

SKILL BOOSTER 3

Drone Design

- Flight Controller : **Pixhawk 4**
 - ↳ Runs ArduPilot
 - ↳ Supports UART, I²C, CAN

- Sensors :

- ↳ IMU + Barometer
(built into FC)
- ↳ Compass - Magnetometer
I²C (QMCS883L)
- ↳ GPS (UART)
u-blox NEO-M8N
- ↳ Camera (UART)
Raspberry Pi Cam
- ↳ RC Receiver (SBUS)
Express LRS

