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Let's look at one example and you can try another one on your own later (hopefully).

$$A = \begin{bmatrix} 1 & 4 & 3 \\ 4 & 1 & 0 \\ 3 & 0 & 1 \end{bmatrix}$$

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Solving this we get z = 1, 6, -4. (Sorry, I am skipping this!)

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Now we have to compute eigen-vectors corresponding to the three distinct eigen values.

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$$A - 6I = \begin{bmatrix} -5 & 4 & 3 \\ 4 & -5 & 0 \\ 3 & 0 & -5 \end{bmatrix}$$

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We need
$$v = \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix}$$
 such that

$$\begin{bmatrix} -5 & 4 & 3 \\ 4 & -5 & 0 \\ 3 & 0 & -5 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

Our goal is to bring the matrix
$$\begin{bmatrix} -5 & 4 & 3 \\ 4 & -5 & 0 \\ 3 & 0 & -5 \end{bmatrix}$$
 into a simple form of the type
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of the type $\begin{bmatrix} 1 & * & * \\ 0 & 1 & * \\ 0 & 0 & 0 \end{bmatrix}$ where * can be any real number and then

work with this changed matrix. This simplifies things and we can easily get relations between v_1, v_2, v_3 .

 $\begin{bmatrix} -5 & 4 & 3 \\ 4 & -5 & 0 \\ 3 & 0 & -5 \end{bmatrix}$

 $\begin{bmatrix} -5 & 4 & 3 \\ 4 & -5 & 0 \\ 3 & 0 & -5 \end{bmatrix} \xrightarrow{R_1 \to -R_1} \begin{bmatrix} 5 & -4 & -3 \\ 4 & -5 & 0 \\ 3 & 0 & -5 \end{bmatrix}$

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$$\frac{R_2 \to R_2 - 4R_1}{3} \begin{bmatrix}
1 & 1 & -3 \\
0 & -9 & 12 \\
3 & 0 & -5
\end{bmatrix}$$

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$$\xrightarrow{R_2 \to R_2 - 4R_1} \begin{bmatrix} 1 & 1 & -3 \\ 0 & -9 & 12 \\ 3 & 0 & -5 \end{bmatrix} \xrightarrow{R_3 \to R_3 - 3R_1} \begin{bmatrix} 1 & 1 & -3 \\ 0 & -9 & 12 \\ 0 & -3 & 4 \end{bmatrix}$$

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\end{bmatrix}
\xrightarrow{R_3 \to -R_3} \xrightarrow{R_2 \to -\frac{1}{3}R_2}$$

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$$\frac{R_2 \to R_2 - 4R_1}{2} \Rightarrow \begin{bmatrix} 1 & 1 & -3 \\ 0 & -9 & 12 \\ 3 & 0 & -5 \end{bmatrix} \xrightarrow{R_3 \to R_3 - 3R_1} \Rightarrow \begin{bmatrix} 1 & 1 & -3 \\ 0 & -9 & 12 \\ 0 & -3 & 4 \end{bmatrix} \xrightarrow{R_3 \to R_3} \frac{R_3 \to R_3}{R_2 \to -\frac{1}{3}R_2}$$

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$$\begin{bmatrix} 1 & 1 & -3 \\ 0 & 1 & -\frac{4}{3} \\ 0 & 0 & 0 \end{bmatrix}$$

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$$\begin{bmatrix} 1 & 1 & -3 \\ 0 & 1 & -\frac{4}{3} \\ 0 & 0 & 0 \end{bmatrix} \xrightarrow{R_1 \to R_1 - R_2} \begin{bmatrix} 1 & 0 & -\frac{5}{3} \\ 0 & 1 & -\frac{4}{3} \\ 0 & 0 & 0 \end{bmatrix}$$

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We got the matrix $\begin{bmatrix} 1 & 0 & -\frac{3}{3} \\ 0 & 1 & -\frac{4}{3} \\ 0 & 0 & 0 \end{bmatrix}$. (We always must have at least one row to be 0, if not we need to check calculations again!)

Now we investigate,

$$\begin{bmatrix} 1 & 0 & -\frac{5}{3} \\ 0 & 1 & -\frac{4}{3} \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

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This gives, $v_1 - \frac{5}{3}v_3 = 0$, $v_2 - \frac{4}{3}v_3 = 0$. That is, $v_1 = \frac{5}{3}v_3$ and $v_2 = \frac{4}{3}v_3$.

We got the matrix $\begin{bmatrix} 1 & 0 & -\frac{2}{3} \\ 0 & 1 & -\frac{4}{3} \\ 0 & 0 & 0 \end{bmatrix}$. (We always must have at least one row to be 0, if not we need to check calculations again!)

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Taking
$$v_3 = 3$$
, we have an eigen vector $\begin{bmatrix} 5 \\ 4 \\ 3 \end{bmatrix}$.

In a similar way, we can find eigen vectors corresponding to z=1,-4. Follow the same method. Try finding at least one of them.

• Given $A_{3\times 3}$, compute $A-z\mathcal{I}_3$; put $\det(A-z\mathcal{I}_3)=0$ to get eigen-values a,b,c which may not be distinct. We are only bothered about real roots for the time being.

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- For each of a, b, c, compute $A a\mathcal{I}_3$, $A b\mathcal{I}_3$, $A c\mathcal{I}_3$ by plugging in z = a, b, c respectively in $A z\mathcal{I}_3$.

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- Bring these matrices into the $\begin{vmatrix} 1 & * & * \\ 0 & 1 & * \\ 0 & 0 & 0 \end{vmatrix}$ forms by operation on rows.

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- \bullet For each simplified matrix, multiply it with $\begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix}$, equate each entry to zero, and find relations.
- You will see that fixing at most two of the v_i 's to be any constants will give you an eigen vector.