Multivariable Calculus and Linear Algebra

Sarang Mohaniraj

Contents

Ι	Mult	ivariable Calculus	1
11	Param	netric Equations and Polar Coordinates	2
	11.1	Curves Defined by Parametric Equations	2
	11.2	Calculus with Parametric Curves	3
	11.3	Polar Coordinates	9
	11.4	Areas and Lengths in Polar Coordinates	11
	11.5	Conic Sections	13
	11.6	Conic Sections in Polar Coordinates	17
12	Infinit	e Sequences and Series	20
	12.1	Sequences	20
	12.2	Series	26
	12.3	The Integral Test and Estimates of Sums	31
	12.4	The Comparison Tests	37
	12.5	Alternating Series	40
	12.6	Absolute Convergence and the Ratio and Root Tests	43
	12.7	Strategy for Testing Series	47
	12.8	Power Series	48
	12.9	Representation of Functions as Power Series	53
	12.10	Taylor and Maclaurin Series	56
	12.11	The Binomial Series	62
	12.12	Applications of Taylor Polynomials	64
13	Vector	rs and the Geometry of Space	66
	13.1	Three-Dimensional Coordinate Systems	66
	13.2	Vectors	69
	13.3	The Dot Product	72
	13.4	The Cross Product	72
	13.5	Equations of Lines and Planes	72
	13.6	Cylinders and Quadric Surfaces	72
	13.7	Cylindrical and Spherical Coordinates	72
14	Vector	Functions	73
	14.1	Vector Functions and Space Curves	73
	14.2	Derivatives and Integrals of Vector Functions	73

	••
CONTENTS	11
CONTENIO	11

II	Line	ear Algebra	78
	18.4	Series Solutions	77
	18.3	Applications of Second-Order Differential Equations	77
	18.2	Nonhomogenous Linear Equations	77
	18.1	Second-Order Linear Equations	77
18		d-Order Differential Equations	77
	a		
	17.10	Summary	76
	17.9	The Divergence Theorem	76
	17.8	Stokes' Theorem	76
	17.7	Surface Integrals	76
	17.6	Parametric Surfaces and Their Areas	76
	17.5	Curl and Divergence	76
	17.4	Green's Theorem	76
	17.3	THe Fundamental Theorem for Line Integrals	76
	17.2	Line Integrals	76
	17.1	Vector Fields	76
17	Vecto	r Calculus	76
	10.9	Change of variables in Multiple integrals	10
	16.9	Change of Variables in Multiple Integrals	75
	16.8	Triple Integrals in Cylindrical and Spherical Coordinates	75
	16.7	Triple Integrals	75 75
	16.6	Surface Area	75 75
	16.4 16.5	Applications of Double Integrals	75
	16.4	Double Integrals in Polar Coordinates	75
	16.2 16.3	Double Integrals over General Regions	75
	16.1 16.2	Iterated Integrals	75
10	16.1	Double Integrals over Rectangles	75
16	M11144	ple Integrals	75
	15.8	Lagrange Multipliers	74
	15.7	Maximum and Minimum Values	74
	15.6	Directional Derivatives and the Gradient Vector	74
	15.5	The Chain Rule	74
	15.4	Tangent Planes and Linear Approximations	74
	15.3	Partial Derivatives	74
	15.2	Limits and Continuity	74
	15.1	Functions of Several Variables	74
15		l Derivatives	74
	14.4	Motion in Space: Velocity and Acceleration	73
	14.3	Arc Length and Curvature	73

CONTENTS	iii
----------	-----

	1.1 1.2 1.3 1.4	The Geometry and Algebra of Vectors	79 79 79 79
2	System 2.1 2.2 2.3 2.4 2.5	Introduction to Systems of Linear Equations Direct Methods for Solving Linear Systems Spanning Sets and Linear Independence Applications Iterative Method for Solving Linear Systems	80 80 80 80 80
3	Matrice 3.1 3.2 3.3 3.4 3.5 3.6 3.7	Matrix Operations	81 81 81 81 81 81
4	4.1 4.2 4.3 4.4 4.5 4.6	values and Eigenvectors Introduction to Eigenvalues and Eigenvectors	82 82 82 82 82 82 82
5	Orthog 5.1 5.2 5.3 5.4 5.5	Gonality Orthogonality in \mathbb{R}^n . Orthogonal Complements and Orthogonal Projections. The Gram-Schmidt Process and the QR Factorization. Orthogonal Diagonalization of Symmetric Matrices. Applications	83 83 83 83 83
6	Vector 6.1 6.2 6.3 6.4 6.5 6.6 6.7	Vector Spaces and Subspaces	84 84 84 84 84 84 84
7	Distan	ce and Approximation	85

CONTENTS			
7.1	Inner Product Spaces	85	
7.2	Norms and Distance Function	85	
7.3	Least Squares Approximation	85	
7.4	The Singular Value Decomposition	85	
7.5	Applications	85	

Part I Multivariable Calculus

Chapter 11

Parametric Equations and Polar Coordinates

11.1 Curves Defined by Parametric Equations

Suppose that x and y are both given as functions of a third variable t (called a **parameter** by the equations)

$$x = f(t)$$
 $y = g(t)$

(called **parametric equations**). Each value of t determines a point (x,y). As t changes, (x,y) = (f(t),g(t)) changes and traces out a curve C, which is called a **parametric curve**. The direction of the arrows on curve C show the change in the position of the equation as t increases.

We can also restrict t to a finite interval. In general, the curve with parametric equations

$$x = f(t)$$
 $y = g(t)$ $a \le t \le b$

has initial point (f(a), g(a)) and terminal point (f(b), g(b)).

The Cycloid



Example 11.1.1. A circle with radius r rolls along the x-axis. The curve traced out by a point P on the circumference of the circle is called a **cycloid**. Find parametric equations for the cycloid.

Solution. We will use the angle of rotation θ as the parameter ($\theta = 0$ when P is at the origin).



Suppose the circle has rotated θ radians. Using the figure, the distance it has rolled from the origin is

$$|OT| = arc \ PT = r\theta$$

because P starts at the origin. Therefore, the center of the circle is $C(r\theta, r)$. Let the coordinates of P be (x, y). Then from the figure,

$$x = |OT| - |PQ| = r\theta - r\sin\theta = r(\theta - \sin\theta)$$
$$y = |TC| - |QC| = r - r\cos\theta = r(1 - \cos\theta)$$

Definition 11.1.1. Paremetric equations of the cycloid are

$$x = r(\theta - \sin \theta)$$
 $y = r(1 - \cos \theta)$

11.2 Calculus with Parametric Curves

We will mainly solve problems involving tangents, area, arc length, and surface area.

Tangents

In the previous section, we saw that some curves defined by parametric equations x = f(t) and y = g(t) can also be expressed, by eliminating the parameter, in the form y = F(x). If we substitute x = f(t) and y = g(t) in the equation y = F(x), we get

$$g(t) = F(f(t))$$

If g, f, and F are differentiable, the Chain Rule gives

$$g'(t) = F'(f(t))f'(t) = F'(x)f'(t)$$

If $f'(t) \neq 0$, we can solve for F'(x):

Definition 11.2.1. The slope of the tangent to the parametric curve y = F(x) is F'(x).

 $F'(x) = \frac{g'(t)}{f'(t)}$

This enables us to find tangents to parametric curves without having to eliminate the parameter. We can rewrite the previous equation in an easily remembered form.

Definition 11.2.2. We can use this to find tangents to parametric curves without having to eliminate the parameter.

$$\frac{dy}{dx} = \frac{\frac{dy}{dt}}{\frac{dx}{dt}} \quad \text{if} \quad \frac{dx}{dt} \neq 0$$

The curve has a

- \bullet horizontal tangent when $\frac{dy}{dt}=0$ (provided that $\frac{dx}{dt}\neq 0)$
- vertical tangent when $\frac{dx}{dt} = 0$ (provided that $\frac{dy}{dt} \neq 0$)

This is useful when sketching parametric curves.

Definition 11.2.3. We can also find $\frac{d^2y}{dx^2}$ by replacing y with $\frac{dy}{dx}$

$$\frac{d^2y}{dx^2} = \frac{d}{dx}\left(\frac{dy}{dx}\right) = \frac{\frac{d}{dt}\left(\frac{dy}{dx}\right)}{\frac{dx}{dt}}$$

Proof. Find $\frac{dy}{dx}$ and $\frac{d^2y}{dx^2}$ considering y(t) and g(t).

1.

Chain rule:
$$\frac{dy}{dt} = \frac{dy}{dx} \frac{dx}{dt} \implies \frac{dy}{dx} = \frac{\frac{dy}{dt}}{\frac{dx}{dt}}$$
 (\implies means "implies")

2.

Chain rule:
$$\frac{d}{dt} \left(\frac{dy}{dx} \right) = \left(\frac{d}{dx} \frac{dy}{dx} \right) \frac{dx}{dt} = \frac{d^2y}{dx^2} \frac{dx}{dt}$$

Substitute: $\frac{d}{dt} \left(\frac{dy}{dx} \right) = \frac{d}{dt} \left(\frac{\frac{dy}{dt}}{\frac{dx}{dt}} \right)$

Quotient rule: $= \frac{\frac{d^2y}{dt^2} \frac{dx}{dt} - \frac{dy}{dt} \frac{d^2x}{dt^2}}{\left(\frac{dx}{dt} \right)^2}$

Set equation from line 1 and line 3 equal and divide both sides by $\frac{dx}{dt}$

$$\frac{d^2y}{dx^2} = \frac{\frac{d^2y}{dt^2}\frac{d^x}{dt} - \frac{dy}{dt}\frac{d^2x}{dt^2}}{\left(\frac{dx}{dt}\right)^2\left(\frac{dx}{dt}\right)}$$
$$= \frac{\frac{d^2y}{dt^2}\frac{d^x}{dt} - \frac{dy}{dt}\frac{d^2x}{dt^2}}{\left(\frac{dx}{dt}\right)^3}$$

Example 11.2.1. A curve C is defined by the parametric equations $x = t^2$, $y = t^3 - 3t$.

- 1. Show that C has two tangents at the point (3,0) and find their equations.
- 2. Find the points on C where the tangent is horizontal or vertical.
- 3. Determine where the curve is concave upward or downward.

Solution. A curve C is defined by the parametric equations $x = t^2$, $y = t^3 - 3t$.

1. Rewrite $y = t^3 - 3t = t(t^2 - 3) = 0$ when t = 0 or $t = \pm \sqrt{3}$. This indicates that C intersects itself at (3.0).

$$\frac{dy}{dx} = \frac{dy/dt}{dx/dt} = \frac{3t^2 - 3}{2t} = \frac{3}{2}\left(t - \frac{1}{t}\right)$$
$$t = \pm\sqrt{3} \rightarrow dy/dx = \pm 6/(2\sqrt{3})$$

so the equations of the tangents at (3,0) are

$$y = \sqrt{3}(x-3)$$
 and $y = -\sqrt{3}(x-3)$

- 2. C has a horizontal tangent when dy/dx = 0. In other words, when dy/dt = 0 and $dx/dt \neq 0$. $dy/dt = 3t^2 3 = 0$ when $t^2 = 1$ so $t = \pm 1$. This means there are horizontal tangents on C at (1,-2) and (1,2). C has a vertical tangent when dx/dt = 2t = 0, so t = 0. This means C has a vertical tangent at (0,0).
- 3. To determine concavity we calculate the second derivative:

$$\frac{d^2y}{dx^2} = \frac{\frac{d}{dt}\left(\frac{dy}{dx}\right)}{\frac{dx}{dt}} = \frac{\frac{3}{2}\left(1 + \frac{1}{t^2}\right)}{2t} = \frac{3(t^2 + 1)}{4t^3}$$

The curve is concave upward when t > 0 and concave downward when t < 0.

Area

We already know that area under a curve y = F(x) from a to b is $A = \int_a^b F(x) dx$. We can apply this to parametric equations using the Substitution Rule for Definite Integrals.

Definition 11.2.4. If the curve C is given by parametric equations x = f(t) and y = g(t) and t increases from α to β ,

$$A = \int_{a}^{b} y dx = \int_{\alpha}^{\beta} g(t) f'(t) dt$$

(Switch α to β if the point on C at β is more left than α .

Example 11.2.2. Find the area under one arch of the cycloid $x = r(\theta - \sin \theta)$, $y = r(1 - \cos \theta)$.

Solution. One arch of the cycloid is given by $0 \le \theta \le 2\pi$. Using the Substitution Rule with $y = r(1 - \cos \theta)$ and $dx = r(1 - \cos \theta)d\theta$, we have

$$A = \int_0^{2\pi} y dx = A = \int_0^{2\pi} r(1 - \cos \theta) r(1 - \cos \theta) d\theta$$

$$= r^2 \int_0^{2\pi} (1 - \cos \theta)^2 d\theta = r^2 \int_0^{2\pi} (1 - 2\cos \theta + \cos^2 \theta) d\theta$$

$$= r^2 \int_0^{2\pi} \left[1 - 2\cos \theta + \frac{1}{2} (1 + \cos 2\theta) \right] d\theta$$

$$= r^2 \left[\frac{3}{2} \theta - 2\sin \theta + \frac{1}{4} \sin 2\theta \right]_0^{2\pi}$$

$$= r^2 \left(\frac{3}{2} \cdot 2\pi \right) = 3\pi r^2$$

Arc Length

We already know how to find length L of a curve C given in the form y = F(x), $a \le x \le b$.

Definition 11.2.5. If F' is continuous, then

$$L = \int_{a}^{b} \sqrt{1 + \left(\frac{dy}{dx}\right)^{2} dx}$$

If C can describe the parametric equations x = f(t) and y = g(t), $\alpha \le t \le \beta$, where dx/dt = f'(t) > 0. Using the substitution rule, we obtain

$$L = \int_{a}^{b} \sqrt{1 + \left(\frac{dy}{dx}\right)^{2} dx} = \int_{\alpha}^{\beta} \sqrt{1 + \left(\frac{dy/dt}{dx/dt}\right)^{2} \frac{dx}{dt} dt}$$

Since dx/dt > 0, we have

Theorem 11.2.1. If a curve C is described by the parametric equations x = f(t), y = g(t), $\alpha \le t \le \beta$, where f' and g' are continuous on $[\alpha, \beta]$ and C is traversed exactly once as t increases from α to β , then the length of C is

$$L = \int_{\alpha}^{\beta} \sqrt{\left(\frac{dx}{dt}\right)^2 + \left(\frac{dy}{dt}\right)^2} dt$$

This is consistent with the general formula $L = \int ds$ and $(ds^2) = (dx^2) + (dy^2)$.

Proof. Prove the length formula of a parametric curve

$$\overrightarrow{ds} = \overrightarrow{i} dx + \overrightarrow{j} dy$$

$$ds^2 = \overrightarrow{ds} \cdot \overrightarrow{ds} = \left(\overrightarrow{i} dx + \overrightarrow{j} dy\right) \cdot \left(\overrightarrow{i} dx + \overrightarrow{j} dy\right) = dx^2 + dy^2$$

$$ds = \sqrt{dx^2 + dy^2} = \sqrt{\left(\frac{dx}{dt}\right)^2 + \left(\frac{dy}{dt}\right)^2} dt$$

$$L = \int_{\alpha}^{\beta} ds = \int_{\alpha}^{\beta} \sqrt{\left(\frac{dx}{dt}\right)^2 + \left(\frac{dy}{dt}\right)^2} dt$$

Example 11.2.3. Find the length of the unit circle as (x,y) moves both once and twice around the circle.

Solution. For one traversal around the unit circle,

$$x = \cos t$$
 $y = \sin t$ $0 \le t \le 2\pi$

so $dx/dt = -\sin t$ and $dy/dt = \cos t$

$$L = \int_0^{2\pi} \sqrt{\left(\frac{dx}{dt}\right)^2 + \left(\frac{dy}{dt}\right)^2} dt = \int_0^{2\pi} \sqrt{\sin^2 t + \cos^2 t} dt$$
$$= \int_0^{2\pi} dt = 2\pi$$

For two traversals around the unit circle,

$$x = \sin 2t$$
 $y = \cos 2t$ $0 \le t \le 2\pi$

so $dx/dt = 2\cos 2t$ and $dy/dt = -2\sin 2t$

$$L = \int_0^{2\pi} \sqrt{\left(\frac{dx}{dt}\right)^2 + \left(\frac{dy}{dt}\right)^2} dt = \int_0^{2\pi} \sqrt{4\cos^2 2t + 4\sin^2 2t} \ dt = \int_0^{2\pi} 2 \ dt = 4\pi$$

Surface Area

We can also adapt the surface area formula to a parametric curve.

Definition 11.2.6. If a curve C is described by the parametric equations $x = f(t), y = g(t), \alpha \le t \le \beta$, is rotated about the **x-axis**, where f', g' are continuous and $g(t) \ge 0$, the surface area is

$$S = \int_{\alpha}^{\beta} 2\pi y \sqrt{\left(\frac{dx}{dt}\right)^2 + \left(\frac{dy}{dt}\right)^2} dt$$

If the curve C is rotated about the **y-axis**, the surface area is

$$S = \int_{\alpha}^{\beta} 2\pi x \sqrt{\left(\frac{dx}{dt}\right)^2 + \left(\frac{dy}{dt}\right)^2} dt$$

The generic formulas $S = \int 2\pi y \ ds$ for rotation about the x-axis and $S = \int 2\pi x \ ds$ for rotation about the y-axis are still valid, but for parametric curves we use

$$ds = \sqrt{\left(\frac{dx}{dt}\right)^2 + \left(\frac{dy}{dt}\right)^2} dt$$

Example 11.2.4. Show that the surface area of a sphere of radius r is $4\pi r^2$

Solution. The sphere is obtained by rotating the semicircle

$$x = r \cos t$$
 $y = r \sin t$ $0 \le t \le \pi$

about the x-axis.

$$S = \int_0^{\pi} 2\pi r \sin t \sqrt{(-r\sin t)^2 + (r\cos t)^2} dt$$

$$= 2\pi \int_0^{\pi} r \sin t \sqrt{r^2 (\sin^2 t + \cos^2 t)} dt$$

$$= 2\pi \int_0^{\pi} r \sin t \cdot r dt = 2\pi r^2 \int_0^{\pi} \sin t dt$$

$$= 2\pi r^2 (-\cos t) \Big|_0^{\pi} = 4\pi r^2$$

11.3 Polar Coordinates

In addition to Cartisian coordinates, we can also use a **polar coordinate system**.



Point P is represented by the ordered pair (r, θ) , where r is the distance to the point from the center and θ is the angle from the polar axis to the point.

The points (r, θ) and $(-r, \theta)$ are on the same line and have the same distance |r| from the center but are on opposite sides of the center. Additionally, $(-r, \theta)$ and $(r, \theta + \pi)$ are also on the same line.

This means a complete counterclockwise rotation is given by an angle 2π , so (r,θ) is also represented by

$$(r, \theta + 2n\pi)$$
 and $(-r, \theta + (2n+1)\pi)$

Relationship Between Cartesian and Polar Coordinates



Example 11.3.1. Convert the point $(2, \pi/3)$ from polar to Cartesian coordinates.

Solution.

$$r=2,\;\theta=\pi/3$$

$$x=r\cos\theta=2\cos\frac{\pi}{3}=2\cdot\frac{1}{2}=1$$

$$y=r\sin\theta=2\sin\frac{\pi}{3}=2\cdot\frac{\sqrt{3}}{2}=\sqrt{3}$$

So the point is $(1, \sqrt{3})$ in Cartesian coordinates.

Example 11.3.2. Represent the Cartesian coordinates (1, -1) in polar coordinates.

Solution.

$$r = \sqrt{x^2 + y^2} = \sqrt{1^2 + (-1)^2} = \sqrt{2}$$
$$\tan \theta = \frac{y}{x} = -1$$

Since the point (1,-1) lies in the fourth quadrant, we can choose $\theta = -pi/4$ or $\theta = 7pi/4$. So the possible answers are either $(\sqrt{2}, -\pi/4 \text{ or } (\sqrt{2}, 7\pi/4.$

Polar Curves

The graph of a polar equation $r = f(\theta)$, or $F(r, \theta) = 0$, consists of all of the points where (r, θ) satisfies the equation.

Tangents to Polar Curves

To find a tangent line to a polar curce $r = f(\theta)$, we regard θ as a parameter and write the parametric equations as

$$x = r\cos\theta = f(\theta)\cos\theta$$
 $y = r\sin\theta = f(\theta)\sin\theta$

So

Definition 11.3.1.

$$\frac{dy}{dx} = \frac{\frac{dy}{d\theta}}{\frac{dx}{d\theta}} = \frac{\frac{dy}{d\theta}\sin\theta + r\cos\theta}{\frac{dr}{d\theta}\cos\theta - r\sin\theta}$$

- horizontal tangent when $\frac{dy}{d\theta}=0$ (provided that $\frac{dx}{d\theta}\neq 0$)
- vertical tangent when $\frac{dx}{d\theta} = 0$ (provided that $\frac{dy}{d\theta} \neq 0$)

Note tangent lines at the pole have r=0 and the slope of the tangent simplifies to

$$\frac{dy}{dr} = \tan\theta \text{ if } \frac{dr}{d\theta} \neq 0$$

Example 11.3.3. For the cardiod $r = 1 + \sin \theta$, find the slope of the tangent line when r=3

Solution.

$$\begin{split} r &= 1 + \sin \theta \\ \frac{dy}{dx} &= \frac{\frac{dy}{d\theta} \sin \theta + r \cos \theta}{\frac{dr}{d\theta} \cos \theta - r \sin \theta} = \frac{\cos \theta \sin \theta + (1 + \sin \theta) \cos \theta}{\cos \theta \cos \theta - (1 + \sin \theta) \sin \theta} \\ &= \frac{\cos \theta (1 + 2 \sin \theta)}{1 - 2 \sin^2 \theta - \sin \theta} = \frac{\cos \theta (1 + 2 \sin \theta)}{(1 + \sin \theta)(1 - \sin \theta)} \end{split}$$

The slope of the tangent where $\theta = \pi/3$ is

$$\frac{dy}{dx} \Big|_{\theta=\pi/3} = \frac{\cos(\pi/3)(1+2\sin(\pi/3))}{(1+\sin(\pi/3))(1-\sin(\pi/3))}$$

$$= \frac{\frac{1}{2}(1+\sqrt{3})}{(1+\sqrt{3}/2)(1-\sqrt{3})} = \frac{1+\sqrt{3}}{(2+\sqrt{3})(1-\sqrt{3})}$$

$$= \frac{1+\sqrt{3}}{-1-\sqrt{3}} = -1$$

NOTE Instead of memorizing the equation, we can instead use the same method we used to derive it.

$$x = r\cos\theta = (1+\sin\theta)\cos\theta = \cos\theta + \frac{1}{2}\sin 2\theta$$
$$y = r\sin\theta = (1+\sin\theta)\sin\theta = \sin\theta + \sin^2\theta$$
$$\frac{dy}{dx} = \frac{dy/d\theta}{dx/d\theta} = \frac{\cos\theta + 2\sin\theta\cos\theta}{-\sin\theta + \cos 2\theta} = \frac{\cos\theta + \sin 2\theta}{-\sin\theta + \cos 2\theta}$$

This is equivalent to the previous equation.

11.4 Areas and Lengths in Polar Coordinates

Area

We can determine the formula for the area of a region whose boundary is given by a polar equation by taking the limit of a Riemann Sum starting with the formula for the area of a sector of a circle $A = \frac{1}{2}r^2\theta$.

Definition 11.4.1. The formula for the area A of the polar region \mathcal{R} is

$$A = \int_a^b \frac{1}{2} [f(\theta)]^2 \ d\theta = \int_a^b \frac{1}{2} r^2 d\theta$$

with the understanding that $r = f(\theta)$.

Example 11.4.1. Find the area enclosed by one loop of the four-leaved rose $r = 2\cos 2\theta$.

Solution. The right loop rotates from $\theta = -\pi/4$ to $\theta = \pi/4$.

$$A = \int_{-\pi/4}^{\pi/4} \frac{1}{2} r^2 d\theta = \frac{1}{2} \int_{-\pi/4}^{\pi/4} \cos^2 2\theta \ d\theta$$
$$= \int_0^{\pi/4} \cos^2 2\theta \ d\theta = \int_0^{\pi/4} \frac{1}{2} (1 + \cos 4\theta) \ d\theta$$
$$= \frac{1}{2} [\theta + \frac{1}{4} \sin 4\theta] = \pi/8$$

We can also adapt the formula to find the area of a region bounded by two polar curves.

Definition 11.4.2. Let \mathcal{R} be a region that is bounded by curves with polar equations $r = f(\theta)$, $r = g(\theta)$, $\theta = a$, and $\theta = b$, where $f(\theta) \geq g(\theta) \geq 0$ and $0 < b - a \leq 2\pi$. The area A of \mathcal{R} is found by subtracting the area inside $r = g(\theta)$ from the area inside $r = f(\theta)$, so

$$A = \int_{a}^{b} \frac{1}{2} [f(\theta)]^{2} d\theta - \int_{a}^{b} \frac{1}{2} [g(\theta)]^{2} d\theta$$
$$= \int_{a}^{b} \frac{1}{2} ([f(\theta)]^{2} - [g(\theta)]^{2}) d\theta$$

Arc Length

To find the length of a polar curve $r=f(\theta),\ a\leq \theta\leq b,$ we regard θ as a parameter and write the parametric equations of the curve as

$$x = r \cos \theta = f(\theta) \cos \theta$$
 $y = r \sin \theta = f(\theta) \sin \theta$

Using the projecut Rule and differentiating with respect to θ , we obtain

$$\frac{dx}{d\theta} = \frac{dr}{d\theta}\cos\theta - r\sin\theta \qquad \frac{dy}{d\theta} = \frac{dr}{d\theta}\sin\theta + r\cos\theta$$

so, using $\cos^2 \theta + \sin^2 \theta = 1$, we have

$$\left(\frac{dx}{d\theta}\right)^2 + \left(\frac{dy}{d\theta}\right)^2 = \left(\frac{dr}{d\theta}\right)^2 \cos^2\theta - 2r\frac{dr}{d\theta}\cos\theta\sin\theta + r^2\sin^2\theta$$
$$+ \left(\frac{dr}{d\theta}\right)^2 \sin^2\theta + 2r\frac{dr}{d\theta}\sin\theta\cos\theta + r^2\cos^2\theta$$
$$= \left(\frac{dr}{d\theta}\right)^2 + r^2$$

Assuming that f' is continuous, we can use the theorem from 11.2 about the arc length of a curve defined by parametric equations to write the arc length as

$$L = \int_{a}^{b} \sqrt{\left(\frac{dx}{d\theta}\right)^{2} + \left(\frac{dy}{d\theta}\right)^{2}} \ d\theta$$

Definition 11.4.3. The length of a curve with polar equation $r = f(\theta), \ a \le \theta \le b$, is

$$L = \int_{a}^{b} \sqrt{r^2 + \left(\frac{dr}{d\theta}\right)^2} \ d\theta$$

Example 11.4.2. Find the arc length of the cardiod $r = 1 + \sin \theta$.

Solution. The full length of the cardiod is given by the parameter interval $0 \le \theta \le 2\pi$.

$$L = \int_0^{2\pi} \sqrt{r^2 + \left(\frac{dr}{d\theta}\right)^2} d\theta = \int_0^{2\pi} \sqrt{(1+\sin\theta)^2 + \cos^2\theta} d\theta$$
$$= \int_0^{2\pi} \sqrt{2+2\sin\theta} d\theta = 8 \text{ (by rationalizing the integrand by } \sqrt{2-2\sin\theta})$$

11.5 Conic Sections

Parabolas, ellipses, and hyperbolas are called **conic sections**, or **conics**, because they result from intersecting a cone with a plane.



Parabolas

A **parabola** is the set of points in a plane that are equidistant from a fixed point F (called the **focus**) and a fixed line (called the **directrix**). The halfway point between the focus and directrix is on the parabola and is called the **vertex**. The line through the focus and the vertex and perpendicular to the directrix is the **axis** of the parabola.



As seen in the figure, the focus is always inside the region of the parabola and the directrix is the same distance away on the opposite side.

Definition 11.5.1. An equation of the parabola with focus (0, p) and directrix y = -p is

$$x^2 = 4py$$

. If we set $a=\frac{1}{4p}$, then the standard equation of a parabola is $y=ax^2$. This opens upward if p>0 and downard if p<0, and is symmetric with respect to the y-axis.

Definition 11.5.2. If we switch x and y, we get

$$y^2 = 4px$$

(reflection about the diagonal line y=x). This parabola opens to the right if p > 0 and to the left if p < 0.

Definition 11.5.3. The vertex form of a parabola is

$$y = a(x - h)^2 + k$$

where (h, k) is the vertex of the parabola and x = h is the axis of symmetry. We can also switch x and y to get the vertex form of the rotated parabola.

Example 11.5.1. Find the focus and directrix of the parabola $y^2 + 10x = 0$.

Solution. We rewrite the equation as $y^2=-10x$. We know $y^2=4px$, so 4px=-10x and $p=-\frac{5}{2}$. Thus, the focus is $(p,0)=-\frac{5}{2},0)$ and the directrix is $x=\frac{5}{2}$.

Ellipses

An **ellipse** is the set of points in a plane surrounding two fixed focal points F_1 and F_2 such that the <u>sum</u> of the two distances to the focal points is a constant. Imagine tracing a line along the furthest path of a string stretched across two different points.

Definition 11.5.4. The ellipse

$$\frac{x^2}{a^2} + \frac{y^2}{b^2} = 1 \quad a \ge b \ge 0$$

has foci $(\pm c, 0)$, where $c^2 = a^2 - b^2$, and vertices $(\pm a, 0)$ (lies on x-axis).

The **vertices** are on the **major axis**, where a is the distance to the center of the ellipse from each vertex. This distance is greater than the distance from a **co-vertex** to the center of the ellipse, b. The co-vertices lie on the **minor axis**. Because the sum of the two distances from a point on the ellipse to the foci is a constant, the distance from a co-vertex to a focal point is also a. If the foci coincide, then c = 0, so a = b and the ellipse becomes a circle with radius r = a = b.

Definition 11.5.5. The ellipse

$$\frac{x^2}{b^2} + \frac{y^2}{a^2} = 1 \quad a \ge b \ge 0$$

has foci $(0, \pm c)$, where $c^2 = a^2 - b^2$, and vertices $(0, \pm a)$ (lies on y-axis).

Definition 11.5.6. The general form of a horizontal ellipse is

$$\frac{(x-h)^2}{h^2} + \frac{(y-h)^2}{a^2} = 1$$

where (h, k) is the center of the ellipse. The same transformation can be done to the standard form of a vertical ellipse.



Example 11.5.2. Find an equation of the ellipse with foci $(0, \pm 2)$ and vertices $(0, \pm 3)$.

Solution. This equation represents a vertical ellipse because the foci and vertices lie on the y-axis. The distance from a focal point to the center is c=2 and the distance from a vertex to the center is a=3. Then we obtain $b^2=a^2+c^2=9-4=5$, so the equation of the ellipse is

$$\frac{x^2}{b^2} + \frac{y^2}{a^2} = \frac{x^2}{5} + \frac{y^2}{9} = 1$$

Hyperbolas

An **ellipse** is the set of points in a plane surrounding two fixed focal points F_1 and F_2 such that the <u>difference</u> of the two distances to the focal points is a constant. The **transverse axis** is the axis of a hyperbola that passes through the two foci. The **conjugate axis** is perpendicular to the transverse axis and passes through the center of the hyperbola.



Definition 11.5.7. The hyperbola along a horizontal transverse axis

$$\frac{x^2}{a^2} - \frac{y^2}{b^2} = 1$$

has foci $(\pm c,0)$, where $c^2=a^2+b^2$, vertices $(\pm a,0)$ (lies on x-axis), and asymptotes $y=\pm \frac{b}{a}x$.

Definition 11.5.8. The hyperbola along a vertical transverse axis

$$\frac{y^2}{a^2} - \frac{x^2}{b^2} = 1$$

has foci $(0, \pm c)$, where $c^2 = a^2 + b^2$, vertices $(0, \pm a)$ (lies on y-axis), and asymptotes $y = \pm \frac{a}{b}x$.

Definition 11.5.9. The general form of a hyperbola along a horizontal transverse axis is

$$\frac{(x-h)^2}{h^2} - \frac{(y-h)^2}{a^2} = 1$$

where (h, k) is the center of the ellipse. The same transformation can be done to the standard form a hyperbola along a vertical transverse axis.

Example 11.5.3. Find the foci and asymptotes of the hyperbola $9x^2 - 16y^2 = 144$.

Solution. If we divide both sides of the equation by 144, it becomes

$$\frac{x^2}{16} - \frac{y^2}{9} = 1$$

which is a hyperbola along a horizontal transverse axis. Therefore, we get a=4 and b=3. Since $c^2=a^2+b^2=16+9=25, c=5$. The foci are $(\pm 5,0)$, and the asymptotes are $y=\pm \frac{3}{4}x$.

Example 11.5.4. Find the foci and asymptotes of the hyperbola $ax^2 - by^2 = r$ in terms of a, b, r.

Solution. We first put the equation in standard form to get

$$\frac{x^2}{\left(\sqrt{\frac{r}{a}}\right)^2} - \frac{y^2}{\left(\sqrt{\frac{r}{b}}\right)^2} = 1$$

which is a hyperbola along a horizontal transverse axis. The foci are at

$$(\pm c, 0) = \left(\pm \sqrt{\frac{r}{a} + \frac{r}{b}}, \ 0\right) = \left(\pm \sqrt{\frac{r(a+b)}{ab}}, \ 0\right)$$

the vertices are at $\left(\pm\sqrt{\frac{r}{a}},\ 0\right)$, and the asymptotes are at $y=\pm\left(\sqrt{\frac{a}{b}}\right)x$.

11.6 Conic Sections in Polar Coordinates

Theorem 11.6.1. Let F be a fixed point (called the **focus**) and l be a fixed line (called the **directrix**). Let e be a fixed positive number (called the **eccentricity**). The set of all points P in the plane such that

$$\frac{|PF|}{|Pl|} = e \quad \text{(the ratio of the distance from } F \text{ to the distance from } l \text{ is the constant e)}$$

is a conic section. The conic is

- 1. an ellipse if e < 1
- 2. a parabola if e=1
- 3. a hyperbola if e > 1



Theorem 11.6.2. A polar equation of the form

$$r = \frac{ed}{1 \pm e \cos \theta}$$
 or $r = \frac{ed}{1 \pm e \sin \theta}$

represents a conic section with eccentricity e and distance d from the center to the directrix, with the focus at the origin. The conic is an ellipse if e < 1, a parabola if e = 1, or a hyperbola is e > 1.

Polar Equation for a Conic with Eccentricity e



To use these polar equations, a focus is located at the origin.

Use " $\cos \theta$ " when the conic section opens rightward or leftward, and use " $\sin \theta$ " when the conic section opens upward or downward. Use "+" if the conic section opens leftward or downward, and use "-" if the conic section opens rightward or upward.

Example 11.6.1. Find a polar equation for a parabola that has its focus at the origin and whose directrix is the line y = -6.

Solution. The eccentricity e=1 because the conic section is a parabola, and the distance from the center to the directrix is d=6. The directrix is on the y-axis and is underneath the center, so the parabola opens upward. Therefore, we use the "sin θ " equation and use "-" in the denominator. The polar equation of the parabola is

$$r = \frac{6}{1 - \sin \theta}$$

Example 11.6.2. A conic is given by the polar equation

$$r = \frac{10}{3 - 2\cos\theta}$$

Find the eccentricity, identify the conic, and locate the directrix.

Solution. Divide the numerator and denominator by 3 to get

$$r = \frac{\frac{10}{3}}{1 - \frac{2}{3}\cos\theta}$$

This represents an ellipses with eccentricity $e = \frac{2}{3}$. Since $ed = \frac{10}{3}$,

$$d = \frac{\frac{10}{3}}{e} = \frac{\frac{10}{3}}{\frac{2}{3}} = 5$$

so the directrix has Cartesian equation x=-5. When $\theta=0,\ r=10$; when $\theta=\pi,\ r=2$, so the vertices have polar coordinates (10,0), and $(2,\pi)$.

Chapter 12

Infinite Sequences and Series

12.1 Sequences

A sequence can be thought of as a list of numbers written in a definite order:

$$a_1, a_2, a_3, a_4, \ldots, a_n, \ldots$$

The number a_1 is the *first term*, a_2 is the *second term*, and in general a_n is the *nth term*. We will deal with infinite sequences exclusively so each term a_n will have a successor $a_n + 1$.

Notice that for every positive integer n there is a corresponding number a_n so a sequence can be defined as a function whose domain is the set of positive integers. We usually write a_n instead of the function notation f(n).

NOTATION The sequence a_1, a_2, a_3, \ldots is also denoted by

$$a_n$$
 or $a_{n} = 1$

Example 12.1.1. Some sequences can be defined by giving a formula for the nth term. In this example, we will describe a sequence in 3 ways: the previous notation, defining a formula, and writing out the terms of the sequence. Note that n doesn't have to start at 1.

1.
$$\left\{ \frac{n}{n+1} \right\}_{n=1}^{\infty} \quad a_n = \frac{n}{n+1} \quad \left\{ \frac{1}{2}, \frac{2}{3}, \frac{3}{4}, \frac{4}{5}, \dots, \frac{n}{n+1}, \dots \right\}$$

2.

$$\left\{ \frac{(-1)^n(n+1)}{3^n} \right\} \quad a_n = \frac{(-1)^n(n+1)}{3^n} \quad \left\{ -\frac{2}{3}, \ \frac{3}{9}, \ -\frac{4}{27}, \ \frac{5}{81}, \dots, \ \frac{(-1)^n(n+1)}{3^n}, \dots \right\}$$

3.

$$\{\sqrt{n-3}\}_{n=3}^{\infty}$$
 $a_n = \sqrt{n-3}, \ n \ge 3 \ \{0, 1, \sqrt{2}, \sqrt{3}, \dots, \sqrt{n-3}, \dots\}$

4.

$$\left\{\cos\frac{n\pi}{6}\right\}_{n=0}^{\infty} \quad a_n = \cos\frac{n\pi}{6}, \ n \ge 0 \quad \left\{1, \ \frac{\sqrt{3}}{2}, \ \frac{1}{2}, \ 0, \dots, \ \cos\frac{n\pi}{6}, \dots\right\}$$

Example 12.1.2. Find a formula for the general term a_n of the sequence

$$\left\{\frac{3}{5}, -\frac{4}{25}, \frac{5}{125}, -\frac{6}{625}, \frac{7}{3125}, \ldots\right\}$$

Solution. We are given the first five terms. The numerator of the fractions start at 3 and increase by 1, so the nth term will have numerator n + 1. The denominators are the powers of 5, so a_n has denominator 5^n . The signs of the terms alternate between positive and negative, so we need to multiply by a power of 1. The factor $(-1)^n$ means we start with a negative term, so here we use $(-1)^{n-1}$ or $(-1)^{n+1}$ because we start with a positive term. Therefore,

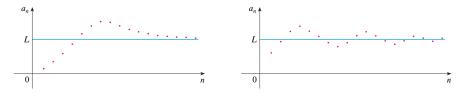
$$a_n = (-1)^{n-1} \frac{n+2}{5^n}$$

Definition 12.1.1. A sequence $\{a_n\}$ has the **limit** L and we write

$$\lim_{n \to \infty} a_n = L \qquad \text{or} \qquad a_n \to L \text{ as } n \to \infty$$

if we can make the terms a_n as close to L as we like by taking n sufficiently large. If $\lim_{n\to\infty} a_n$ exists, we say the sequence **converges** (or is **convergent**). Otherwise, we say the sequence **diverges** (or is **divergent**).

The figure below graphs examples of two sequences that have the limit L.



A more precise version of the previous definition is

Definition 12.1.2. A sequence $\{a_n\}$ has the **limit** L and we write

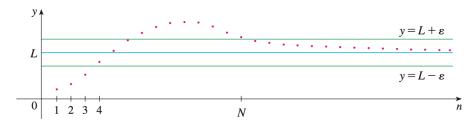
$$\lim_{n \to \infty} a_n = L \quad \text{or} \quad a_n \to L \text{ as } n \to \infty$$

if for every $\varepsilon > 0$ there is a corresponding integer N such that

$$|a_n - L| < \varepsilon$$
 whenever $n > N$

No matter how small an interval $(L - \varepsilon L + \varepsilon)$ is chosen, there exists an N such that all terms of the sequence from a_{N+1} onward must lie in that interval.

The points on the graph of a_n must lie between the horizontal lines $y = L + \varepsilon$ and $y = L - \varepsilon$ if n > N. This picture must be valid no matter how small ε is chosen, but usually a smaller ε requires a larger N.



The only difference between $\lim_{n\to\infty} a_n = L$ and $\lim_{x\to\infty} f(x) = L$ is that n is required to be an integer.

Theorem 12.1.1. If $\lim_{x\to\infty} f(x) = L$ and $f(n) = a_n$ when n is an integer, then $\lim_{n\to\infty} = a_n = L$.

Since we know that $\lim_{x\to\infty}(1/x^r)=0$ when r>0, we can use the previous theorem to get

Definition 12.1.3.

$$\lim_{n \to \infty} \frac{1}{n^r} = 0 \quad \text{if } r > 0$$

If a_n grows as n grows, we use the notation $\lim_{n\to\infty} a_n = \infty$. We say that a_n diverges to ∞ .

Definition 12.1.4. $\lim_{n\to\infty} a_n = \infty$ means that for every positive number M there is an integer N such that

$$a_n > M$$
 whenever $n > N$

Definition 12.1.5 (Limit Laws for Sequences (similar to original Limit Laws)). If $\{a_n\}$ and $\{b_n\}$ are convergent sequences and c is a constant, then

$$\lim_{n \to \infty} (a_n + b_n) = \lim_{n \to \infty} a_n + \lim_{n \to \infty} b_n$$

$$\lim_{n \to \infty} (a_n - b_n) = \lim_{n \to \infty} a_n - \lim_{n \to \infty} b_n$$

$$\lim_{n \to \infty} ca_n = c \lim_{n \to \infty} a_n$$

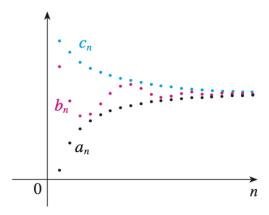
$$\lim_{n \to \infty} c = c$$

$$\lim_{n \to \infty} (a_n b_n) = \lim_{n \to \infty} a_n \cdot \lim_{n \to \infty} b_n$$

$$\lim_{n \to \infty} \frac{a_n}{b_n} = \frac{\lim_{n \to \infty} a_n}{\lim_{n \to \infty} b_n} \quad \text{if } b_n \neq 0$$

$$\lim_{n \to \infty} (a_n^p) = \left[\lim_{n \to \infty} a_n\right]^p \quad \text{if } p > 0 \text{ and } a_n > 0$$

Theorem 12.1.2 (The Squeeze Theorem for Sequences (same as original)). If $a_n \leq b_n \leq c_n$ for $n \geq n_0$ and $\lim_{n \to \infty} a_n = \lim_{n \to \infty} c_n = L$, then $\lim_{n \to \infty} b_n = L$.



Theorem 12.1.3. If $\lim_{n\to\infty} |a_n| = 0$, then $\lim_{n\to\infty} a_n = 0$.

Example 12.1.3. Evaluate $\lim_{n\to\infty} \frac{(-1)^n}{n}$ if it exists.

Solution.

$$\lim_{n \to \infty} \left| \frac{(-1)^n}{n} \right| = \lim_{n \to \infty} \frac{1}{n} = 0 \quad \text{so } \lim_{n \to \infty} \frac{(-1)^n}{n} = 0$$

Example 12.1.4. Find $\lim_{n\to\infty}\frac{n}{n+1}$.

Solution. Divide the numerator and denominator by the highest power of n and then use the Limit Laws.

$$\lim_{n \to \infty} \frac{n}{n+1} = \lim_{n \to \infty} \frac{1}{1 + \frac{1}{n}} = \frac{\lim_{n \to \infty} 1}{\lim_{n \to \infty} 1 + \lim_{n \to \infty} \frac{1}{n}}$$
$$= \frac{1}{1+0} = 1$$

Example 12.1.5. Calculate $\lim_{n\to\infty} \frac{\ln n}{n}$.

Solution. Both the numerator and denominator approach infinity as $n \to \infty$. We can't apply l'Hospital;s Rule directly because it applies to functions, not sequences. However, we can apply it to the related function.

$$\lim_{x\to\infty}\frac{\ln x}{x}=\lim_{x\to\infty}\frac{1/x}{1}=0\quad\text{so }\lim_{n\to\infty}\frac{\ln n}{n}=0$$

Example 12.1.6. Determine whether the sequence $a_n = (-1)^n$ is convergent or divergent.

Solution. If we write out the terms of the sequence, we get $\{-1, 1, -1, 1, -1, 1, -1, \ldots\}$. Since the terms oscillate between 1 and -1, a_n does not approach any number. Thus, $\lim_{n\to\infty} (-1)^n$ does not exist so the sequence $\{(-1)^n\}$ is divergent.

Example 12.1.7. Discuss the convergence of the sequence $a_n = n!/n^n$.

Solution. Both the numerator and denominator approach infinity as $n \to \infty$, but we have no corresponding functions to use l'Hospital's Rule because x! is not defined when x is not an integer. if we write the general formula for the sequence, we get

$$a_n = \frac{1 \cdot 2 \cdot 3 \cdot \ldots \cdot n}{n \cdot n \cdot n \cdot n \cdot \ldots \cdot n} = \frac{1}{n} \left(\frac{2 \cdot 3 \cdot \ldots \cdot n}{n \cdot n \cdot n \cdot \ldots \cdot n} \right)$$

The expression in the parenthesis is at most 1 because the numerator is less than (or equal) to the denominator, so

$$0 < a_n \le \frac{1}{n}$$

We can use the squeeze theorem because both 0 and $1/n \to 0$ as $n \to \infty$, so $a_n \to \infty$ as $n \to \infty$.

Example 12.1.8. Determine if the sequences below converge. If they do, find the limits as $n \to \infty$.

- 1. $\frac{\sin n}{n}$
- $2. ne^{-n}$

Solution. 1. $\frac{\sin n}{n}$ converges to 0 by the squeeze theorem

$$-\frac{1}{n} \le \frac{\sin n}{n} \le -\frac{1}{n} , \lim_{n \to \infty} \frac{1}{n} = 0 , \text{ so}$$
$$0 \le \frac{\sin n}{n} \le 0 \implies \lim_{n \to \infty} \frac{\sin n}{n} = 0$$

2. $ne^{-n} = \frac{n}{e^n}$. The denominator e^n converges faster than the numerator n does. Use l'Hospital's Rule to get

$$\lim_{x \to \infty} \frac{x}{e^x} = \lim_{x \to \infty} \frac{1}{e^x} = 0 \text{ so } \lim_{n \to \infty} ne^{-n} = 0$$

Example 12.1.9. Show that if $\lim_{n\to\infty} a_{2n} = L$ and $\lim_{n\to\infty} a_{2n+1} = L$, $\{a_n\}$ is convergent and $\lim_{n\to\infty} a_n = L$.

Solution. The solution uses the symbols \exists ("exists") and \Longrightarrow ("implies").

Since
$$\lim_{n\to\infty} a_{2n} = L$$
, $\exists N_1 \implies |a_{2n} - L| < \varepsilon \text{ for } n > N_1$
Since $\lim_{n\to\infty} a_{2n+1} = L$, $\exists N_2 \implies |a_{2n+1} - L| < \varepsilon \text{ for } n > N_2$

Let $N = \max\{2N_1, 2N_2 + 1\}$ and let n > N.

If n is even,
$$n = 2m, m > N_1, |a_n - L| = |a_{2m} - L| < \varepsilon$$

If n is odd, $n = 2m + 1, m > N_2, |a_n - L| = |a_{2m+1} - L| < \varepsilon$

Therefore, $\{a_n\}$ is convergent and $\lim_{n\to\infty} a_n = L$.

Definition 12.1.6. The sequence $\{r^n\}$ is convergent if $-1 < r \le 1$ and divergent for all other values of r.

$$\lim_{n \to \infty} r^n = \begin{cases} 0 & \text{if } -1 < r < 1\\ 0 & \text{if } r = 1 \end{cases}$$

Definition 12.1.7. A sequence $\{a_n\}$ is **increasing** if $a_n < a_{n+1}$ for all $n \ge 1$ $(a_1 < a_2 < a_3 < \cdots)$. It is **decreasing** is $a_n < a_{n+1}$ for all $n \ge 1$. It is **monotonic** if the is either increasing or decreasing.

Example 12.1.10. The sequence $\left\{\frac{3}{n+5}\right\}$ is decreasing because

$$\frac{3}{n+5} < \frac{3}{(n+1)+5} = \frac{3}{n+6}$$

for all $n \ge 1$ (the right side is smaller because it has a larger denominator).

Example 12.1.11. Show that the sequence $a_n = \frac{n}{n^2+1}$ is decreasing.

Solution (1). We must show that $a_{n+1} < a_n$.

$$\frac{n+1}{(n+1)^2+1} < \frac{n}{n^2+1}$$

We can simplify this by cross-multiplying. \iff means "if and only if".

$$\frac{n+1}{(n+1)^2+1} < \frac{n}{n^2+1} \iff (n+1)(n^2+1) < n[(n+1)^2+1]$$

$$\iff n^3+n^2+n+1 < n^3+2n^2+2n$$

$$\iff 1 < n^2+n$$

Since $n \geq 1$, we know that the inequality $n^2 + n > 1$ is true. Therefore, $a_{n+1} < a_n$ so $\{a_n\}$ is decreasing.

Solution (2). Consider the function $f(x) = \frac{x}{x^2+1}$:

$$f'(x) = \frac{x^2 + 1 - 2x^2}{(x^2 + 1)^2} = \frac{1 - x^2}{(x^2 + 1)^2} < 0$$
 whenever $x^2 > 1$

This, f is decreasing on $(1, \infty)$ so f(n) > f(n+1). Therefore, $\{a_n\}$ is decreasing.

Theorem 12.1.4 (Monotonic Sequence Theorem). Every bounded, monotonic sequence is convergent.

The proof is based on the **Completeness Axiom** for the set \mathbb{R} of real numbers, which says that if S is a nonempty set of real numbers that has an upper bound M ($x \leq M$ for all x in S), then S has a **least upper bound** b (This means that b is an upper bound for S, but if M is any other upper bound, then $b \leq M$). The Completeness Axiom is an expression of the fact that there is no gap or hole in the real number line.

Proof. Suppose $\{a_n\}$ is an increasing sequence. Since $\{a_n\}$ is bounded, the set $S=\{a_n|n\geq 1\}$ has an upper bound. By the Completeness Axiom it has a least upper bound L. Given $\varepsilon>0$, $L-\varepsilon$ is not an upper bound for S (since L) is the least upper bound). Therefore

$$a_N > L - \varepsilon$$
 for some integer N

But the sequence is increasing so $a_n \ge a_N$ for every n > N. Thus, if n > N we have

$$a_n > L - \varepsilon$$
$$0 \le L - a_n < \varepsilon$$

since $a_n \leq L$. Thus

$$|L - a_n| < \varepsilon$$
 whenever $n > N$

so $\lim_{n\to\infty} a_n = L$.

A similar proof (using the greatest lower bound) works if $\{a_n\}$ is decreasing.

12.2 Series

If we try to add the terms of an infinite sequence $a_{n}_{n=1}^{\infty}$ we get the expression of the form

$$a_1 + a_2 + a_3 + \dots + a_n + \dots$$

which is called an **infinite series** (or just a **series**) and is denoted by the symbol

$$\sum_{n=1}^{\infty} a_n \quad \text{or} \quad \sum a_n$$

We also consider the **partial sums**

$$s_1 = a_1$$

$$s_2 = a_1 + a_2$$

$$s_3 = a_1 + a_2 + a_3$$

$$s_4 = a_1 + a_2 + a_3 + a_4$$

$$s_n = a_1 + a_2 + a_3 + \dots + a_n = \sum_{i=1}^{\infty} a_i$$

These partial sums form a new sequence $\{s_n\}$, which may or may not have a limit. If the $\lim_{n\to\infty} s_n = s$ exists (as a finite number), then we call it the sum of the infinite series $\sum a_n$.

Definition 12.2.1. Given a series $\sum_{n=1}^{\infty} a_n = a_1 + a_2 + a_3 + \cdots$, let s_n denote its *n*th partial sum:

$$s_n = \sum_{i=1}^{\infty} a_i = a_1 + a_2 + \dots + a_n$$

If the sequence $\{s_n\}$ is convergent and $\lim_{n\to\infty} s_n = s$ exists as a real number, then the series $\sum a_n$ is **convergent** and we write

$$s_n = a_1 + a_2 + \dots + a_n = s$$
 or $\sum_{n=1}^{\infty} a_n = s$

The number s is the **sum** of the series. Otherwise, the series is **divergent**.

Notice that

$$\sum_{n=1}^{\infty} a_n = \lim_{n \to \infty} \sum_{i=1}^{\infty} a_i$$

Definition 12.2.2 (Geometric Series). The geometric series

$$\sum_{n=1}^{\infty} ar^{n-1} = a + ar + ar^2 + \cdots$$

is convergent if |r| < 1 and its sum is

$$\sum_{n=1}^{\infty} ar^{n-1} = \frac{a}{1-r} \qquad |r| < 1$$

If $|r| \geq 1$, the geometric series is divergent.

"The sum of a convergent geometric series is $\frac{\text{first term}}{1-\text{common ratio}}$ ".

Proof.

$$a + ar + ar^{2} + ar^{3} + \dots + ar^{n-1} + \dots = \sum_{n=1}^{\infty} ar^{n-1}$$

Each term is obtained from the preceding one by multiplying it by the **common ratio** r.

If r=1, then $s_n=a+a+\cdots+a=na\to\pm\infty$. Since $\lim_{n\to\infty} s_n$ doesn't exist, the geometric series diverges in this case. If $r\neq 1$, then

$$s_n = a + ar + ar^2 + \dots + ar^{n-1}$$

$$rs_n = ar + ar^2 + \dots + ar^{n-1} + ar^n$$

Subtracting these equations, we get

$$s_n - rs_n = a - ar^n$$

Definition 12.2.3 (Partial Sum of a Geometric Series).

$$s_n = \frac{a(1 - r^n)}{1 - r}$$

If -1 < r < 1, we know that $r^n \to 0$ as $n \to \infty$, so

$$\lim_{n \to \infty} s_n = \lim_{n \to \infty} \frac{a(1 - r^n)}{1 - r} = \frac{a}{1 - r} - \frac{a}{1 - r} \lim_{n \to \infty} r^n = \frac{a}{1 - r}$$

Thus, when |r| < 1, the geometric series is convergent and its sum is a/(1-r). If $r \le -1$ or r > 1, the sequence $\{r^n\}$ is divergent, so $\lim_{n \to \infty} s_n$ does not exist.

Example 12.2.1. Find the sum of the geometric series

$$5 - \frac{10}{3} + \frac{20}{9} - \frac{40}{27} + \cdots$$

Solution. The first time is a=5 and the common ratio is $r=-\frac{2}{3}$. Since $|r|=\frac{2}{3}<1$, the series is convergent and its sum is

$$5 - \frac{10}{3} + \frac{20}{9} - \frac{40}{27} + \dots = \frac{5}{1 - (-\frac{2}{3})} = \frac{5}{\frac{5}{3}} = 3$$

Example 12.2.2. Write the number $2.3\overline{17} = 2.3171717...$ as a ratio of integers.

Solution.

$$2.3171717... = 2.3 + \frac{17}{10^3} + \frac{17}{10^5} + \frac{17}{10^7} + \cdots$$

After the first term, we have a geometric series with $a = \frac{17}{10^3}$ and $r = 1/10^2$.

$$2.3\overline{17} = 2.3 + \frac{\frac{17}{10^3}}{1 - \frac{1}{10^2}} = 2.3 + \frac{\frac{17}{1000}}{\frac{99}{100}}$$
$$= \frac{23}{10} + \frac{17}{990} = \frac{1147}{495}$$

Example 12.2.3. Show that the series $\sum_{n=1}^{\infty} \frac{1}{n(n+1)}$ is convergent and find its sum.

Solution. This is not a geometric series, so we go back to the definition of a convergent series and compute the partial sums.

$$s_n = \sum_{i=1}^{\infty} \frac{1}{i(i+1)} = +\frac{1}{2 \cdot 3} + \frac{1}{3 \cdot 4} + \dots + \frac{1}{n(n+1)}$$

We simplify this expression if we use the partial fraction decomposition

$$\frac{1}{i(i+1)} = \frac{1}{i} - \frac{1}{i+1}$$

Thus, we have

$$s_n = \sum_{i=1}^{\infty} \frac{1}{i(i+1)} = \sum_{n=1}^{\infty} \left(\frac{1}{i} - \frac{1}{i+1}\right)$$

$$= \left(1 - \frac{1}{2}\right) + \left(\frac{1}{2} - \frac{1}{3}\right) + \left(\frac{1}{3} - \frac{1}{4}\right) + \dots + \left(\frac{1}{n} - \frac{1}{n+1}\right)$$

$$= 1 - \frac{1}{n+1} \quad \text{so}$$

$$\lim_{n \to \infty} s_n = \lim_{n \to \infty} \left(1 - \frac{1}{n+1}\right) = 1 - 0 = 1$$

Therefore, the given series is convergent and

$$\sum_{n=1}^{\infty} \frac{1}{n(n+1)} = 1$$

Definition 12.2.4. The harmonic series $\sum_{n=1}^{\infty} \frac{1}{n}$ is divergent.

Theorem 12.2.1. If the series $\sum_{n=1}^{\infty} a_n$ is convergent, then $\lim_{n\to\infty} a_n = 0$.

NOTE 1 With any series $\sum a_n$, we associate two sequences: the sequence $\{s_n\}$ of its partial sums and the sequence $\{a_n\}$ of its terms. If $\sum a_n$ is convergent, then the limit of the sequence $\{s_n\}$ is s (the sum of the series) and the limit of the sequence $\{a_n\}$ is 0.

NOTE 2 The converse is not true in general. If $\lim_{n\to\infty} a_n = 0$, we cannot conclude that $\sum_{n=1}^{\infty} a_n$ is convergent.

Proof. Let $s_n = \sum_{i=1}^{\infty} a_i = a_1 + a_2 + \dots + a_n$. Then $a_n = s_n - s_{n-1}$. Since $\sum a_n$ is convergent, the sequence $\{s_n\}$ is convergent. Let $\lim_{n\to\infty} s_n = s$. Since $n-1\to\infty$ as $n\to\infty$, we also have $\lim_{n\to\infty} s_{n-1} = s$. Therefore

$$\lim_{n \to \infty} a_n = \lim_{n \to \infty} (s_n - s_{n-1}) = \lim_{n \to \infty} s_n - \lim_{n \to \infty} s_{n-1}$$
$$= s - s = 0$$

Definition 12.2.5 (The Test for Divergence). If $\lim_{n\to\infty} a_n$ does not exist or

if $\lim_{n\to\infty} a_n \neq 0$, then the series $\sum_{n=1}^{\infty} a_n$ is divergent.

Example 12.2.4. Show that the series $\sum_{n=1}^{\infty} \frac{n^2}{5n^2+4}$ diverges.

Solution.

$$\lim_{n \to \infty} a_n = \sum_{n=1}^{\infty} \frac{n^2}{5n^2 + 4} = \sum_{n=1}^{\infty} \frac{1}{5 + 4/n^2} = \frac{1}{5} \neq 0$$

So the series diverges by the Test for Divergence.

NOTE 3 If we find that $\lim_{n\to\infty} a_n \neq 0$, we know that $\sum a_n$ is divergent. If we find that $\lim_{n\to\infty} a_n = 0$, we know *nothing* about the convergence or divergence about $\sum a_n$.

Theorem 12.2.2. If $\sum a_n$ and $\sum b_n$ are convergent series, then so are the series $\sum ca_n$ (where c is a constant), $\sum (a_n + b_n)$, and $\sum (a_n - b_n)$.

(i)
$$\sum_{n=1}^{\infty} ca_n = c \sum_{n=1}^{\infty} a_n$$

(ii)
$$\sum_{n=1}^{\infty} (a_n + b_n) = \sum_{n=1}^{\infty} a_n + \sum_{n=1}^{\infty} b_n$$

(iii)
$$\sum_{n=1}^{\infty} (a_n - b_n) = \sum_{n=1}^{\infty} a_n - \sum_{n=1}^{\infty} b_n$$

Example 12.2.5. Find the sum of the series $\sum_{n=1}^{\infty} \left(\frac{3}{n(n+1)} + \frac{1}{2^n} \right).$

Solution. The series $\sum 1/2^n$ is a geometric series with $a=\frac{1}{2}$ and $r=\frac{1}{2}$, so

$$\sum_{n=1}^{\infty} \frac{1}{2^n} = \frac{\frac{1}{2}}{1 - \frac{1}{2}} = 1$$

We found that

$$\sum_{n=1}^{\infty} \frac{1}{n(n+1)} = 1$$

So the given series is convergent and

$$\sum_{n=1}^{\infty} \left(\frac{3}{n(n+1)} + \frac{1}{2^n} \right) = 3 \sum_{n=1}^{\infty} \frac{1}{n(n+1)} + \sum_{n=1}^{\infty} \frac{1}{2^n}$$
$$= 3 \cdot 1 + 1 = 4$$

NOTE 4 A finite number of terms doesn't affect the convergence or divergence of a series. For instance, suppose that we were able to show that the series $\sum_{n=0}^{\infty} \frac{n}{n^3+1}$ is convergent. Since

$$\sum_{n=1}^{\infty} \frac{n}{n^3 + 1} = \frac{1}{2} + \frac{2}{9} + \frac{3}{28} = \sum_{n=4}^{\infty} \frac{n}{n^3 + 1}$$

we can conclude that the entire series $\sum_{n=1}^{\infty} \frac{n}{n^3+1}$ is convergent.

Similarly, if it is known that the series $\sum_{n=N+1}^{\infty} a_n$ converges, then the full series

$$\sum_{n=1}^{\infty} a_n = \sum_{n=1}^{N} a_n + \sum_{n=N+1}^{\infty} a_n$$

is also convergent.

12.3 The Integral Test and Estimates of Sums

Definition 12.3.1 (The Integral Test). Suppose f is a continuous, positive, decreasing function on $[1,\infty)$ and let $a_n=f(n)$. Then the series $\sum_{n=1}^{\infty}$ is convergent if and only if the improper integral $\int_1^{\infty} f(x) \ dx$ is convergent. In other words:

(i) If
$$\int_{1}^{\infty} f(x) dx$$
 is convergent, then $\sum_{n=1}^{\infty}$ is convergent.

(i) If
$$\int_1^\infty f(x) \ dx$$
 is divergent, then $\sum_{n=1}^\infty$ is divergent.

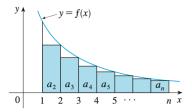
NOTE When we use the Integral Test, it is not necessary to start the series or the integral at n = 1. For instance, in testing the series

$$\sum_{n=4}^{\infty} \frac{1}{(n-3)^2} \quad \text{we use} \quad \int_{1}^{\infty} \frac{1}{(n-3)^2} \ dx$$

Also, it is not necessary that f is always decreasing; it is important that f is ultimately decreasing.

Proof. We will prove the convergence and divergence of the Integral Test for the general series $\sum a_n$

(i) Convergence



The area of the first shaded rectangle is $f(2) = a_2$. Because there is always space underneath the curve, the sum of the area of the shaded triangles from 1 to n is always less than the area under the curve (since f is decreasing).

$$a_2 + a_3 + \dots + a_n \le \int_1^n f(x) \ dx$$

If $\int_{1}^{\infty} f(x) dx$ is convergent, then

$$\sum_{i=2}^{n} a_i \le \int_1^n f(x) \ dx \le \int_1^\infty f(x) \ dx$$

since $f(x) \ge 0$. Therefore,

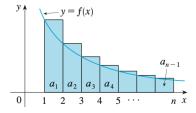
$$s_n = a_1 + \sum_{i=2}^n a_i \le a_1 + \int_1^\infty f(x) \ dx = M$$
 (random variable)

Since $s_n \leq M$ for all n, the sequence $\{s_n\}$ is bounded above. Also

$$s_{n+1} = s_n + a_{n+1} \ge s_n$$

since $a_{n+1} = f(n+1) \ge 0$. Thus, $\{s_n\}$ is an increasing bounded sequence so it it convergent by the Monotonic Sequence Theorem. This means that $\sum a_n$ is convergent.

(ii) Divergence



Because there is always space above the curve, the sum of the area of the shaded triangles from 1 to n is always greater than the area under the curve.

 $\int_{1}^{n} f(x) \ dx \le a_1 + a_2 + \dots + a_{n-1}$

If $\int_1^\infty f(x)\ dx$ is divergent, then $\int_1^n f(x)\ dx \to \infty$ as $n\to\infty$ because $f(x)\geq 0$. But

$$\int_{1}^{n} f(x) \ dx \le \sum_{i=1}^{n-1} a_{i} = s_{n-1}$$

so $s_{n-1} \to \infty$. This implies that $s_n \to \infty$ so $\sum a_n$ is diverges.

Example 12.3.1. Test the series $\sum_{n=1}^{\infty} \frac{1}{n^2+1}$ for convergence or divergence.

Solution. The function $f(x) = 1/(x^2+1)$ is continuous, positive, and decreasing on $[1, \infty)$ so we use the Integral Test:

$$\int_{1}^{\infty} \frac{1}{x^2 + 1} dx = \lim_{t \to \infty} \int_{1}^{t} \frac{1}{x^2 + 1} dx = \lim_{t \to \infty} \tan^{-1} x \Big]_{1}^{t}$$
$$= \lim_{t \to \infty} \left(\tan^{-1} t - \frac{\pi}{4} \right) = \frac{\pi}{2} - \frac{\pi}{4} = \frac{\pi}{4}$$

Thus, $\int_1^\infty \frac{1}{x^2+1} \, dx$ is a convergent integral. The series $\sum 1/(n^2+1)$ is convergent by the Integral Test.

Definition 12.3.2. The *p*-series $\sum_{n=1}^{\infty} \frac{1}{n^p}$ is convergent if p > 1 and divergent if $p \le 1$.

For p = 1, the series is a harmonic series.

Proof. If p < 0, then $\lim_{n \to \infty} \frac{1}{n^p} = 0$. If p = 0, then $\lim_{n \to \infty} \frac{1}{n^p} = 1$. In either case, $\lim_{n \to \infty} \frac{1}{n^p} \neq 0$, so the p-series diverges by the Test for Divergence.

If p > 0, then the function $f(x) = \frac{1}{x^p}$ is clearly continuous, positive, and decreasing on $[1, \infty)$. We know that

$$\int_{1}^{\infty} \frac{1}{x^{p}} \text{ converges if } p > 1 \text{ and diverges if } p \le 1$$

Using the Integral Test, the series $\sum 1/n^p$ converges if p>1 and diverges if 0.

Example 12.3.2.

(a) The series

$$\sum_{n=1}^{\infty} \frac{1}{n^3} = \frac{1}{1^3} + \frac{1}{2^3} + \frac{1}{3^3} + \frac{1}{4^3} + \cdots$$

is convergent because it is a p-series with p = 3 > 1.

(b) The series

$$\sum_{n=1}^{\infty} \frac{1}{n^{1/3}} = \sum_{n=1}^{\infty} \frac{1}{\sqrt[3]{n}} = 1 + \frac{1}{\sqrt[3]{2}} + \frac{1}{\sqrt[3]{3}} + \frac{1}{\sqrt[3]{4}} + \cdots$$

is divergent because it is a p-series with $p = \frac{1}{3} < 1$.

NOTE We should *not* infer that the sum of the series is equal to the value of the integral from the Integral Test. In fact,

$$\sum_{n=1}^{\infty} \frac{1}{n^2} = \frac{\pi^2}{6} \quad \text{whereas} \quad \int_{n}^{\infty} \frac{1}{n^2} = 1$$

Therefore, in general,

$$\sum_{n=1}^{\infty} a_n \neq \int_n^{\infty} f(x) \ dx$$

Example 12.3.3. Determine whether the series $\sum -n = 1^{\infty} \frac{\ln n}{n}$ converges or diverges.

Solution. The function $\frac{\ln x}{x}$ is positive and continuous for x > 1 because the logarithm function is continuous, but it is not obvious whether or not f is decreasing, so we take its derivative:

$$f'(x) = \frac{(1/x)x - \ln x}{x^2} = \frac{1 - \ln x}{x^2}$$

Thus, f'(x) < 0 when $\ln x > 1$, which is when x > e. We conclude that f is decreasing when x > e so we can apply the Integral Test:

$$\int_{1}^{\infty} \frac{\ln x}{x} dx = \lim_{t \to \infty} \int_{1}^{t} \frac{\ln x}{x} dx = \lim_{t \to \infty} \frac{(\ln x)^{2}}{2} \bigg]_{1}^{t}$$
$$= \lim_{t \to \infty} \frac{(\ln t)^{2}}{2} = \infty$$

Since this improper integral is divergent, the series $\sum (\ln n)/n$ is also divergent by the Integral Test.

Estimating the Sum of a Series

We can show if a series $\sum a_n$ is converging. Now we want to find an approximation to the sum s of the series. ANy partial sum s_n is an approximation to s because $\lim_{n\to\infty} s_n = s$, but how good is that approximation? To find out, we need to estimate the size of the **remainder**

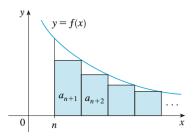
$$R_n = s - s_n = a_{n+1} + a_{n+2} + a_{n+3} + \cdots$$

The remainder R_n is the *error* made when s_n , the sum of the first n terms, is used as an approximation of the total sum.

Definition 12.3.3 (Remainder Estimate for the Integral Test). Suppose that $f(k) = a_k$, where f is a continuous, positive, decreasing function for $x \ge n$ and $\sum a_n$ is convergent. If $R_n = s - s_n$, then

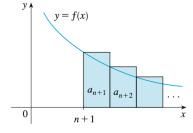
$$\int_{n+1}^{\infty} f(x) \ dx \le R_n \le \int_{n}^{\infty} f(x) \ dx$$

Proof. We use the same concept as the Integral test, assuming that f is decreasing on $[n, \infty)$.



We compare the sum of the area of the rectangles with the area under y=f(x) for x>n to see that

$$R_n = a_{n+1} + a_{n+2} + \dots \le \int_n^\infty f(x) \ dx$$



Similarly, we see that

$$R_n = a_{n+1} + a_{n+2} + \dots \ge \int_n^\infty f(x) \ dx$$

- **Example 12.3.4.** (a) Approximate the sum of the series $\sum 1/n^3$ by using the sum of the first 10 terms. Approximate the error involved in the approximation.
 - (b) How many terms are required to ensure that the sum is accurate to within 0.0005?

Example 12.3.5.

$$\int_{n}^{\infty} \frac{1}{x^3} dx = \lim_{t \to \infty} \left[-\frac{1}{2x^2} \right]_{n}^{t} = \lim_{t \to \infty} \left(-\frac{1}{2t^2} + \frac{1}{2n^2} \right) = \frac{1}{2n^2}$$

(a) $\sum_{n=1}^{\infty} \frac{1}{n^3} \approx \frac{1}{1^3} + \frac{1}{2^3} + \frac{1}{3^3} + \dots + \frac{1}{10^3} \approx 1.1975$

According to the remainder estimate, we have

$$R_{10} \le \int_{10}^{\infty} \frac{1}{x^3} dx = \frac{1}{2(10)^2} = \frac{1}{200}$$

So the size of the error is at most 0.005.

(b) Accuracy to within 0.0005 means that we have to find a value of n such that $R_n \leq 0.0005$. Since

$$R_n \le \int_{10}^{\infty} \frac{1}{x^3} dx = \frac{1}{2n^2}$$

We want

$$\frac{1}{2n^2} \le 0.0005$$

Solving this inequality, we get

$$n^2 > \frac{1}{0.001} = 1000$$
 or $n > \sqrt{1000} \approx 31.6$

We need 32 terms to ensure accuracy to within 0.0005.

If we add s_n to each side of the inequality of the Remainder Estimate for the Integral Test, we get

Definition 12.3.4.

$$s_n + \int_{n+1}^{\infty} f(x) dx \le s \le s_n + \int_{n}^{\infty} f(x) dx$$

because $s_n + R_n = s$. These inequalities give a lower bound and an upper bound for s. They provide a more accurate approximation than the partial sum s_n does.

Example 12.3.6. Use the improved remainder estimate with n = 10 to estimate the sum of the series $\sum_{n=1}^{\infty} \frac{1}{n^3}$.

Solution.

$$s_{11} + \int_{11}^{\infty} \frac{1}{x^3} dx \le s \le s_{10} + \int_{10}^{\infty} \frac{1}{x^3} dx$$

We know from the previous example that

$$\int_{n}^{\infty} \frac{1}{x^3} \ dx = \frac{1}{2n^2}$$

SO

$$s_{11} + \frac{1}{2(11)^2} \le s \le s_{10} + \frac{1}{2(10)^2}$$

Using $s_{10} \approx 1.197532$, we get

$$1.201664 \le s \le 1.202532$$

If we approximate s by the midpoint of this interval, then the error is at most half the length of the interval, so

$$\sum_{n=1}^{\infty} \frac{1}{n^3} \approx 1.2021 \text{ with error} < 0.0005$$

We get a much better estimate with this method than the estimate $s \approx s_n$ in the previous example. Also, we only had to use 10 terms to get the error smaller than 0.0005 instead of 32 terms.

12.4 The Comparison Tests

In comparison tests, the idea is to compare a given series with a series that is know to be convergent or divergent.

Definition 12.4.1 (The Comparison Test). Suppose that $\sum a_n$ and $\sum b_n$ are series with positive terms.

- (i) If $\sum b_n$ is convergent and $a_n \leq b_n$ for all n, then $\sum a_n$ is also convergent.
- (ii) If $\sum b_n$ is divergent and $a_n \geq b_n$ for all n, then $\sum a_n$ is also divergent. In other words,
- (i) If we have a series whose terms are *smaller* than those of a known *convergent* series, then our series is also convergent.
- (ii) If we have a series whose terms are *larger* than those of a known *divergent* series, then our series is also divergent.

Proof. Let

$$s_n = \sum_{i=1}^n a_i$$
 $t_n = \sum_{i=1}^n b_i$ $t = \sum_{n=1}^n b_n$

(i) Convergence

The sequences $\{s_n\}$ and $\{t_n\}$ are increasing $(s_{n+1} = s_n + a_{n+1} \ge s_n)$ because both series have positive terms. Also $t_n \to t$, so $t_n \le t$ for all n. This means that $\{s_n\}$ is increasing and bounded above and therefore converges by the Monotonic Sequence Theorem. Thus, $\sum a_n$ converges.

(ii) Divergence

If $\sum b_n$ is divergent, then $t \to \infty$ (since $\{t_n\}$ is increasing). BUt $a_i \ge b_i$ so $s_n \ge t_n$. Thus, $s_n \to \infty$. Therefore, $\sum a_n$ diverges.

Example 12.4.1. Determine whether the series $\sum_{n=1}^{\infty} \frac{5}{2n^2 + 4n + 3}$ converges or diverges.

Solution. As n gets larger, the dominant term in the denominator is $2n^2$, so we compare the given series with the series $\sum 5/(2n^2)$. Observe that

$$\frac{5}{2n^2+4n+3}<\frac{5}{2n^2}$$

because the left side has a bigger denominator. We know the

$$\sum_{n=1}^{\infty} \frac{5}{2n^2} = \frac{5}{2} \sum_{n=1}^{\infty} \frac{1}{n^2}$$

is convergent because it is a constant times a p-series with p=2>1. Therefore, $\sum_{n=1}^{\infty} \frac{5}{2n^2+4n+3}$ is convergent by the Comparison Test.

NOTE Although the condition $a_n \leq b_n$ for $a_n \geq b_n$ in the Comparison Test is given for all n, we only need to verify it for $n \geq N$, where N is some fixed integer, because the convergence of a series is not affected by a finite number.

Definition 12.4.2 (The Limit Comparison Test). Suppose that $\sum a_n$ and $\sum b_n$ are series with positive terms. If

$$\lim_{n \to \infty} \frac{a_n}{b_n} = c$$

where c is a finite number and c > 0, then either both series converge or diverge.

Proof. Let m and M be positive numbers such that m < c < M. Because a_n/b_n is close to c for a large n, there is an integer N such that

$$m < \frac{a_n}{b_n} < M \quad \text{when } n > N \quad \text{so}$$

$$mb_n < a_n < Mb_n \quad \text{when } n > N$$

We can conclude the following:

- (i) If $\sum b_n$ converges, so does $\sum Mb_n$, so $\sum a_n$ converges by the Comparison Test.
- (i) If $\sum b_n$ diverges, so does $\sum Mb_n$, so $\sum a_n$ diverges by the Comparison Test.

Example 12.4.2. Test the series $\sum_{n=1}^{\infty} \frac{1}{2^n - 1}$ for convergence or divergence.

Solution. We use the limit comparison test with

$$a_n = \frac{1}{2^n - 1} \qquad b_n = \frac{1}{2^n}$$

and obtain

$$\lim_{n \to \infty} \frac{a_n}{b_n} = \lim_{n \to \infty} \frac{1(2^n - 1)}{1/2^n} = \lim_{n \to \infty} \frac{2^n}{2^n - 1} = \lim_{n \to \infty} \frac{1}{1 - 1/2^n} = 1 > 0$$

Since this limit exists and $\sum 1/2^n$ is a convergent geometric series, the given series converges by the Limit Comparison Test.

Estimating Sums

We used the Comparison test to series $\sum a_n$ by comparison with $\sum b_n$. We can also use it to estimate the sum by comparing remaindeds. We continue to consider the remainder R_n and consider T_n for the comparison series $\sum b_n$ as the corresponding remainder.

$$R_n = s - s_n = a_{n+1} + a_{n+2} + \cdots$$

 $T_n = t - t_n = b_{n+1} + b_{n+2} + \cdots$

Since $a_n \leq b_n$, $R_n \leq T_n$.

Example 12.4.3. Use the sum of the first 100 terms to approximate the sum of the series $\sum 1/(n^3+1)$. Estimate the error involved in this approximation.

Solution. Since

$$\frac{1}{n^3+1}<\frac{1}{n^3}$$

the given series is convergent by the Comparison Test. Using the Remainder Estimate for the Integral Test in section 12.3 we found that

$$T_n \le \int_n^\infty \frac{1}{x^3} \ dx = \frac{1}{2n^2}$$

Therefore, the remainder R_n for the given series satisfies

$$R_n \le T_n \le \frac{1}{2n^2}$$

With n = 100 we have

$$R_{100} \le \frac{1}{2(100)^2} = 0.00005$$

Using a calculator, we find that

$$\sum_{n=1}^{\infty} \frac{1}{n^3 + 1} \approx \sum_{n=1}^{100} \frac{1}{n^3 + 1} \approx 0.6864538$$

with error less than 0.00005.

12.5 Alternating Series

An alternating series is a series whose terms are alternately positive and negative. Here are two examples:

$$1 - \frac{1}{2} + \frac{1}{3} - \frac{1}{4} + \frac{1}{5} - \frac{1}{6} + \dots = \sum_{n=1}^{\infty} \frac{(-1)^{n-1}}{n}$$
$$-\frac{1}{2} + \frac{2}{3} - \frac{3}{4} + \frac{4}{5} - \frac{5}{6} + \frac{6}{7} - \dots = \sum_{n=1}^{\infty} (-1)^n \frac{n}{n+1}$$

We see from these examples that the nth term of an alternating series is of the form

$$a_n = (-1)^{n-1}b_n$$
 or $a_n = (-1)^n b_n$

where b_n is a positive number. (In fact, $b_n = |a_n|$).

Definition 12.5.1 (The Alternating Series Test). If the alternating series

$$\sum_{n=1}^{\infty} (-1)^{n-1} b_n = b_1 - b_2 + b_3 - b_4 + b_5 - b_6 + \dots \qquad (b_n > 0)$$

satisfies

(i)
$$b_{n+1} \le b_n$$
 for all n

(ii)
$$\lim_{n\to\infty} b_n = 0$$

then the series is convergent.

"The alternating series converges if its terms decrease toward 0 in absolute value".

Proof. We consider the even and odd partial sums separately.

We first consider *even* partial sums:

$$s_2 = b_1 - b_2 \ge 0$$
 since $b_2 \le b_1$
 $s_4 = s_2 + (b_3 - b_4) \ge s_2$ since $b_4 \le b_3$
 $s_{2n} = s_{2n-2} + (b_{2n-1} - b_{2n}) \ge s_{2n-2}$ since $b_{2n} \le b_{2n-1}$

In general

Thus

$$0 \le s_2 \le s_4 \le s_6 \le \dots \le s_{2n} \le \dots$$

But we can also write

$$s_{2n} = b_1 - (b_2 - b_3) - (b_4 - b_5) - \dots - (b_{2n-2} - b_{2n-1}) - b_{2n}$$

Every term in brackets is positive, so $s_{2n} \leq b_1$ for all n. Therefore, the sequence $\{s_{2n}\}$ of even partial sums is increasing and bounded above. It is therefore convergent by the Monotonic Sequence Theorem. Let's call this limit s:

$$\lim_{n \to \infty} s_{2n} = s$$

Next we compute the limit of the *odd* partial sums:

$$\lim_{n \to \infty} s_{2n+1} = \lim_{n \to \infty} (s_{2n} + b_{2n+1})$$

$$= \lim_{n \to \infty} s_{2n} + \lim_{n \to \infty} b_{2n+1}$$

$$= s + 0$$

$$= s$$

Since both partial sums converge to s, we have $\lim_{n\to\infty} s_{2n} = s$ and so the series is convergent.

Example 12.5.1. The alternating harmonic series

$$1 - \frac{1}{2} + \frac{1}{3} - \frac{1}{4} + \dots = \sum_{n=1}^{\infty} \frac{(-1)^{n-1}}{n}$$

satisfies

(i)
$$b_{n+1} \le b_n$$
 because $\frac{1}{n+1} < \frac{1}{n}$

(ii)
$$\lim_{n \to \infty} b_n = \lim_{n \to \infty} \frac{1}{n} = 0$$

so the series is convergent by the Alternating Series Test

Example 12.5.2. The series $\sum_{n=1}^{\infty} \frac{(-1)^n 3n}{4n-1}$ is alternating but

$$\lim_{n \to \infty} b_n = \lim_{n \to \infty} \frac{3n}{4n - 1} = \lim_{n \to \infty} \frac{3}{4 - \frac{1}{n}} = \frac{3}{4} \neq 0$$

Instead, we look at the nth term of the series:

$$\lim_{n \to \infty} a_n = \lim_{n \to \infty} \frac{(-1)^n 3n}{4n - 1}$$

The limit does not exist, so the series diverges by the Test for Divergence.

Estimating Sums

Theorem 12.5.1 (Alternating Series Estimation Theorem). If $s = \sum (-1)^{n-1}b_n$ is the sum of an alternating series that satisfies

(i)
$$0 \le b_{n+1} \le b_n$$
 and $\lim_{n \to \infty} b_n = 0$

then

$$|R_n| = |s - s_n| \le b_{n+1}$$

Proof. We know from the proof of the Alternating Series Test that s lies between any two consecutive partial sums s_n and s_{n+1} . It follows that

$$|s - s_n| \le |s_{n+1} - s_n| = b_{n+1}$$

"The size of the error is smaller than b_{n+1} , which is the absolute value of the first neglected term" (valid only for alternating series that satisfy the Alternating Series Estimation, not other theorems.

Example 12.5.3. Find the sum of the series $\sum_{n=0}^{\infty} \frac{(-1)^n}{n!}$ correct to three decimal places (By definition, 0! = 1).

Solution. We first observe that the series is convergent by the Alternating Series Test because

(i)
$$\frac{1}{(n+1)!} = \frac{1}{n!(n+1)} \le \frac{1}{n!}$$

(ii)
$$0 < \frac{1}{n!} < \frac{1}{n} \to 0$$
 so $\frac{1}{n!} \to 0$ as $n \to \infty$

To get a feel for how many terms we need to use in our approximation, let's write out the first few terms of the series:

$$s = \frac{1}{0!} - \frac{1}{1!} + \frac{1}{2!} - \frac{1}{3!} + \frac{1}{4!} - \frac{1}{5!} + \frac{1}{6!} - \frac{1}{7!} + \cdots$$
$$= 1 - 1 + \frac{1}{2} - \frac{1}{6} + \frac{1}{24} - \frac{1}{120} + \frac{1}{720} - \frac{1}{5040} + \cdots$$

Notice that

$$b_7 = \frac{1}{5040} < \frac{1}{5000} = 0.0002$$

and

$$s_n = 1 - 1 + \frac{1}{2} - \frac{1}{6} + \frac{1}{24} - \frac{1}{120} + \frac{1}{720} \approx 0.369056$$

By the Alternating Series Estimation Theorem, we know that

$$|s - s_6| \le b_7 < 0.0002$$

This error of less than 0.0002 does not affect the third decimal place, so we have

$$s \approx 0.368$$

correct to three decimal places.

12.6 Absolute Convergence and the Ratio and Root Tests

Given any series $\sum a_n$, we can consider the corresponding series

$$\sum_{n=1}^{\infty} |a_n| = |a_1| + |a_2| + |a_3| + \cdots$$

whose terms are the absolute value of the terms of the original series.

Definition 12.6.1. A series $\sum a_n$ is called **absolutely convergent** if the series of absolute values $\sum |a_n|$ is convergent.

Notice that if $\sum a_n$ is a series with positive terms, then $\sum |a_n| = \sum a_n$ and so absolute convergence is the same as convergence in this case.

Example 12.6.1. The series

$$\sum_{n \to \infty}^{\infty} \frac{(-1)^{n-1}}{n^2} = 1 - \frac{1}{2^2} + \frac{1}{3^2} - \frac{1}{4^2} + \cdots$$

is absolutely convergent because

$$\sum_{n=0.00}^{\infty} \left| \frac{(-1)^{n-1}}{n^2} \right| = 1 + \frac{1}{2^2} + \frac{1}{3^2} + \frac{1}{4^2} + \cdots$$

is a convergent p-series (p=2).

Definition 12.6.2. A series $\sum a_n$ is **conditionally convergent** if it is convergent but not absolutely convergent.

Definition 12.6.3. If a series $\sum a_n$ is absolutely convergent, then it is convergent.

Proof. Observe that the inequality

$$0 \le a_n + |a_n| \le 2|a_n|$$

is true because $|a_n|$ is either a_n or $-a_n$. If $\sum a_n$ is absolutely convergent, then $\sum |a_n|$ is convergent, $\sum 2|a_n|$. Therefore, by the comparison test, $\sum (a_n + |a_n|)$ is convergent. Then

$$\sum a_n = \sum (a_n + |a_n|) - \sum |a_n|$$

is the difference of the two convergent series and is therefore convergent.

Definition 12.6.4. The Ratio Test

- (i) If $\lim_{n\to\infty} \left| \frac{a_{n+1}}{a_n} \right| = L < 1$, then the series $\sum_{n=1}^{\infty} a_n$ is absolutely convergent (and therefore convergent).
- (ii) If $\lim_{n\to\infty} \left| \frac{a_{n+1}}{a_n} \right| = L > 1$ or If $\lim_{n\to\infty} \left| \frac{a_{n+1}}{a_n} \right| = \infty$, then the series $\sum_{n=1}^{\infty} a_n$ is divergent.
- (iii) If $\lim_{n\to\infty} \left| \frac{a_{n+1}}{a_n} \right| = 1$, the Ratio Test is inconclusive (no conclusion can be drawn about the convergence or divergence of $\sum a_n$).

Proof.

(i) The idea is to compare the given series with a convergent geometric series. Since L > 1, we can choose a number r such that L < r < 1. Since

$$\lim_{n \to \infty} \left| \frac{a_{n+1}}{a_n} \right| = L \quad \text{and} \quad L < r$$

the ratio $|a_{n+1}/a_n|$ will eventually be less than r; this means that there exists an integer N such that

$$\left| \frac{a_{n+1}}{a_n} \right| < r \quad \text{whenever } n \ge N$$

or, equivalently,

$$a_{n+1} < r|a_n|$$
 whenever $n \ge N$

Putting n successively equal to N, N+1, N+2,... in the previous equation, we obtain

$$|a_{N+1}| < |a_N|r$$

 $|a_{N+2}| < |a_{N+1}|r < |a_N|r^2$
 $|a_{N+3}| < |a_{N+2}|r < |a_N|r^3$

and, in general,

$$|a_{N+k}| < |a_N|r^k$$
 for all $k \ge 1$

Now the series

$$\sum_{k=1}^{\infty} |a_N| r^k = |a_N| r + |a_N| r^2 + |a_N| r^3 + \cdots$$

is convergent because it is a geometric series with 0 < r < 1. So the previous inequality , together with the Comparison Test, shows that the series

$$\sum_{n=N+1}^{\infty} |a_n| = \sum_{k=1}^{\infty} |a_{N+k}| = |a_{N+1}| + |a_{N+2}| + |a_{N+3}| + \cdots$$

is also convergent. It follows that the series $\sum_{n=1}^{\infty} |a_n|$ is also convergent. Therefore, $\sum a_n$ is absolutely convergent.

(ii) If $|a_{n+1}/a_n| \to L > 1$ or $|a_{n+1}/a_n| \to \infty$, then the ratio $|a_{n+1}/a_n|$ will eventually be greater than 1. This means that there exists an integer N such that

$$\left| \frac{a_{n+1}}{a_n} \right| > 1$$
 whenever $n \ge N$

This means that $|a_{n+1}/a_n| > |a_n|$ whenever $n \ge N$ and so

$$\lim_{n\to\infty} a_n \neq 0$$

Therefore $\sum a_n$ diverges by the Test for Divergence.

(iii) The Ratio Test gives no information if $\lim_{n\to\infty} |a_{n+1}/a_n| = 1$. For instance,

for the convergent series $\sum 1/n^2$ we have

$$\left| \frac{a_{n+1}}{a_n} \right| = \frac{\frac{1}{(n+1)^2}}{\frac{1}{n^2}} = \frac{n^2}{(n+1)^2} = \frac{1}{\left(1 + \frac{1}{n}\right)^2} \to 1 \quad \text{as } n \to \infty$$

whereas for the divergent series $\sum 1/n$ we have

$$\left| \frac{a_{n+1}}{a_n} \right| = \frac{\frac{1}{n+1}}{\frac{1}{n}} = \frac{n}{n+1} = \frac{1}{1+\frac{1}{n}} \to 1 \text{ as } n \to \infty$$

Therefore, if $\lim_{n\to\infty} |a_{n+1}/a_n| = 1$, the series $\sum a_n$ might converge or diverge. In this case, the Ratio Test fails and we must use some other test.

Example 12.6.2. Test the series $\sum_{n=1}^{\infty} (-1)^n \frac{n^3}{3^n} for absolute convergence.$

Solution. We use the Ratio Test with $a_n = (-1)^n n^3/3^n$.

$$\left| \frac{a_{n+1}}{a_n} \right| = \left| \frac{\frac{(-1)^{n+1}(n+1)^3}{3(n+1)}}{\frac{(-1)^n n^3}{3^n}} \right| = \frac{(n+1)^3}{3^{n+1}} \cdot \frac{3^n}{n^3}$$
$$= \frac{1}{3} \left(\frac{n+1}{n} \right)^3 = \frac{1}{3} \left(1 + \frac{1}{n} \right)^3 \to \frac{1}{3} < 1$$

The given series is absolutely convergent by the Ratio Test and therefore convergent.

Definition 12.6.5. The Root Test

- (i) If $\lim_{n\to\infty} \sqrt[n]{|a_n|} = L < 1$, then the series $\sum_{n=1}^{\infty} a_n$ is is absolutely convergent (and therefore convergent).
- (ii) If $\lim_{n\to\infty} \sqrt[n]{|a_n|} = L > 1$ or $\lim_{n\to\infty} \sqrt[n]{|a_n|} = \infty$, then the series $\sum_{n=1}^{\infty} a_n$ is divergent.
- (iii) If $\lim_{n\to\infty} \sqrt[n]{|a_n|} = 1$, then the Root Test is inconclusive.

Note If L=1 in the Ratio Test, don't try the Root Test because L will also be 1.

Example 12.6.3. Test the convergence of the series $\sum_{n=1}^{\infty} \left(\frac{2n+3}{3n+2}\right)^n$

Solution.

$$a_n = \left(\frac{2n+3}{3n+2}\right)^n$$

$$\sqrt[n]{|a_n|} = \frac{2n+3}{3n+2} = \frac{2+\frac{3}{n}}{3+\frac{2}{n}} \to \frac{2}{3} < 1$$

The given series converges by the Root Test.

12.7 Strategy for Testing Series

The main strategy for testing series is to classify the series according to its form.

- 1. If the series is of the form $\sum 1/n^p$, it is a *p*-series, which we know to be convergent if p > 1 and divergent if $p \le 1$.
- 2. If the series has form $\sum ar^{n-1}$ or $\sum ar^n$, it is a geometric series, which converges is |r| < 1 and diverges if $|r| \ge 1$. You may need to manipulate the equation to bring the series into this form.
- 3. If the series has a form that is similar to a p-series or a geometric series, then one of the comparison tests should be considered. In particular, if a_n is a rational function or algebraic function of n (involving roots of polynomials), then the series should be compared with a p-series (the values of p should be chosen by keeping only the highest powers of p in the numerator and denominator). The comparison tests apply only to series with positive terms, but if $\sum a_n$ has some negative terms, we can apply the Comparison Tests to $\sum |a_n|$ and test for absolute convergence.
- 4. If it is obvious that $\lim_{n\to\infty}\neq 0$, then use the Test for Divergence.
- 5. If the series is of the form $\sum (-1)^{n-1}b_n$ or $\sum (-1)^nb_n$, then the Alternating Series Test is an obvious possibility.
- 6. Series that involve factorials or other products (including a constant raised to the *n*th power) are often conveniently tested using the Ratio Test. Bear in mind that $|a_{n+1}/a_n| \to 1$ as $n \to \infty$ for all *p*-series and therefore all rational or algebraic functions of n. Thus, the Ratio Test should not be used for such series.
- 7. If a_n is of the form $(b_n)^n$, then the Root Test may be useful.
- 8. If $a_n = f(n)$, where $\int_1^\infty f(x) dx$ is easily evaluated, then the Integral Test is effective (assuming the hypotheses of this test are satisfied).

Example 12.7.1. These examples show demonstrate how to identify which test should be used.

(a)
$$\sum_{n=1}^{\infty} \frac{n-1}{2n+1}$$

Since $a_n \to \frac{1}{2} \neq 0$ as $n \to \infty$, we should use the Test for Divergence.

(b)
$$\sum_{n=1}^{\infty} \frac{\sqrt{n^3 + 1}}{3n^3 + 4n^2 + 2}$$

Since a_n is an algebraic function of n, we should compare the given series with a p-series. The comparison series for the Limit Comparison Test is b_n , where

$$b_n = \frac{\sqrt{n^3}}{3n^3} = \frac{n^{3/2}}{3n^3} = \frac{1}{3n^{3/2}}$$

(c)
$$\sum_{n=1}^{\infty} ne^{-n^2}$$

Since the integral $\int_1^\infty xe^{-x^2}\ dx$ is easily evaluated, we use the Integral Test. The Ratio Test also works.

(d)
$$\sum_{n=1}^{\infty} (-1)^n \frac{n^3}{n^4 + 1}$$

Since the series is alternating, we use the Alternating Series Test.

(e)
$$\sum_{n=1}^{\infty} \frac{2^k}{k!}$$

Since the series is involves k!, we use the Ratio Test.

(f)
$$\sum_{n=1}^{\infty} \frac{1}{2+3^n}$$

Since the series is closely related to the geometric series $\sum 1/3^n$, we use the Comparison Test.

12.8 Power Series

Definition 12.8.1. A **power series** is a series of the form

$$\sum_{n=0}^{\infty} c_n x^n = c_0 + c_1 x + c_2 x^2 + c_3 x^3 + \cdots$$

where x is a variable and the c_n 's are constants called the **coefficients** of the series.

For each fixed x, the series is a series of constants that we can test for convergence or divergence. A power series may converge for some values of x and diverge for other values of x. The sum of the series is a function

$$f(x) = c_0 + c_1 x + c_2 x^2 + \dots + c_n x^n + \dots$$

whose domain is the set of all x for which the series converges. Notice that f resembles a polynomial. The only difference is that f has infinitely many terms.

For instance, if we take $c_n = 1$ for all n, the power series becomes the geometric series

$$\sum_{n=0}^{\infty} x^n = 1 + x + x^2 + \dots + x^n + \dots$$

which converges when -1 < x < 1 and diverges when $|x| \ge 1$.

Definition 12.8.2. A series of the form

$$\sum_{n=0}^{\infty} c_n (x-a)^n = c_0 + c_1 (x-a) + c_2 (x-a)^2 + c_3 (x-a)^3 + \cdots$$

is called a power series in (x - a) or a power series centered at a or a power series about a.

Notice that when x = a all of the terms are 0 for $n \ge 1$, so the power series always converges when x = a.

Fun Fact A power series is a series in which each term is a power function. A **trignometric series**

$$\sum_{n=0}^{\infty} (a_n \cos nx + b_n \sin nx)$$

is a series whose terms are trignometric functions.

Example 12.8.1. For what values of x is the series $\sum_{n=0}^{\infty} n! x^n$ convergent?

Solution. We use the Ratio Test. If we let a_n denote the nth term of the series, then $a_n = n!x^n$. If $x \neq 0$, we have

$$\lim_{n\to\infty}\left|\frac{a_{n+1}}{a_n}\right|=\lim_{n\to\infty}\left|\frac{(n+1)!x^{n+1}}{n!x^n}\right|=\lim_{n\to\infty}(n+1)|x|=\infty$$

By the Ratio Test, the series diverges when $x \neq 0$, so it converges only when x = 0.

Example 12.8.2. For what values of x does the series $\sum_{n=1}^{\infty} \frac{(x-3)^n}{n}$ converge?

Solution. Let $a_n = (x-3)^n/n$

$$\left| \frac{a_{n+1}}{a_n} \right| = \left| \frac{(x-3)^{n+1}}{n+1} \cdot \frac{n}{(x-3)^n} \right|$$

$$= \frac{1}{1+\frac{1}{n}} |x-3| \to |x-3| \quad \text{as } n \to \infty$$

By the Ratio Test, the given series is absolutely convergent, and therefore convergent, when |x-3| < 1 and divergent when |x-3| > 1. We rewrite the inequality as

$$|x-3| < 1 \iff -1 < x-3 < 1 \iff 2 < x < 4$$

Now we know the series converges when 2 < x < 4 and diverges when x < 2 or x > 4.

The Ratio Test gives no information when |x-3|=1, so we must consider x=2 and x=4 separately.

- (a) If we put x=4 in the series, it becomes the harmonic series $\sum 1/n$, which is divergent.
- (b) If x = 2, the series is $\sum (-1)^n/n$, which converges by the Alternating Series Test.

We can summarize our results by concluding that the power series converges for $2 \le x < 4$.

Theorem 12.8.1. For a given power series $\sum_{n=0}^{\infty}$ there are only three possibilities:

- 1. The series converges only when x = a.
- 2. The series converges for all x.
- 3. There is a positive number R such that the series converges if |x-a| < R and diverges if |x-a| > R.

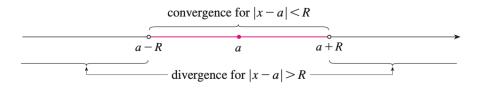
The proof of this theorem is at the end of this chapter because this theorem is more relevant than the proof.

The number R in case 3 is called the **radius of convergence** of the power series. By convention, the radius of convergence is R=0 in case 1 and $R=\infty$ in case (ii).

The **interval of convergence** of a power series is the interval that consists of just a single point a. in case 2, the interval is $(-\infty, \infty)$. In case 3, note that the inequality |x-a| < R can be rewritten as a-R < x < a+R. When x is an *endpoint* of the interval $(x=a\pm R)$, anything can happen—the series might converge at one or both endpoints, or it might diverge at both endpoints.

Thus, in case 3 there are four possibilities for the interval of convergence:

$$(a - R, a + R)$$
 $(a - R, a + R)$ $[a - R, a + R)$ $[a - R, a + R]$



We summarize the radius and interval for convergence for each of the examples in this section.

	Series	Radius of Convergence	Interval of Convergence
Geometric Series	$\sum_{n=0}^{\infty} x^n$	R = 1	(-1,1)
Example 12.8.1	$\sum_{n=0}^{\infty} n! x^n$	R = 0	{0}
Example 12.8.2	$\sum_{n=1}^{\infty} \frac{(x-3)^n}{n}$	R=1	[2,4)

In general, the Ratio Test (or sometimes the Root Test) should always be used to determine the radius of convergence R. The Ratio and Root Tests always fail when x is an endpoint of the interval of convergence, so the endpoints must be checked with some other test.

Example 12.8.3. Find the radius and interval of convergence of the series

$$\sum_{n=0}^{\infty} \frac{(-3)^n x^n}{\sqrt{n+1}}$$

Solution. Let $a_n = (-3)^n x^n / \sqrt{n+1}$.

$$\left| \frac{a_{n+1}}{a_n} \right| = \left| \frac{(-3)^{n+1} x^{n+1}}{\sqrt{n+2}} \cdot \frac{\sqrt{n+1}}{(-3)^n x^n} \right| = \left| -3x \sqrt{\frac{n+1}{n+2}} \right|$$
$$= 3\sqrt{\frac{1+(1/n)}{1+(2/n)}} |x| \to 3|x| \quad \text{as } n \to \infty$$

By the Ratio Test, the given series converges if 3|x| < 1 and diverges if 3|x| > 1. Thus, it converges if $|x| < \frac{1}{3}$ and diverges if $|x| > \frac{1}{3}$, meaning that the radius of convergences is $R = \frac{1}{3}$.

We know the series converges in the interval $(-\frac{1}{3}, \frac{1}{3})$, but we must now test for convergence at the endpoints of this interval.

(a) If
$$x = -\frac{1}{3}$$
, the series becomes $\sum_{n=0}^{\infty} \frac{(-3)^n x^n}{\sqrt{n+1}} = \sum_{n=0}^{\infty} \frac{1}{\sqrt{n+1}}$ which diverges (using the Integral Test or simply observing that it is a p -series with $p = \frac{1}{2} < 1$).

(b) If $x = \frac{1}{3}$, the series becomes $\sum_{n=0}^{\infty} \frac{(-3)^n x^n}{\sqrt{n+1}} = \sum_{n=0}^{\infty} \frac{(-1)^n}{\sqrt{n+1}}$ which converges by the Alternating Series Test. Therefore, the given power series converges when $-\frac{1}{3} < x \le \frac{1}{3}$, so the interval of convergence is $(-\frac{1}{3}, \frac{1}{3}]$.

Proof

To prove the theorem that is found earlier in this section, we first need to prove 2 theorems.

Theorem 12.8.2.

- 1. If a power series $\sum c_n x^n$ converges when x = b (where $b \neq 0$), then it converges whenever |x| < |b|.
- 2. If a power series $\sum c_n x^n$ diverges when x = d (where $d \neq 0$), then it converges whenever |x| > |d|.

Proof.

1. Suppose that $\sum c_n x^n$ converges. Then, we know $\lim_{n\to\infty} c_n b^n = 0$. According to the definition of a limit of a sequence with $\varepsilon = 1$, there is a positive integer N such that $|c_n b^n| < 1$ whenever $n \ge N$,

$$|c_n x^n| = \left| \frac{c_n b^n x^n}{b^n} \right| = |c_n b^n| \left| \frac{x}{b} \right|^n < \left| \frac{x}{b} \right|^n$$

If |x| < |b|, then |x/b| < 1, so $\sum |x/b|^n$ is a convergent geometric series. Therefore, by the Comparison Test, the series $\sum_{n=N}^{\infty} |c_n b^n|$ is convergent. Thus, the series $\sum c_n b^n$ is absolutely convergent and therefore convergent.

2. Suppose that $\sum c_n d^n$ diverges. If x is any number such that |x| > |d|, then $\sum c_n x^n$ cannot converge because, by part 1, the convergence of $\sum c_n x^n$ would imply the convergence of $\sum c_n d^n$. Therefore $\sum c_n x^n$ diverges whenever |x| > |d|.

Theorem 12.8.3. For a power series $\sum c_n x^n$ there are only three possibilities

- 1. The series converges only when x = 0.
- 2. The series converges for all x.
- 3. There is a positive number R such that the series converges if |x| < R and diverges if |x| > R.

Proof. We use the preceding theorem to prove this theorem. The symbol \in means "is an element of" or "in".

Suppose that neither case 1 nor case 2 is true. Then there are nonzero numbers b and d such that $\sum c_n x^n$ converges for x=b and diverges for x=d. Therefore, the set $S=\{x|\sum c_n x^n \text{ converges}\}$ is not empty. By the preceding theorem, the series diverges if |x|>|d|, so $|x|\geq |d|$ for all $x\in S$. This says that |d| is an upper bound for the set S. Thus, by the Completeness Axiom (see Section 12.1), S has a least upper bound R. If |x|>R, then $x\notin S$, so $\sum c_n x^n$ diverges. If |x|< R, then |x| is not an upper bound for S and so there exists $b\in S$ such that b>|x|. Since $b\in S$, $\sum c_n b^n$ converges, so by the preceding theorem $\sum c_n x^n$ converges.

Now we are ready for the proof of the main theorem found earlier in the section. We use the preceding theorem to prove it.

Proof. If we can make the change of variable u = x - a, then the power series becomes $\sum c_n u^n$ and we can apply the preceding theorem to this series. In case 3 we have convergence for |u| < R and divergence for |u| > R. Thus, we have convergence for |x - a| < R and divergence for |x - a| > R.

12.9 Representation of Functions as Power Series

In this section we learn how to represent certain types of functions as sums of power series by manipulating geometric series or by differentiating or integrating such a series.

Example 12.9.1. Express $\frac{1}{1+x^2}$ as the sum of a power series and find the interval of convergence.

Solution. Replace x with $-x^2$.

$$\frac{1}{1+x^2} = \frac{1}{1-(-x^2)} = \sum_{n=0}^{\infty} (-x^2)^n$$
$$= \sum_{n=0}^{\infty} (-1)^n x^{2n} = 1 - x^2 + x^4 - x^6 + x^8 - \dots$$

Because this is a geometric series, it converges when $|x^2| < 1$, which is the same as $x^2 < 1$ or |x| < 1. Therefore, the interval of convergence is (-1,1).

Differentiation and Integration of Power Series

The sum of a power series is a function $f(x) = \sum_{n=0}^{\infty} c_n (x-a)^n$ whose domain is the interval of convergence of the series. We would like to be able to differentiate and integrate such functions, and the following theorem says that we can do so by differentiating or integrating each individual term in the series, just as we would for a polynomial. This is called **term-by-term differentiation and integration**.

Theorem 12.9.1. If the power series $\sum c_n(x-a)^n$ has radius of convergence R > 0, then the function f defined by

$$f(x) = c_0 + c_1(x-2) + c_2(x-2)^2 + \dots = \sum_{n=0}^{\infty} c_n(x-a)^n$$

is differentiable (and therefore continuous) on the interval (a - R, a + R) and

(i)
$$f'(x) = c_1 + 2c_2(x-a) + 3c_3(x-a)^2 + \dots = \sum_{n=0}^{\infty} nc_n(x-a)^{n-1}$$

(i)
$$\int f(x) dx = C + c_0(x - a) + c_1 \frac{(x - a)^2}{2} + c_2 \frac{(x - a)^3}{3} + \cdots$$
$$= C + \sum_{n=0}^{\infty} c_n \frac{(x - a)^{n+1}}{n+1}$$

The radii of convergence of the power series in both equations are R.

Note The equations can be rewritten in the form

(i)
$$\frac{d}{dx} \left[\sum_{n=0}^{\infty} c_n (x-a)^n \right] = \sum_{n=0}^{\infty} \frac{d}{dx} [c_n (x-a)^n]$$

(ii)
$$\int \left[\sum_{n=0}^{\infty} c_n (x-a)^n \right] dx = \sum_{n=0}^{\infty} \int \left[c_n (x-a)^n \right] dx$$

Example 12.9.2. Express $\frac{1}{(1-x)^2}$ as a power series by differenting the sum of a geometric series.

Solution. Differentiate both sides of the equation

$$\frac{1}{1-x} = 1 + x + x^2 + x^3 + \dots = \sum_{n=0}^{\infty} x^n$$
$$\frac{1}{(1-x)^2} = 1 + 2x + 3x^2 + \dots = \sum_{n=0}^{\infty} nx^{n-1}$$

If we wish, we can replace n by n+1 and write the answer as

$$\frac{1}{(1-x)^2} = \sum_{n=0}^{\infty} (n+1)x^n$$

The radius of convergence of the differentiated series is the same as the radius of convergence of the original series, so R=1.

Example 12.9.3. Find a power series representation for $\ln(1-x)$ and its radius of convergence.

Solution. We notice that, besides from a factor of -1, the derivitive of this function is 1/(1-x). So we integrate both sides of the equation:

$$-\ln(1-x) = \int \frac{1}{1-x} dx = \int (1+x+x^2+\cdots) dx$$
$$= x + \frac{x^2}{2} + \frac{x^3}{3} + \cdots + C = \sum_{n=0}^{\infty} \frac{x^{n+1}}{n+1} + C$$
$$= \sum_{n=1}^{\infty} \frac{x^n}{n} + C \qquad |x| < 1$$

To determine the value of C, we plug in x=0 into the equation and get $-\ln(1-0)=C$, so C=0 and

$$\ln(1-x) = -x - \frac{x^2}{2} - \frac{x^3}{3} - \dots = \sum_{n=1}^{\infty} \frac{x^n}{n} \qquad |x| < 1$$

The radius of convergence is the same as the original series: R = 1.

Example 12.9.4.

- (a) Evaluate $\int \frac{1}{1+x^7} dx$ as a power series.
- (b) Use part (a) to approximate $\int_0^{0.5} \frac{1}{1+x^7} dx$ correct to within 10^{-7} . Solution.
- (a) First express the integrand, $\frac{1}{1+x^7}$, as the sum of apower series. We start with the sum of a geometric series and replace it x with $-x^7$.

$$\frac{1}{1+x^7} = \frac{1}{1-(-x^7)} = \sum_{n=0}^{\infty} (-x^7)^n$$
$$= \sum_{n=0}^{\infty} (-1)^n x^{7n} = 1 - x^7 + x^{14} - \dots$$

Now we integrate by term:

$$\int \frac{1}{1+x^7} dx = \int \sum_{n=0}^{\infty} (-1)^n x^{7n} dx = C + \sum_{n=0}^{\infty} (-1)^n \frac{x^{7n+1}}{7n+1}$$
$$= C + x - \frac{x^8}{8} + \frac{x^{15}}{15} - \frac{x^{22}}{22} + \cdots$$

THe series converges for $|-x^7| < 1$ which is the same as |x| < 1.

(b) We apply the Fundamental Theorem of Calculus to the antiderivative from part (a) with C=0:

$$\int_0^{0.5} \frac{1}{1+x^7} dx = \left[-\frac{x^8}{8} + \frac{x^{15}}{15} - \frac{x^{22}}{22} + \dots \right]_0^{1/2}$$
$$= \frac{1}{2} - \frac{1}{8 \cdot 2^8} + \frac{1}{15 \cdot 2^{15}} - \frac{1}{22 \cdot 2^{22}} + \dots + \frac{(-1)^n}{(7n+1)2^{7n+1}} + \dots$$

This infinite series is the exact value of the definite integral, but since it is an alternating series, we can approximate the sum using the Alternating Series Estimation Theorem. If we stop adding after the term n=3, the error is smaller than the term with n=4:

$$\frac{1}{29 \cdot 2^2 9} \approx 6.4 \times 10^{-11}$$

So we have

$$\int_0^{0.5} \frac{1}{1+x^7} dx \approx \frac{1}{2} - \frac{1}{8 \cdot 2^8} + \frac{1}{15 \cdot 2^{15}} - \frac{1}{22 \cdot 2^{22}} \approx 0.49951374$$

12.10 Taylor and Maclaurin Series

Theorem 12.10.1. If f has a power series representation (expansion) at a, that is, if

$$f(x) = \sum_{n=0}^{\infty} c_n (x-a)^n \qquad |x-a| < R$$

then its coefficients are given by the formula

$$c_n = \frac{f^{(n)}(a)}{n!}$$

Substituting this formula for c_n back into the series, we see that if f has a power series expansion at a, then it must be of the following form.

Definition 12.10.1. The Taylor series of the function f at a (or about a or centered at a) is of the form

$$f(x) = \sum_{n=0}^{\infty} \frac{f^{(n)}(a)}{n!} (x - a)^n$$

= $f(a) + \frac{f'(a)}{1!} (x - a) + \frac{f''(a)}{2!} (x - a)^2 + \frac{f'''(a)}{3!} (x - a)^3 + \cdots$

Definition 12.10.2. The Maclaurin series is a special case of the Taylor series when a = 0.

$$f(x) = \sum_{n=0}^{\infty} \frac{f^{(n)}(0)}{n!} x^n = f(0) + \frac{f'(0)}{1!} x + \frac{f''(0)}{2!} x^2 + \cdots$$

Example 12.10.1. Find the Maclaurin series of the function $f(x) = e^x$ and its radius of convergence. Also, find the Taylor series at a.

Solution. If $f(x) = e^x$, then $f^n(x) = e^x$, so $f^n(0) = e^x = e^0 = 1$ for all n. Therefore, the Taylor series for f at 0 (Maclaurin series) is

$$\sum_{n=0}^{\infty} \frac{f^{(n)}(0)}{n!} = \sum_{n=0}^{\infty} \frac{x^n}{n!}$$

To find the radius of convergence we let $a_n = x^n/n!$, so

$$\left| \frac{a_{n+1}}{a_n} \right| = \left| \frac{x^{n+1}}{(n+1)!} \cdot \frac{n!}{x^n} \right| = \frac{|x|}{n+1} \to 0 < 1$$

so the series converges for all x by the Ratio Test and the radius of convergence is $R = \infty$.

The Taylor series at a is

$$f(x) = \sum_{n=0}^{\infty} \frac{f^{(n)}(a)}{n!} (x-a)^n = \sum_{n=0}^{\infty} \frac{e^a}{n!} (x-a)^n$$

Theorem 12.10.2. If $f(x) = T_n(x) + R_n(x)$, where T_n is the *n*th degree polynomial if f at a, R_n is the remainder of the Taylor series, and

$$\lim_{n \to \infty} R_n(x) = 0$$

for |x-a| < R, then f is equal to the sum of its Taylor series on the interval |x-a| < R.

Proof. We are determining under what circumstances is a function equal to the sum of its Taylor Series. In other words, if f has derivatives of all orders, when is it true that

$$f(x) = \sum_{n=0}^{\infty} \frac{f^{(n)}(a)}{n!} (x-a)^n$$

As with any convergent series, this means that f(x) is the limit of the sequence of partial sums. In the case of the Taylor series, the partial sums are

$$T_n(x) = \sum_{i=0}^{\infty} \frac{f^{(i)}(a)}{n!} (x-a)^i$$

= $f(a) + \frac{f'(a)}{1!} (x-a) + \frac{f''(a)}{2!} (x-a)^2 + \dots + \frac{f^{(n)}(a)}{n!} (x-a)^n$

For example, for the polynomial function $f(x) = e^x$, the Taylor polynomials at 0 (or Maclaurin polynomials) with n = 1, 2, and 3 are

$$T_1(x) = 1 + x$$
 $T_2(x) = 1 + x + \frac{x^2}{2!}$ $T_3(x) = 1 + x + \frac{x^2}{2!} + \frac{x^3}{3!}$

In general, f(x) is the sum of its Taylor series if

$$f(x) = \lim_{n \to \infty} T_n(x)$$

If we let

$$R_n(x) = f(x) - T_n(x)$$
 so that $f(x) = T_n(x) + R_n(x)$

then $R_n(x)$ is the remainder of the Taylor series. If we can somehow show that $\lim_{n\to\infty} R_n(x) = 0$, then it follows that

$$\lim_{n \to \infty} T_n(x) = \lim_{n \to \infty} [f(x) - R_n(x)] = f(x) - \lim_{n \to \infty} R_n(x) = f(x)$$

In trying to show that $\lim_{n\to\infty} R_n(x) = 0$ for a specific function f, we usually use the following fact.

Definition 12.10.3 (Taylor's Inequality). If $|f^{(n+1)}(x)| \leq M$ for $|x-a| \leq d$, then the remainder $R_n(x)$ of the Taylor series satisfies the inequality

$$|R_n(x)| \le \frac{M}{(n+1)!} |x-a|^{n+1}$$
 for $|x-a| \le d$

It is helpful to use the following fact.

Definition 12.10.4. $\lim_{n\to\infty}\frac{x^n}{n!}=0$ for every real number x

Definition 12.10.5

$$e^x = \sum_{n=0}^{\infty} \frac{x^n}{n!}$$
 for every real number x

If we plug in x=1, we get the following expression for the number e as a sum of an infinite series:

$$e = \sum_{n=0}^{\infty} \frac{1}{n!} = 1 + \frac{1}{1!} + \frac{2}{2!} + \frac{3}{3!} + \cdots$$

Proof. If $f(x) = e^x$, then $f^{(n+1)}(x) = e^x$ for all n. If d is a positive number and $|x| \le d$, then $|f^{(n+1)}(x)| = e^x \le e^d$. So Taylor's inequality, with a = 0, and $M = e^d$, says that

$$|R_n(x)| \le \frac{e^d}{(n+1)!} |x|^{n+1} \quad \text{for} |x| \le d$$

Notice that we have the same constant $M=e^d$ for every value of n. But because $\lim_{n\to\infty}\frac{x^n}{n!}=0$, we have

$$\lim_{n \to \infty} \frac{e^d}{(n+1)!} |x|^{n+1} = e^d \lim_{n \to \infty} \frac{|x|^{n+1}}{(n+1)!} = 0$$

It follows from the Squeeze Theorem that $\lim_{n\to\infty} |R_n(x)| = 0$ and therefore $\lim_{n\to\infty} R_n(x) = 0$ for all values of x.

Definition 12.10.6.

(i)
$$\sin x = \sum_{n=0}^{\infty} (-1)^n \frac{x^{2n+1}}{(2n+1)!}$$
 for all x

(ii)
$$\cos x = \sum_{n=0}^{\infty} (-1)^n \frac{x^{2n}}{(2n)!}$$
 for all x

Proof. The strategy is to find the Maclaurin series for $\sin x$ and prove that it represents $\sin x$ for all x, and then differentiate it to find the Maclaurin series for $\cos x$.

(i) We arrange our computation in two columns:

$$f(x) = \sin x \qquad f(0) = 0$$

$$f'(x) = \cos x \qquad f'(0) = 1$$

$$f''(x) = -\sin x \qquad f''(0) = 0$$

$$f'''(x) = -\cos x \qquad f'''(0) = -1$$

$$f^{(4)}(x) = \sin x \qquad f^{(4)}(0) = 0$$

Since the derivatives repeat in a cycle of four, we can write the Maclaurin series as

$$f(0) + \frac{f'(0)}{1!} + \frac{f''(0)}{2!} + \frac{f'''(0)}{3!} + \cdots$$

$$= x - \frac{x^3}{x!} + \frac{x^5}{5!} - \frac{x^7}{7!} + \cdots$$

$$= \sum_{n=0}^{\infty} (-1)^n \frac{x^{2n+1}}{(2n+1)!}$$

Since $f^{(n+1)}(x)$ is $\pm \sin x$ or $\pm \cos x$, we know that $|f^{(n+1)}(x)| < \le 1$ for all x, so we can take M = 1 in Taylor's inequality:

$$|R_n(x)| \le \frac{M}{(n+1)!} |x|^{n+1} = \frac{|x|^{n+1}}{(n+1)!}$$

Since $\lim_{n\to\infty} \frac{x^n}{n!} = 0$, the right side of this inequality approaches 0 as $n\to\infty$, so $|R_n(x)|\to 0$ by the Squeeze Theorem. It follows that $R_n(x)\to 0$ as $n\to\infty$, so $\sin x$ is equal to the sum of its Maclaurin series.

(ii) We could proceed directly as the previous proof but it is easier to differentiate the Maclaurin series for $\sin x$.

$$\cos x = \frac{d}{dx}\sin x = \frac{d}{dx}\left(x - \frac{x^3}{x!} + \frac{x^5}{5!} - \frac{x^7}{7!} + \cdots\right)$$
$$= 1 - \frac{3x^2}{3!} + \frac{5x^4}{5!} - \frac{7x^6}{7!} + \cdots = 1 - \frac{x^2}{2!} + \frac{x^4}{4!} - \frac{x^6}{6!} + \cdots$$

Since the Maclaurin series for $\sin x$ converges for all x, the differentiated series for $\cos x$ also converges for all x, so

$$= \sum_{n=0}^{\infty} (-1)^n \frac{x^{2n}}{(2n)!} \quad \text{for all } x$$

Example 12.10.2. Find the Maclaurin series for the function $f(x) = x \cos x$.

Solution. Multiply the series for $\cos x$ by x.

$$x\cos x = x\sum_{n=0}^{\infty} (-1)^n \frac{x^{2n}}{(2n)!} = \sum_{n=0}^{\infty} (-1)^n \frac{x^{2n+1}}{(2n)!}$$

Important Maclaurin series Interval of Convergence $\frac{\infty}{1-\frac{\infty}{2}}$

$$\frac{1}{1-x} = \sum_{n=0}^{\infty} x^n = 1 + x + x^2 + x^3 + \dots$$
 (-1,1)

$$e^{x} = \sum_{n=0}^{\infty} \frac{x^{n}}{n!} = 1 + \frac{x}{1!} + \frac{x^{2}}{2!} + \frac{x^{3}}{3} + \dots$$
 $(-\infty, \infty)$

$$\sin x = \sum_{n=0}^{\infty} (-1)^n \frac{x^{2n+1}}{(2n+1)!} = x - \frac{x^3}{x!} + \frac{x^5}{5!} - \frac{x^7}{7!} + \dots$$
 $(-\infty, \infty)$

$$\cos x = \sum_{n=0}^{\infty} (-1)^n \frac{x^{2n}}{(2n)!} = 1 - \frac{x^2}{2!} + \frac{x^4}{4!} - \frac{x^6}{6!} + \dots$$
 $(-\infty, \infty)$

$$\tan^{-1} x = \sum_{n=0}^{\infty} (-1)^n \frac{x^{2n+1}}{2n+1} = x - \frac{x^3}{x!} + \frac{x^5}{5!} - \frac{x^7}{7!} + \dots$$
 (-1,1]

Example 12.10.3.

- (a) Evaluate $\int e^{-x^2} dx$ as an infinite series.
- (b) Evaluate $\int_0^1 e^{-x^2} dx$ correct to within an error of 0.001.

Solution.

(a) First we find the Maclaurin series for e^{-x^2} dx by replacing x with $-x^2$ in the series for e^x given in the table for Maclaurin series. Thus, for all values of x,

$$e^{-x^2} = \sum_{n=0}^{\infty} \frac{(-x^2)^n}{n!} = \sum_{n=0}^{\infty} (-1)^n \frac{x^{2n}}{n!} = 1 - \frac{x^2}{1!} + \frac{x^4}{2!} - \frac{x^6}{3} + \cdots$$

Now integrate by term:

$$\int e^{-x^2} dx = \int \left(1 - \frac{x^2}{1!} + \frac{x^4}{2!} - \frac{x^6}{3} + \cdots\right) dx$$
$$= C + x - \frac{x^3}{3 \cdot 1!} + \frac{x^5}{5 \cdot 2!} - \frac{x^7}{7 \cdot 3!} + \cdots + (-1)^n \frac{x^{2n+1}}{(2n+1)n!} + \cdots$$

The series converges for all x because the original series e^{-x^2} converges for all x.

(b)

$$\int_0^1 e^{-x^2} dx = \left[x - \frac{x^3}{3 \cdot 1!} + \frac{x^5}{5 \cdot 2!} - \frac{x^7}{7 \cdot 3!} + \frac{x^9}{9 \cdot 3!} - \dots \right]_0^1$$
$$= 1 - \frac{1}{3} + \frac{1}{10} - \frac{1}{42} + \frac{1}{216} - \dots$$
$$\approx 1 - \frac{1}{3} + \frac{1}{10} - \frac{1}{42} + \frac{1}{216} \approx 0.7475$$

The Alternating Series Estimation THeorem shows that the error involved in this approximation is less than

$$\frac{1}{11 \cdot 5!} = \frac{1}{1320} < 0.001$$

Multiplication and Division of Power Series

If power series are added or subtracted they behave like polynomials. In fact, they can also be multiplied and divided like polynomials. We only find the first few terms because they are the most important ones and the calculations for the later terms become tedious.

Example 12.10.4. Find the first three nonzero terms in the Maclaurin series for (a) $e^x \sin x$ and (b) $\tan x$.

Solution.

(a) Using the Maclaurin series for e^x and $\sin x$ from the table,

$$e^x \sin^x = \left(1 + \frac{x}{1!} + \frac{x^2}{2!} + \frac{x^3}{3} + \cdots\right) \left(x - \frac{x^3}{x!} + \cdots\right)$$

We multiply these expressions like polynomials and get

$$e^x \sin^x = x + x^2 + \frac{1}{3}x^3 + \cdots$$

(b) Using the Maclaurin series in the table, we have

$$\tan x = \frac{\sin x}{\cos x} = \frac{x - \frac{x^3}{3!} + \frac{x^5}{5!} - \dots}{1 - \frac{x^2}{2!} + \frac{x^4}{4!} - \dots}$$

Use long-division to get

$$\tan x = x + \frac{1}{3}x^3 + \frac{2}{15}x^5 + \cdots$$

12.11 The Binomial Series

The **Binomial Theorem** states that if a and b are any real numbers and k is a positive integer, then

$$(a+b)^k = a^k + ka^{k-1}b + \frac{k(k-1)}{2!}a^{k-2}b^2 + \frac{k(k-1)(k-2)}{3!}a^{k-3}b^3 + \dots + \frac{k(k-1)(k-2)\cdots(k-n+1)}{n!}a^{k-n}b^n + \dots + kab^{k-1} + b^k$$

The traditional notation for the binomial coefficients is

$$\binom{k}{0} = 1$$
 $\binom{k}{n} = \frac{k(k-1)(k-2)\cdots(k-n+1)}{n!}$ $n = 1, 2, \dots, k$

which enables us to write the Binomial Theorem in the abbreviated form

$$(a+b)^k = \sum_{n=0}^k \binom{k}{n} a^{k-n} b^n$$

Definition 12.11.1 (The Binomial Series). If k is any real number and |x| < 1, then

$$(1+x)^k = 1 + kx + \frac{k(k-1)}{2!}x^2 + \frac{k(k-1)(k-2)}{3!}x^3 + \cdots$$
$$= \sum_{n=0}^{\infty} {n \choose n} x^n$$

where
$$\binom{k}{n} = \frac{k(k-1)\cdots(k-n+1)}{n!}$$
 $(n \ge 1)$ and $\binom{k}{0} = 1$

Proof. Newton extended the Binomial Theorem to the case in which k is no longer a positive integer. In particular, if we put a=1 and b=k, we get

$$(1+x)^k = \sum_{n=0}^{\infty} \binom{k}{n} x^n$$

To find this series we compute the Maclaurin series of $(1+x)^k$ in the usual way.

$$f(x) = (1+x)^{k} f(0) = 1$$

$$f'(x) = k(1+x)^{k-1} f'(0) = k$$

$$f''(x) = k(k-1)(1+x)^{k-2} f''(0) = k(k-1)$$

$$f'''(x) = k(k-1)(k-2)(1+x)^{k-3} f'''(0) = k(k-1)(k-2)$$

$$\vdots \vdots \vdots$$

$$f^{(n)}(x) = k(k-1) \cdots (k-n+1)(1+x)^{k-n} f^{(n)}(0) = k(k-1) \cdots (k-n+1)$$

Therefore the Maclaurin series of $f(x) = (1+x)^k$ is

$$\sum_{n=0}^{\infty} \frac{f^{(n)}(0)}{n!} x^n = \sum_{n=0}^{\infty} \frac{k(k-1)\cdots(k-n+1)}{n!} x^n$$

Now we use the Ratio Test to test the binomial series for convergence. If the nth term is a_n , then

$$\left| \frac{a_{n+1}}{a_n} \right| = \left| \frac{k(k-1)\cdots(k-n+1)(k-n)x^{n+1}}{(n+1)!} \cdot \frac{n!}{k(k-1)\cdots(k-n+1)x^n} \right|$$

$$= \frac{|k-n|}{x+1}|x| = \frac{\left| 1 - \frac{k}{n} \right|}{1 + \frac{1}{n}}|x| \to |x| \quad \text{as } n \to \infty$$

The binomial series converges if |x| < 1 and diverges if |x| > 1 by the Ratio Test.

Example 12.11.1. Expand $\frac{1}{(1+x)^2}$ as a power series.

Solution. Use the binomial series with k=2. The binomial coefficient is

$${\binom{-2}{n}} = \frac{(-2)(-3)(-4)\cdots(-2-n+1)}{n!}$$
$$= \frac{(-1)^n 2 \cdot 3 \cdot 4 \cdot \dots \cdot n(n+1)}{n!} = (-1)^n (n+1)$$

and so, when |x| < 1,

$$\frac{1}{(1+x)^2} = (1+x)^{-2} = \sum_{n=0}^{\infty} {\binom{-2}{n}} x^n$$
$$= \sum_{n=0}^{\infty} (-1)^n (n+1) x^n = 1 - 2x + 3x^2 - 4x^3 + \cdots$$

12.12 Applications of Taylor Polynomials

Two applications of Taylor polynomials are to approximate functions and use them in physics.

Approximating Functions by Polynomials

In section 12.10, we introduced the notion for $T_n(x)$ for the *n*th partial sum of this series. Since f is the sum of its Taylor series, we know that $T_n(x) \to \infty$ as $n \to \infty$ so T_n can be used as an approximation to f: $f(x) \approx T_n(x)$.

When using a Taylor polynomial T_n to approximate a function f, we have to ask the questions: How good an approximation is it? How large should we take n to be in order to achieve a desired accuracy? To answer these questions we need to look at the absolute value of the remainder:

$$|R_n(x)| = |f(x) - T_n(x)|$$

There are three possible methods for estimating the size of the error:

- 1. If a graphing device is available, we can use it to graph $|R_n(x)|$ and thereby graphing the error.
- 2. If the series happens to be an alternating series, we can use the Alternating Series Estimation Theorem.
- 3. In all cases we can use Taylor's Inequality, which says that if $|f^{(n+1)}(x)| \le M$, then

$$|R_n(x)| \le \frac{M}{(n+1)!} |x-a|^{n+1}$$

Example 12.12.1.

- (a) Approximate the function $f(x) = \sqrt[3]{x}$ by a Taylor polynomial of degree 2 at a = 8.
- (b) How accurate is this approximation when $7 \le x \le 9$? Solution.

(a)
$$f(x) = \sqrt[3]{x} = x^{1/3} \qquad f(8) = 2$$

$$f'(x) = \frac{1}{3}x^{-2/3} \qquad f'(8) = \frac{1}{12}$$

$$f''(x) = -\frac{2}{9}x^{-5/3} \qquad f'(8) = -\frac{1}{144}$$

$$f'''(x) = \frac{10}{12}x^{-8/3}$$

Thus, the second-degree Taylor polynomial is

$$T_2(x) = f(8) + \frac{f'(8)}{1!}(x-8) + \frac{f'(8)}{2!}(x-8)^2$$
$$= 2 + \frac{1}{12}(x-8) - \frac{1}{288}(x-8)^2$$

The desired approximation is

$$\sqrt[3]{x} \approx T_2(x) = 2 + \frac{1}{12}(x-8) - \frac{1}{288}(x-8)^2$$

(b) The Taylor series is not alternating when x < 8, so we can't use the Alternating Series Estimation Theorem, but we can use Taylor's Inequality with n = 2 and a = 8:

$$|R_2(x)| \le \frac{M}{3!}|x - 8|^3$$

where $|f'''(x)| \leq M$. Because $x \geq 7$, we have $x^{8/3} \geq 7^{8/3}$ and so

$$f'''(x) = \frac{10}{27} \cdot \frac{1}{x^{8/3}} \le \frac{10}{27} \cdot \frac{1}{7^{8/3}} < 0.0021$$

Therefore, we can take M=0.0021. Also $7\leq x\leq 9$ so $-1\leq x-8\leq 1$ and $|x-8|\leq 1$. Taylor's inequality gives

$$|R_2(x)| \le \frac{0.0021}{3!} \cdot 1^3 = \frac{0.0021}{6} \le 0.0004$$

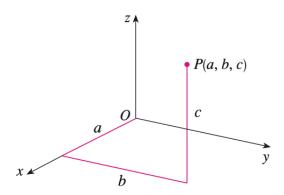
Thus, if $7 \le x \le 9$, the approximation in part (a) is accurate to within 0.0004.

Chapter 13

Vectors and the Geometry of Space

13.1 Three-Dimensional Coordinate Systems

An ordered pair (a, b) of real numbers is used to represent a point in a plane, which is two-dimensional. To locate a point in space, which is three-dimensional, we use an ordered triple (a, b, c) of real numbers.



To represent points in space we draw three perpendicular lines, called the **coordinate axes** and labeled the x-axis, y-axis, and z-axis, through a fixed point O (the origin). The three coordinate axes determine the three **coordinate planes**: the xy-plane contains the x- and y-axes; the yz-plane contains the y- and z-axes; the xz-plane contains the x- and z-axes. The three coordinate planes divided space into eight parts called **octants**. The **first octant** is the side we typically see and represents the positive axes.

If P is any point in space, let a be the x-coordinate, let b be the y-coordinate, and let c be the z-coordinate. We represent point P by the ordered triple

(a, b, c). If we drop a perpendicular from P to the xy-plane, we get a point Q with coordinates (a, b, 0) called the **projection** of P on the xy-plane. Similarly, R(0, b, c) is the projection of P on the yz-plane and S(a, 0, c) is the projection of P on the xz-plane.

The Cartesian product $\mathbb{R} \times \mathbb{R} \times \mathbb{R} = \{(x, y, z) | x, y, z \in \mathbb{R}\}$ is the set of all ordered triples of real numbers and is denoted by \mathbb{R}^3 . This is called a **three-dimensional rectangular coordinate system**.

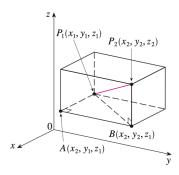
In two-dimensional analytic geomemtry, the graph of an equation involving x and y is a **curve** in \mathbb{R}^2 . In three-dimensional analytic geomemtry, an equation in x, y, and z is a **surface** in \mathbb{R}^3 .

The formula for distance between two points in a plane is easily extended to a formula for three dimensions.

Definition 13.1.1 (Distance Formula in Three Dimensions). The distance $|P_1P_2|$ between the points $P_1(x_1, y_1, z_1)$ and $P_2(x_2, y_2, z_2)$ is

$$|P_1P_2| - \sqrt{(x_2 - x_1)^2 + (y_2 - y_1)^2 + (z_2 - z_1)^2}$$

Proof. Construct a rectangular box where P_1 and P_2 are opposite vertices and the sides of the box is parallel to the coordinate planes.



If $A(x_2, y_1, z_1)$ and $B(x_2, y_2, z_1)$ are the vertices of the box indicated in the figure, then

$$|P_1A| = |x_2 - x_1|$$
 $|AB| = |y_2 - y_1|$ $|BP_2| = |z_2 - z_1|$

Because triangles P_1BP_2 and P_1AB are both right triangles, two applications of the Pythagorean Theorem give

$$|P_1P_2|^2 = |P_1B|^2 + |BP_2|^2$$

 $|P_1B|^2 = |P_1A|^2 + |AB|^2$

Combine these equations through substitution to get

$$|P_1P_2|^2 = |P_1A|^2 + |AB|^2 + |BP_2|^2$$

$$= |x_2 - x_1|^2 + |y_2 - y_1|^2 + |z_2 - z_1|^2$$

$$= (x_2 - x_1)^2 + (y_2 - y_1)^2 + (z_2 - z_1)^2$$

$$= \sqrt{(x_2 - x_1)^2 + (y_2 - y_1)^2 + (z_2 - z_1)^2}$$

Example 13.1.1. The distance from point P(2, -1, 7) to the point Q(1, -3, 5) is

$$|PQ| = \sqrt{(1-2)^2 + (-3-1)^2 + (5-7)^2} = \sqrt{1+4+4} = 3$$

Just as the two-dimensional distance formula can be used to define the equation of a circle, the three-dimensional distance formula can be used to define the equaition of a sphere.

Definition 13.1.2 (Equation of a Sphere). An equation of a sphere with center C(h, k, l) and radius r is

$$(x-h)^2 + (y-k)^2 + (z-l)^2 = r^2$$

In particular, if the center is the origin O, then an equation of the sphere is

$$x^2 + y^2 + z^2 = r^2$$

Proof. By definition, a sphere is the set of all points P(x, y, z) whos distance from center C(h, k, l) is radius r. Thus, P is on the sphere if and only if |PC| = r. Squaring both sides, we have $|PC|^2 = r^2$, or

$$(x-h)^2 + (y-k)^2 + (z-l)^2 = r^2$$

Example 13.1.2. Show that $x^2 + y^2 + z^2 + 4x - 6y + 2z + 6 = 0$ is the equation of a sphere, and find its center and radius.

Solution. We can rewrite the given equation in the form of an equation of a sphere by completing the square:

$$(x^{2} + 4x + 4) + (y^{2} - 6y + 9)(z^{2} + 2z + 1) = -6 + 4 + 9 + 1$$
$$(x + 2)^{2} + (y - 3)^{2} + (z + 1)^{2} = 8$$

Comparing this equation with the standard form, we see that it is the equation of a sphere with center (-2, 3, -1) and radius $\sqrt{8} = 2\sqrt{2}$.

Example 13.1.3. What region in \mathbb{R}^3 is represented by $1 \le x^2 + y^2 + z^2 \le 4$, $z \le 0$?

Solution. Rewrite the inequality as $1 \le \sqrt{x^2 + y^2 + z^2} \le 2$, which represents the points whose distance from the origin is at least 1 and at most 2. Since $z \le 0$, the points lie on or below the xy-plane. The inequalities represent the lower hemisphere between the radii 1 and 2.

13.2 Vectors

A **vector** indicates a quantity that has both magnitude and direction and is often represented by an arrow. The length of the arrow represents its magnitude and the direction represents the vector's direction. A vector is generally typed in boldface (\mathbf{v}) and written with an arrow above the letter (\vec{v}) .

Suppose a particle moves from A to B, so its **displacement vector v** is \overrightarrow{AB} . The vector has **initial point** A and **terminal point** B and the vector is indicated by $\mathbf{v} = \overrightarrow{AB}$. Suppose another vector \mathbf{u} has the same length and direction as \mathbf{v} even though it is in a different position. We can say that \mathbf{u} and \mathbf{v} are **equivalent** (or **equal**) and we write $\mathbf{u} = \mathbf{v}$. The **zero vector**, denoted by $\mathbf{0}$, has length $\mathbf{0}$. It is the only vector with no specific direction.

Definition 13.2.1 (**Definition of Vector Addition**). If \mathbf{u} and \mathbf{v} are vectors positioned so the initial point of \mathbf{v} is at the terminal point of \mathbf{u} , then the sum $\mathbf{u} + \mathbf{v}$ is the vector from the initial point of \mathbf{u} to the terminal point of \mathbf{v} .

The definition of vector addition is sometimes called the **Triangle Law**. We can also use what we know about vectors to visualize the **Parallelogram Law**.





Definition 13.2.2 (**Definition of Scalar Multiplication**). If c is a scalar and \mathbf{v} is a vector, the the **scalar multiple** $c\mathbf{v}$ is the vector whose length is |c| times the length of \mathbf{v} and whose direction is the same as \mathbf{v} if c > 0 and is opposite if c < 0. If c = 0 or $\mathbf{v} = \mathbf{0}$, then $c\mathbf{v} = \mathbf{0}$.

For instance, $2\mathbf{v}$ is the same as $\mathbf{v} + \mathbf{v}$, which has the same direction as \mathbf{v} but is twice as long.

Two nonzero vectors are **parallel** if they are scaler multiples of one another. In particular, the vector $-\mathbf{v} = (-1)\mathbf{v}$ has the same length as \mathbf{v} but points in the opposite direction and is called the **negative** of \mathbf{v} .

The **difference** $\mathbf{u} - \mathbf{v}$ is

$$\mathbf{u} - \mathbf{v} = \mathbf{u} + (-\mathbf{v})$$

We can construct $\mathbf{u} - \mathbf{v}$ in two ways:

- 1. Draw the negative of \mathbf{v} , $-\mathbf{v}$, and add it to \mathbf{u} by the Parallelogram Law.
- 2. $\mathbf{v} + (\mathbf{u} \mathbf{v} = \mathbf{u})$, which also equals \mathbf{u} , so we could construct $\mathbf{u} \mathbf{v}$ by the Triangle Law.



Components

If we place the initial point of a vector \mathbf{a} at the origin of a rectangular coordinate system, then the terminal point of \mathbf{a} has coordinates of the form (a_1, a_2) or (a_1, a_2, a_3) depending on the dimensions of the coordinate system. These coordinates are called the **components** of \mathbf{a} .

$$\mathbf{a} = \langle a_1, a_2 \rangle$$
 or $\mathbf{a} = \langle a_1, a_2, a_3 \rangle$

We use the notation $\langle a_1, a_2 \rangle$ that refers to a vector so we don't confuse it with the ordered pair (a_1, a_2) that refers to a point in the plane.

Definition 13.2.3. Given the points $A(x_1, y_1, z_1)$ and $B(x_2, y_2, z_2)$, the vector \vec{a} with representation \vec{AB} is

$$\mathbf{a} = \langle x_2 - x_1, y_2 - y_1, z_2 - z_1 \rangle$$

Example 13.2.1. Find the vector represented by the directed line segment with initial point A(2, -3, 4) and B(-2, 1, 1).

Solution. The vector corresponding to \vec{AB} is

$$\mathbf{a} = \langle -2 - 2, 1 - (-3), 1 - 4 \rangle = \langle -4, 4, -3 \rangle$$

The **magnitude** or **length** of the vector \mathbf{v} is the length of any of its representations and is denoted by the symbol |v| or ||v||. By using the distance formula to compute the length of a segment OP, we obtain the following formulas.

Definition 13.2.4.

The length of the two-dimensional vector $\mathbf{a} = \langle a_1, a_2 \rangle$ is

$$|\mathbf{a}| = \sqrt{a_1^2 + a_2^2}$$

The length of the three-dimensional vector $\mathbf{a} = \langle a_1, a_2, a_3 \rangle$ is

$$|\mathbf{a}| = \sqrt{a_1^2 + a_2^2 + a_3^2}$$

Definition 13.2.5. If $\mathbf{a} = \langle a_1, a_2 \rangle$ and $\mathbf{b} = \langle b_1, b_2 \rangle$, then

$$\mathbf{a} + \mathbf{b} = \langle a_1 + b_1, a_2 + b_2 \rangle$$

$$\mathbf{a} - \mathbf{b} = \langle a_1 - b_1, a_2 - b_2 \rangle$$

$$c\mathbf{a} = \langle ca_1, ca_2 \rangle$$

Similarly, for three-dimensional vectors,

$$\langle a_1, a_2, a_3 \rangle + \langle b_1, b_2, b_3 \rangle = \langle a_1 + b_1, a_2 + b_2, a_3 + b_3 \rangle$$

 $\langle a_1, a_2, a_3 \rangle - \langle b_1, b_2, b_3 \rangle = \langle a_1 - b_1, a_2 - b_2, a_3 - b_3 \rangle$
 $c \langle a_1, a_2, a_3 \rangle = \langle ca_1, ca_2, ca_3 \rangle$

We denote V_2 as the set of all two-dimensional vectors and V_3 as the set of all three-dimensional vectors. More generally, we consider V_n the set of all n-dimensional vectors. An n-dimensional vector is an ordered n-tuple:

$$\mathbf{a} = \langle a_1, a_2, \dots, a_n \rangle$$

Definition 13.2.6 (Properties of Vectors). If \mathbf{a} , \mathbf{b} , and \mathbf{c} are vectors in V_n and c and d are scalars, then

- 1. a + b = b + a
- 2. $\mathbf{a} + (\mathbf{b} + \mathbf{c}) = (\mathbf{a} + \mathbf{b}) + \mathbf{c}$
- 3. a + 0 = a
- 4. $\mathbf{a} + (-\mathbf{a}) = \mathbf{0}$
- 5. $c(\mathbf{a} + \mathbf{b}) = c\mathbf{a} + c\mathbf{b}$
- 6. $(c+d)\mathbf{a} = c\mathbf{a} + d\mathbf{a}$
- 7. $(cd)\mathbf{a} = c(d\mathbf{a})$
- 8. 1a = a

Any vector in V_3 can be expressed in terms of the **standard basis vectors** $\hat{\mathbf{i}}$, $\hat{\mathbf{j}}$, and $\hat{\mathbf{k}}$. Such vectors are typically written with a hat. Let

$$\hat{\mathbf{i}} = \langle 1, 0, 0 \rangle$$
 $\hat{\mathbf{j}} = \langle 0, 1, 0 \rangle$ $\hat{\mathbf{k}} = \langle 0, 0, 1 \rangle$

Then $\hat{\mathbf{i}}$, $\hat{\mathbf{j}}$, and $\hat{\mathbf{k}}$ are vectors that have length 1 and point in the direction of the positive x-, y-, and z-axes. Similarly, in two dimensions we define $\hat{\mathbf{i}} = \langle 1, 0 \rangle$ and $\hat{\mathbf{j}} = \langle 0, 1 \rangle$.



Proof. We prove that these any vectors in V_3 can be in terms of $\hat{\mathbf{i}}$, $\hat{\mathbf{j}}$, and $\hat{\mathbf{k}}$.

If $\mathbf{a} = \langle a_1, a_2, a_3 \rangle$, then we write

$$\mathbf{a} = \langle a_1, a_2, a_3 \rangle = \langle a_1, 0, 0 \rangle + \langle 0, a_2, 0 \rangle + \langle 0, 0, a_3 \rangle$$
$$= a_1 \langle 1, 0, 0 \rangle + a_2 \langle 0, 1, 0 \rangle + a_3 \langle 0, 0, 1 \rangle$$
$$\mathbf{a} = a_1 \hat{\mathbf{i}} + a_2 \hat{\mathbf{j}} + a_3 \hat{\mathbf{k}}$$

Similarly, in two dimensions, we write

$$\mathbf{a} = \langle a_1, a_2 \rangle = a_1 \mathbf{\hat{i}} + a_2 \mathbf{\hat{j}}$$

Example 13.2.2. For instance,

$$\langle 1, -2, 6 \rangle = \hat{\mathbf{i}} - 2\hat{\mathbf{j}} + 6\hat{\mathbf{k}}$$

A unit vector is a vector whose length is 1. For instance $\hat{\mathbf{i}}$, $\hat{\mathbf{j}}$, and $\hat{\mathbf{k}}$ are all unit vectors.

Definition 13.2.7. In general, if $\mathbf{a} \neq \mathbf{0}$, then the unit vector that has the same direction as \mathbf{a} is

$$\mathbf{u} = \frac{1}{|\mathbf{a}|} \mathbf{a} = \frac{\mathbf{a}}{|\mathbf{a}|}$$

Proof. Let $c = 1/|\mathbf{a}|$. Then $\mathbf{u} = c\mathbf{a}$ and c is a positive scalar, so \mathbf{u} has the same direction as \mathbf{a} . Also

$$|\mathbf{u}| = |c\mathbf{a}| = |c||\mathbf{a}| = \frac{1}{|\mathbf{a}|}\mathbf{a} = 1$$

Example 13.2.3. Find the unit vector in the same direction of the vector $2\hat{\mathbf{i}} - \hat{\mathbf{j}} - 2\hat{\mathbf{k}}$.

Solution. The given vector has length

$$|2\hat{\mathbf{i}} - \hat{\mathbf{j}} - 2\hat{\mathbf{k}}| = \sqrt{2^2 + (-1)^2 + (-2)^2} = \sqrt{9} = 3$$

We divide the vector by its length to find the unit vector with the same direction:

$$\frac{1}{3}(2\hat{\mathbf{i}} - \hat{\mathbf{j}} - 2\hat{\mathbf{k}}) = \frac{2}{3}\hat{\mathbf{i}} - \frac{1}{3}\hat{\mathbf{j}} - \frac{2}{3}\hat{\mathbf{k}}$$

- 13.3 The Dot Product
- 13.4 The Cross Product
- 13.5 Equations of Lines and Planes
- 13.6 Cylinders and Quadric Surfaces
- 13.7 Cylindrical and Spherical Coordinates

Vector Functions

- 14.1 Vector Functions and Space Curves
- 14.2 Derivatives and Integrals of Vector Functions
- 14.3 Arc Length and Curvature
- 14.4 Motion in Space: Velocity and Acceleration

Partial Derivatives

- 15.1 Functions of Several Variables
- 15.2 Limits and Continuity
- 15.3 Partial Derivatives
- 15.4 Tangent Planes and Linear Approximations
- 15.5 The Chain Rule
- 15.6 Directional Derivatives and the Gradient Vector
- 15.7 Maximum and Minimum Values
- 15.8 Lagrange Multipliers

Multiple Integrals

16.1	Double Integrals over Rectangles
16.2	Iterated Integrals
16.3	Double Integrals over General Regions
16.4	Double Integrals in Polar Coordinates
16.5	Applications of Double Integrals
16.6	Surface Area
16.7	Triple Integrals
16.8	Triple Integrals in Cylindrical and Spherical Coordinates
16.9	Change of Variables in Multiple Integrals

Vector Calculus

- 17.1 Vector Fields
- 17.2 Line Integrals
- 17.3 THe Fundamental Theorem for Line Integrals
- 17.4 Green's Theorem
- 17.5 Curl and Divergence
- 17.6 Parametric Surfaces and Their Areas
- 17.7 Surface Integrals
- 17.8 Stokes' Theorem
- 17.9 The Divergence Theorem
- **17.10** Summary

Second-Order Differential Equations

- 18.1 Second-Order Linear Equations
- 18.2 Nonhomogenous Linear Equations
- 18.3 Applications of Second-Order Differential Equations
- 18.4 Series Solutions

Part II Linear Algebra

Vectors

- 1.1 The Geometry and Algebra of Vectors
- 1.2 Length and Angle: The Dot Product
- 1.3 Lines and Planes
- 1.4 Code Vectors and Modular Systems

Systems of Linear Equations

- 2.1 Introduction to Systems of Linear Equations
- 2.2 Direct Methods for Solving Linear Systems
- 2.3 Spanning Sets and Linear Independence
- 2.4 Applications
- 2.5 Iterative Method for Solving Linear Systems

Matrices

- 3.1 Matrix Operations
- 3.2 Matrix Algebra
- 3.3 The Inverse of a Matrix
- 3.4 The LU Factorization
- 3.5 Subspaces, Basis, Dimension, and Rank
- 3.6 Introduction to Linear Transformations
- 3.7 Applications

Eigenvalues and Eigenvectors

- 4.1 Introduction to Eigenvalues and Eigenvectors
- 4.2 Determinants
- 4.3 Eigenvalues and Eigenvectors of $n \times n$ Matrices
- 4.4 Similarity and Diagonalization
- 4.5 Iterative Methods for Computing Eigenvalues
- 4.6 Applications and the Perron-Frobenius Theorem

Orthogonality

- 5.1 Orthogonality in \mathbb{R}^n
- 5.2 Orthogonal Complements and Orthogonal Projections
- 5.3 The Gram-Schmidt Process and the QR Factorization
- 5.4 Orthogonal Diagonalization of Symmetric Matrices
- 5.5 Applications

Vector Spaces

- 6.1 Vector Spaces and Subspaces
- 6.2 Linear Independence, Basis, and Dimension
- 6.3 Change of Basis
- 6.4 Linear Transformation
- 6.5 The Kernel and Range of a Linear Transformation
- 6.6 The Matrix of a Linear Transformation
- 6.7 Applications

Distance and Approximation

- 7.1 Inner Product Spaces
- 7.2 Norms and Distance Function
- 7.3 Least Squares Approximation
- 7.4 The Singular Value Decomposition
- 7.5 Applications