

Memory Address (16b)	Data Byte 1	Data Byte 0	Data Description	Data Size
0	joint index	cmd id	overall command to hand	
1	j1	j0	Target Position Data (degrees)	int8_t
2	j3	j2		
3	j5	j4		
50	j0 high word		Target Force Data (N)	float
51	j0 low word			
52	j1 high word			
53	j1 low word			
54	j2 high word			
55	j2 low word			
56	j3 high word			
57	j3 low word			
58	j4 high word			
59	j4 low word			
60	j5 high word			
61	j5 low word			
150		j0	Target Velocity Data (abs degrees/s)	uint16_t
151		j1		
152		j2		
153		j3		
154		j4		
155		j5		
200	null	feedback status	overall status of hand	uint8_t
201	j1	j0	Feedback Position Data (degrees)	int8_t
202	j3	j2		
203	j5	j4		
250	j0 high word		Feedback Force Data (N)	float
251	j0 low word			
252	j1 high word			
253	j1 low word			
254	j2 high word			
255	j2 low word			
256	j3 high word			
257	j3 low word			
258	j4 high word			
259	j4 low word			
260	j5 high word			
261	j5 low word			
150		j0	Feedback Velocity Data (abs degrees/s)	uint16_t
151		j1		
152		j2		
153		j3		
154		j4		
155		j5		

400	j1	j0	temperature (deg c)	int8_t
401	j3	j2		
402	j5	j4		
500	j1	j0	actuator error reports	uint8_t
501	j3	j2		
502	j5	j4		
600	j1	j0	actuator mode status	uint8_t
601	j3	j2		
602	j5	j4		
650	thumb x high word		Feedback Force Data Fingertip (Contactile) (N)	float
651	thumb x low word			
652	thumb y high			
653	thumb y low			
654	thumb z high			
655	thumb z low			
656	index x high			
657	index x low			
658	index y high			
659	index y low			
660	index z high		Feedback Force Data Fingertip (Contactile) (N)	
661	index z low			
662	middle x high			
663	middle x low			
664	middle y high			
665	middle y low			
666	middle z high			
667	middle z low			
668	ring x high			
669	ring x low		Feedback Force Data Fingertip (Contactile) (N)	
670	ring y high			
671	ring y low			
672	ring z high			
673	right z low			
674	pinky x high			
675	pinky x low			
676	pinky y high			
677	pinky y low			
678	pinky z high			
679	pinky z low		Feedback Force Data Fingertip (Contactile) (N)	