Memory Address (16b)	Data Byte 1	Data Byte 0	Data Description	Data Size
0	joint index	cmd id	overall command to hand	uint8_t
1	null	j0	Target Position Data (mm)	int8_t
50	j0 high word		Target Force Data (N)	
51	j0 low word			float
150		j0	Target Velocity Data (mm/s)	int16_t
200	null	feedback status	overall status of hand	uint8_t
201	null	j0	Feedback Position Data (mm)	int8_t
250	j0 high word		Feedback Force Data (N)	
251	j0 low word			float
350		j0	Feedback Velocity Data (mm/s)	int16_t
400	null	j0	temperature (deg c)	int8_t
650	left x high word		Feedback Force Data (Contactile) (N)	
651	left x low word			
652	left y high			
653	lef y low			
654	left z high			
655	left z low			
656	right x high			
657	right x low			
658	right y high			
659	right y low			
660	right z high		Feedback Force Data (Contactile) (N)	
661	right z low			float