

A* SEARCH ALGORITHM

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PROGRAM:

```
from collections import deque
```

```
class Graph:
```

```
    def __init__(self, adjacency_list):
```

```
        self.adjacency_list = adjacency_list
```

```
    def get_neighbors(self, v):
```

```
        return self.adjacency_list[v]
```

```
    def h(self, n):
```

```
        H = { 'A': 1, 'B': 1, 'C': 1, 'D': 1 }
```

```
        return H[n]
```

```
    def a_star_algorithm(self, start_node, stop_node):
```

```
        open_list = set([start_node])
```

```
        closed_list = set([])
```

```
        g = {} g[start_node] = 0
```

```
        parents = {}
```

```
        parents[start_node] = start_node
```

```
        while len(open_list) > 0:
```

```
            n = None
```

```
            for v in open_list:
```

```
                if n == None or g[v] + self.h(v) < g[n] + self.h(n):
```

```
                    n = v
```

```
            if n == None:
```

```
                print('Path does not exist!')
```

```
                return None
```

```
            if n == stop_node:
```

```

reconst_path = []

while parents[n] != n:
    reconst_path.append(n)
    n = parents[n]

reconst_path.append(start_node)
reconst_path.reverse()

print('Path found: {}'.format(reconst_path))

return reconst_path

for (m, weight) in self.get_neighbors(n):
    if m not in open_list and m not in closed_list:
        open_list.add(m)
        parents[m] = n
        g[m] = g[n] + weight
    else:
        if g[m] > g[n] + weight:
            g[m] = g[n] + weight
            parents[m] = n
        if m in closed_list:
            closed_list.remove(m)
            open_list.add(m)

open_list.remove(n)
closed_list.add(n)

print('Path does not exist!')

return None

```

OUTPUT:

```
Path found: ['A', 'B', 'D']
```

```
=== Code Execution Successful ===
```