Assignment4

Prahlad

6/13/2020

Load Packages

```
suppressMessages(library(ggplot2))
suppressMessages(library(caret))
suppressMessages(library(e1071))
library(randomForest)

## randomForest 4.6-14

## Type rfNews() to see new features/changes/bug fixes.

##
## Attaching package: 'randomForest'

## The following object is masked from 'package:ggplot2':
##
## margin
```

Read Data

```
setwd("C:/Users/SPRAHLA2/Desktop/ml_rcourse")
#Load DataSet
df_training <- read.csv("C:/Users/SPRAHLA2/Desktop/ml_rcourse/pml-
training.csv",stringsAsFactors = FALSE)
df_testing <- read.csv("C:/Users/SPRAHLA2/Desktop/ml_rcourse/pml-
testing.csv",stringsAsFactors = FALSE)</pre>
```

Understanding Data

dimension of data

```
#colnames of data
dim(df_training)
## [1] 19622 160
```

160 variables

no of unique users

```
#no of unique users
unique(df_training$user_name)
## [1] "carlitos" "pedro" "adelmo" "charles" "eurico" "jeremy"
```

6 users in dataset

no of classes in classe

```
#classe dependent variable
unique(df_training$classe)
## [1] "A" "B" "C" "D" "E"
```

6 classe classes and number of users != number of classe

range of data

```
#data recording start and end time

min(df_training$cvtd_timestamp)

## [1] "02/12/2011 13:32"

max(df_training$cvtd_timestamp)

## [1] "30/11/2011 17:12"
```

Data is from november 30th to december 2nd

Are There Any Missing Value In Data?

```
which(sapply(df_training,function(x) sum(is.na(x))/nrow(df_training)*100)>95)
##
                                                                   min_roll_belt
              max_roll_belt
                                        max_picth_belt
##
##
             min_pitch_belt
                                   amplitude roll belt
                                                            amplitude_pitch_belt
##
       var_total_accel_belt
                                         avg_roll_belt
                                                                stddev_roll_belt
##
##
                                                               stddev_pitch_belt
##
              var roll belt
                                        avg_pitch_belt
##
##
             var_pitch_belt
                                          avg_yaw_belt
                                                                 stddev_yaw_belt
##
##
               var_yaw_belt
                                         var_accel_arm
                                                                    avg_roll_arm
##
                                                    50
                                                                               51
##
            stddev_roll_arm
                                          var_roll_arm
                                                                   avg_pitch_arm
##
                                                    53
                                                                               54
##
                                                                     avg_yaw_arm
           stddev_pitch_arm
                                         var_pitch_arm
                                                                               57
##
```

```
##
              stddev_yaw_arm
                                                                      max roll arm
                                            var_yaw_arm
##
                           58
                                                      59
                                                                                75
##
               max_picth_arm
                                                                      min_roll_arm
                                            max_yaw_arm
##
                           76
                                                      77
##
               min_pitch_arm
                                            min_yaw_arm
                                                               amplitude_roll_arm
##
                                                      80
##
        amplitude pitch arm
                                     amplitude yaw arm
                                                                max roll dumbbell
##
##
         max_picth_dumbbell
                                     min_roll_dumbbell
                                                               min_pitch_dumbbell
##
                           94
                                                      96
    amplitude roll dumbbell amplitude pitch dumbbell
##
                                                               var_accel_dumbbell
##
                           99
                                  stddev roll dumbbell
##
          avg roll dumbbell
                                                                var roll dumbbell
##
                                                    105
                                                                               106
##
         avg_pitch_dumbbell
                                 stddev_pitch_dumbbell
                                                               var_pitch_dumbbell
##
##
           avg_yaw_dumbbell
                                   stddev_yaw_dumbbell
                                                                 var_yaw_dumbbell
##
                                                    111
                                                                               112
                         110
##
           max roll forearm
                                     max picth forearm
                                                                 min roll forearm
##
                         131
                                                    132
                                                                               134
##
          min pitch forearm
                                amplitude roll forearm
                                                          amplitude pitch forearm
##
                         135
                                                    137
                                                                                138
##
                                                              stddev_roll_forearm
          var_accel_forearm
                                      avg_roll_forearm
##
                                                    142
                                                             stddev_pitch_forearm
##
           var roll forearm
                                     avg_pitch_forearm
##
                          144
                                                    145
                                                                                146
##
                                        avg_yaw_forearm
          var pitch forearm
                                                               stddev yaw forearm
##
                                                    148
                          147
                                                                               149
##
            var_yaw_forearm
##
                         150
```

Yes there are missing values.67 variables have missing value % greater than 95%. We have to be careful of variable selection for model building

Taking only set of variables which are not having high percentage of missing value and leaving out statistical derived variables like (max,min,avg,skewness,kurtosis,variance,standard deviation) for analysis

```
colnames(df_training)
##
     [1]
                                      "user name"
##
         "raw timestamp part 1"
                                      "raw timestamp part 2"
     [5] "cvtd timestamp"
                                      "new window"
##
         "num window"
                                      "roll belt"
##
     [7]
##
     [9]
         "pitch belt"
                                      "yaw belt"
                                      "kurtosis_roll_belt"
##
         "total_accel_belt"
    [13] "kurtosis picth belt"
                                      "kurtosis_yaw_belt"
```

```
[15] "skewness_roll_belt"
                                      "skewness_roll_belt.1"
                                      "max_roll_belt"
##
    [17] "skewness_yaw_belt"
##
    [19] "max_picth_belt"
                                      "max_yaw_belt"
##
    [21] "min_roll_belt"
                                      "min_pitch_belt"
##
    [23]
         "min_yaw_belt"
                                      "amplitude_roll_belt"
                                      "amplitude_yaw_belt"
##
    [25]
         "amplitude_pitch_belt"
    [27] "var_total_accel_belt"
                                      "avg_roll_belt"
    [29] "stddev_roll_belt"
                                      "var_roll_belt"
##
    [31] "avg_pitch_belt"
                                      "stddev_pitch_belt"
    [33] "var_pitch_belt"
##
                                      "avg_yaw_belt"
    [35] "stddev_yaw_belt"
##
                                      "var_yaw_belt"
                                      "gyros_belt_y"
    [37] "gyros_belt_x"
##
    [39] "gyros_belt_z"
                                      "accel_belt_x"
##
##
    [41] "accel_belt_y"
                                      "accel_belt_z"
    [43] "magnet_belt_x"
                                      "magnet_belt_y"
##
##
    [45] "magnet_belt_z"
                                      "roll_arm"
##
    [47] "pitch_arm"
                                      "yaw_arm"
    [49] "total_accel_arm"
##
                                      "var_accel_arm"
##
    [51]
         "avg_roll_arm"
                                      "stddev_roll_arm"
                                      "avg_pitch_arm"
##
    [53] "var_roll_arm"
##
    [55] "stddev_pitch_arm"
                                      "var_pitch_arm"
    [57] "avg_yaw_arm"
##
                                      "stddev_yaw_arm"
                                      "gyros_arm_x"
##
    [59] "var_yaw_arm"
                                      "gyros_arm_z"
##
    [61] "gyros_arm_y"
    [63] "accel_arm_x"
                                      "accel_arm_y"
##
    [65] "accel_arm_z"
                                      "magnet_arm_x"
    [67] "magnet_arm_y"
##
                                      "magnet_arm_z"
##
    [69] "kurtosis_roll_arm"
                                      "kurtosis_picth_arm"
##
    [71] "kurtosis_yaw_arm"
                                      "skewness_roll_arm"
##
    [73] "skewness_pitch_arm"
                                      "skewness_yaw_arm"
##
    [75] "max_roll_arm"
                                      "max_picth_arm"
##
    [77] "max_yaw_arm"
                                      "min_roll_arm"
##
    [79] "min_pitch_arm"
                                      "min_yaw_arm"
                                      "amplitude_pitch_arm"
    [81] "amplitude_roll_arm"
    [83] "amplitude_yaw_arm"
                                      "roll_dumbbell"
##
    [85] "pitch_dumbbell"
##
                                      "yaw_dumbbell"
    [87] "kurtosis_roll_dumbbell"
##
                                      "kurtosis_picth_dumbbell"
##
    [89] "kurtosis_yaw_dumbbell"
                                      "skewness_roll_dumbbell"
    [91] "skewness_pitch_dumbbell"
                                      "skewness_yaw_dumbbell"
##
    [93] "max_roll_dumbbell"
                                      "max_picth_dumbbell"
##
##
    [95] "max_yaw_dumbbell"
                                      "min_roll_dumbbell"
                                      "min_yaw_dumbbell"
##
    [97] "min_pitch_dumbbell"
    [99] "amplitude_roll_dumbbell"
                                      "amplitude_pitch_dumbbell"
## [101] "amplitude_yaw_dumbbell"
                                      "total_accel_dumbbell"
## [103] "var_accel_dumbbell"
                                      "avg_roll_dumbbell"
## [105] "stddev_roll_dumbbell"
                                      "var_roll_dumbbell"
## [107] "avg_pitch_dumbbell"
                                      "stddev_pitch_dumbbell"
## [109] "var_pitch_dumbbell"
                                      "avg_yaw_dumbbell"
## [111] "stddev_yaw_dumbbell"
                                      "var_yaw_dumbbell"
## [113] "gyros_dumbbell_x"
                                      "gyros_dumbbell_y"
```

```
## [115] "gyros_dumbbell_z"
                                     "accel dumbbell x"
## [117] "accel dumbbell y"
                                     "accel dumbbell z"
## [119] "magnet_dumbbell_x"
                                     "magnet_dumbbell_y"
## [121] "magnet_dumbbell_z"
                                     "roll forearm"
## [123] "pitch_forearm"
                                     "yaw_forearm"
## [125] "kurtosis_roll_forearm"
                                     "kurtosis_picth_forearm"
## [127] "kurtosis_yaw_forearm"
                                     "skewness_roll_forearm"
## [129] "skewness_pitch_forearm"
                                     "skewness_yaw_forearm"
                                     "max_picth_forearm"
## [131] "max_roll_forearm"
## [133] "max_yaw_forearm"
                                     "min roll forearm"
## [135] "min_pitch_forearm"
                                     "min_yaw_forearm"
## [137] "amplitude roll forearm"
                                     "amplitude_pitch_forearm"
## [139] "amplitude_yaw_forearm"
                                     "total_accel_forearm"
## [141] "var_accel_forearm"
                                     "avg_roll_forearm"
## [143] "stddev_roll_forearm"
                                     "var_roll_forearm"
                                     "stddev_pitch_forearm"
## [145] "avg_pitch_forearm"
## [147] "var_pitch_forearm"
                                     "avg_yaw_forearm"
## [149] "stddev_yaw_forearm"
                                     "var_yaw_forearm"
## [151] "gyros_forearm_x"
                                     "gyros_forearm_y"
## [153] "gyros_forearm_z"
                                     "accel_forearm_x"
## [155] "accel_forearm_y"
                                     "accel forearm z"
## [157] "magnet_forearm_x"
                                     "magnet_forearm_y"
## [159] "magnet forearm z"
                                     "classe"
```

data variable selection

```
df_training_selected <-
df_training[,c("user_name","cvtd_timestamp","new_window","num_window","roll_b
elt","pitch_belt","yaw_belt","total_accel_belt","roll_arm","pitch_arm","yaw_a
rm","total_accel_arm","roll_dumbbell","pitch_dumbbell","yaw_dumbbell","total_
accel_dumbbell","roll_forearm","pitch_forearm","yaw_forearm","total_accel_for
earm","classe")]</pre>
```

check missing value %

sapply(df_training_selected, function(x) sum(is.na(x))/nrow(df_training)*100)

```
##
                                cvtd timestamp
                                                           new window
               user name
##
##
              num_window
                                      roll_belt
                                                           pitch_belt
##
##
                yaw_belt
                              total_accel_belt
                                                             roll arm
##
                                                                     0
##
               pitch arm
                                        yaw arm
                                                      total accel arm
##
##
           roll_dumbbell
                                pitch_dumbbell
                                                         yaw_dumbbell
##
## total_accel_dumbbell
                                  roll_forearm
                                                        pitch_forearm
##
                                                                     0
##
            yaw forearm
                           total_accel_forearm
                                                                classe
##
```

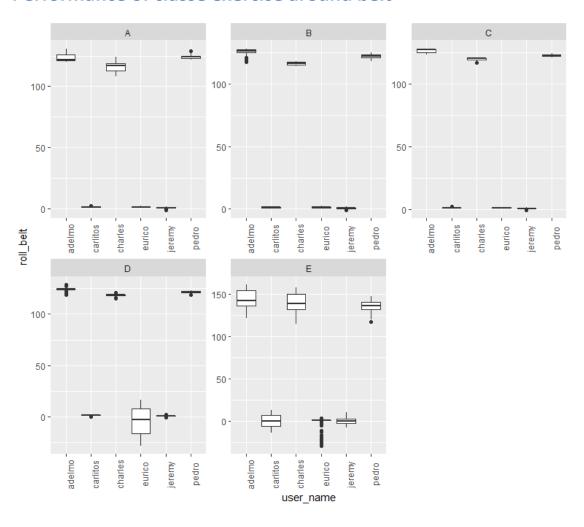
Exploratory Analysis(Only 5 plots are recommended so i am picking just one variable in each of arm,dumbbell,forearm,belt from selected variable done in the above step)

Usage of belt,arm,dumbbell,forearm among users each day(4 days!)

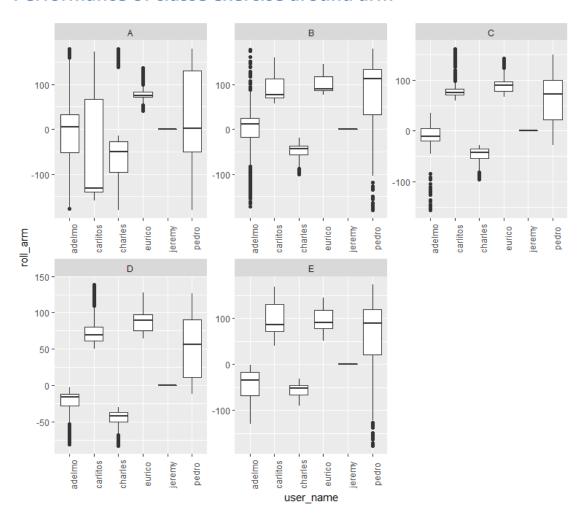
```
df_training_selected$day <-</pre>
as.character(as.Date(df_training_selected$cvtd_timestamp,"%d/%m/%Y"))
table(df_training_selected$user_name,df_training_selected$day)
##
##
              2011-11-28 2011-11-30 2011-12-02 2011-12-05
##
     adelmo
                                   0
                                           3892
##
     carlitos
                       0
                                   0
                                              0
                                                       3112
     charles
##
                       0
                                   0
                                           3536
                                                          0
##
     eurico
                    3070
                                                          0
                                              0
##
     jeremy
                       0
                                3402
                                              0
                                                          0
                       0
##
     pedro
                                              0
                                                       2610
```

In distribution of 4 days usage each user has tried on different days

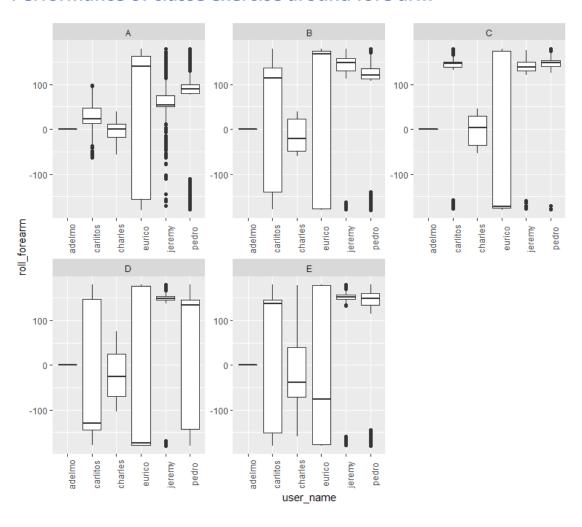
Performance of classe exercise around belt



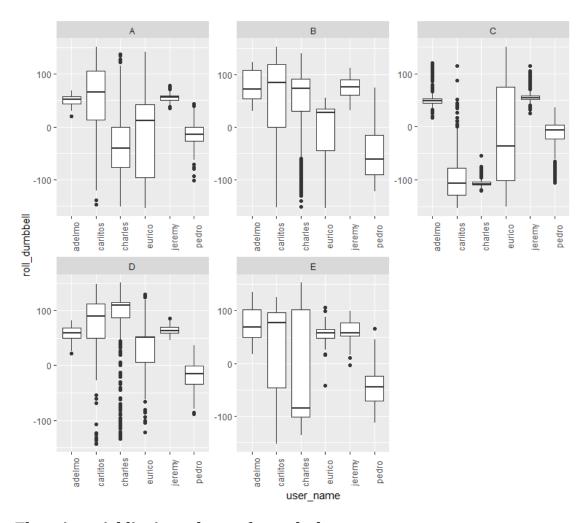
Performance of classe exercise around arm



Performance of classe exercise around fore arm



Performance of classe exercise around dumbbell



There is variablity in each user for each classe

Check For Multicollinearity Between Numerical Variables

```
suppressMessages(library(pander))
p <- sapply(df_training_selected, function(x) is.numeric(x))
t <- df_training_selected[,p]
#Remove Na's
q1 <- na.omit(t)
c <-as.data.frame(cor(q1))
panderOptions('table.split.table', Inf)
pander(c)</pre>
```

```
y
                                                                                     tota
nu
                                                             total
                                                                     ro
                                                                                ya
                             pi
                                                  pit
                                                                          pit
     0
         pi
              a
                   tot
                         r
                                      tot
                                            rol
                                                        ya
                                  У
                                                                                     l_ac
m_{-}
                             tc
                                                              _acc
                                                                     ll
                                                                                W_{-}
     ll
         tc
              W
                   al_
                        ol
                                  a
                                      al_
                                            l_d
                                                  ch_
                                                        W_
                                                                          ch
                                                                                     cel f
                                                                                for
wi
                            h_
                                                              el_d
                        l
                                                  du
                                                        du
                                                                     fo
                                                                          fo
         h
                   acc
                                 W
                                      acc
                                             u
nd
                                                             umb
                                                                                      ore
          b
                                                       mb
     b
              b
                   el_{-}
                             ar
                                      el_
                                                  mb
                                                                     re
                                                                          re
                                                                                ea
                         a
                                  _a
                                            m
ow
                                                              bell
                                                                                rm
                                                                                     arm
     el
         el
              el
                   bel
                             m
                                            bb
                                                  bel
                                                       bel
                         r
                                  r
                                       ar
                                                                     ar
                                                                           ar
```

num _win dow	1	t 0. 0 7 1 9	t - 0. 1 0 2 3	t 0. 0 8 5 8 9	t 0.0 66 03	m - 0. 1 1 9	0. 0 3 3 8 8	m - 0. 0 4 7 9	m - 0.0 64 55	ell 0.0 34 07	l - 0.1 52 7	0.1 08 4	0.08 873	m - 0. 01 11 3	m - 0.0 46 97	0. 08 41 3	- 0.02 651
roll_ belt	0. 07 19 8	1	0. 2 1 5	0. 8 1 5 2	0.9 80 9	0. 3 7 2	0. 0 5 9 7	0. 2 2 5 9	- 0.2 78 3	- 0.1 26 5	0.0 64 03	0.0 25 64	0.19 21	0. 15 02	0.1 74 6	0. 26 64	0.06 556
pitc h_be lt	0. 10 23	0. 2 1 5	1	- 0. 6 9 9	0.1 39	0. 1 7 0 2	0. 1 6 1 5	0. 1 4 3 4	0.0 93 02	0.3 50 2	0.2 31 6	0.6 6	0.31 75	0. 14 52	0.2 53 6	0. 04 85 1	0.32 93
yaw _belt	0. 08 58 9	0. 8 1 5 2	0. 6 9 9	1	0.7 62 1	0. 3 3 6 9	0. 1 3 6 2	0. 2 2 8 6	0.2 40 7	0.0 97 13	0.0 93 12	0.3 47 7	0.04 576	0. 18 07	0.0 30 71	0. 19 57	0.22 78
total _acc el_b elt	0. 06 60 3	0. 9 8 0 9	0. 1 3 9	0. 7 6 2 1	1	0. 3 6 1 5	0. 0 5 3 6 1	0. 2 1 0 4	0.2 66	0.1 31 4	0.0 58 95	0.0 60 43	0.17 14	0. 11 27	0.1 84 5	0. 23 87	0.03 222
roll_ arm	0. 11 99	0. 3 7 2	0. 1 7 0 2	0. 3 3 6 9	0.3 61 5	1	0. 0 4 1 3 6	0. 4 0 7	0.0 57 71	0.1 49 2	0.2 28 6	0.2 79 6	0.15 54	0. 07 58 8	0.1 65 7	0. 23 65	0.01 191
pitc h_ar m	0. 03 38 8	0. 0 5 9 7	0. 1 6 1	0. 1 3 6 2	0.0 53 61	0. 0 4 1	1	0. 0 8 2	0.0 30 89	0.0 21 54	0.1 52 6	- 0.1 78 4	0.19 72	0. 02 28 7	- 0.1 54 5	0. 07 97 7	0.10 89

		7	5			3		3 5									
yaw _ar m	0. 04 79 8	0. 2 2 5 9	0. 1 4 3 4	0. 2 2 8 6	0.2 10 4	0. 4 0 7	0. 0 8 2 3 5	1	0.0 14 91	0.1 25	0.0 86 96	0.1 44 3	0.06 311	0. 05 71 6	0.0 60 93	0. 18 45	0.11 29
total _acc el_a rm	0. 06 45 5	0. 2 7 8 3	0. 0 9 3 0 2	0. 2 4 0 7	0.2 66	0. 0 5 7 7	0. 0 3 0 8 9	0. 0 1 4 9	1	0.0 05 29 3	0.0 72 26	0.0 28 83	0.13	0. 02 37 5	0.1 86 7	0. 09 28 8	- 0.07 364
roll_ dum bbel l	0. 03 40 7	0. 1 2 6 5	0. 3 5 0 2	0. 0 9 7 1 3	0.1 31 4	0. 1 4 9 2	0. 0 2 1 5 4	0. 1 2 5	0.0 05 29 3	1	0.2 12 9	0.2 77 1	0.35 99	0. 02 39 2	0.1 08 3	0. 00 02 38 1	0.18 71
pitc h_du mbb ell	0. 15 27	0. 0 6 4 0 3	0. 2 3 1 6	0. 0 9 3 1 2	0.0 58 95	0. 2 2 8 6	0. 1 5 2 6	0. 0 8 6 9	0.0 72 26	0.2 12 9	1	0.5 17 4	0.40 52	0. 07 23 6	0.2 90 8	0. 09 26 4	0.01 484
yaw _du mbb ell	0. 10 84	0. 0 2 5 6 4	0. 6 6	0. 3 4 7	0.0 60 43	0. 2 7 9 6	0. 1 7 8 4	0. 1 4 4 3	0.0 28 83	- 0.2 77 1	0.5 17 4	1	0.52 67	0. 01 27 6	0.2 80 4	0. 05 57 9	0.18 94
total _acc el_d umb bell	0. 08 87 3	0. 1 9 2 1	0. 3 1 7 5	0. 0 4 5 7 6	- 0.1 71 4	0. 1 5 5 4	0. 1 9 7 2	0. 0 6 3 1	0.1 37	0.3 59 9	0.4 05 2	- 0.5 26 7	1	0. 21 9	- 0.3 44 9	0. 22 89	0.12 57
roll_ fore	- 0.	- 0.	0. 1	- 0.	0.1	0. 0	0. 0	0. 0	0.0 23	0.0	0.0	0.0 12	0.21 9	1	0.0	0. 34	0.08

```
72
                                                                            54
       01
            1
                4
                    1
                         12
                              7
                                  2
                                      5
                                           75
                                                23
                                                           76
                                                                                 67
                                                                                      146
arm
       11
            5
                5
                    8
                         7
                              5
                                  2
                                      7
                                                92
                                                     36
                                                                            41
                2
       3
            0
                    0
                              8
                                  8
                                      1
            2
                    7
                              8
                                  7
                                      6
pitc
            0.
                0.
                    -
                        0.1
                             0.
                                      0.
                                                     0.2
                                                          0.2
                                                                            1
                                          0.1
                                                0.1
                                                     90
                                                                       0.
                                                                                 0.
                                                                                      0.17
h_fo
       0.
            1
                2
                    0.
                        84
                              1
                                  0.
                                      0
                                                           80
                                                                0.34
                5
            7
                    0
                         5
                              6
                                  1
                                      6
                                          86
                                                80
                                                      8
                                                                 49
                                                                      05
                                                                                 22
                                                                                      93
rear
       04
                                                           4
            4
                3
                    3
                              5
                                  5
                                      0
                                           7
                                                3
                                                                                 80
       69
                                                                      44
 m
                              7
                                      9
       7
            6
                6
                    0
                                  4
                                                                       1
                    7
                                  5
                                      3
                    1
yaw
                0.
                             0.
                                  0.
                                      0.
                                          0.0
                                                                0.22
                                                                       0.
                                                                                 1
                                                                                      0.19
_for
       0.
            0.
                0
                    0.
                        0.2
                              2
                                  0
                                      1
                                          92
                                               0.0
                                                     0.0
                                                          0.0
                                                                 89
                                                                      34
                                                                           0.2
                                                                                      98
       80
            2
                4
                    1
                         38
                              3
                                  7
                                      8
                                          88
                                                00
                                                     92
                                                           55
                                                                      67
                                                                           20
ear
                    9
                                  9
            6
                8
                         7
                              6
                                      4
                                                23
                                                     64
                                                           79
                                                                            8
       41
 m
       3
                5
                    5
                              5
                                  7
                                      5
            6
                                                81
            4
                1
                    7
                                  7
total
            0.
                    0.
                        0.0
                                  0.
                                                0.1
                                                     0.0
                                                                0.12
                                                                                 0.
                                                                                       1
                    2
                                                                           0.1
                0.
                        32
                              0.
                                      0.
                                          0.0
                                                87
                                                     14
                                                          0.1
                                                                 57
                                                                       0.
                                                                                 19
_acc
       0.
            0
                                  1
            6
                3
                    2
                        22
                              0
                                  0
                                      1
                                          73
                                                     84
                                                          89
                                                                      80
                                                                           79
                                                                                 98
el_fo
       02
                                                1
                2
rear
       65
            5
                    7
                              1
                                  8
                                      1
                                          64
                                                           4
                                                                      14
                                                                            3
            5
                9
                    8
                                  9
                                      2
                              1
                                                                       6
 m
       1
                3
                                      9
            6
                              9
                              1
```

Multi collinearity exists but since we are building tree based models including rf where each tree is different.we can try to remove them in further iterations

Model Building

distribution of classe variable

```
table(df_training_selected$classe)
##
## A B C D E
## 5580 3797 3422 3216 3607
```

Equal distribution of classes. We can go for accuracy as metric

Building a default RF with no hyper parameters and OOB is a CV metric

1)Since the user names are same in both train and test we can use user name

2) dropping new wndow as test set only has value "no"

```
#convert dependent to factor
df_training_selected$classe <- as.factor(df_training_selected$classe)</pre>
# dropping unwanted column
df training selected$day <- NULL</pre>
#character to factor
df training selected$new window <- as.factor(df training selected$new window)</pre>
df training selected$user name <- as.factor(df training selected$user name)</pre>
set.seed(3457)
#training
model_rf <- randomForest(classe~.-cvtd_timestamp-</pre>
new_window,data=df_training_selected)
model rf
##
## Call:
## randomForest(formula = classe ~ . - cvtd_timestamp - new_window,
data = df_training_selected)
                     Type of random forest: classification
##
                            Number of trees: 500
## No. of variables tried at each split: 4
##
            OOB estimate of error rate: 0.09%
## Confusion matrix:
## A B C D E class.error
## A 5580 0 0 0 0 0.0000000000
## B 1 3795 0 1 0 0.0005267316
## C 0 4 3416 2 0 0.0017533606
## D 0 1 1 3213 1 0.0009328358
## E 0 0 3 3 3601 0.0016634322
```

The accuracy is 0.99 and the oob error is 1% wich is equivalent to validation test error

Varimp

```
varImp(model_rf)
##
                          Overall
## user name
                         457.9678
## num window
                        2942.2121
## roll belt
                        1936.1633
## pitch belt
                        1253.7556
## yaw_belt
                        1541.9041
## total_accel_belt
                         538.2202
## roll arm
                         524.8097
## pitch arm
                         272.3909
## yaw arm
                         437.8473
## total accel arm
                         233.3761
## roll dumbbell
                         843.3334
## pitch_dumbbell
                         451.4661
## yaw dumbbell
                         626.2025
## total_accel_dumbbell 689.6410
## roll forearm
                         930.6746
## pitch_forearm
                        1225.7259
## yaw_forearm
                         384.6047
## total accel forearm 220.3053
```

we could see from model_rf that variables user_name,num_window,roll_belt,pitch_belt,yaw_belt have high importance compared to other predictors

Prediction on test data

```
df_testing_selected <-
df_testing[,c("user_name","cvtd_timestamp","new_window","num_window","roll_be
lt","pitch_belt","yaw_belt","total_accel_belt","roll_arm","pitch_arm","yaw_ar
m","total_accel_arm","roll_dumbbell","pitch_dumbbell","yaw_dumbbell","total_a
ccel_dumbbell","roll_forearm","pitch_forearm","yaw_forearm","total_accel_fore
arm")]

#character to factor
df_testing_selected$new_window <- as.factor(df_testing_selected$new_window)
df_testing_selected$user_name <- as.factor(df_testing_selected$user_name)

predictions <- predict(model_rf,df_testing_selected)

predictions

## 1 2 3 4 5 6 7 8 9 10 11 12 13 14 15 16 17 18 19 20

## B A B A A E D B A A B C B A E E A B B B

## Levels: A B C D E</pre>
```