

Memory Address (16b)	Data Byte 1	Data Byte 0	Data Description	Data Size
0	joint index	cmd id	overall command to hand	
1	j1	j0	Target Position Data (degrees)	int8_t
2	j3	j2		
3	j5	j4		
50	j0 high word		Target Force Data (N)	float
51	j0 low word			
52	j1 high word			
53	j1 low word			
54	j2 high word			
55	j2 low word			
56	j3 high word			
57	j3 low word			
58	j4 high word			
59	j4 low word			
60	j5 high word			
61	j5 low word			
200	null	feedback status	overall status of hand	uint8_t
201	j1	j0	Feedback Position Data (degrees)	int8_t
202	j3	j2		
203	j5	j4		
250	j0 high word		Feedback Force Data (N)	float
251	j0 low word			
252	j1 high word			
253	j1 low word			
254	j2 high word			
255	j2 low word			
256	j3 high word			
257	j3 low word			
258	j4 high word			
259	j4 low word			
260	j5 high word			
261	j5 low word			
400	j1	j0	temperature (deg c)	int8_t
401	j3	j2		
402	j5	j4		
500	j1	j0	actuator error reports	uint8_t
501	j3	j2		
502	j5	j4		
600	j1	j0	actuator mode status	uint8_t
601	j3	j2		
602	j5	j4		
650	thumb x high word		Feedback Force Data Fingertip (Contactile) (N)	
651	thumb x low word			
652	thumb y high			

653	thumb y low		float
654	thumb z high		
655	thumb z low		
656	index x high		
657	index x low		
658	index y high		
659	index y low		
660	index z high	Feedback Force Data Fingertip (Contactile) (N)	
661	index z low		
662	middle x high		
663	middle x low		
664	middle y high		
665	middle y low		
666	middle z high		
667	middle z low		
668	ring x high		
669	ring x low	Feedback Force Data Fingertip (Contactile) (N)	
670	ring y high		
671	ring y low		
672	ring z high		
673	right z low		
674	pinky x high		
675	pinky x low		
676	pinky y high		
677	pinky y low		
678	pinky z high		
679	pinky z low	Feedback Force Data Fingertip (Contactile) (N)	