Chapter 3: Maximum-Likelihood & Bayesian Parameter Estimation (part 1)

- I Introduction
- I Maximum-Likelihood Estimation
 - I Example of a Specific Case
 - ι The Gaussian Case: unknown μ and σ
 - ı Bias
- I Appendix: ML Problem Statement

I Introduction

- Data availability in a Bayesian framework
 - We could design an optimal classifier if we knew:
 - $IP(\omega_i)$ (priors)
 - $P(x \mid \omega_i)$ (class-conditional densities)

Unfortunately, we rarely have this complete information!

- Design a classifier from a training sample
 - No problem with prior estimation
 - Samples are often too small for class-conditional estimation (large dimension of feature space!)

- A priori information about the problem
- I Normality of $P(x \mid \omega_i)$

$$P(x \mid \omega_i) \sim N(\mu_i, \Sigma_i)$$

- Characterized by 2 parameters
- I Estimation techniques
 - Maximum-Likelihood (ML) and the Bayesian estimations
 - Results are nearly identical, but the approaches are different

- Parameters in ML estimation are fixed but unknown!
- Best parameters are obtained by maximizing the probability of obtaining the samples observed
- Bayesian methods view the parameters as random variables having some known distribution
- In either approach, we use $P(\omega_i \mid x)$ for our classification rule!

I Maximum-Likelihood Estimation

- Has good convergence properties as the sample size increases
- Simpler than any other alternative techniques

General principle

Assume we have c classes and

$$P(x \mid \omega_j) \sim N(\mu_j, \Sigma_j)$$

$$P(x \mid \omega_j) \equiv P(x \mid \omega_j, \theta_j) \text{ where:}$$

$$q = (m_j, S_j) = (m_j^1, m_j^2, ..., s_j^{11}, s_j^{22}, cov(x_j^m, x_j^n)...)$$

- Use the information provided by the training samples to estimate $\theta = (\theta_1,\,\theta_2,\,...,\,\theta_c), \text{ each } \theta_i \text{ (i = 1, 2, ..., c) is associated with each category}$
- I Suppose that D contains n samples, $x_1, x_2,..., x_n$ (samples drawn independently)

$$P(D \mid q) = \bigcup_{k=1}^{k=n} P(x_k \mid q) = F(q)$$

P(D | q) is called the likelihood of q w.r.t. the set of samples)

ı ML estimate of θ is, by definition the value that \mathbf{q} maximizes P(D | θ)

"It is the value of θ that best agrees with the actually observed training sample"

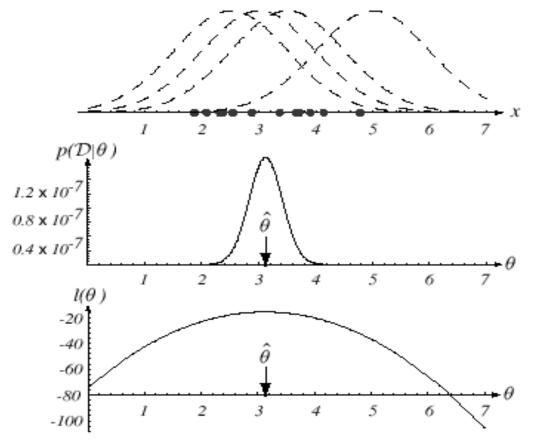


FIGURE 3.1. The top graph shows several training points in one dimension, known or assumed to be drawn from a Gaussian of a particular variance, but unknown mean. Four of the infinite number of candidate source distributions are shown in dashed lines. The middle figure shows the likelihood $p(\mathcal{D}|\theta)$ as a function of the mean. If we had a very large number of training points, this likelihood would be very narrow. The value that maximizes the likelihood is marked $\hat{\theta}$; it also maximizes the logarithm of the likelihood—that is, the log-likelihood $I(\theta)$, shown at the bottom. Note that even though they look similar, the likelihood $p(\mathcal{D}|\theta)$ is shown as a function of θ whereas the conditional density $p(x|\theta)$ is shown as a function of x. Furthermore, as a function of θ , the likelihood $p(\mathcal{D}|\theta)$ is not a probability density function and its area has no significance. From: Richard O. Duda, Peter E. Hart, and David G. Stork, Pattern Classification. Copyright © 2001 by John Wiley & Sons, Inc.

Optimal estimation

Let $\theta = (\theta_1, \theta_2, ..., \theta_p)^t$ and let ∇_{θ} be the gradient operator

$$\tilde{N}_{q} = \frac{\acute{e}}{\mathring{e}} \frac{\P}{\P q_{1}}, \frac{\P}{\P q_{2}}, \dots, \frac{\P}{\P q_{p}} \hat{u}^{t}$$

We define $\ell(\theta)$ as the log-likelihood function

$$\ell(\theta) = \text{In P}(D \mid \theta)$$

New problem statement:
 determine θ that maximizes the log-likelihood

$$\hat{q} = \arg \max_{q} \mathbf{l}(q)$$

Set of necessary conditions for an optimum is:

$$(\nabla_q \mathbf{l} = \sum_{k=1}^{k=n} \nabla_q \ln P(x_k \mid \mathbf{q}))$$

$$\nabla_{\theta} \ell = 0$$

- Example of a specific case: unknown μ
 - ι $P(x_i | \mu) \sim N(\mu, \Sigma)$ (Samples are drawn from a multivariate normal population)

InP(x_k | m) =
$$-\frac{1}{2}$$
In[(2p)^d|S|] $-\frac{1}{2}$ (x_k - m)^t $\overset{-1}{a}$ (x_k - m)
and \tilde{N}_{qm} InP(x_k | m) = $\overset{-1}{a}$ (x_k - m)

 $\theta = \mu$ therefore:

The ML estimate for μ must satisfy:

$$a^{k=n} S^{-1}(x_k - \hat{m}) = 0$$

Multiplying by Σ and rearranging, we obtain:

$$\mathbf{\hat{m}} = \frac{1}{a} \mathbf{X}_{k}$$

$$\mathbf{\hat{n}}_{k=1}$$

Just the arithmetic average of the samples of the training samples!

Conclusion:

If $P(x_k \mid \omega_j)$ (j = 1, 2, ..., c) is supposed to be Gaussian in a *d*-dimensional feature space; then we can estimate the vector $\theta = (\theta_1, \theta_2, ..., \theta_c)^t$ and perform an optimal classification!

ML Estimation:

I Gaussian Case: unknown m and s (one dimension) $q = (q_1, q_2) = (\mu, \sigma^2)$

$$\mathbf{l} = \ln P(\mathbf{x}_{k} | \mathbf{q}) = -\frac{1}{2} \ln(2 \pi \mathbf{q}_{2}) - \frac{1}{2\mathbf{q}_{2}} (\mathbf{x}_{k} - \mathbf{q}_{1})^{2}$$

$$\nabla_{\theta} \mathbf{l} = \begin{pmatrix} \frac{\partial}{\partial \mathbf{q}_{1}} (\ln P(\mathbf{x}_{k} | \mathbf{q})) \\ \frac{\partial}{\partial \mathbf{q}_{2}} (\ln P(\mathbf{x}_{k} | \mathbf{q})) \end{pmatrix} = 0$$

$$\begin{cases} \frac{1}{\mathbf{q}_{2}} (\mathbf{x}_{k} - \mathbf{q}_{1}) = 0 \\ -\frac{1}{2\mathbf{q}_{2}} + \frac{(\mathbf{x}_{k} - \mathbf{q}_{1})^{2}}{2\mathbf{q}_{2}^{2}} = 0 \end{cases}$$

Summation:

$$\begin{cases} \sum_{k=1}^{k=n} \frac{1}{\hat{q}_2} (x_k - \hat{q}_1) = 0 \\ -\sum_{k=1}^{k=n} \frac{1}{\hat{q}_2} + \sum_{k=1}^{k=n} \frac{(x_k - \hat{q}_1)^2}{\hat{q}_2^2} = 0 \end{cases}$$
 (1)

Combining (1) and (2), one obtains:

$$m = \overset{k=n}{\underset{k=1}{a}} \frac{x_k}{n} \quad ; \quad s^2 = \frac{\overset{k=n}{a} (x_k - m)^2}{n}$$

I Bias

I ML estimate for σ^2 is biased

$$E_{\hat{\xi}}^{\acute{e}1}S(x_i - \overline{x})^2\hat{t} = \frac{n-1}{n}.S^2 \cdot S^2$$

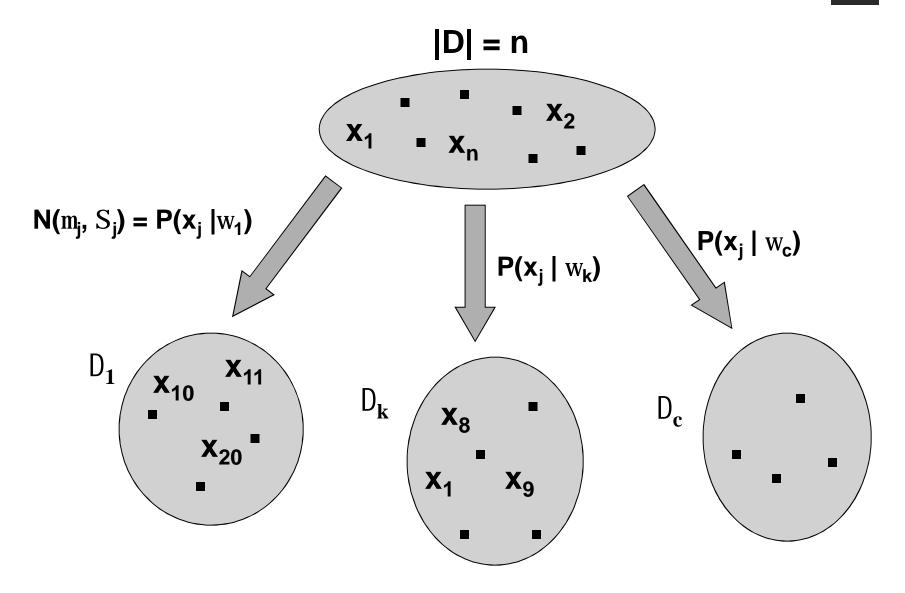
I An elementary unbiased estimator for Σ is:

I Appendix: ML Problem Statement

ı Let D =
$$\{x_1, x_2, ..., x_n\}$$

$$P(x_1,..., x_n | \theta) = \Pi^{1,n}P(x_k | \theta); |D| = n$$

Our goal is to determine $\hat{\mathbf{q}}$ (value of θ that makes this sample the most representative!)



$$\theta = (\theta_1, \theta_2, ..., \theta_c)$$

Problem: find $\hat{\mathbf{q}}$ such that:

$$\begin{aligned} \text{MaxP(D | q) &= \text{MaxP(x}_1,...,x_n | q) \\ q \end{aligned} &= \text{Max} \overset{n}{\text{O}} P(x_k | q) \\ &= \text{k=1} \end{aligned}$$

summary

$$P(x) = \frac{1}{\sqrt{2\pi\sigma^{2}}} e^{\left[\frac{1(x-\mu)^{2}}{2\sigma^{2}}\right]}$$

$$\theta = \left[\mu - \sigma^{2}\right]^{T}$$

$$\frac{\partial}{\partial \mu} \ln(P(X_{k}|\theta)) = \frac{(X_{k}-\mu)}{\sigma^{2}}$$

$$\frac{\partial}{\partial (\sigma^{2})} \ln(P(X_{k}|\theta)) = -\frac{1}{2\sigma^{2}} + \frac{(X_{k}-\mu)^{2}}{2(\sigma^{2})^{2}}$$

$$\sum_{k=1}^{N} \frac{(X_{k}-\mu)}{\sigma^{2}} = 0$$

$$\frac{1}{2\sigma^{2}} \sum_{k=1}^{N} \left(\frac{(X_{k}-\mu)^{2}}{\sigma^{2}} - 1\right) = 0$$