# **SARATH M**

# Machine Learning Engineer

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Kerala, India

# **EXPERIENCE**

### **Specialist**

#### Tata Elxsi

July 2016 - Ongoing

Technopark, Trivandrum

### **Embedded System Engineer**

#### **Unisync Technologies**

**a** Jan 2015 - July 2016

Vyttila, Ernakulam

# MOST PROUD OF

4

My Professional Achievement

Awarded the highest rating "Outstanding" in three consecutive appraisal cycles in Tata Elxsi



My Academic Achievement

Final year academic project "Hexapod" was selected for the finals in State level competition



Martial Arts

Black Belt holder in Shito-Ryu style of Karate

# **EDUCATION**

### Course in Embedded Systems

Vector India Institute, Bangalore, Karnataka

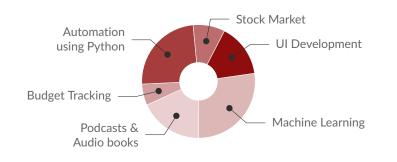
**=** 2014

### B.Tech (ECE)

Govt. College of Engineering Cherthala, Cochin University Of Science and Technology, Kerala

**2010 - 2014** 

# **INTERESTS**



# MY LIFE PHILOSOPHY

"Quality is not an act; it is a habit."

# **STRENGTHS**

Team Player

Passionate Programmer

Fast Learner

Hard-working

Eye for detail

# **SKILLS**

• Machine Learning Frameworks

Tensorflow Scikit-learn NLTK



Visualization & Data Processing

Pandas Numpy Flask Bokeh Plotly Grafana Twitter Bootstrap PyQt4, Qt Designer



Distributed Systems

ROS Paho MQTT Redis Apache Kafka



Test Automation & CI

Jenkins

Robot Framework



Devops

Docker Ansible



# **LANGUAGES**

English Malayalam Hindi



# **PROJECTS**

### ADAS features for Autonomous Vehicle project

Responsibilities:

- Development of Object detection system using Convolutional Neural Networks
  - Faster-RCNN, Yolo V2, Single Shot Detectors
- Development of Drivable Area using Image Segmentation
  - SegNet, Mask R-CNN
- Design and development of Distributed System using Robotic Operating System (ROS)
- Testing and deployment of the ML model in NVidia Jetson TX1 platform
- Object detection in 3D Point cloud data using PointNet

Lidargen Role: Project Lead

Responsibilities:

- The User is given the freedom to place and orient the multiple meshes
- Used in the optimized placement of multiple Lidar's to reduce blind spot
- To mathematical model the behavior of Lidar and simulate the same using Ray Casting.
- A UI capable of 3D visualization was created using Qt and ROS RViz

# Intelligent Battery Management System

Role: Project Lead

Role: Project Lead

Responsibilities:

- Implemented Neural Network Regression model as a benchmark
- Implemented LSTM models to improve upon the benchmark results
- Supported in development of 'Digital Twin' of a cell with ML models mimicking the electrochemical characteristics
- Developed a POC on Anomaly detection algorithm to demonstrate online-learning capabilities of the framework
- Create a Data dashboard for monitoring sensor data in real-time using Flask and Bokeh

### Natural Language Processing for JIRA ticket Analytics Role: Project Lead

Responsibilities:

- Data cleaning and Exploratory Data Analysis using NLTK
  - Remove stop words and Stemming the corpus
  - Named Entity Recognition using Spacy
  - · Visualizations using Word Cloud
- · Search and filter feature using BERT model and Elasticsearch
  - Converting each ticket into fixed length vector using BERT
  - · Save the vectors into Elasticsearch
  - Use Cosine Similarity to compare and filter tickets

### Automated Testing and CI Framework

Role: Project Lead

Responsibilities:

- Enables rapid and Automated testing
- The framework supports both SIL and HIL testing
- Continuous Integration using Jenkins, Ansible and Robot framework
- Centralized Logging using Fluentd, Elasticsearch and Kibana
- · Containerization using Docker