AMERICAN INTERNATIONAL UNIVERSITY BANGLADESH

Assignment Cover Sheet



Students must complete all details except the faculty use part.

Please submit all assignments to your subject lecturers or the office of the concerned lecturer.

Assignment Title: Timero: Implementation of a fraffic control 194	stem
Assignment Number: 02 Due Date:03-10-22 Semester:	
Subject Code:Subject Name: micro processor Section: N	
Course Instructor: DR. Mo hamm & Shiduzo Degree Program: CSE	

Declaration and Statement of Authorship:

- I/we hold a copy of this assignment, which can be produced if the original is lost/ damaged. This assignment is my/our original work and no part of it has been copied from any other student's work or from any other source except where due acknowledgement is made.
- 3. No part of this assignment has been written for me/us by any other person except where such collaboration has been authorized by the lecturer/teacher concerned and is clearly acknowledged in the assignment.
- 4. I/we have not previously submitted or currently submitting this work for any other course/unit.
- 5. This work may be reproduced, communicated, compared and archived for the purpose of detecting plagiarism.
- 6. I/we give permission for a copy of my/our marked work to be retained by the School for review and comparison, including review by external examiners.

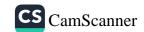
I/we understand that

- 7. Plagiarism is the presentation of the work, idea or creation of another person as though it is your own. It is a form of cheating and is a very serious academic offence that may lead to expulsion from the University. Plagiarized material can be drawn from, and presented in, written, graphic and visual form, including electronic data, and oral presentations. Plagiarism occurs when the origin of the material used is not appropriately cited.
- 8. Enabling plagiarism is the act of assisting or allowing another person to plagiarize or to copy your work

Gro	oup Name (if applicable):	03	
No	Ctudent No.		

No.	Student Name	Student Number	Student Signature	Date
1	MD. MODE HOMOUN	20-42460-1	- COLOW.	03-11-22
2	RAHMAN, RUBAIYAT	20-43501-1	Rubaiyat	03-10-22
3	Alamgir, Abdullah	19-40920-2	ATOM	03-10-22
4	Tasnia Amin Neha	20-43398-1	Neha	63-10-22
5 .	Abu Shaleh Md. Kaium	20-42475-1	piash	03-10-22
6		758-16-	, ,	

For faculty use only:	Total Marks:Marks Obtain	ned:
Faculty comments	TO THE WAY WAS TO THE WAY.	



Introduction: In this expriment we have tearened about micro contorollers, we have tearen about itraduino we have to tasign a project name to braffic control. we have done this project in lab andato tinker cod software which is available in online plateorem. we have used code code for simulating the project. we have design a fraffic system on a run it by codes. The objective of this experiment to to get familiarized with Timers and use then for the inplementation of a traffic control system.

Theory and methodology!

Timere! Every etectronie component of a requential logie etecuit worker on a time bone. This time home helps to keep all the works synchronoize, with out a time bore, devices would have no idea as to

when to perstrom particular action. Thus the stimer is an imposedant concept in the field of electronics.

& timer/counter is a piece of hose worker built into the Archino controller. gt. is like a clock and can be used to measure time events. A limer is a register who re value increares / de creares automatically.

In AVR timeres are of two types: 8-bits and 16 bit 9 non 8-bit timer the register used by 8 bit wide whereof . In a 16 bit tomore the register width 10.16 bits.

Apparatus:

- Assilino uno
- 11) LED lights (yellow, Red, and green.)
- 11) Resindory (220.0hm).

Experimental setup:



```
// C-= code
//
void setup()

pinMode(2, OUTPUT);
pinMode(4, OUTPUT);
pinMode(8, OUTPUT);

void loop()

digitalMrite(2, RION);
digitalMrite(4, LON);
delay(5000); // Wait for 5000 millisecond(s)

digitalMrite(4, RION);
digitalMrite(4, RION);
digitalMrite(8, LON);
digitalMrite(8, LON);
digitalMrite(8, LON);
digitalMrite(8, LON);
delay(5000); // Wait for 3000 millisecond(s)

digitalMrite(8, LON);
delay(5000); // Wait for 5000 millisecond(s)

digitalMrite(8, RION);
delay(5000); // Wait for 5000 millisecond(s)

digitalMrite(8, RION);
delay(5000); // Wait for 5000 millisecond(s)
```

RESULT:

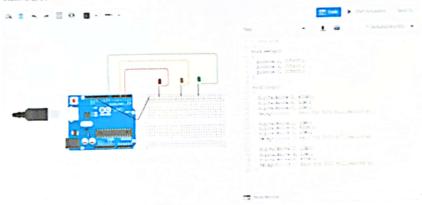


Figure 1: Total Traffic Signal Model

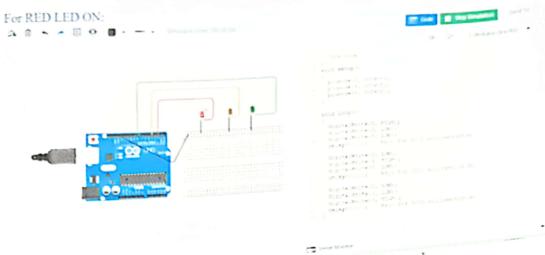


Figure 2: Simulation For Only Red LED IS On For 5 second

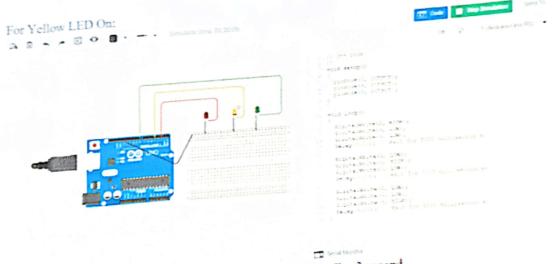


Figure 3: Simulation For Only Yellow LFD IS On For 3 second

For Green LED On:

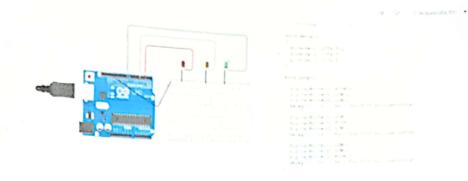


Figure 4: Simulation For Only Green LED IS On For 5 second

Discussion ?-

In this experiment, traffic control system has been implemented by using Andrino Uno. For implementing this, a mebsite called tink encad com has been used. In here, 3 LED light REd, yellow. and green has been taken with 3 nesistons along with a breadboard. The resistons have been taken to the ground. After designing the circuit, the code was implemented. Codes were written in Andrino IDE 1.8.13 where LED Blink and delay functions were added into the codes.

References:

- 1. https://www.arduino.cc/.
- 2. ATMega 328 manual
- 3. https://www.avnfreaks.net/Somm/tut-c-newbies-gaide-avn-timens.
- A. https://maxembedded.com/2011/06/avn-timens-timents/