SEARCH**

05

**DIJKSTRA'S  
SEARCH**

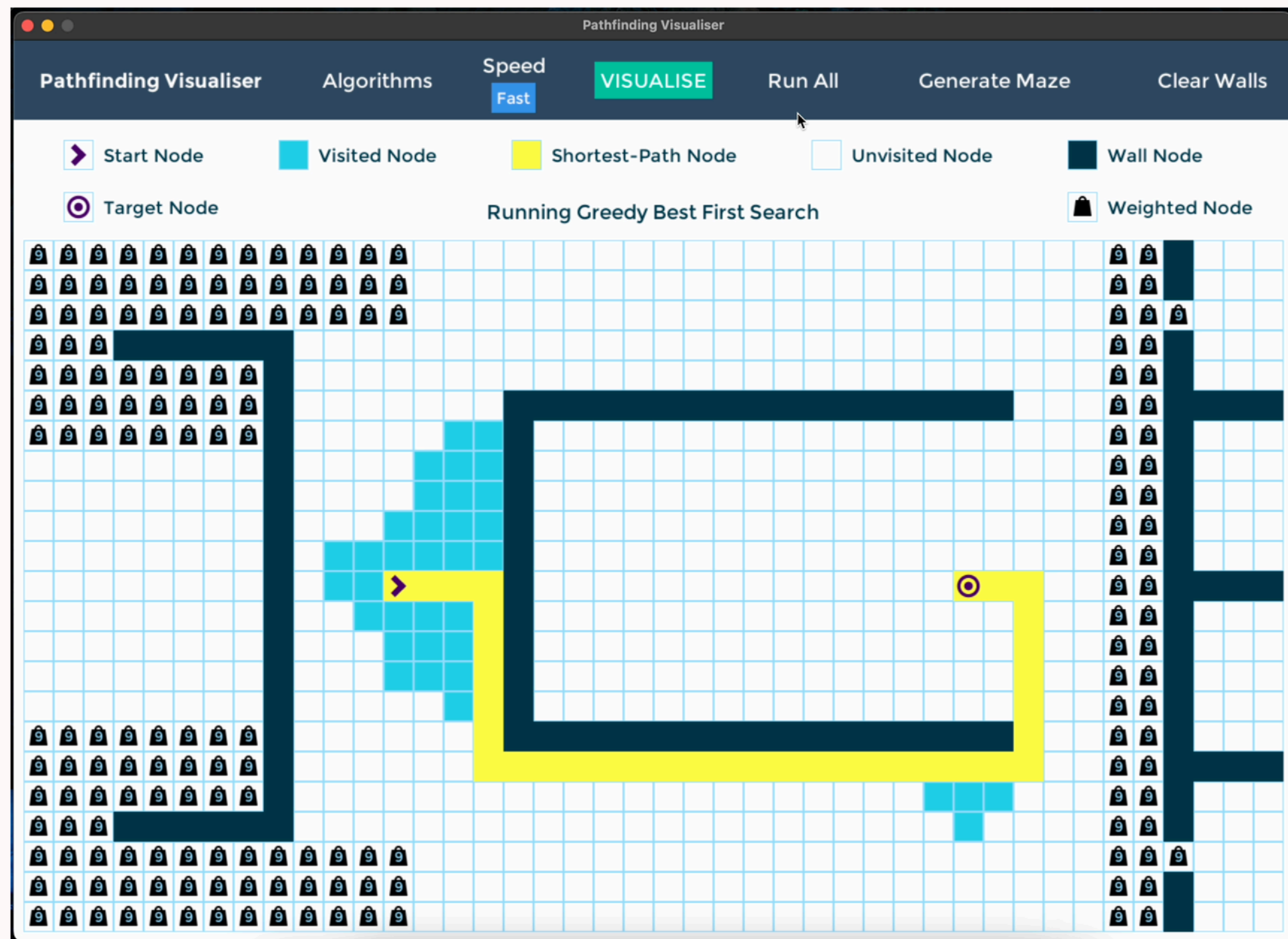


# TESTING (INPUT)

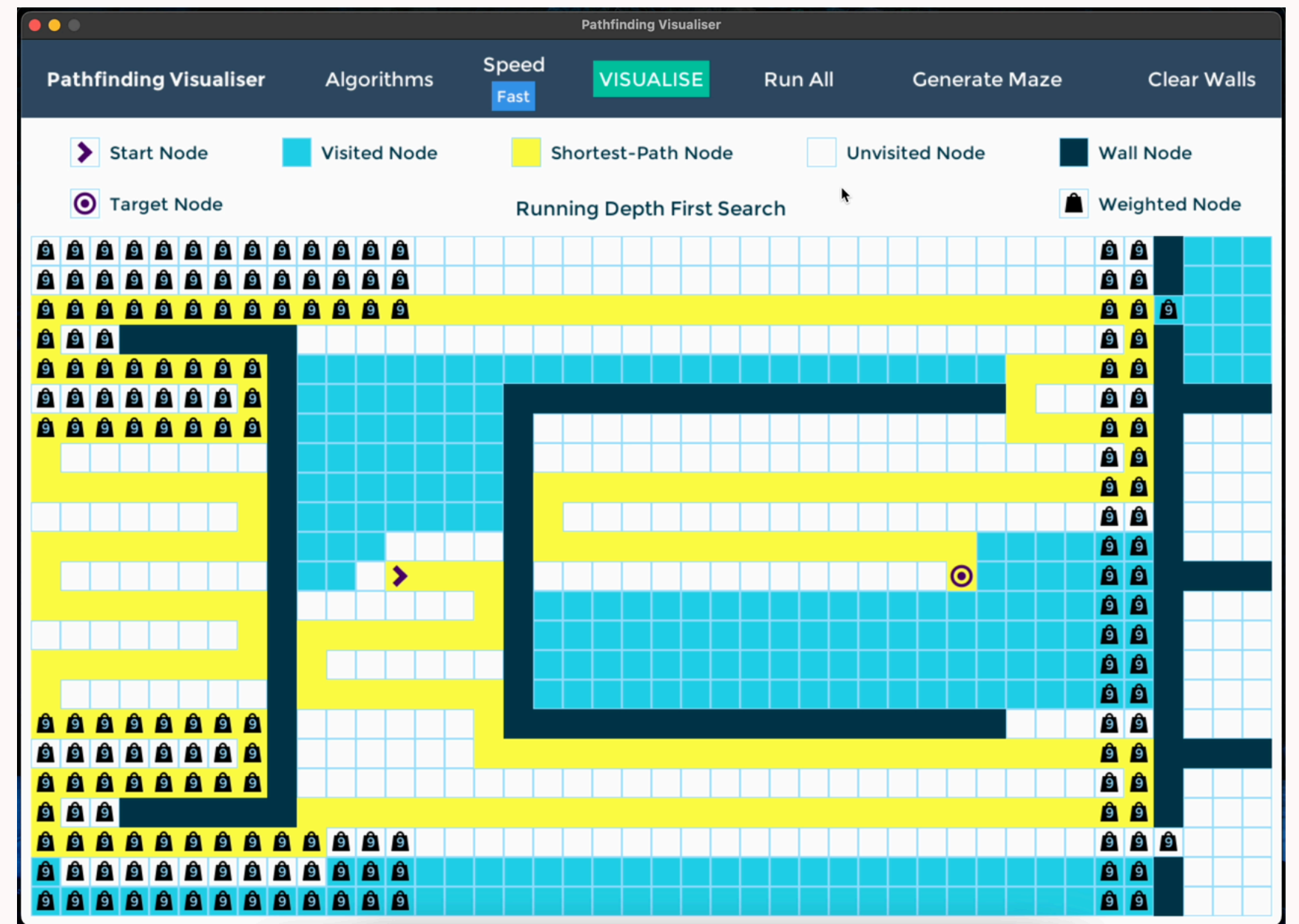


# TESTING (OUTPUT)

## Greedy Breadth First Search

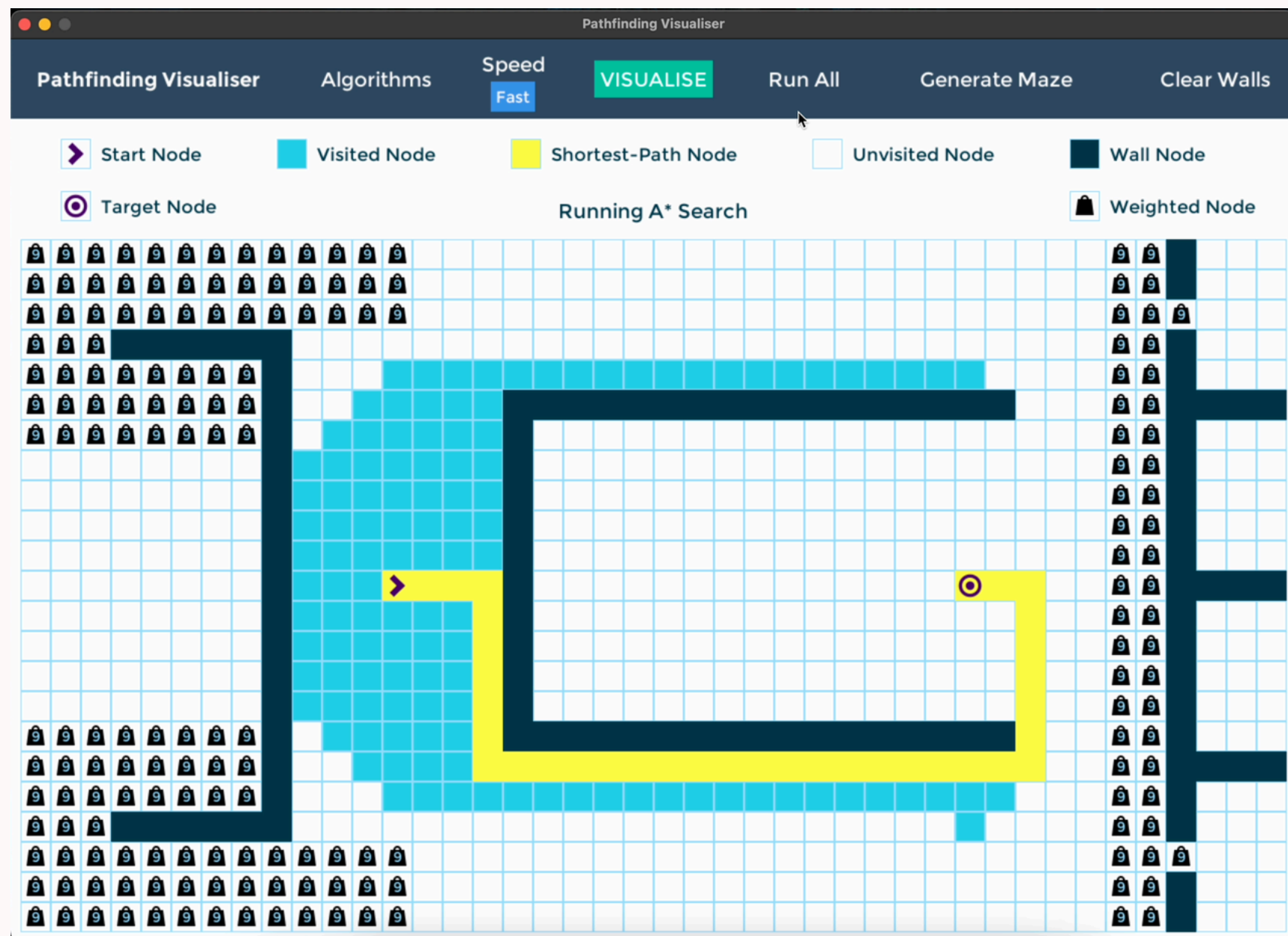


## Depth First Search

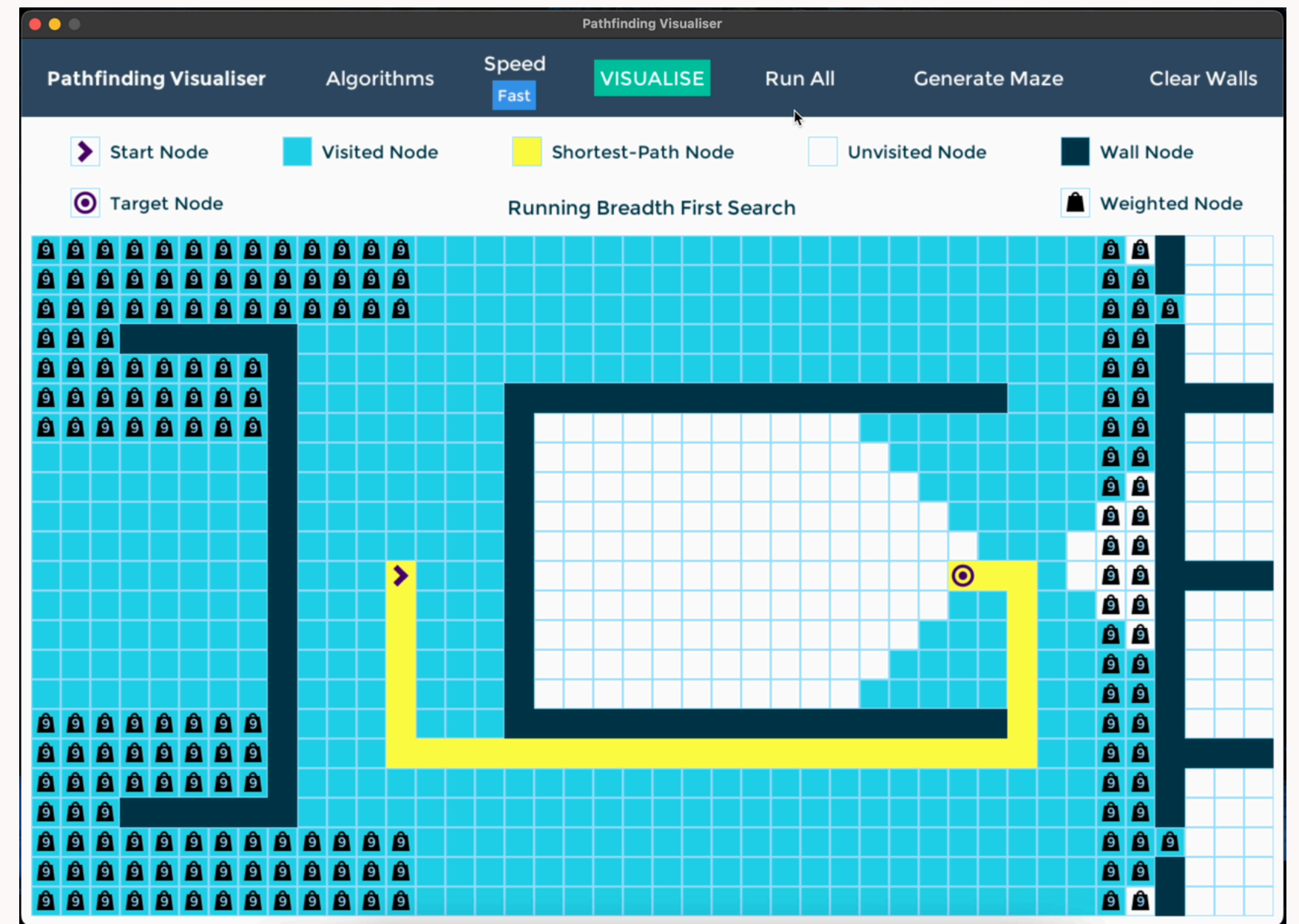


# TESTING (OUTPUT)

## A\* Search



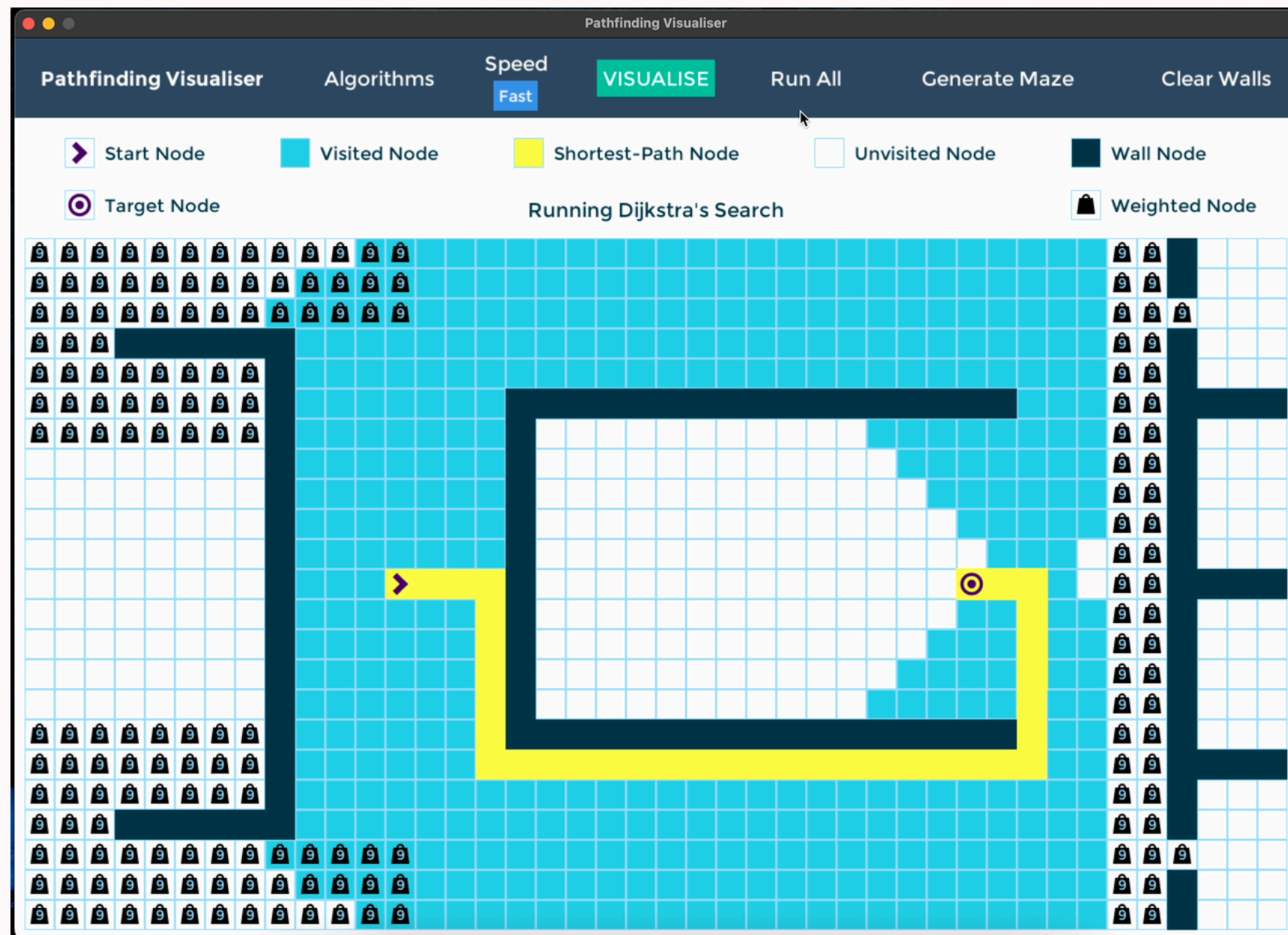
## Breadth First Search



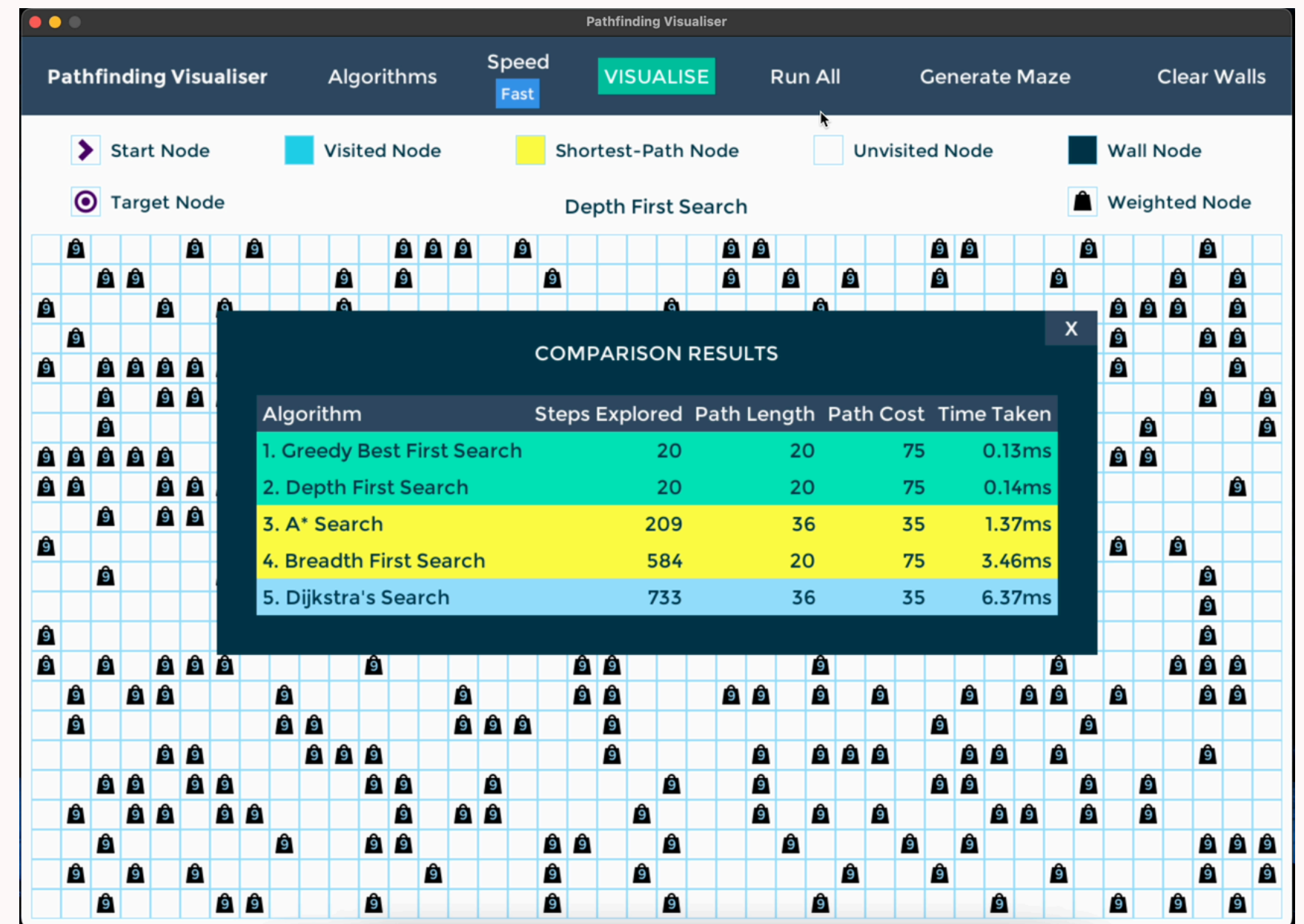


# TESTING (OUTPUT)

## Dijkstra's Search



## Results



# FUTURE IMPLEMENTATION

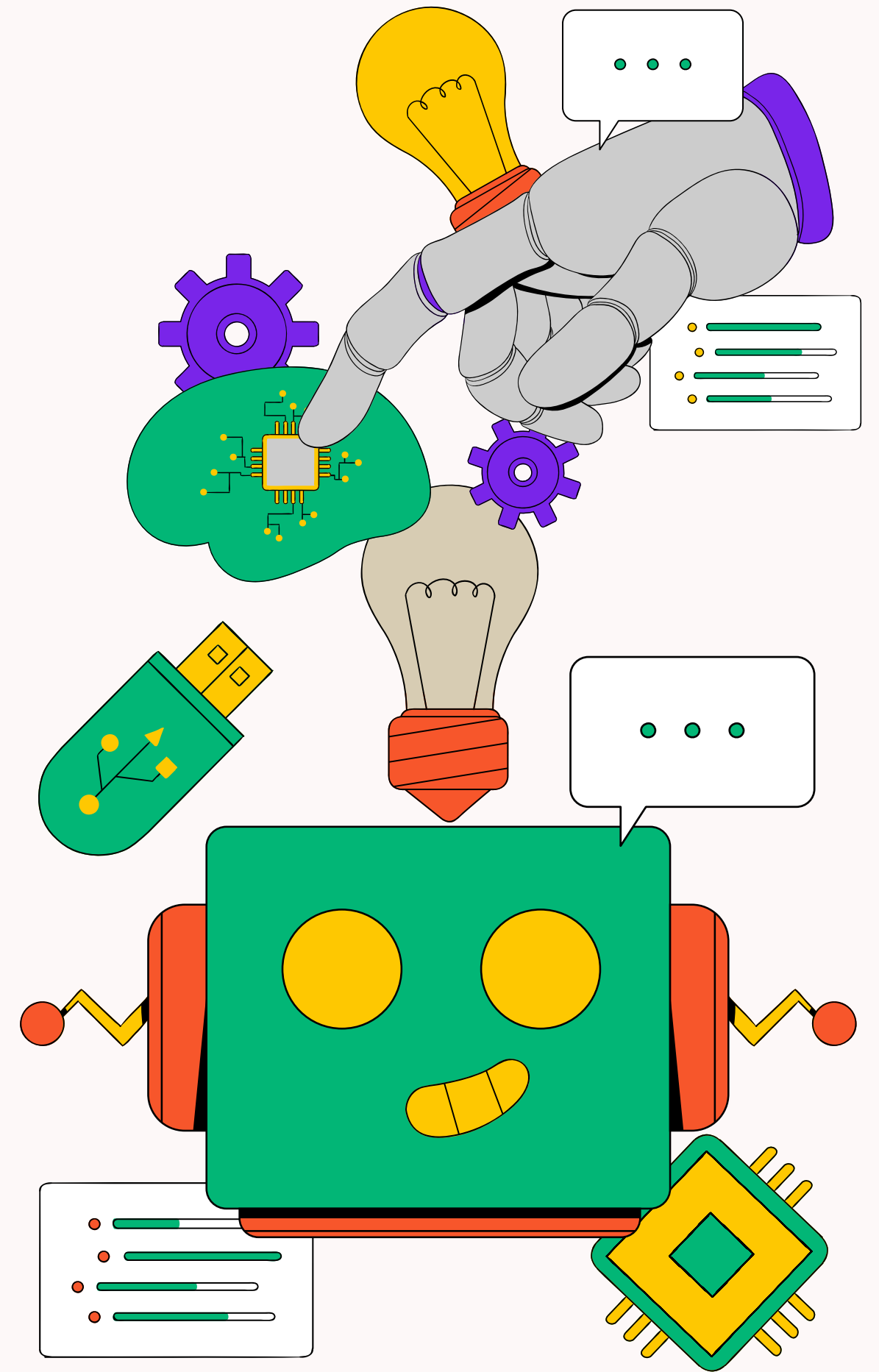


- Add more algorithms
- Add options to save and load custom grids
- Improve the user experience
- Support diagonal movement.
- Integration with real world application



# CONCLUSION

This project makes learning algorithms engaging and visual. It is a great educational tool for students and educators. Future additions can make it even more interactive and useful.



**THANK  
YOU**