

Project 5 Pollution Vision

This manuscript ([permalink](#)) was automatically generated from [Saran-Wang/dsproject@8575815](#) on December 6, 2020.

Authors

- **Shiyuan Wang**

-  [Saran-Wang](#)

Department of Civil and Environmental, University of Illinois

- **Weiqi Ni**

-  [weiqini](#)

Department of Civil and Environmental, University of Illinois; Department of Environmental and Resources, Zhejiang University

- **Gemma Clark**

-  [441gclark](#)

Department of Civil and Environmental, University of Illinois

- **Xueao Li**

-  [XueaoLi](#)

Department of Civil and Environmental, University of Illinois

Abstract

Introduction

Literature review

There are many studies using digital camera and advanced algorithm to estimate the concentrations of Particulate Matters. Hong et al. [[1](#)] developed a novel method of predicting the concentrations and diameters of outdoor ultrafine particles using street-level images and audio data in Montreal, Canada. Convolutional neural networks, multivariable linear regression and generalized additive models were used to make the predictions.

Model

Shiyuan's model

My model setup splits into two part, the first is image data extraction, the second is the selection of appropriate model to fit this dataset.

Image Extraction

First I want to digitize images by extracting image features, there are mainly 6 features I want to extract: RGB, image luminance, image contrast, image entropy, transmission and amount of haze removed and number of cars on streets.

1. RGB

The RGB color model is one of the most straightforward parameters describing an image. Intuitively, in this case, we may expect more blueness and greenness if the PM concentrations are low since the color of tree and sky would be brighter when the air conditions are good. For each image, after deriving the RGB of each pixel, we take the average of them, and then divide each value by 255 to normalize it. The figure below [1](#) shows the distributions of RGB in this dataset. We can see that they are nearly normally distributed with mean 0.45, 0.55 and 0.35 respectively. For blueness, we could see a second peak at around 0.42.

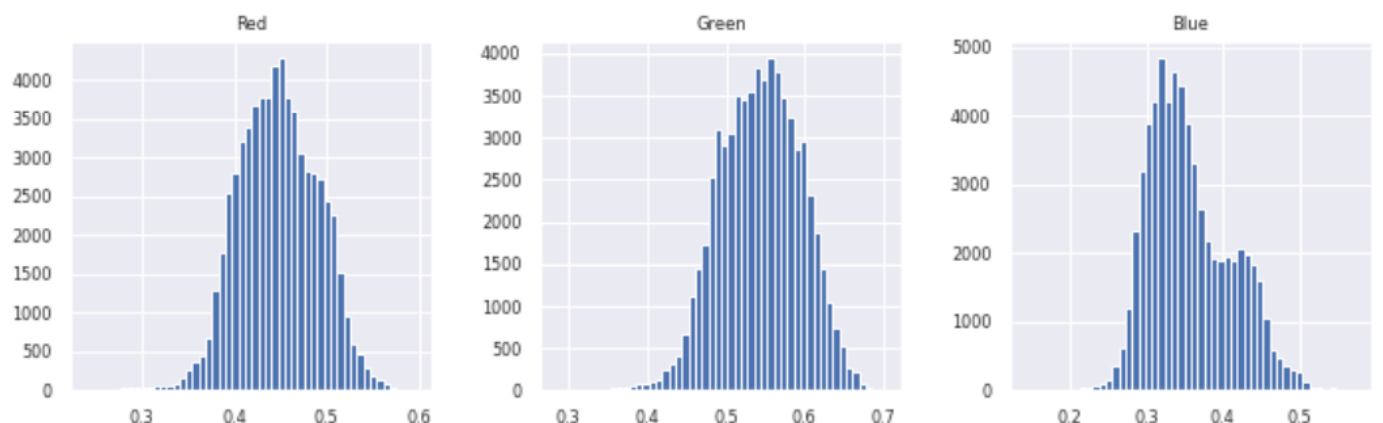


Figure 1: RGB Distribution Loaded from the latest version of image on GitHub.

2. Luminance
3. Contrast
4. Entropy
5. Transmission and amount of haze removed
6. Number of cars on streets

Model selection

Gemma's model

WeiQi's model

Xueao's model

Conclusion

References

1. **Predicting outdoor ultrafine particle number concentrations, particle size, and noise using street-level images and audio data**

Kris Y. Hong, Pedro O. Pinheiro, Scott Weichenthal

Environment International (2020-11) <https://doi.org/ghnh6n>

DOI: [10.1016/j.envint.2020.106044](https://doi.org/10.1016/j.envint.2020.106044) · PMID: [32805577](https://pubmed.ncbi.nlm.nih.gov/32805577/)