Multivariable Calculus and Linear Algebra

Sarang Mohaniraj

Contents

Part I

Multivariable Calculus

Chapter 11

Parametric Equations and Polar Coordinates

11.1 Curves Defined by Parametric Equations

Suppose that x and y are both given as functions of a third variable t (called a **parameter** by the equations)

$$x = f(t) \quad y = g(t)$$

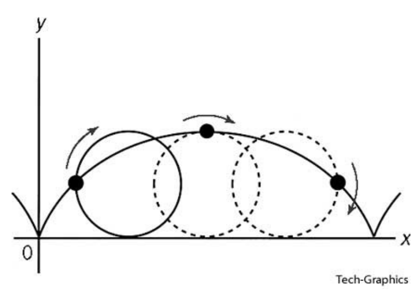
(called **parametric equations**). Each value of t determines a point (x,y). As t changes, $(x, y) = (f(t), g(t))$ changes and traces out a curve C, which is called a **parametric curve**. The direction of the arrows on curve C show the change in the position of the equation as t increases.

We can also restrict t to a finite interval. In general, the curve with parametric equations

$$x = f(t) \quad y = g(t) \quad a \leq t \leq b$$

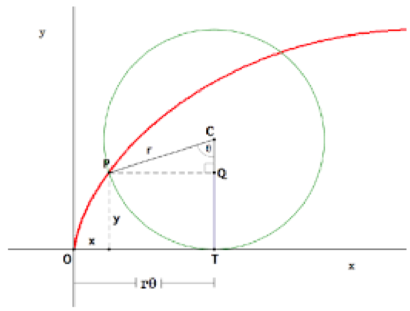
has **initial point** $(f(a), g(a))$ and **terminal point** $(f(b), g(b))$.

The Cycloid



Example 11.1.1. A circle with radius r rolls along the x-axis. The curve traced out by a point P on the circumference of the circle is called a **cycloid**. Find parametric eqations for the cycloid.

Solution. We will use the angle of rotation θ as the parameter ($\theta = 0$ when P is at the origin).



Suppose the circle has rotated θ radians. Using the figure, the distance it has rolled from the origin is

$$|OT| = arc\ PT = r\theta$$

because P starts at the origin. Therefore, the center of the circle is $C(r\theta, r)$. Let the coordinates of P be (x, y). Then from the figure,

$$x = |OT| - |PQ| = r\theta - r\sin\theta = r(\theta - \sin\theta)$$
$$y = |TC| - |QC| = r - r\cos\theta = r(1 - \cos\theta)$$

Definition 11.1.1. Paremetric equations of the cycloid are

$$x = r(\theta - \sin\theta) \quad y = r(1 - \cos\theta)$$

11.2 Calculus with Parametric Curves

We will mainly solve problems involving tangents, area, arc length, and surface area.

Tangents

In the previous section, we saw that some curves defined by parametric equations $x = f(t)$ and $y = g(t)$ can also be expressed, by eliminating the parameter, in the form $y = F(x)$. If we substitute $x = f(t)$ and $y = g(t)$ in the equation $y = F(x)$, we get

$$g(t) = F(f(t))$$

If g, f, and F are differentiable, the Chain Rule gives

$$g'(t) = F'(f(t))f'(t) = F'(x)f'(t)$$

If $f'(t) \neq 0$, we can solve for $F'(x)$:

Definition 11.2.1. The slope of the tangent to the parametric curve $y = F(x)$ is $F'(x)$.

$$F'(x) = \frac{g'(t)}{f'(t)}$$

This enables us to find tangents to parametric curves without having to eliminate the parameter. We can rewrite the previous equation in an easily remembered form.

Definition 11.2.2. We can use this to find tangents to parametric curves without having to eliminate the parameter.

$$\frac{dy}{dx} = \frac{\frac{dy}{dt}}{\frac{dx}{dt}} \text{ if } \frac{dx}{dt} \neq 0$$

The curve has a

- horizontal tangent when $\frac{dy}{dt} = 0$ (provided that $\frac{dx}{dt} \neq 0$)
- vertical tangent when $\frac{dx}{dt} = 0$ (provided that $\frac{dy}{dt} \neq 0$)

This is useful when sketching parametric curves.

Definition 11.2.3. We can also find $\frac{d^2y}{dx^2}$ by replacing y with $\frac{dy}{dx}$

$$\frac{d^2y}{dx^2} = \frac{d}{dx}\left(\frac{dy}{dx}\right) = \frac{\frac{d}{dt}\left(\frac{dy}{dx}\right)}{\frac{dx}{dt}}$$

Proof. Find $\frac{dy}{dx}$ and $\frac{d^2y}{dx^2}$ considering $y(t)$ and $g(t)$.

1.

$$\text{Chain rule: } \frac{dy}{dt} = \frac{dy}{dx}\frac{dx}{dt} \implies \frac{dy}{dx} = \frac{\frac{dy}{dt}}{\frac{dx}{dt}} \quad (\implies \text{ means "implies"})$$

2.

$$\text{Chain rule: } \frac{d}{dt}\left(\frac{dy}{dx}\right) = \left(\frac{d}{dx}\frac{dy}{dx}\right)\frac{dx}{dt} = \frac{d^2y}{dx^2}\frac{dx}{dt}$$

$$\text{Substitute: } \frac{d}{dt}\left(\frac{dy}{dx}\right) = \frac{d}{dt}\left(\frac{\frac{dy}{dt}}{\frac{dx}{dt}}\right)$$

$$\text{Quotient rule: } = \frac{\frac{d^2y}{dt^2}\frac{d^x}{dt} - \frac{dy}{dt}\frac{d^2x}{dt^2}}{\left(\frac{dx}{dt}\right)^2}$$

Set equation from line 1 and line 3 equal and divide both sides by $\frac{dx}{dt}$

$$\frac{d^2y}{dx^2} = \frac{\frac{d^2y}{dt^2}\frac{d^x}{dt} - \frac{dy}{dt}\frac{d^2x}{dt^2}}{\left(\frac{dx}{dt}\right)^2\left(\frac{dx}{dt}\right)}$$

$$= \frac{\frac{d^2y}{dt^2}\frac{d^x}{dt} - \frac{dy}{dt}\frac{d^2x}{dt^2}}{\left(\frac{dx}{dt}\right)^3}$$

□

Example 11.2.1. A curve C is defined by the parametric equations $x = t^2,\ y = t^3 - 3t$.

1. Show that C has two tangents at the point (3,0) and find their equations.
2. Find the points on C where the tangent is horizontal or vertical.
3. Determine where the curve is concave upward or downward.

Solution. A curve C is defined by the parametric equations $x = t^2,\ y = t^3 - 3t$.

1. Rewrite $y = t^3 - 3t = t(t^2 - 3) = 0$ when $t = 0$ or $t = \pm\sqrt{3}$. This indicates that C intersects itself at (3.0).

$$\frac{dy}{dx} = \frac{dy/dt}{dx/dt} = \frac{3t^2 - 3}{2t} = \frac{3}{2}\left(t - \frac{1}{t}\right)$$

$$t = \pm\sqrt{3} \to dy/dx = \pm 6/(2\sqrt{3})$$

so the equations of the tangents at (3,0) are

$$y = \sqrt{3}(x - 3) \quad \textit{and} \quad y = -\sqrt{3}(x - 3)$$

2. C has a horizontal tangent when $dy/dx = 0$. In other words, when $dy/dt = 0$ and $dx/dt \neq 0$. $dy/dt = 3t^2 - 3 = 0$ when $t^2 = 1$ so $t = \pm 1$. This means there are horizontal tangents on C at (1,-2) and (1,2). C has a vertical tangent when $dx/dt = 2t = 0$, so $t = 0$. This means C has a vertical tangent at (0,0).

3. To determine concavity we calculate the second derivative:

$$\frac{d^2y}{dx^2} = \frac{\frac{d}{dt}\left(\frac{dy}{dx}\right)}{\frac{dx}{dt}} = \frac{\frac{3}{2}\left(1 + \frac{1}{t^2}\right)}{2t} = \frac{3(t^2+1)}{4t^3}$$

   The curve is concave upward when $t > 0$ and concave downward when $t < 0$.

Area

We already know that area under a curve $y = F(x)$ from a to b is $A = \int_a^b F(x)dx$. We can apply this to parametric equations using the Substitution Rule for Definite Integrals.

Definition 11.2.4. If the curve C is given by parametric equations $x = f(t)$ and $y = g(t)$ and t increases from α to β,

$$A = \int_a^b y dx = \int_\alpha^\beta g(t)f'(t)dt$$

(Switch α to β if the point on C at β is more left than α.

Example 11.2.2. Find the area under one arch of the cycloid $x = r(\theta - \sin\theta),\ y = r(1 - \cos\theta)$.

Solution. One arch of the cycloid is given by $0 \leq \theta \leq 2\pi$. Using the Substitution Rule with $y = r(1-\cos\theta)$ and $dx = r(1-\cos\theta)d\theta$, we have

$$\begin{aligned}
A = \int_0^{2\pi} y dx = A &= \int_0^{2\pi} r(1-\cos\theta)r(1-\cos\theta)d\theta \\
&= r^2 \int_0^{2\pi} (1-\cos\theta)^2 d\theta = r^2 \int_0^{2\pi} (1 - 2\cos\theta + \cos^2\theta)d\theta \\
&= r^2 \int_0^{2\pi} \left[1 - 2\cos\theta + \frac{1}{2}(1+\cos 2\theta)\right] d\theta \\
&= r^2 \left[\frac{3}{2}\theta - 2\sin\theta + \frac{1}{4}\sin 2\theta\right]_0^{2\pi} \\
&= r^2 \left(\frac{3}{2} \cdot 2\pi\right) = 3\pi r^2
\end{aligned}$$

Arc Length

We already know how to find length L of a curve C given in the form $y = F(x)$, $a \leq x \leq b$.

Definition 11.2.5. If F' is continuous, then

$$L = \int_a^b \sqrt{1 + \left(\frac{dy}{dx}\right)^2}\, dx$$

If C can describe the parametric equations $x = f(t)$ and $y = g(t)$, $\alpha \leq t \leq \beta$, where $dx/dt = f'(t) > 0$. Using the substitution rule, we obtain

$$L = \int_a^b \sqrt{1 + \left(\frac{dy}{dx}\right)^2}\, dx = \int_\alpha^\beta \sqrt{1 + \left(\frac{dy/dt}{dx/dt}\right)^2}\, \frac{dx}{dt} dt$$

Since $dx/dt > 0$, we have

Theorem 11.1. If a curve C is described by the parametric equations $x = f(t)$, $y = g(t)$, $\alpha \leq t \leq \beta$, where f' and g' are continuous on $[\alpha, \beta]$ and C is traversed exactly once as t increases from α to β, then the length of C is

$$L = \int_\alpha^\beta \sqrt{\left(\frac{dx}{dt}\right)^2 + \left(\frac{dy}{dt}\right)^2}\, dt$$

This is consistent with the general formula $L = \int ds$ and $(ds^2) = (dx^2) + (dy^2)$.

Proof. Prove the length formula of a parametric curve

$$\begin{aligned}
\overrightarrow{ds} &= \overrightarrow{i}\, dx + \overrightarrow{j}\, dy \\
ds^2 &= \overrightarrow{ds} \cdot \overrightarrow{ds} = \left(\overrightarrow{i}\, dx + \overrightarrow{j}\, dy\right) \cdot \left(\overrightarrow{i}\, dx + \overrightarrow{j}\, dy\right) = dx^2 + dy^2 \\
ds &= \sqrt{dx^2 + dy^2} = \sqrt{\left(\frac{dx}{dt}\right)^2 + \left(\frac{dy}{dt}\right)^2}\, dt \\
L &= \int_\alpha^\beta ds = \int_\alpha^\beta \sqrt{\left(\frac{dx}{dt}\right)^2 + \left(\frac{dy}{dt}\right)^2}\, dt
\end{aligned}$$

Example 11.2.3. Find the length of the unit circle as (x,y) moves both once and twice around the circle.

Solution. For one traversal around the unit circle,

$$x = \cos t \quad y = \sin t \quad 0 \leq t \leq 2\pi$$

so $dx/dt = -\sin t$ and $dy/dt = \cos t$

$$\begin{aligned}
L &= \int_0^{2\pi} \sqrt{\left(\frac{dx}{dt}\right)^2 + \left(\frac{dy}{dt}\right)^2}\, dt = \int_0^{2\pi} \sqrt{\sin^2 t + \cos^2 t}\, dt \\
&= \int_0^{2\pi} dt = 2\pi
\end{aligned}$$

For two traversals around the unit circle,

$$x = \sin 2t \quad y = \cos 2t \quad 0 \leq t \leq 2\pi$$

so $dx/dt = 2\cos 2t$ and $dy/dt = -2\sin 2t$

$$L = \int_0^{2\pi} \sqrt{\left(\frac{dx}{dt}\right)^2 + \left(\frac{dy}{dt}\right)^2} dt = \int_0^{2\pi} \sqrt{4\cos^2 2t + 4\sin^2 2t}\ dt \quad = \int_0^{2\pi} 2\ dt = 4\pi$$

Surface Area

We can also adapt the surface area formula to a parametric curve.

Definition 11.2.6. If a curve C is described by the parametric equations $x = f(t)$, $y = g(t)$, $\alpha \leq t \leq \beta$, is rotated about the **x-axis**, where f',g' are continuous and $g(t) \geq 0$, the surface area is

$$S = \int_\alpha^\beta 2\pi y \sqrt{\left(\frac{dx}{dt}\right)^2 + \left(\frac{dy}{dt}\right)^2} dt$$

If the curve C is rotated about the **y-axis**, the surface area is

$$S = \int_\alpha^\beta 2\pi x \sqrt{\left(\frac{dx}{dt}\right)^2 + \left(\frac{dy}{dt}\right)^2} dt$$

The generic formulas $S = \int 2\pi y\ ds$ for rotation about the x-axis and $S = \int 2\pi x\ ds$ for rotation about the y-axis are still valid, but for parametric curves we use

$$ds = \sqrt{\left(\frac{dx}{dt}\right)^2 + \left(\frac{dy}{dt}\right)^2} dt$$

Example 11.2.4. Show that the surface area of a sphere of radius r is $4\pi r^2$

Solution. The sphere is obtained by rotating the semicircle

$$x = r\cos t \quad y = r\sin t \quad 0 \leq t \leq \pi$$

about the x-axis.

$$\begin{aligned} S &= \int_0^\pi 2\pi r \sin t \sqrt{(-r\sin t)^2 + (r\cos t)^2}\ dt \\ &= 2\pi \int_0^\pi r\sin t \sqrt{r^2(sin^2 t + \cos^2 t)}\ dt \\ &= 2\pi \int_0^\pi r\sin t \cdot r\ dt = 2\pi r^2 \int_0^\pi \sin t\ dt \\ &= 2\pi r^2(-\cos t)]_0^\pi = 4\pi r^2 \end{aligned}$$

11.3 Polar Coordinates

11.4 Areas and Lengths in Polar Coordinates

11.5 Conic Sections

11.6 Conic Sections in Polar Coordinates

Chapter 12

Infinite Sequences and Series

12.1 Sequences

12.2 Series

12.3 The Integral Test and Estimates of Sums

12.4 The Comparison Tests

12.5 Alternating Series

12.6 Absolute Convergence and the Ratio and Root Tests

12.7 Strategy for Testing Series

12.8 Power Series

12.9 Representation of Functions as Power Series

12.10 Taylor and Maclaurin Series

12.11 The Binomial Series

12.12 Applications of Taylor Polynomials

Chapter 13

Vectors and the Geometry of Space

Chapter 14

Vector Functions

14.1 Vector Functions and Space Curves

14.2 Derivatives and Integrals of Vector Functions

14.3 Arc Length and Curvature

14.4 Motion in Space: Velocity and Acceleration

Chapter 15

Partial Derivatives

Chapter 16

Multiple Integrals

16.1 Double Integrals over Rectangles

16.2 Iterated Integrals

16.3 Double Integrals over General Regions

16.4 Double Integrals in Polar Coordinates

16.5 Applications of Double Integrals

16.6 Surface Area

16.7 Triple Integrals

16.8 Triple Integrals in Cylindrical and Spherical Coordinates

16.9 Change of Variables in Multiple Integrals

Chapter 17

Vector Calculus

17.1 Vector Fields

17.2 Line Integrals

17.3 THe Fundamental Theorem for Line Integrals

17.4 Green's Theorem

17.5 Curl and Divergence

17.6 Parametric Surfaces and Their Areas

17.7 Surface Integrals

17.8 Stokes' Theorem

17.9 The Divergence Theorem

17.10 Summary

Chapter 18

Second-Order Differential Equations

Part II

Linear Algebra

Chapter 1

Vectors

Chapter 2

Systems of Linear Equations

Chapter 3

Matrices

3.1 Matrix Operations

3.2 Matrix Algebra

3.3 The Inverse of a Matrix

3.4 The LU Factorization

3.5 Subspaces, Basis, Dimension, and Rank

3.6 Introduction to Linear Transformations

3.7 Applications

Chapter 4

Eigenvalues and Eigenvectors

4.1 Introduction to Eigenvalues and Eigenvectors

4.2 Determinants

4.3 Eigenvalues and Eigenvectors of $n \times n$ Matrices

4.4 Similarity and Diagonalization

4.5 Iterative Methods for Computing Eigenvalues

4.6 Applications and the Perron-Frobenius Theorem

Chapter 5

Orthogonality

5.1 Orthogonality in $\mathbb{R}^n$

5.2 Orthogonal Complements and Orthogonal Projections

5.3 The Gram-Schmidt Process and the $\boldsymbol{QR}$ Factorization

5.4 Orthogonal Diagonalization of Symmetric Matrices

5.5 Applications

Chapter 6

Vector Spaces

6.1 Vector Spaces and Subspaces

6.2 Linear Independence, Basis, and Dimension

6.3 Change of Basis

6.4 Linear Transformation

6.5 The Kernel and Range of a Linear Transformation

6.6 The Matrix of a Linear Transformation

6.7 Applications

Chapter 7

Distance and Approximation

7.1 Inner Product Spaces

7.2 Norms and Distance Function

7.3 Least Squares Approximation

7.4 The Singular Value Decomposition

7.5 Applications