

Adaptive Traffic Light Controller Project

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December 7, 2024

Contents

1	Introduction	2
2	Problem Statement	2
3	System Requirements	2
4	FSM Overview	3
4.1	States	3
4.2	Transitions	3
5	FSM Table	3
6	State and Transition Explanations	5
6.1	NS1 (North-South Lane 1)	5
6.2	NS2 (North-South Lane 2)	5
6.3	EW1 (East-West Lane 1)	6
6.4	EW2 (East-West Lane 2)	6

1 Introduction

This project involves designing an **adaptive traffic light controller** for a four-way intersection. The system adapts dynamically to real-time traffic conditions to ensure collision-free operation and prioritize heavily congested lanes.

The traffic light controller is modeled as a **Finite State Machine (FSM)** with 16 states corresponding to each lane's traffic light conditions, including **primary green**, **extended green**, and **yellow states**.

2 Problem Statement

The goal is to develop a **traffic control system** with:

1. **Dynamic Timing:** Extend green light duration for congested lanes based on sensor inputs.
2. **Collision Avoidance:** Only one lane can have a green or yellow light at any time.
3. **Timer-Based Yellow and Extended Green:** These states remain active until the timer expires if no next state is defined.
4. **Skipping Idle Lanes:** If no cars are detected in a lane, the FSM skips to the next lane in the sequence.
5. **Efficient Lane Priority:** Ensure a fair balance between lane priorities while dynamically adjusting for congestion.

3 System Requirements

1. **Lanes:** Four main lanes: NS1, NS2, EW1, EW2.
2. **Sensors:**
 - S1_NS1, S5_NS1 for North-South Lane 1.
 - S1_NS2, S5_NS2 for North-South Lane 2.
 - S1_EW1, S5_EW1 for East-West Lane 1.
 - S1_EW2, S5_EW2 for East-West Lane 2.
3. **Traffic Lights:** States: **RED, PRIMARY GREEN, EXTENDED GREEN, YELLOW**.
4. **Timers:**
 - Default green timer: 20 seconds.
 - Yellow timer: 5 seconds.
 - Extended green timer: 30 seconds if congestion ($S5 = 1$) is detected.

4 FSM Overview

4.1 States

The FSM has **16 states**:

1. NS1_RED, NS1_PRIMARY_GREEN, NS1_EXTENDED_GREEN, NS1_YELLOW
2. NS2_RED, NS2_PRIMARY_GREEN, NS2_EXTENDED_GREEN, NS2_YELLOW
3. EW1_RED, EW1_PRIMARY_GREEN, EW1_EXTENDED_GREEN, EW1_YELLOW
4. EW2_RED, EW2_PRIMARY_GREEN, EW2_EXTENDED_GREEN, EW2_YELLOW

4.2 Transitions

Transitions are triggered by:

1. **Sensor Inputs:** Cars detected ($S1 = 1$) or congestion ($S5 = 1$).
2. **Timer Expiry:** States transition when their timers expire.
3. **Timer-Based Yellow and Extended Green:** If no next state is triggered, remain in the current state until the timer expires.
4. **Idle Lane Skipping:** If a lane is in RED and no cars are detected ($S1 = 0$), the FSM skips to the next lane in sequence.

5 FSM Table

Current State	Condition (Inputs)	Next State	Output	Timer Extension Condition
NS1_RED	$S1_NS1 = 1$	NS1_PRIMARY_GREEN	NS1: Green; All others: Red	No
NS1_RED	$S1_NS1 = 0$	NS2_RED	NS1: Red; All others: Red	No
NS1_PRIMARY_GREEN	$S5_NS1 = 1$	NS1_EXTENDED_GREEN	Extend Green for NS1	Yes
NS1_PRIMARY_GREEN	Timer expires && $S5_NS1 = 0$	NS1_YELLOW	NS1: Yellow; All others: Red	No
NS1_EXTENDED_GREEN	Timer running	NS1_EXTENDED_GREEN	Extend Green; NS1 active	Yes
NS1_EXTENDED_GREEN	Timer expires	NS1_YELLOW	NS1: Yellow; All others: Red	No
NS1_YELLOW	Timer running	NS1_YELLOW	NS1: Yellow; All others: Red	No

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Table 1 – Continued from previous page

Current State	Condition (Inputs)	Next State	Output	Timer Extension Condition
NS1_YELLOW	Timer expires	NS2_RED	NS1: Red; All others: Red	No
NS2_RED	S1_NS2 = 1	NS2_PRIMARY_GREEN	NS2: Green; All others: Red	No
NS2_RED	S1_NS2 = 0	EW1_RED	NS2: Red; All others: Red	No
NS2_PRIMARY_GREEN	S5_NS2 = 1	NS2_EXTENDED_GREEN	Extend Green for NS2	Yes
NS2_PRIMARY_GREEN	Timer expires && S5_NS2 = 0	NS2_YELLOW	NS2: Yellow; All others: Red	No
NS2_EXTENDED_GREEN	Timer running	NS2_EXTENDED_GREEN	Extend Green; NS2 active	Yes
NS2_EXTENDED_GREEN	Timer expires	NS2_YELLOW	NS2: Yellow; All others: Red	No
NS2_YELLOW	Timer running	NS2_YELLOW	NS2: Yellow; All others: Red	No
NS2_YELLOW	Timer expires	EW1_RED	NS2: Red; All others: Red	No
EW1_RED	S1_EW1 = 1	EW1_PRIMARY_GREEN	EW1: Green; All others: Red	No
EW1_RED	S1_EW1 = 0	EW2_RED	EW1: Red; All others: Red	No
EW1_PRIMARY_GREEN	S5_EW1 = 1	EW1_EXTENDED_GREEN	Extend Green for EW1	Yes
EW1_PRIMARY_GREEN	Timer expires && S5_EW1 = 0	EW1_YELLOW	EW1: Yellow; All others: Red	No
EW1_EXTENDED_GREEN	Timer running	EW1_EXTENDED_GREEN	Extend Green; EW1 active	Yes
EW1_EXTENDED_GREEN	Timer expires	EW1_YELLOW	EW1: Yellow; All others: Red	No
EW1_YELLOW	Timer running	EW1_YELLOW	EW1: Yellow; All others: Red	No
EW1_YELLOW	Timer expires	EW2_RED	EW1: Red; All others: Red	No
EW2_RED	S1_EW2 = 1	EW2_PRIMARY_GREEN	EW2: Green; All others: Red	No
EW2_RED	S1_EW2 = 0	NS1_RED	EW2: Red; All others: Red	No
EW2_PRIMARY_GREEN	S5_EW2 = 1	EW2_EXTENDED_GREEN	Extend Green for EW2	Yes
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Current State	Condition (Inputs)	Next State	Output	Timer Extension Condition
EW2_PRIMARY_GREEN	Timer expires && S5_EW2 = 0	EW2_YELLOW	EW2: Yellow; All others: Red	No
EW2_EXTENDED_GREEN	Timer running	EW2_EXTENDED_GREEN	Extend Green; EW2 active	Yes
EW2_EXTENDED_GREEN	Timer expires	EW2_YELLOW	EW2: Yellow; All others: Red	No
EW2_YELLOW	Timer running	EW2_YELLOW	EW2: Yellow; All others: Red	No
EW2_YELLOW	Timer expires	NS1_RED	EW2: Red; All oth- ers: Red	No

6 State and Transition Explanations

6.1 NS1 (North-South Lane 1)

1. NS1_RED:

- If S1_NS1 = 1, transition to NS1_PRIMARY_GREEN.
- If S1_NS1 = 0, skip to NS2_RED.

2. NS1_PRIMARY_GREEN:

- If S5_NS1 = 1, extend green duration by transitioning to NS1_EXTENDED_GREEN.
- If Timer expires, transition to NS1_YELLOW.

3. NS1_EXTENDED_GREEN:

- Remain in this state until the timer expires if Timer running.
- If Timer expires, transition to NS1_YELLOW.

4. NS1_YELLOW:

- Remain in this state until the timer expires.
- When the timer expires, transition to NS2_RED.

6.2 NS2 (North-South Lane 2)

1. NS2_RED:

- If S1_NS2 = 1, transition to NS2_PRIMARY_GREEN.
- If S1_NS2 = 0, skip to EW1_RED.

2. NS2_PRIMARY_GREEN:

- If `S5_NS2 = 1`, extend green duration by transitioning to `NS2_EXTENDED_GREEN`.
- If `Timer expires`, transition to `NS2_YELLOW`.

3. `NS2_EXTENDED_GREEN`:

- Remain in this state until the timer expires if `Timer running`.
- If `Timer expires`, transition to `NS2_YELLOW`.

4. `NS2_YELLOW`:

- Remain in this state until the timer expires.
- When the timer expires, transition to `EW1_RED`.

6.3 EW1 (East-West Lane 1)

1. `EW1_RED`:

- If `S1_EW1 = 1`, transition to `EW1_PRIMARY_GREEN`.
- If `S1_EW1 = 0`, skip to `EW2_RED`.

2. `EW1_PRIMARY_GREEN`:

- If `S5_EW1 = 1`, extend green duration by transitioning to `EW1_EXTENDED_GREEN`.
- If `Timer expires`, transition to `EW1_YELLOW`.

3. `EW1_EXTENDED_GREEN`:

- Remain in this state until the timer expires if `Timer running`.
- If `Timer expires`, transition to `EW1_YELLOW`.

4. `EW1_YELLOW`:

- Remain in this state until the timer expires.
- When the timer expires, transition to `EW2_RED`.

6.4 EW2 (East-West Lane 2)

1. `EW2_RED`:

- If `S1_EW2 = 1`, transition to `EW2_PRIMARY_GREEN`.
- If `S1_EW2 = 0`, skip to `NS1_RED`.

2. `EW2_PRIMARY_GREEN`:

- If `S5_EW2 = 1`, extend green duration by transitioning to `EW2_EXTENDED_GREEN`.
- If `Timer expires`, transition to `EW2_YELLOW`.

3. `EW2_EXTENDED_GREEN`:

- Remain in this state until the timer expires if `Timer running`.

- If `Timer` expires, transition to `EW2_YELLOW`.

4. `EW2_YELLOW`:

- Remain in this state until the timer expires.
- When the timer expires, transition to `NS1_RED`.