Chapter 3: PCA and FLD Techniques (part 3)

- **q** Dimensionality Problem
- **q** Component Analysis
- Scatter Matrix
- Principal Component Analysis
- **q** Fisher Linear Discriminant

FEATURE SELECTION

Desired properties:

- Patterns belonging to different classes have dissimilar-valued features. Patterns associated with different classes should have feature values as far apart as possible.
- Patterns belonging to the same class have similar-valued features. Patterns belonging to the same class should be as close as possible to their mean.

Dimensionality problem:

- Combining features to reduce the dimensionality can be used to mitigate the adverse effects of "curse of dimensionality".
- ❖ Idea: represent a set of N d-dimensional samples vectors using a single, p-dimensional vector, where p < d (i.e. reducing the feature space). If p=1, all samples patterns are projected on one direction.
- Techniques for reducing excessive dimensionality by combining features through linear transformations:
 - Component Analysis: Principal Component Analysis (PCA) seeks a projection that best represents the data.
 - Discriminant Analysis: Fisher Linear Discriminant (FLD) seeks a projection that best separates (discriminates) the data.

COMPONENT ANALYSIS

- Goal: represent a set of N d-dimensional samples X₁, X₂, ..., XŊ, using a single vector X₀ so that the squared distances between X₀ and any Xk are as small as possible.
- Let where m is the sample mean:

$$m = \frac{1}{N} \sum_{k=1}^{N} X_{k}$$

The squared-error criterion function is:

$$\begin{split} J(X_0) &= \sum_{k=1}^N \left\| X_0 - X_k \right\|^2 = \sum_{k=1}^N \left\| \left(X_0 - m \right) - \left(X_k - m \right) \right\|^2 \\ J(X_0) &= \sum_{k=1}^N \left\| X_0 - m \right\|^2 - 2(X_0 - m)^T \sum_{k=1}^N \left(X_k - m \right) + \sum_{k=1}^N \left\| X_k - m \right\|^2 = \sum_{k=1}^N \left\| X_0 - m \right\|^2 + \sum_{k=1}^N \left\| X_k - m \right\|^2 \end{split}$$

- **Observation:** $J(X_0)$ is minimized by selecting $X_0 = m$.
- This is a zero-dimensional representation of the data set

ONE-DIMENSIONAL PROJECTION

- Observation: best 1-D representation of data (minimizing the least-square error) is the projection onto a line through the sample mean.
- One-dimensional representation: $\widetilde{X}_k = m + a_k e$ where e is the unit vector of the projection direction, and a is a scalar.
- \square Optimal sets of coefficients a_k are obtained by minimizing the squared-error criterion function:

$$J_1(a,e) = \sum_{k=1}^N \left\| (m+a_k e) - X_k \right\|^2 = \sum_{k=1}^N \left\| a_k e - \left(X_k - m \right) \right\|^2 = \sum_{k=1}^N a_k^2 \left\| e \right\|^2 - 2 \sum_{k=1}^N a_k e^T \left(X_k - m \right) + \sum_{k=1}^N \left\| X_k - m \right\|^2 = \sum_{k=1}^N \left\| a_k e - \left(X_k - m \right) \right\|^2 = \sum_{k=1}^N \left\| a_k e^T \left(X_k - m \right) \right\|^2 + \sum_{k=1}^N \left\| a_k e^T \left(X_k - m \right) \right\|^2 = \sum_{k=1}^N \left\| a_k e^T \left(X_k - m \right) \right\|^2 + \sum_{k=1}^N \left\| a_k e^T \left(X_k - m \right) \right\|^2 = \sum_{k=1}^N \left\| a_k e^T \left(X_k - m \right) \right\|^2 + \sum_{k=1}^N \left\| a_k e^T \left(X_k - m \right) \right\|^2 + \sum_{k=1}^N \left\| a_k e^T \left(X_k - m \right) \right\|^2 + \sum_{k=1}^N \left\| a_k e^T \left(X_k - m \right) \right\|^2 + \sum_{k=1}^N \left\| a_k e^T \left(X_k - m \right) \right\|^2 + \sum_{k=1}^N \left\| a_k e^T \left(X_k - m \right) \right\|^2 + \sum_{k=1}^N \left\| a_k e^T \left(X_k - m \right) \right\|^2 + \sum_{k=1}^N \left\| a_k e^T \left(X_k - m \right) \right\|^2 + \sum_{k=1}^N \left\| a_k e^T \left(X_k - m \right) \right\|^2 + \sum_{k=1}^N \left\| a_k e^T \left(X_k - m \right) \right\|^2 + \sum_{k=1}^N \left\| a_k e^T \left(X_k - m \right) \right\|^2 + \sum_{k=1}^N \left\| a_k e^T \left(X_k - m \right) \right\|^2 + \sum_{k=1}^N \left\| a_k e^T \left(X_k - m \right) \right\|^2 + \sum_{k=1}^N \left\| a_k e^T \left(X_k - m \right) \right\|^2 + \sum_{k=1}^N \left\| a_k e^T \left(X_k - m \right) \right\|^2 + \sum_{k=1}^N \left\| a_k e^T \left(X_k - m \right) \right\|^2 + \sum_{k=1}^N \left\| a_k e^T \left(X_k - m \right) \right\|^2 + \sum_{k=1}^N \left\| a_k e^T \left(X_k - m \right) \right\|^2 + \sum_{k=1}^N \left\| a_k e^T \left(X_k - m \right) \right\|^2 + \sum_{k=1}^N \left\| a_k e^T \left(X_k - m \right) \right\|^2 + \sum_{k=1}^N \left\| a_k e^T \left(X_k - m \right) \right\|^2 + \sum_{k=1}^N \left\| a_k e^T \left(X_k - m \right) \right\|^2 + \sum_{k=1}^N \left\| a_k e^T \left(X_k - m \right) \right\|^2 + \sum_{k=1}^N \left\| a_k e^T \left(X_k - m \right) \right\|^2 + \sum_{k=1}^N \left\| a_k e^T \left(X_k - m \right) \right\|^2 + \sum_{k=1}^N \left\| a_k e^T \left(X_k - m \right) \right\|^2 + \sum_{k=1}^N \left\| a_k e^T \left(X_k - m \right) \right\|^2 + \sum_{k=1}^N \left\| a_k e^T \left(X_k - m \right) \right\|^2 + \sum_{k=1}^N \left\| a_k e^T \left(X_k - m \right) \right\|^2 + \sum_{k=1}^N \left\| a_k e^T \left(X_k - m \right) \right\|^2 + \sum_{k=1}^N \left\| a_k e^T \left(X_k - m \right) \right\|^2 + \sum_{k=1}^N \left\| a_k e^T \left(X_k - m \right) \right\|^2 + \sum_{k=1}^N \left\| a_k e^T \left(X_k - m \right) \right\|^2 + \sum_{k=1}^N \left\| a_k e^T \left(X_k - m \right) \right\|^2 + \sum_{k=1}^N \left\| a_k e^T \left(X_k - m \right) \right\|^2 + \sum_{k=1}^N \left\| a_k e^T \left(X_k - m \right) \right\|^2 + \sum_{k=1}^N \left\| a_k e^T \left(X_k - m \right) \right\|^2 + \sum_{k=1}^N \left\| a_k e^T \left(X_k - m \right) \right\|^2 + \sum_{k=1}^N \left\| a_k e^T \left(X_k - m \right) \right\|^2 + \sum_{k=1}^N \left\| a_$$

- Since ||e|| = 1, then: $\frac{\partial J_1}{\partial a_k} = 0$ $a_k = e^T (X_k m)$
- The best direction e for the projection line can be found by minimizing:

$$J_1(e) = \sum_{k=1}^{N} a_k^2 - 2\sum_{k=1}^{N} a_k^2 + \sum_{k=1}^{N} \left\| X_k - m \right\|^2 = -\sum_{k=1}^{N} \left[e^T (X_k - m) \right]^2 + \sum_{k=1}^{N} \left\| X_k - m \right\|^2$$

SCATTER MATRIX

Finding the best direction e for the projection line involves the scatter matrix S defined as (N-1) times the covariance matrix of the samples:

$$S = (N-1)\Sigma = \sum_{k=1}^{N} (X_k - m)(X_k - m)^T$$

Criterion function (to minimize):

$$\begin{split} J_{1}(e) &= -\sum_{k=1}^{N} \Big[e^{T} \big(X_{k} - m \big) \Big]^{2} + \sum_{k=1}^{N} \left\| X_{k} - m \right\|^{2} = -\sum_{k=1}^{N} e^{T} \big(X_{k} - m \big) \big(X_{k} - m \big)^{T} e + \sum_{k=1}^{N} \left\| X_{k} - m \right\|^{2} \\ & \boxed{J_{1}(e) = -e^{T} Se + \sum_{k=1}^{N} \left\| X_{k} - m \right\|^{2}} \end{split}$$

□ $J_1(e)$ is minimized when e^T Se is maximized. Applying Lagrange optimization method (with λ an undetermined multiplier):

$$u = e^{T} S e - I(e^{T} e - 1)$$

$$\frac{\partial u}{\partial e} = 2S e - 2\lambda e$$

$$S e = \lambda e$$

Conclusion: since e^TSe = λe^Te = λ, maximizing e^TSe means selecting the eigenvector corresponding to the largest eigenvalue of the scatter matrix.

MATH REMINDER

Eigenvector and Eigenvalue: given dxd matrix M and a scalar λ, the d-dimensional vector x satisfying the set of linear equations:

$$Mx = \lambda x$$

is called the *eigenvector* of M corresponding to scalar λ . If I is the identity matrix, then the system of linear equations can be rewritten as:

$$(M - \lambda I)x = 0$$

The solution vector $x = e_k$ and corresponding scalar $\lambda = \lambda_k$ are called, respectively, *eigenvector* and associated *eigenvalue*. Note that any multiple of eigenvector x is also an eigenvector.

Lagrange optimization: suppose we seek the extremum x_0 of function f(x) subject to a constraint expressed in the form g(x) = 0. The constrained optimization problem can be solved by employing the Lagrange undetermined multiplier λ to form Lagrangian function:

$$L(x, \lambda) = f(x) + \lambda g(x)$$

The position of the extremum is given by the solution of equation:

$$\frac{\partial L(x,\lambda)}{\partial x} = \frac{\partial f(x)}{\partial x} + \lambda \frac{\partial g(x)}{\partial x} = 0$$

PCA

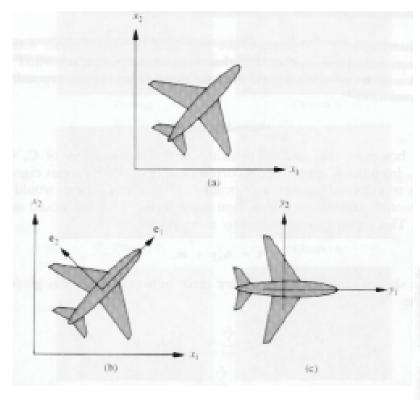
- Principal Component Analysis (PCA) leads to the projection that best best represents the data in the least-square sense:
 - Optimal projection is onto a line passing through the sample mean.
 - The projection line has the direction of the eigenvector corresponding to the largest eigenvalue of the scatter matrix.
- □ Coefficients $a_k = e^T(X_k m)$ are called **principal components**; e^T is the unit vector on the projection direction (and happens to be the eigenvector associated with the largest eigenvalue).
- **General case:** extending projection from one to p dimensions (p < d):

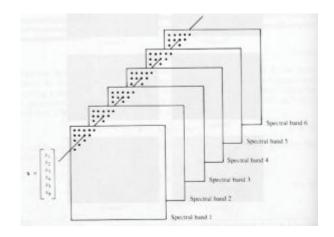
$$\widetilde{x} = m + \sum_{j=1}^{p} a_j e_j$$

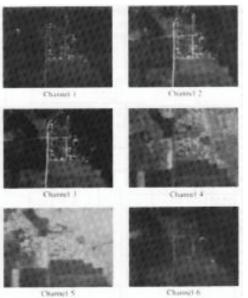
$$J_p(a, e) = \sum_{k=1}^{N} \left\| \left(m + \sum_{j=1}^{p} a_j e_j \right) - X_k \right\|^2$$

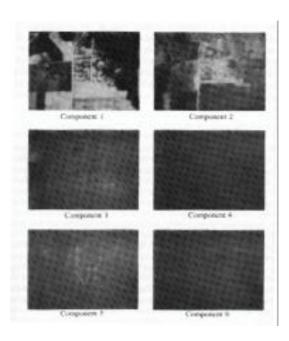
■ PCA optimization: in p-dimensions, the best representation of the sample data is the p-eigenvectors of the scatter matrix, corresponding to the largest p-eigenvalues.

Examples of PCA's Applications







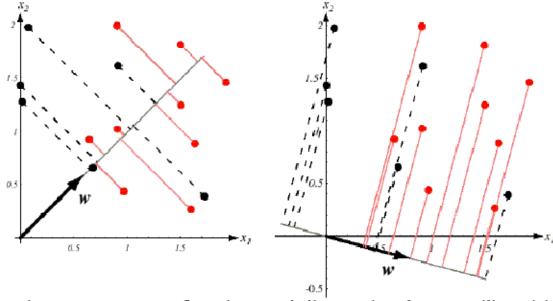


DISCRIMINANT ANALYSIS

- PCA finds the minimum number of components that best represents the data (that is, the best representation is in the least square sense). It does not guarantee any usefulness for classification.
- There is a need to reduce the dimensionality, under some constraint of maximizing the class separation (i.e. discrimination).
- While PCA aims to find the directions most efficient for representing the data, discriminant analysis attempts to identify the directions that are efficient for discriminating data between different classes.
- Discriminant Analysis: maximizing the discrimination can be achieved by increasing the inter-cluster distances while reducing the intra-cluster distances. These distances are obtained by employing, respectively, the between and within class scatter matrices.

OPTIMAL PROJECTION

Projection of the same set of samples onto two different lines in the directions marked by vector w. The figure on the right shows greater separation between the red and the black projected points.



If samples are seen as forming a *d*-dimension hyper-ellipsoidally shaped cloud, then the eigenvectors of the scatter matrix are the principal axes of that hyper-ellipsoid.

FISHER LINEAR DISCRIMINANT

- Data: a set of N d-dimensional samples X₁, X₂, ..., X_N are distributed into c subsets, D₁, D₂, ..., D_c, subset D_k being associated with class C_k. Let n_k be the number of samples in subset D_k.
- ☐ Fisher Linear Discriminant (FLD) is simply based on a linear transformation such as:

$$y = w^T X$$

where X is the $[d \times N]$ matrix of the samples and w is a [dxp] projection matrix

Observations:

- ❖ FLD transforms the set of samples X₁, X₂, ..., XŊ (via y₂= w^TX₂) into a set of sample projections y₁, y₂, ..., yŊ of reduced dimensionality (p < d).</p>
- Projections are distributed into subsets Y₁, Y₂, ..., Y₂, with Yk = {yk | Xk ∈ Dk}, corresponding to class-based subsets D₁, D₂, ..., D₂.
- If ||w|| = 1, then y_k is the projection of X_k on a line in the direction w.
- It can be shown that the the samples mean has a similar projection:

$$m_k = \frac{1}{n_k} \sum_{X_k \in D_k} X_k \longrightarrow \widetilde{m}_k = \frac{1}{n_k} \sum_{y_k \in Y_k} y_k = \frac{1}{n_k} \sum_{X_k \in D_k} w^T x_k \longrightarrow \widetilde{m}_k = w^T m_k$$

TWO-CLASS CRITERIA

Definitions:

- Distance between 2 projected means:
- Scatter for projected samples:

Desired Criteria:

- Maximize separation: separation of projected class means should be as large as possible.
- Preserve compactness: sum of the scatter of each of the sets of projected values should be as small as possible.

FLD Criterion function:

- overall measure of FLD "goodness" is given by the separation of the means relative to the compactness.
- w maximizing J(w) leads to the best separation between two projects sets.

$$\left|\widetilde{m}_1 - \widetilde{m}_2\right| = \left|w^T \left(m_1 - m_2\right)\right|$$

$$\widetilde{S}_k = \sum_{y \in Y_k} (y - \widetilde{m}_k)^2$$

$$\left| \widetilde{m}_1 - \widetilde{m}_2 \right| = \left| w^T \left(m_1 - m_2 \right) \right| \rightarrow \max$$

$$\widetilde{s_1}^2 + \widetilde{s_2}^2 \rightarrow \min$$

$$J(w) = \frac{\left|\widetilde{m}_1 - \widetilde{m}_2\right|^2}{\left(\widetilde{s}_1^2 + \widetilde{s}_2^2\right)} \to \max$$

$$\frac{\partial J(w)}{\partial w} = 0$$

SCATTER MATRICES

- Scatter matrix: covariance matrix times size of samples population. $S_k = (n_k 1)\Sigma_k = \sum_{X \in D_k} (X m_k)(X m_k)^T$
- Within-class scatter matrix: sum of the scatter matrices for both classes.

$$S_W = S_1 + S_2$$

Between-class scatter matrix: defined through the class means.

$$S_B = (m_1 - m_2)(m_1 - m_2)^T$$

■ Scatter of projected X_k samples:

$$\widetilde{s}_{k}^{2} = \sum_{X \in D_{k}} (w^{T}X - w^{T}m_{k})^{2} = \sum_{X \in D_{k}} w^{T}(X - m_{k})(X - m_{k})^{T}w = w^{T}S_{k}w$$

■ Within-class scatter of projected samples (that should be as small as possible):

$$\widetilde{S_1}^2 + \widetilde{S_2}^2 = w^T S_w w$$

■ Between-class scatter of projected samples (that should be as large as possible):

$$\left|\widetilde{m}_1 - \widetilde{m}_2\right|^2 = w^T S_B w$$

FINDING BEST FEATURES

- **Problem:** identify the matrix w for the linear transformation $y = w^T X$ to reduce feature vector dimension from d to p (with p < d). For a c-class problem
- **Fisher Linear Discriminant:** set of w values that maximizes the criterion function J(w).
- ☐ FLD Criterion:

$$J(w) = \frac{\left|\widetilde{m}_1 - \widetilde{m}_2\right|^2}{\left(\widetilde{s}_1^2 + \widetilde{s}_2^2\right)} = \frac{w^T S_B w}{w^T S_W w}$$

- Methods:
 - 1. Start with a good guess and iteratively adjust w, so that J(w) increases with each iteration (i.e. w is getting better and better).
 - 2. Solve directly:

$$\frac{\partial J(w)}{\partial w} = 0$$

$$S_B w = \lambda S_w w$$

Solution: the eigenvector of $S_W^{-1}S_B$ with the largest absolute eigenvalue. $S_w^{-1}S_Bw = \lambda w \longrightarrow w = S_w^{-1}(m_1 - m_2)$

GENERAL CASE

Total mean vector:

$$m = \frac{1}{N} \sum_{k=1}^{c} X_k = \frac{1}{N} \sum_{k=1}^{c} n_k m_k$$

■ Total scatter matrix:

$$S_{T} = \sum_{k=1}^{N} (X_{k} - m)(X_{k} - m)^{T}$$

Within-class scatter matrix:

$$S_W = \sum_{k=1}^{c} S_k = \sum_{k=1}^{c} \sum_{X \in D_k} (X - m_k) (X - m_k)^T$$

Between-class scatter matrix:

$$S_B = \sum_{k=1}^{c} (m_k - m)(m_k - m)^T$$

FLD Criterion function:

$$J(w) = \frac{w^T S_B w}{w^T S_W w}$$

FLD TECHNIQUE

- □ FLD tries to find the w transformation matrix that will maximize the J(w) criterion function. It is considered that maximizing this function will increase the inter-cluster distances (through maximizing the between class cluster matrix) and will decrease the intra-cluster distances (through minimizing the within class scatter matrix).
- ☐ The columns of the optimal (in least-square sense) W matrix are the generalized eigenvectors (of $S_W^{-1}S_B$) corresponding to the largest eigenvalues.

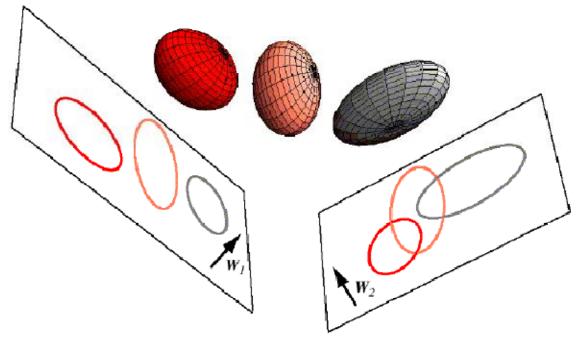
$$S_B w_k = \lambda_k S_W w_k$$
$$S_W^{-1} S_B w_k = \lambda_k w_k$$

□ This generalized eigenvalue problem can be solved by first computing the eigenvalues as the roots of the characteristic polynomial, and then solving the linear set for w_k, the columns of the w matrix.

$$\begin{aligned} & S_B - \lambda_k S_W = 0 \\ & (S_B - \lambda_k S_W) w_k = 0 \end{aligned}$$

■ Note: procedure might generate d eigenvalues, and d corresponding eigenvectors. However, only p of these eigenvalues should end up being non-zero.

MAXIMIZING SEPARATION



Three three-dimensional distributions are projected onto two-dimensional subspaces, described by a normal vectors w_1 and w_2 . Informally, multiple discriminant methods seek the optimum such subspace, that is, the one with the greatest separation of the projected distributions for a given total within-scatter matrix, here as associated with w_1 .