

### **INTRODUCTION**

- □ A Convolutional Neural Network (CNN) is a type of artificial neural network designed for processing structured grid data, such as images and videos.
- ☐ The primary purpose of a CNN is to efficiently and automatically learn hierarchical representations of features from input data.
- ☐ In the context of image processing, CNNs excel at tasks like image classification, object detection, and image segmentation
- □ Popular CNN architectures include LeNet, AlexNet, VGGNet, GoogLeNet, DenseNet, MobileNet, and ResNet.

# Characteristics of CNN

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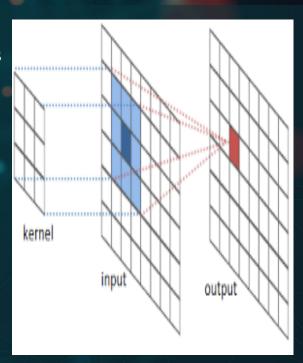
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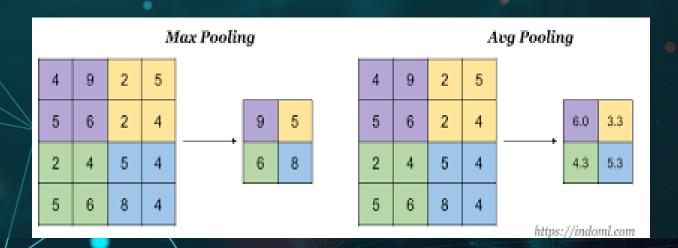
# **CONVOLUTIONAL LAYERS**

- ☐ CNNs use convolutional layers to scan an input image or feature map using small, learnable filters (kernels).
- ☐ These filters slide over the input data, applying convolution operations to detect patterns and features.
- Convolutional layers are responsible for feature extraction.



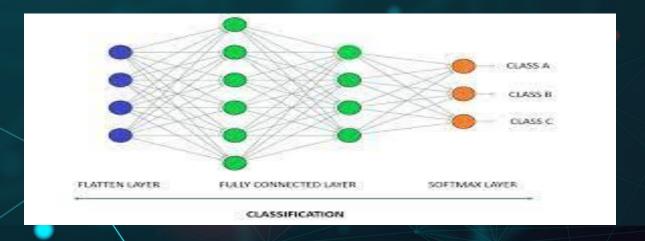
### **POOLING LAYERS**

- ☐ The main purpose of pooling layer is to progressively reduce the spatial size of the input image, so that number of computations in the network are reduced.
- Pooling performs down sampling by reducing the size and sends only the important data to next layers in CNN.



# **FULLY CONNECTED LAYERS**

- ☐ Fully connected layers are used to perform high-level reasoning and classification.
- ☐ These layers take the output from the previous layers and map it to the desired output, such as class probabilities.

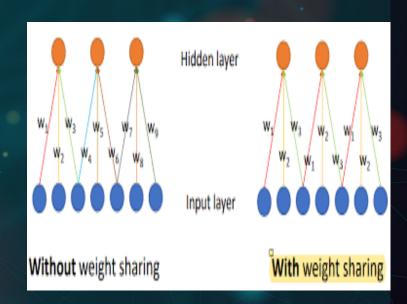




- ☐ An activation function is a mathematical operation applied to each neuron's output in a neural network layer.
- □ Activation functions introduce non-linearities to the network, allowing it to learn complex patterns and relationships in the data.

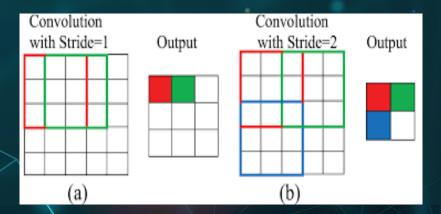
#### **WEIGHT SHARING**

- Weight sharing is a way to reduce the number of parameters while allowing for more robust feature detection.
- ☐ This property enables the network to recognize patterns anywhere in the image.



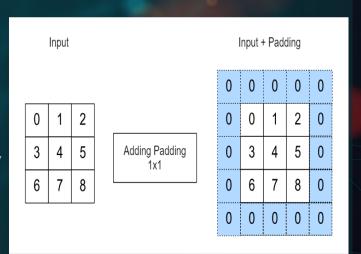
## STRIDE

- □ Stride is the number of pixels shifts over the input matrix. When the stride is 1 then we move the filters to 1 pixel at a time.
- □ When the stride is 2 then we move the filters to 2 pixels at a time and so on.



## **PADDING**

- Padding in CNN refers to the addition of extra pixels around the borders of the input images or feature map.
- Adding padding to an image processed by a CNN allows for more accurate analysis of images.

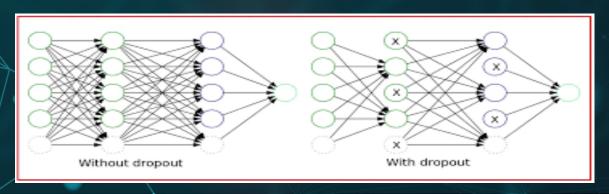


#### **FEATURE MAPS AND DROPOUT**

Feature mapping involves selecting or designing a set of functions that map the original data to a new set of features.

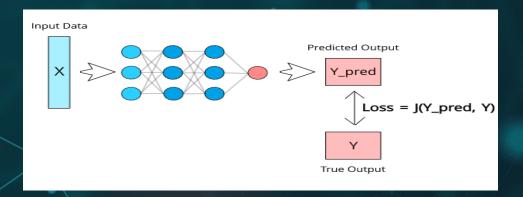


Dropout layers are sometimes used to prevent overfitting.



# **LOSS FUNCTION**

- □ CNNs are typically trained using a loss function that measures the difference between predicted and actual values (to prevent over fitting).
- ☐ It measures the model's performance and guides the optimization process by providing feedback on how well it fits the data.

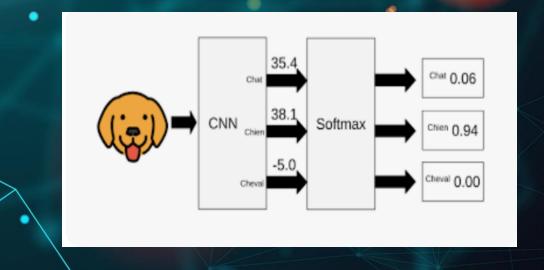


#### **OPTIMIZATION ALGORITHMS**

- ☐ In deep learning, optimizers are algorithms that adjust the model's parameters during training to minimize a loss function.
- ☐ They enable neural networks to learn from data by iteratively updating weights and biases.
- □ Common optimizers include Stochastic Gradient Descent (SGD) and Adam.

# **SOFTMAX**

- ☐ The softmax function is commonly used in the output layer to generate class probabilities for multiclass classification problems.
- ☐ It is usually placed as the last layer in the CNN model.



# LIMITATIONS OF CNN

- □ Limited Understanding of Global Context
- Data Dependency and Overfitting
- Computational Intensity
- □ Lack of Interpretability
- □ Not Universally Applicable
- □ Vulnerability to Adversarial Attacks
- □ Large Memory Requirements
- □ Difficulty in Handling Sequential Data

# **APPLICATIONS OF CNN**

- □ Image Classification
- □ Facial Recognition
- □ Natural Language Processing (NLP)
- □ Video Analysis
- □ Gesture Recognition
- □ Document Analysis





# DROWSINESS DETECTION USING CNN

Classification	Report: precision	recall	f1-score	support
Closed_Eyes	0.99	0.99	0.99	422
Open_Eyes	0.99	0.98	0.99	378
accuracy			0.99	800
macro avg	0.99	0.99	0.99	800
weighted avg	0.99	0.99	0.99	800

## SCORES

$$Precision = rac{TP}{TP+FP}$$

$$Recall = rac{TP}{TP + FN}$$

$$F1 = 2 imes rac{ ext{Precision} imes ext{Recall}}{ ext{Precision} + ext{Recall}}$$

$$Accuracy = \frac{TP + TN}{TP + TN + FP + FN}$$

