

Lecture 1

Qiong Wang

Formulation

definition

standard form

Solution

# Lecture 1

## Linear Programming: Formulation and Solution

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# Example

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You plan to invest in three companies. Expected returns from investment in companies 1, 2, and 3 are  $r_1 = 0.05$ ,  $r_2 = 0.12$ , and  $r_3 = 0.09$  respectively. For strategic reasons, you do not want to invest more than 40% your budget in company 1, 50% in company 2, and at least 30% in company 3. Determine the percentage of your budget to be invested in each company to maximize your expected return?

- *variables:*  $x_1, x_2, x_3$  be the fractions invested in three companies.
- *objective function:*

$$\max_{x_1, x_2, x_3} \{0.05x_1 + 0.12x_2 + 0.09x_3\}$$

- *constraints:*

$$x_1 + x_2 + x_3 \leq 1,$$

$$x_1 \leq 0.4, \quad x_2 \leq 0.5, \quad x_3 \geq 0.3,$$

$$x_1 \geq 0, \quad x_2 \geq 0, \quad x_3 \geq 0.$$

# More general formulation

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You plan to invest in  $n$  different assets with the expected returns  $r_i$  ( $i = 1, \dots, n$ ). You are required to invest at least a fraction of  $s_i$  and at most  $S_i$  of your budget in asset  $i$  ( $i = 1, \dots, n$ ). Determine an investment solution to maximize the total expected returns.

$x_i$ : fraction of the budget in excess of  $s_i$  invested in asset  $i$  (the actual fraction is  $x_i + s_i$ ),  $i = 1, \dots, n$ .

let

$$\Delta s_i = S_i - s_i, \quad i = 1, \dots, n, \quad \bar{s} = \sum_{i=1}^n s_i, \quad \bar{R} = \sum_{i=1}^n r_i s_i.$$

$$\begin{aligned} & \max_{x_1, \dots, x_n} \{r_1 x_1 + \dots + r_n x_n\} + \bar{R} \\ \text{subject to: } & x_1 \leq \Delta s_1, \quad x_2 \leq \Delta s_2, \dots, x_n \leq \Delta s_n, \\ & x_1 + \dots + x_n \leq 1 - \bar{s}, \\ & x_1 \geq 0, \quad x_2 \geq 0, \dots, x_n \geq 0. \end{aligned}$$

# Definition of Linear Programming Problem

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Solution

Linear Programming (LP) is an optimization model in which

- *all* decision variables take real values,
- the objective is a linear function of decision variables,
- *all* constraints are linear (in)equalities of decision variables.

$$\begin{aligned} & \max_{x_1, \dots, x_n} \{r_1 x_1 + \dots + r_n x_n\} + \bar{R} \\ \text{subject to: } & x_1 \leq \Delta s_1, \ x_2 \leq \Delta s_2, \dots, x_n \leq \Delta s_n, \\ & x_1 + \dots + x_n \leq 1 - \bar{s}, \\ & x_1 \geq 0, \ x_2 \geq 0, \dots, x_n \geq 0. \end{aligned}$$

$n$  decision variables:  $x_1, \dots, x_n$ .

$2n + 2$  parameters:  $\bar{R}$ ,  $\bar{s}$ ,  $(r_1, \dots, r_n)$  and  $(\Delta s_1, \dots, \Delta s_n)$ .

$(n + 1)$  "regular" constraints and  $n$  nonnegativity constraints.

# Standard Form

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LP in standard form:

- 1 Maximize an objective.
- 2 Left Hand Side (LHS) of each constraint, which is a linear combination of decision variables, is less than or equal to its Right Hand Side (RHS), which is a constant.
- 3 All decision variables are positive.

LP formulation with  $n$  decision variables and  $m = n + k$  constraints

$$\begin{aligned} & \max_{x_1, \dots, x_n} \{c_1 x_1 + \dots + c_n x_n\} \\ \text{subject to: } & a_{11} x_1 + \dots + a_{1n} x_n \leq b_1, \\ & \dots\dots\dots \\ & a_{k1} x_1 + \dots + a_{kn} x_n \leq b_k, \\ & x_1 \geq 0, \dots, x_n \geq 0. \end{aligned}$$

# Transform an LP into Its Standard Form

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## Solution

$$\begin{aligned} & \max_{x_1, \dots, x_n} \{c_1 x_1 + \dots + c_n x_n\} \\ \text{subject to: } & a_{j1}x_1 + \dots + a_{jn}x_n \leq b_j, \quad j = 1, \dots, k \\ & x_1 \geq 0, \dots, x_n \geq 0. \end{aligned}$$

how to fit following situations into the standard LP form?

- the objective is  $\min_{x_1, \dots, x_n} \{c_1 x_1 + \dots + c_n x_n\}$ ?

$$\max_{x_1, \dots, x_n} \{-c_1 x_1 - \dots - c_n x_n\}$$

- constraint  $a_{j1}x_1 + \dots + a_{jn}x_n \geq b_j$ ?

$$-a_{j1}x_1 - \dots - a_{jn}x_n \leq -b_j,$$

- constraint  $a_{j1}x_1 + \dots + a_{jn}x_n = b_j$ ?

$$a_{j1}x_1 + \dots + a_{jn}x_n \leq b_j \quad \text{and} \quad a_{j1}x_1 + \dots + a_{jn}x_n \geq b_j.$$

$$\text{i.e., } a_{j1}x_1 + \dots + a_{jn}x_n \leq b_j \quad \text{and} \quad -a_{j1}x_1 - \dots - a_{jn}x_n \leq -b_j.$$

- a decision variable  $x$  can be negative?

$$x = y_1 - y_2, \quad y_1 \geq 0, y_2 \geq 0.$$

# Another Standard Formulation

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### Solution

Dual of the maximization problem (to be discussed later in the course):

① instead of

$$\max_{x_1, \dots, x_n} \{c_1 x_1 + \dots + c_n x_n\}$$

write the objective function as

$$\min_{y_1, \dots, y_n} \{h_1 y_1 + \dots + h_n y_n\}$$

② instead of

$$a_{j1}x_1 + \dots + a_{jn}x_n \leq b_j$$

make the LHS of constraints greater than or equal to the RHS:

$$a_{11}y_1 + \dots + a_{n1}y_n \geq d_1,$$

③ all decision variables are positive.

$$y_1 \geq 0, \dots, y_n \geq 0.$$

# Linear Programming (LP) in Standard Form

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Solution

$$\begin{array}{ll}\max_{x_1, \dots, x_n} & \{c_1x_1 + \dots + c_nx_n\} \\ \text{subject to} & a_{11}x_1 + \dots + a_{1n}x_n \leq b_1, \\ & \dots\dots\dots \\ & a_{k1}x_1 + \dots + a_{kn}x_n \leq b_k, \\ & x_1 \geq 0, \dots, x_n \geq 0.\end{array}$$

- all decision variables take non-negative real values;
- the objective is to maximize a linear function of decision variables;
- all constraints are linear inequalities of decision variables;

variables are on the LHS and the constant is on the RHS

$$\text{LHS} \leq \text{RHS}.$$



# Why Solving LP Needs a New Approach

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Basic calculus, we know how to solve a (simple) optimization problem like

$$\max_{x_1, x_2} \left\{ g(x_1, x_2) = 6x_1 - x_1^2 + x_2 - 2x_2^2 \right\},$$

by the use of the first-order condition

$$\frac{\partial g}{\partial x_1} = 6 - 2x_1 = 0 \quad \text{and} \quad \frac{\partial g}{\partial x_2} = 1 - 4x_2 = 0,$$

the optimal solution  $x_1^* = 3$ ,  $x_2^* = 1/4$  and  $g(x_1^*, x_2^*) = 9\frac{1}{8}$ .

Try this approach on a linear objective function, e.g.,

$$g(x_1, x_2) = 6x_1 + x_2?$$

what happened, and why?

# Linear versus Nonlinear Optimization

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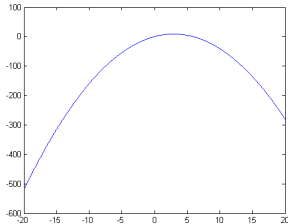
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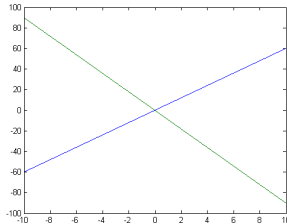
nonlinear function:

$$g(x) = 6x - x^2$$



linear function:

$$g(x) = 6x \text{ or } g(x) = -9x$$



implications of the above comparisons:

- a meaningful LP problem must have constraints.
- optimal solution at the boundary of some constraints.

# "Push to the Boundary" in the 2-Dimensional Case

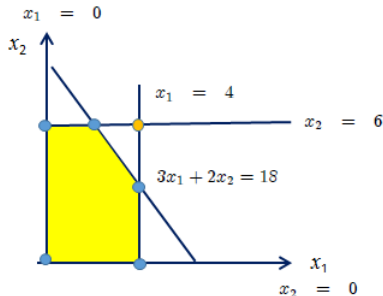
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Solution

$$\begin{array}{ll}\max & \{2x_1 + x_2\} \\ \text{subject to} & x_1 \leq 4, \\ & x_2 \leq 6, \\ & 3x_1 + 2x_2 \leq 18, \\ & x_1 \geq 0, \ x_2 \geq 0.\end{array}$$



"Corner Feasible Point" (CFP) solutions

- $(x_1, x_2) = (0, 0) \longrightarrow 2x_1 + x_2 = 0 \quad (x_1 = 0, x_2 = 0).$
- $(x_1, x_2) = (0, 6) \longrightarrow 2x_1 + x_2 = 6 \quad (x_1 = 0, x_2 = 6).$
- $(x_1, x_2) = (2, 6) \longrightarrow 2x_1 + x_2 = 10 \quad (3x_1 + 2x_2 = 18, x_2 = 6).$
- $(x_1, x_2) = (4, 0) \longrightarrow 2x_1 + x_2 = 8 \quad (x_1 = 4, x_2 = 0).$
- $(x_1, x_2) = (4, 3) \longrightarrow 2x_1 + x_2 = 11 \quad (x_1 = 4, 3x_1 + 2x_2 = 18).$

# What about Other Points at the "Boundary"

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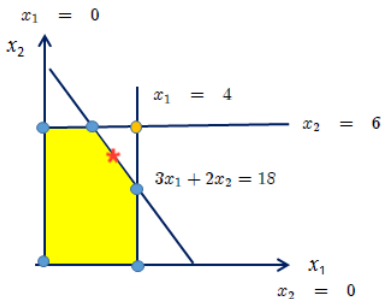
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Solution

$$\begin{array}{ll}\max & \{2x_1 + x_2\} \\ \text{subject to} & x_1 \leq 4, \\ & x_2 \leq 6, \\ & 3x_1 + 2x_2 \leq 18, \\ & x_1 \geq 0, \ x_2 \geq 0.\end{array}$$



Let point \* in the figure be  $\mathbf{x} = (x_1, x_2)$ .

$$\mathbf{x} = \alpha * (2, 6) + (1 - \alpha) * (4, 3) \quad \text{i.e.} \quad x_1 = 2\alpha + 4(1 - \alpha), \quad x_2 = 6\alpha + 3(1 - \alpha)$$

and

$$2x_1 + x_2 = \alpha(2 * 2 + 6) + (1 - \alpha) * (2 * 4 + 3) \leq \max\{2 * 2 + 6, 2 * 4 + 3\}.$$

so the objective value at \* cannot be better than both CFP solutions.

# A Fundamental Fact about LP

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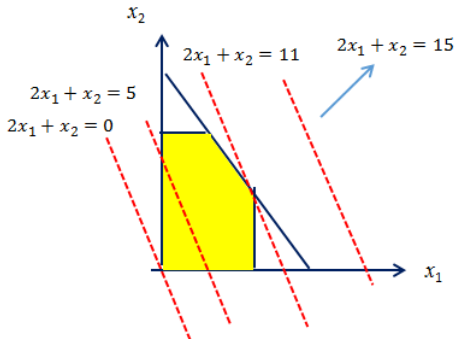
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## Solution

If the optimal objective value of an LP exists and is finite, then this value can always be obtained at one of the “corner points” (solutions to  $n$  simultaneous equations).



# Systems of Equations and Feasible Solutions

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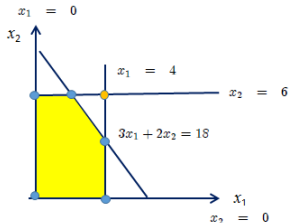
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## Solution

$$\begin{array}{ll}\max & \{2x_1 + x_2\} \\ \text{subject to} & x_1 \leq 4, \\ & x_2 \leq 6, \\ & 3x_1 + 2x_2 \leq 18, \\ & x_1 \geq 0, \ x_2 \geq 0.\end{array}$$



observation: to solve for  $n = 2$  variables, we need a pair of equations.

*question: with  $3 + 2$  (regular+non-negativity) constraints, how many pairs of equations can we possibly have? 10.*

question: why we only get five pairs of equations?

- some pairs of equations have no solution: e.g.,

$$x_1 = 0 \text{ and } x_1 = 4.$$

- some solutions violate other constraints: e.g.,

$$x_1 = 4 \text{ and } x_2 = 6 \text{ or } x_1 = 0 \text{ and } 3x_1 + 2x_2 = 18.$$

# Possible Procedure

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## Solution

select  $n$  out of  $n + m$  ( $m$  regular,  $n$  non-negativity) constraints to form a system of equations

- if the system has no solution, next!
- if the solution does not satisfy another constraint, next!
- if the solution is feasible for all constraints, evaluate the corresponding objective value.
- compare all objective values to pick the best solution.

Question: how many systems of equations we need to evaluate?

- $n = 2$  and  $m + n = 10$ ?

$$\frac{10 \times 9}{2} = 45$$

- $n = 20$  and  $m + n = 30$ ?

$$\frac{30 \times 29 \times \dots \times 11}{20!} = \text{huge (about 30 million)}$$

- $n = 10k$  and  $m + n = 30k$ ?

don't even think about it!

# Searching Optimal Solutions

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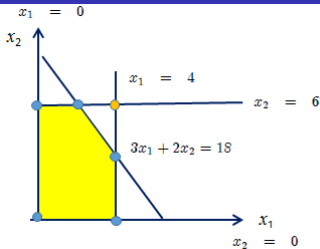
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## Solution

$$\begin{array}{ll}\max & \{2x_1 + x_2\} \\ \text{subject to} & x_1 \leq 4, \\ & x_2 \leq 6, \\ & 3x_1 + 2x_2 \leq 18, \\ & x_1 \geq 0, \ x_2 \geq 0.\end{array}$$



$$x_1 = 0, x_2 = 0, (2x_1 + x_2 = 0):$$

$$\text{neighbors: } x_1 = 4, x_2 = 0 \rightarrow 2x_1 + x_2 = 8$$

$$x_1 = 0, x_2 = 6 \rightarrow 2x_1 + x_2 = 6.$$

$$x_1 = 4, x_2 = 0, (2x_1 + x_2 = 8):$$

$$\text{new neighbor: } x_1 = 4, 3x_1 + 2x_2 = 18 \rightarrow (x_1, x_2) = (4, 3) \rightarrow 2x_1 + x_2 = 11.$$

$$x_1 = 4, x_2 = 3, (2x_1 + x_2 = 11):$$

$$\text{new neighbor: } 3x_1 + 2x_2 = 18, x_2 = 6 \rightarrow (x_1, x_2) = (2, 6) \rightarrow 2x_1 + x_2 = 10.$$



# Illustration: Optimality of the Solution

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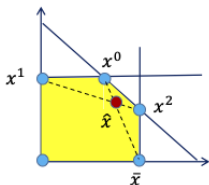
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## Solution

write the objective function in vector form  $c^T x = c_1 x_1 + \cdots c_n x_n$



$x^0$  is a corner solution and  $x^1$  and  $x^2$  are its neighbors, and

$$c^T x^0 \geq c^T x^1, \quad c^T x^0 \geq c^T x^2.$$

- if  $x^0$  is not optimal, then there exists  $\bar{x}$  such that  $c^T \bar{x} > c^T x^0$ .
- lines  $x^1 - x^2$ , and  $x^0 - \bar{x}$  must intersect at some point  $\hat{x}$ , so

$$\hat{x} = \alpha x^1 + (1 - \alpha) x^2 = \beta x^0 + (1 - \beta) \bar{x}, \quad 0 < \alpha, \beta < 1.$$

- a contradiction:

$$c^T \hat{x} = \alpha c^T x^1 + (1 - \alpha) c^T x^2 \leq c^T x^0 < \beta c^T x^0 + (1 - \beta) c^T \bar{x} = c^T \hat{x}.$$

# General Idea of SIMPLEX Method

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- ① **Fact 1:** The objective function of an LP is optimized by solutions to one of  $n$  simultaneous equations.
- ② **Fact 2:** If a solution is not optimal, then it is always possible to get a better solution by swapping in/out one equation.

### **SIMPLEX procedure:**

- ① start from a feasible solution to a system of  $n$  equations, compare its objective value with that of its “adjacent solutions”.
- ② if the current solution is better than all its adjacent solutions, stop! the current solution is optimal.
- ③ otherwise, move to an adjacent solution with higher objective value.
- ④ repeat steps 2 and 3 until the optimal solution is found.

<https://www.youtube.com/watch?v=x8rYyQjEMMs>

# Special Case (Non-unique Optimal Solutions)

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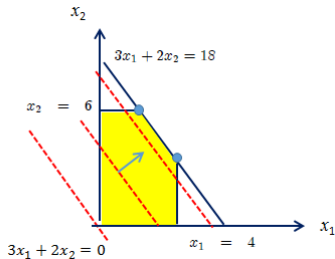
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### Solution

$$\begin{array}{ll}\max & \{3x_1 + 2x_2\} \\ \text{subject to} & x_1 \leq 4, \\ & x_2 \leq 6, \\ & 3x_1 + 2x_2 \leq 18, \\ & x_1 \geq 0, x_2 \geq 0.\end{array}$$



- every points on a segment of  $3x_1 + 2x_2 = 18$  is an optimal solution.
- both  $(2, 6)$  and  $(4, 3)$  are optimal.

so we can still maximize the LP objective function by going through solutions of  $n$  simultaneous equations.

# Exceptions (Don't solve, fix the model!)

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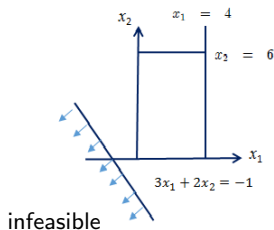
Formulation

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Solution

$$\begin{array}{ll}\max & \{2x_1 + x_2\} \\ \text{subject to} & x_1 \leq 4, \ x_2 \leq 6, \\ & 3x_1 + 2x_2 \leq -1, \\ & x_1 \geq 0, \ x_2 \geq 0.\end{array}$$



$$\begin{array}{ll}\max & \{2x_1 + x_2\} \\ \text{subject to} & x_1 \leq 4, \\ & x_1 \geq 0, \ x_2 \geq 0.\end{array}$$

