

Memory Address (16b)	Data Byte 1	Data Byte 0	Data Description	Data Size
0	joint index	cmd id	overall command to hand	
1	j1	j0	Target Position Data (degrees)	
2	j3	j2		
3	j5	j4		int8_t
50	j0 high word		Target Force Data (N)	
51	j0 low word			
52	j1 high word			
53	j1 low word			
54	j2 high word			
55	j2 low word			
56	j3 high word			
57	j3 low word			
58	j4 high word			
59	j4 low word			
60	j5 high word			
61	j5 low word			float
200	null	feedback status	overall status of hand	uint8_t
201	j1	j0	Feedback Position Data (degrees)	
202	j3	j2		
203	j5	j4		int8_t
250	j0 high word		Feedback Force Data (N)	
251	j0 low word			
252	j1 high word			
253	j1 low word			
254	j2 high word			
255	j2 low word			
256	j3 high word			
257	j3 low word			
258	j4 high word			
259	j4 low word			
260	j5 high word			
261	j5 low word			float
400	j1	j0	temperature (deg c)	
401	j3	j2		
402	j5	j4		int8_t
500	j1	j0	actuator error reports	
501	j3	j2		
502	j5	j4		uint8_t
600	j1	j0	actuator mode status	
601	j3	j2		
602	j5	j4		uint8_t
650	thumb x high word		Feedback Force Data Fingertip (Contactile) (N)	
651	thumb x low word			
652	thumb y high			

653	thumb y low	
654	thumb z high	
655	thumb z low	
656	index x high	
657	index x low	
658	index y high	
659	index y low	
660	index z high	Feedback Force Data Fingertip (Contactile) (N)
661	index z low	
662	middle x high	
663	middle x low	
664	middle y high	
665	middle y low	
666	middle z high	
667	middle z low	
668	ring x high	
669	ring x low	Feedback Force Data Fingertip (Contactile) (N)
670	ring y high	
671	ring y low	
672	ring z high	
673	right z low	
674	pinky x high	
675	pinky x low	
676	pinky y high	
677	pinky y low	
678	pinky z high	
679	pinky z low	Feedback Force Data Fingertip (Contactile) (N)

float