

# SARATH M

## Machine Learning Engineer

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## EXPERIENCE

### Specialist

#### Tata Elxsi

July 2016 – Ongoing

Technopark, Trivandrum

### Embedded System Engineer

#### Unisync Technologies

Jan 2015 – July 2016

Vyttila, Ernakulam

## MOST PROUD OF



#### My Professional Achievement

Awarded the highest rating "Outstanding" in three consecutive appraisal cycles in Tata Elxsi



#### My Academic Achievement

Final year academic project "Hexapod" was selected for the finals in State level competition



#### Martial Arts

Black Belt holder in Shito-Ryu style of Karate

## EDUCATION

### Course in Embedded Systems

#### Vector India Institute, Bangalore, Karnataka

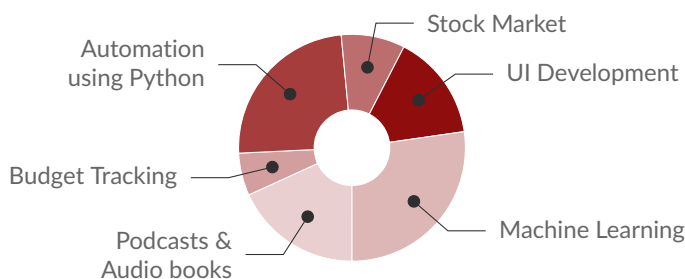
2014

### B.Tech (ECE)

#### Govt. College of Engineering Cherthala, Cochin University Of Science and Technology, Kerala

2010 - 2014

## INTERESTS



## MY LIFE PHILOSOPHY

*"Quality is not an act; it is a habit."*

## STRENGTHS

Team Player

Passionate Programmer

Fast Learner

Hard-working

Eye for detail

## SKILLS

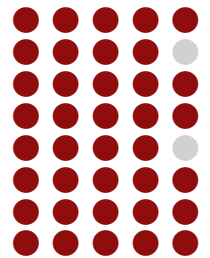
### Machine Learning Frameworks

Tensorflow  
Scikit-learn  
NLTK



### Visualisation & Data Processing

Pandas  
Numpy  
Flask  
Bokeh  
Plotly  
Grafana  
Twitter Bootstrap  
PyQt4, Qt Designer



### Distributed Systems

ROS  
Paho MQTT  
Redis  
Apache Kafka



### Test Automation & CI

Jenkins  
Robot Framework



### Devops

Docker  
Ansible



## LANGUAGES

English  
Malayalam  
Hindi



# PROJECTS

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## ADAS features for Autonomous Vehicle project

The objective of the project is to develop an L2 Autonomous Car

- Development of Object detection system using Convolutional Neural Networks
    - Faster-RCNN, Yolo V2, Single Shot Detectors
  - Development of Drivable Area using Image Segmentation
    - SegNet, Mask R-CNN
  - Design and development of Distributed System using Robotic Operating System (ROS)
  - Testing and deployment of the ML model in NVidia Jetson TX1 platform
  - Object detection in 3D Point cloud data using PointNet
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## Lidargen

The objective of the project was to create a tool that would simulate the actual output from a LIDAR sensor. The tool takes three dimensional CAD objects as input and generates corresponding pointcloud.

- The User is given the freedom to place and orient the multiple meshes
  - Used in the optimised placement of multiple Lidars to reduce blind spot
  - To mathematical model the behavior of Lidar and simulate the same using Ray Casting.
  - A UI capable of 3D visualization was created using Qt and ROS RViz
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## Intelligent Battery Management System

The objective of the project is to estimate State of Health (SOH) and State of Charge (SOC) of a Lithium Ion battery using Machine Learning

- Implemented Neural Network Regression model as a benchmark
  - Implemented LSTM models to improve upon the bencharm results
  - Supported in development of 'Digital Twin' of a cell with ML models mimicing the electrochemical characteristics
  - Developed a POC on Anomaly detection algorithm to demonstrate online-learning capabilities of the framework
  - Create a Data dashboard for monitoring sensor data in real-time using Flask and Bokeh
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## Natural Language Processing for JIRA ticket Analytics

Use NLP and visualisation techniques to allow team members and managers to more effectively manage projects

- Data cleaning and Exploratory Data Analysis using NLTK
    - Remove stop words and Stemming the corpus
    - Named Entity Recognition using Spacy
    - Visualisations using Word Cloud
  - Search and filter feature using BERT model and Elasticsearch
    - Converting each ticket into fixed lenght vector using BERT
    - Save the vectors into Elasticsearch
    - Use Cosine Similarity to compare and filter tickets
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## Automated Testing and CI Framework

A Test automation framework was developed with the following key features

- Enables rapid and Automated testing
- The framework supports both SIL and HIL testing
- Continuous Integration using Jenkins, Ansible and Robot framework
- Centralized Logging using Fluentd, Elasticsearch and Kibana
- Containerization using Docker