

# EMBEDDED SENSING IN ELASTIC PASSIVE ACTUATORS



The City College  
of New York

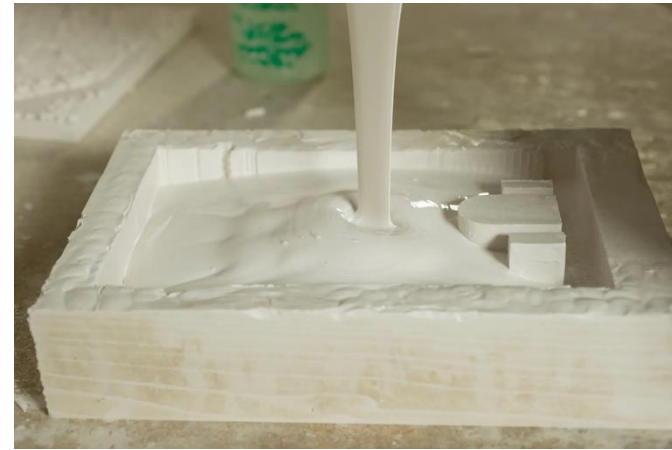


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# OBJECTIVE

Method of incorporating  
conductive material into an  
elastic material to reduce the  
need of an external sensor  
Determining an elastic +  
conductive material that can  
easily composited into a  
passive actuator for hip  
assistance during active  
motion



*Liquid latex molding Image source <https://www.artnews.com>*



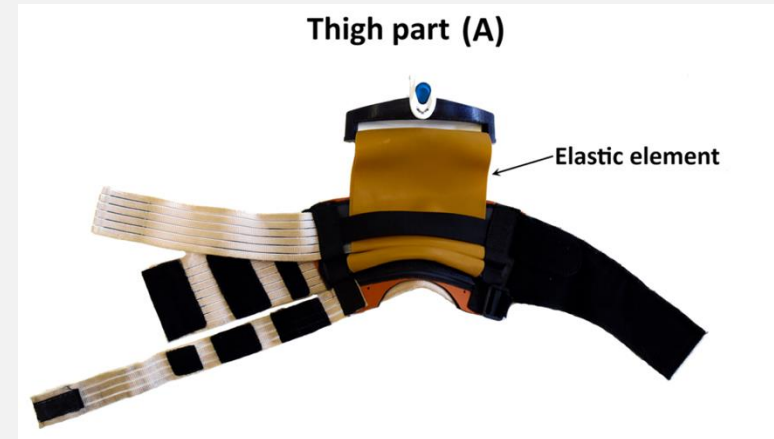
*Silicon Rubber. Image source:  
<http://www.teximinternational.com/product/silicon-rubber/>*

## DEVELOPING METHODOLOGY:

Review of existing technology for passive actuations and current embedded sensing technology to develop a novel prototype of both elements. A basic setup to achieve such goal will be developed to create a prototype as well as a method to test mechanical and conductive properties.

## CURRENT TECHNOLOGY

- Passive Actuators: use of elastic bands to support movement
- Use of external sensors for monitoring the assistance of an elastic band. Increases weight + cost of actuator



*Exoband components and their working principle. Waist belt (a) and thigh part Image source from Panizzolo, F., et. al.*

# CURRENT TECHNOLOGY

- Embedded sensors in an elastic material. Goal is to increase the force assistance of such material to be viable in use for walking.
- Active Actuators: more often explored. Use of powered actuators Ways to improve user experience by size/placements as well as ways to be more efficient in use of actuators has been and is still being explored



*Natural rubber/Pristine  $2.8E-7$  graphene composite strain sensor. Image source from Liu, H., Gao H., Hu, G.*



*Load Cell. Image source <https://www.vetek.com/>*

## MATERIALS SELECTIONS: 3D PRINTING

FDM printing – Creating molds to utilize different materials

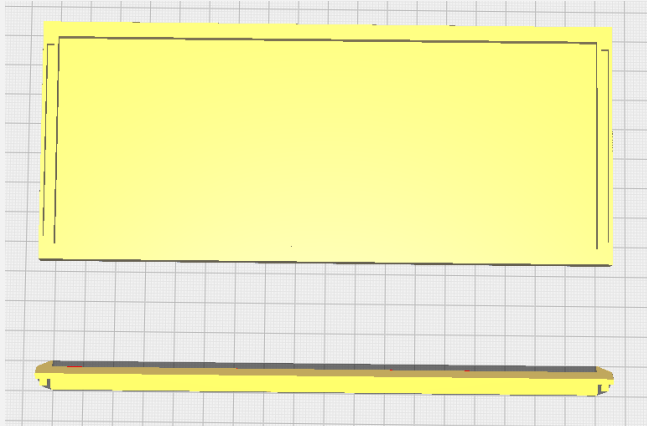
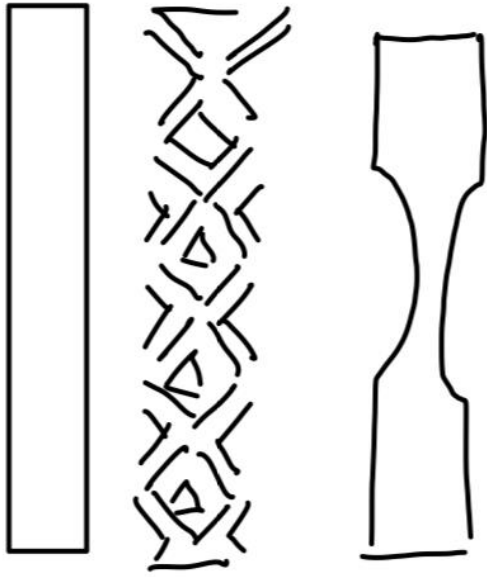
SLA Printer – allows for more detailed designs to be of high quality while allowing direct integration of conductive materials. Limited by properties of available resins



*Ultimaker Connect 2+ image source  
<https://ultimaker.com/3d-printers/s-series/ultimaker-2-connect/>*



*Saturn 3 Ultra image source  
<https://www.elegoo.com>*



## PROTOTYPING

The use of 3D Printing as a means of rapid prototyping. Mold used to easily change dimensions of the band. Future works include changing geometry within the molding process

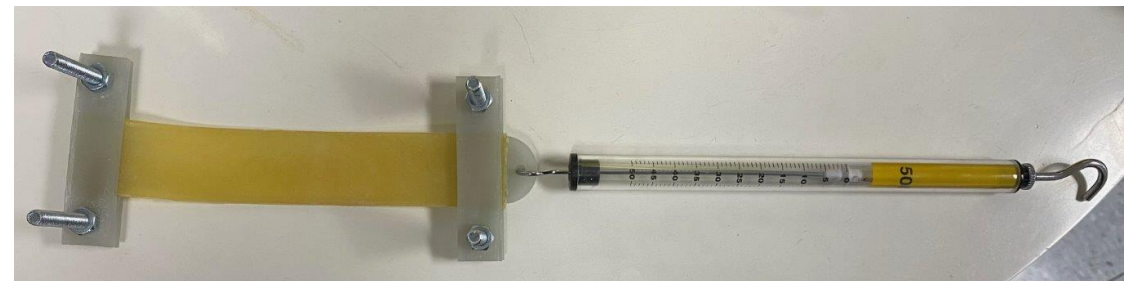
## MATERIAL SELECTION: ELASTIC MATERIALS

<b>Material</b>	<b>Elongation at Break</b>	<b>Max Tensile Strength (MPa)</b>	<b>Elastic modulus (GPa)</b>	<b>Tear Strength (N/mm)</b>	<b>Shore Hardness (A)</b>
TPU	200-1000 %	48-83	.001-.05	50-100	60-95
TPE	8-2000 %	2-56.5	0.0130-2.25	20-70	65-99
Elastic Resin	100-160%	1.61-3.4	0.03	10-30	40-85
Silicon Rubber	300-1500 %	0.135-165	0.0005-0.06	15-50	10-95
Latex	700-1100%	15-30	0.001-0.01	15-30	30-90



## ASSISTIVE FORCE TESTING

- Testing without Graphene determining the necessary band for required force. Serves as comparison for change due to graphene additives.
- Assumed parameters: provide an assisted for of 50 N



# INITIAL MECHANICAL PROPERTIES TESTING

Stiffness coefficient (K): 0.07384

N/mm

Elastic modulus (E): 0.08111 MPa

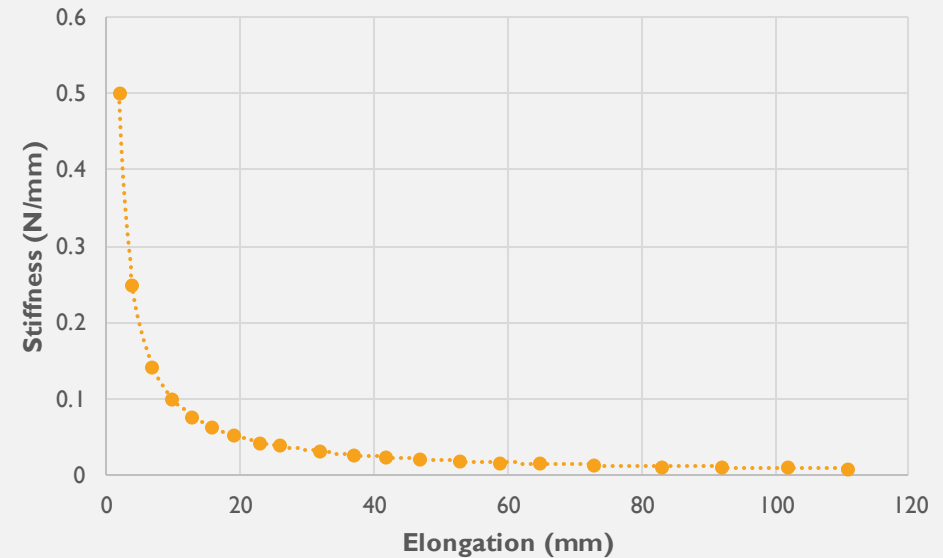
Elongation needed (Maximum  
flexure):

14 mm

Hooke's Law:  $\sigma = E\varepsilon$

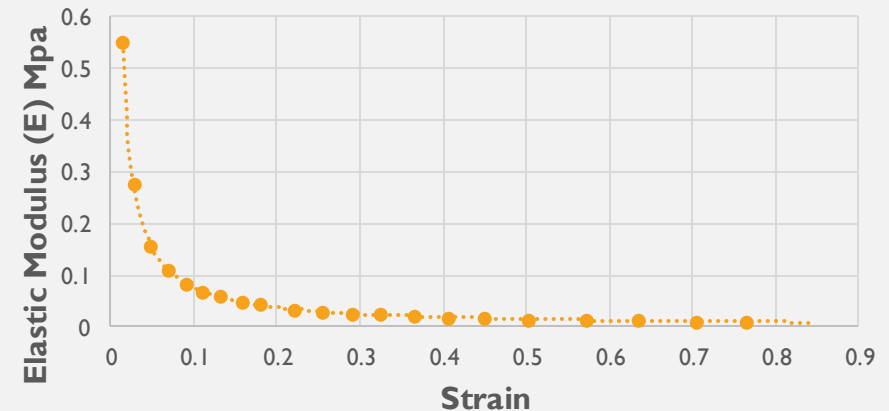
$$\frac{F}{A} = E \frac{\Delta L}{L}$$

Stiffness vs Elongation



Plot of slopes of Stiffness vs Elongation giving an average stiffness of 0.07384 N/mm

Elastic modulus vs Strain



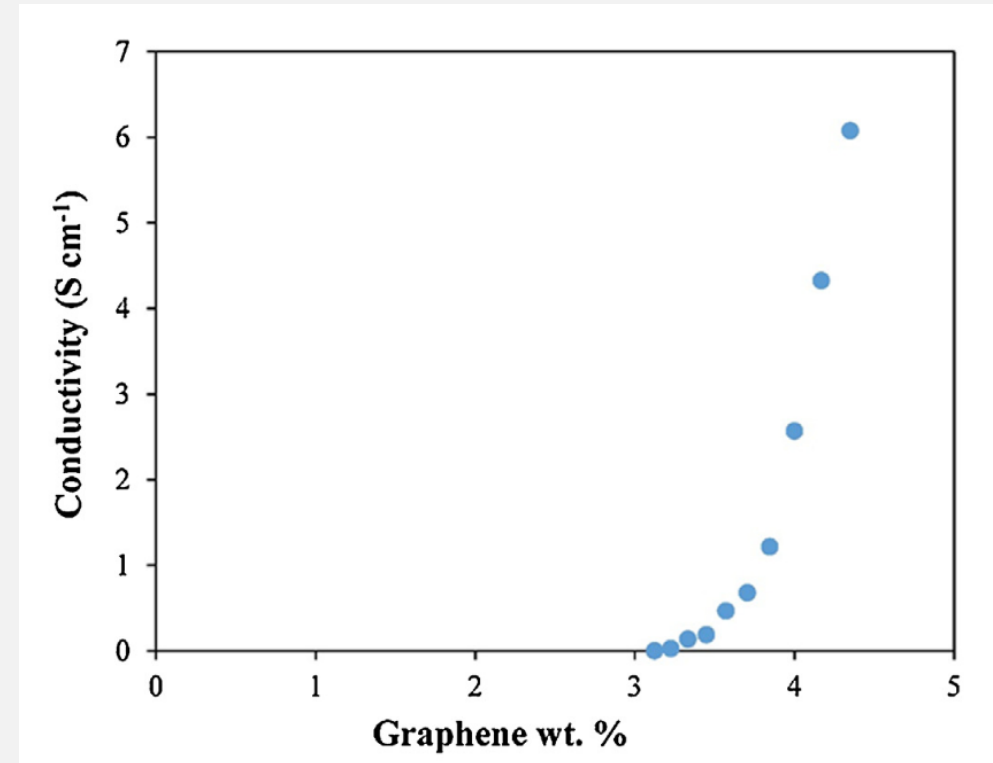
Plot of slopes of Elastic Modulus vs Strain giving an average Elastic Modulus: 0.08111 MPa

# CONDUCTIVE ADDITIVE - GRAPHENE

Changes properties of elastic materials – possible to increase mechanical properties the strongest, most electrically conductive

Different graphene loading will be tested to determine optimal mechanical and conductive properties

$$GF = \frac{\Delta R/R}{\varepsilon}$$



Conductivity of G/SR composites with different graphene wt. %, . Image source Kuriana, A. S., Mohana V. B., Bhattacharyya, D.

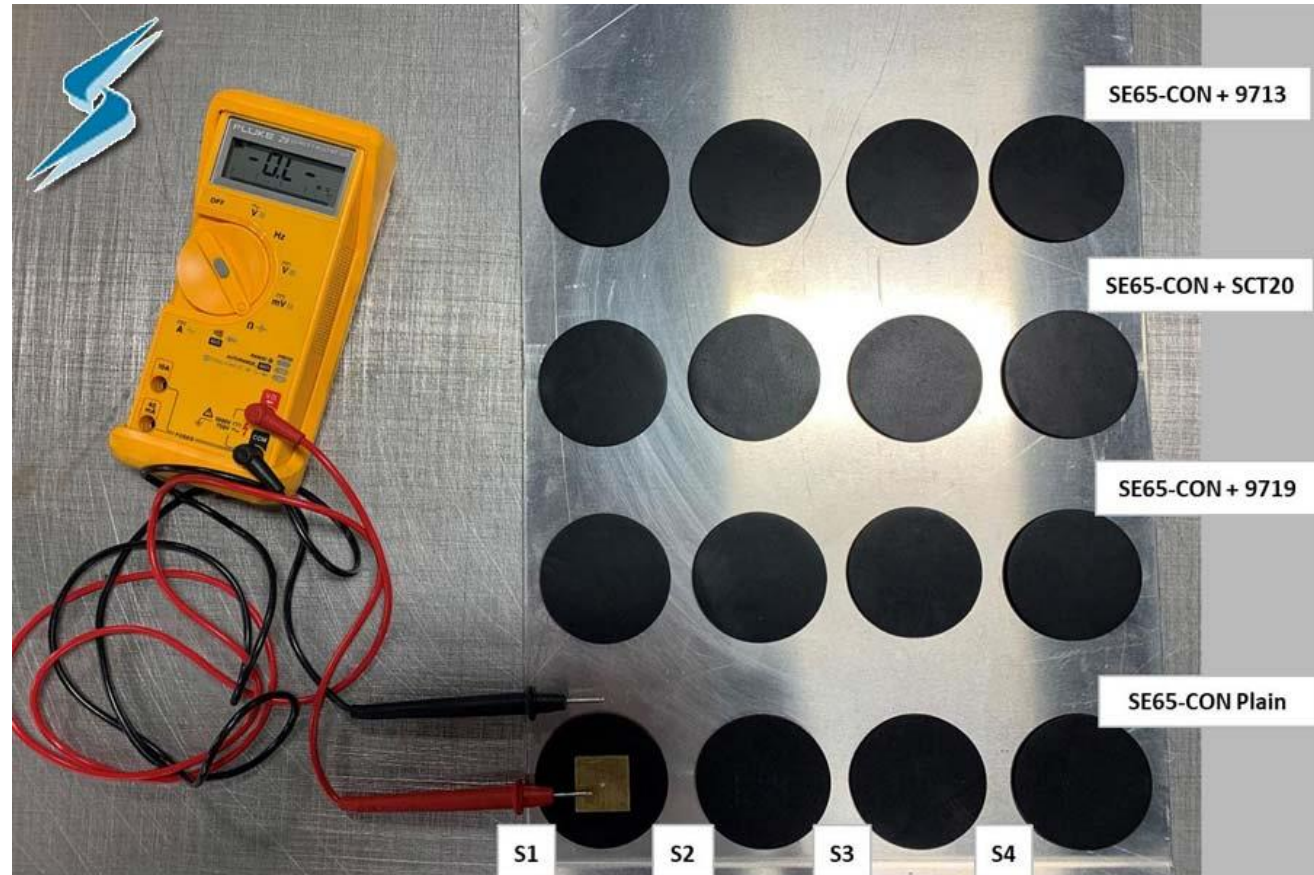


## FUTURE WORK

- Conductive testing of the composite materials and finding optimal graphene loading concentration.
- Variation in band configuration to change mechanical properties (assistive force based on geometry)

# CONDUCTIVITY TESTING

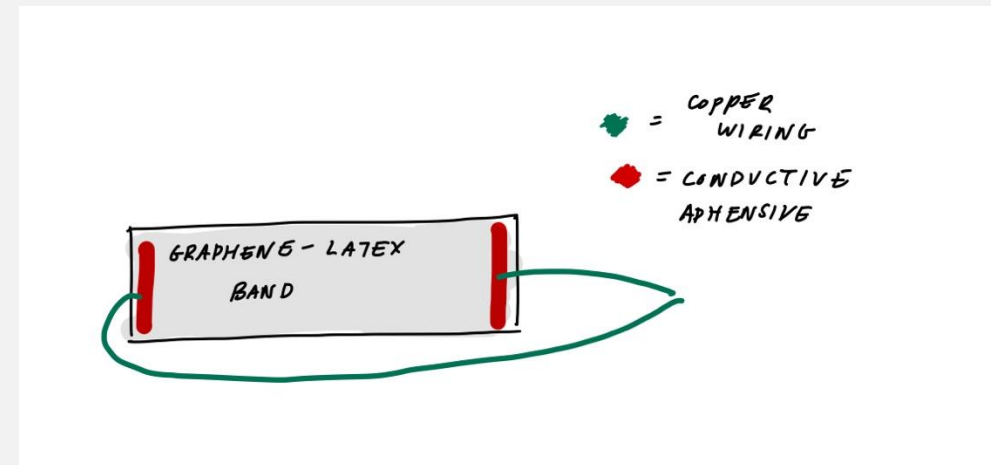
- Materials:
- Digital Voltage Meter
- Copper wiring
- Conductive adhesive



Conductive adhesive testing with digital voltage meter. Image source: Stockwell.com

# CONDUCTIVITY TESTING

- Conductive testing to determine proper graphene concentration.
- Use of adhesive for accounting for the stretching of passive actuator.
- Configuration setup to achieve linearity for analyzing the data.



Setup for future conductive testing of the graphene/latex band

PRESENTATION ENDING

Thank You



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