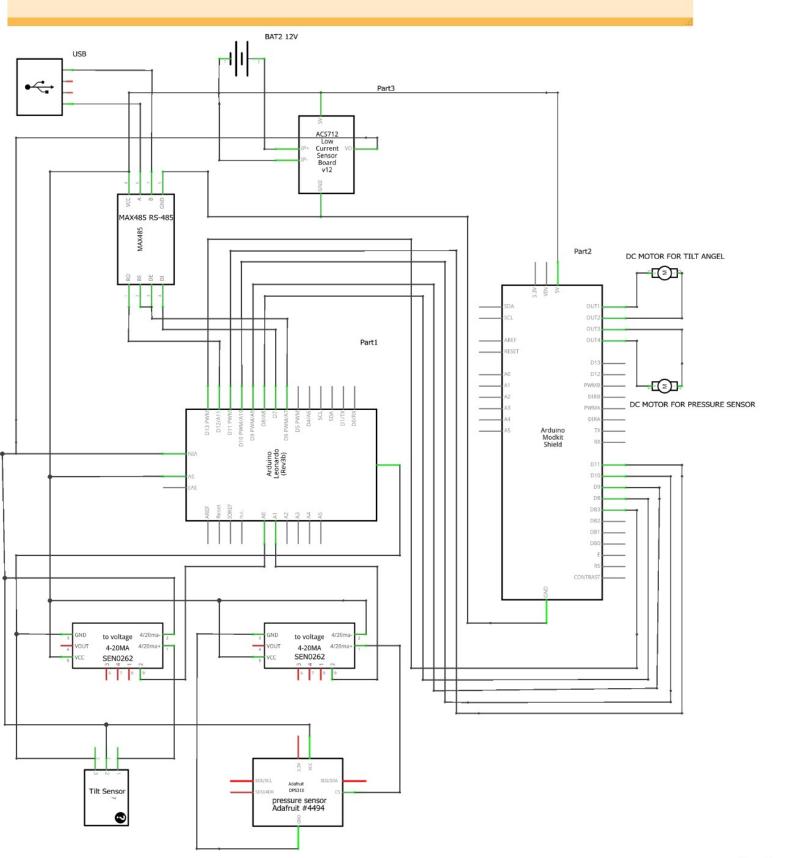


## Arduino Leonardo-Based Precision Motion Control System

This project implements a precise motion control system using an Arduino Leonardo, TMS22E-PKH090 tilt sensor, DFRobot SEN0262 pressure sensor, and MAX485 module for RS-485 communication. It controls two DC motors using an L298P motor driver: one for the tilt axis and one for the vertical axis.



```
0:27:41.741 -> Voltage: 0.992 V | Current: 4.00 mA | Depth: 0.0 cm
0:27:42.754 -> Voltage: 0.992 V | Current: 4.00 mA | Depth: 0.0 cm
0:27:43.765 -> Voltage: 0.992 V | Current: 4.00 mA | Depth: 0.0 cm
0:27:44.738 -> Voltage: 0.997 V | Current: 4.00 mA | Depth: 0.0 cm
0:27:45.749 -> Voltage: 0.997 V | Current: 4.00 mA | Depth: 0.0 cm
0:27:46.780 -> Voltage: 0.992 V | Current: 4.00 mA | Depth: 0.0 cm
0:27:47.780 -> Voltage: 1.022 V | Current: 4.09 mA | Depth: 2.7 cm
0:27:48.750 -> Voltage: 1.031 V | Current: 4.13 mA | Depth: 3.9 cm
0:27:49.766 -> Voltage: 1.036 V | Current: 4.14 mA | Depth: 4.5 cm
0:27:50.762 -> Voltage: 1.041 V | Current: 4.16 mA | Depth: 5.1 cm
0:27:51.773 -> Voltage: 1.051 V | Current: 4.20 mA | Depth: 6.4 cm
0:27:52.776 -> Voltage: 1.051 V | Current: 4.20 mA | Depth: 6.4 cm
0:27:53.790 -> Voltage: 1.056 V | Current: 4.22 mA | Depth: 7.0 cm
```

```
20:26:20.668 -> Voltage: 0.982 V | Current: 4.00 mA | Depth: 0.0 cm
20:26:21.632 -> Voltage: 0.978 V | Current: 4.00 mA | Depth: 0.0 cm
20:26:22.646 -> Voltage: 0.978 V | Current: 4.00 mA | Depth: 0.0 cm
20:26:23.660 -> Voltage: 0.978 V | Current: 4.00 mA | Depth: 0.0 cm
20:26:24.630 -> Voltage: 0.978 V | Current: 4.00 mA | Depth: 0.0 cm
20:26:25.662 -> Voltage: 0.978 V | Current: 4.00 mA | Depth: 0.0 cm
20:26:26.661 -> Voltage: 0.978 V | Current: 4.00 mA | Depth: 0.0 cm
20:26:27.662 -> Voltage: 0.982 V | Current: 4.00 mA | Depth: 0.0 cm
20:26:28.677 -> Voltage: 0.978 V | Current: 4.00 mA | Depth: 0.0 cm
20:26:29.685 -> Voltage: 0.978 V | Current: 4.00 mA | Depth: 0.0 cm
20:26:30.661 -> Voltage: 0.982 V | Current: 4.00 mA | Depth: 0.0 cm
20:26:31.683 -> Voltage: 0.982 V | Current: 4.00 mA | Depth: 0.0 cm
20:26:32.679 -> Voltage: 0.982 V | Current: 4.00 mA | Depth: 0.0 cm
20:26:33.665 -> Voltage: 0.978 V | Current: 4.00 mA | Depth: 0.0 cm
```



