

Sarita Sangree

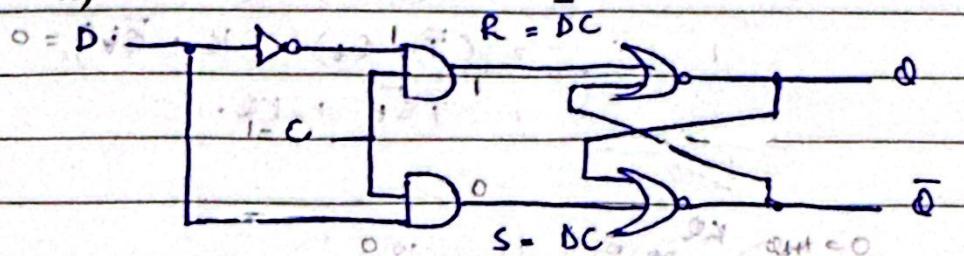
23 - 2028

Date:

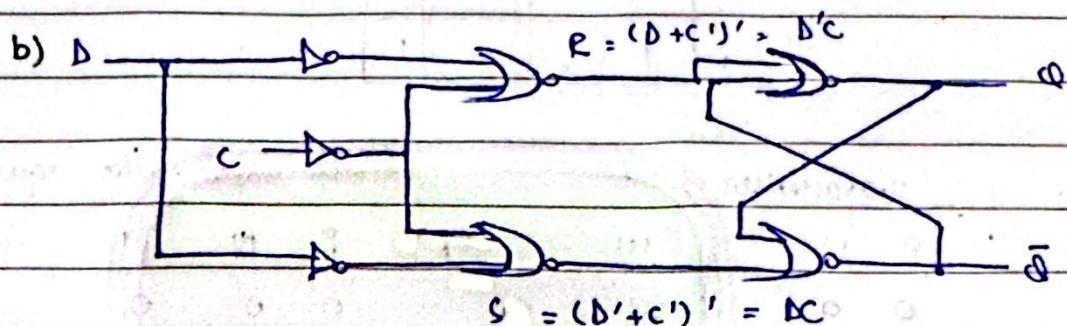
04-A

Assignment No 05

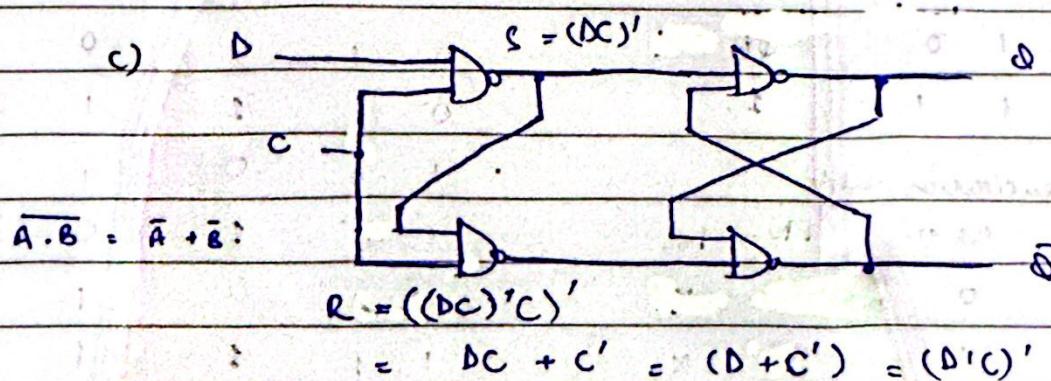
Q.1. a)



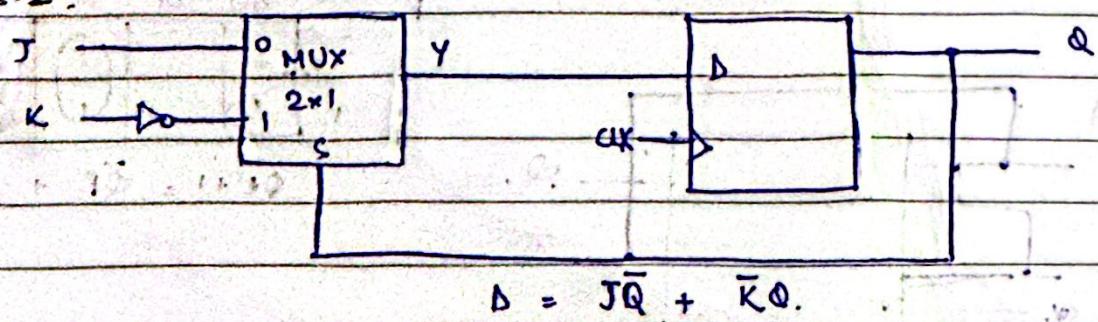
b)



c)



Q.2:



DALMATIAN

Date:

5.3. Equation of JK FF: $Q_{t+1} = \bar{Q}_t J + Q_t K$

$$Q_{t+1} = (J\bar{Q}_t + \bar{K}Q_t)' = (\bar{J}\bar{Q}_t) \cdot (\bar{\bar{K}}Q_t) \\ \stackrel{A+B}{=} \bar{A} \cdot \bar{B}$$

J	K	Q _t	Q _{t+1}
0	0	0	1
0	1	0	0
1	0	1	0
1	1	1	1

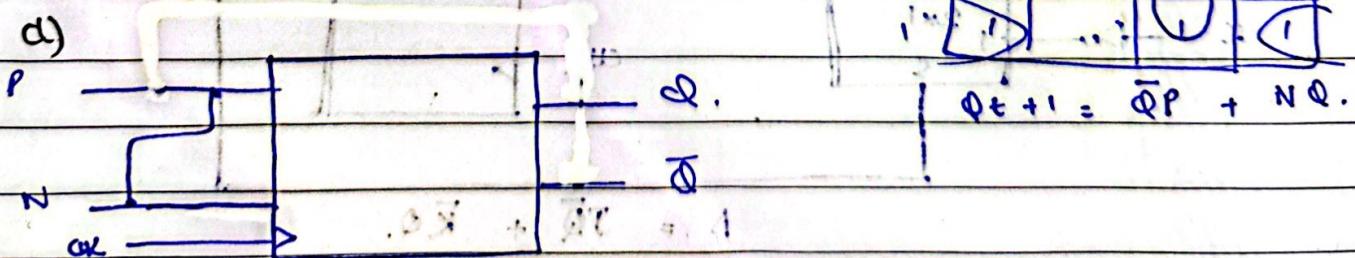
5.4. characteristic table characteristic equation

a)	P	N	Q _{t+1}	b)	P	N	Q _t	Q _{t+1}
	0	0	1		0	0	0	0
	0	1	0		0	0	1	0
	1	0	0		0	1	0	0
	1	1	1		0	1	1	1

excitation table

c)	Q _t	Q _{t+1}	P	N	→	1	0	0	i
	0	0	(0)	x	→	1	0	1	0
	0	1	(1)	x	→	0	1	0	1
	1	0	(0)	x	→	0	1	1	1

d)	Q _t	Q _{t+1}	P	N	→	1	0	0	i
	0	0	(0)	x	→	1	0	1	0
	0	1	(1)	x	→	0	1	0	1
	1	0	(0)	x	→	0	1	1	1



connect P and N together.

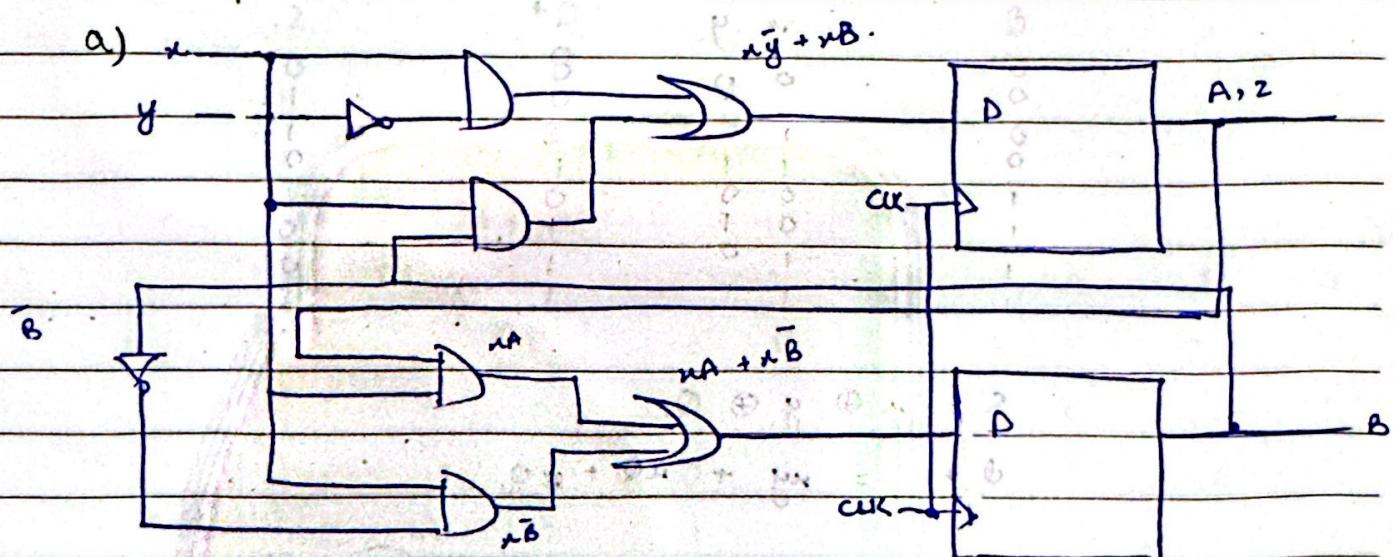
DALMATIAN

Date:

- 5.5.
- 1) Truth table describes the combinational circuit
 - 2) The state table describes a sequential circuit
 - 3) The characteristic table describes the operation of flip-flop.
 - 1) Excitation table gives values of flip flop inputs for a given state transition.
 - 2) The 4 equations correspond to the algebraic expression of the 4 tables.

5.6.

a)



b)

$$A_{t+1} = \bar{x}\bar{y} + \bar{x}B$$

$$B_{t+1} = \bar{x}A + \bar{x}B$$

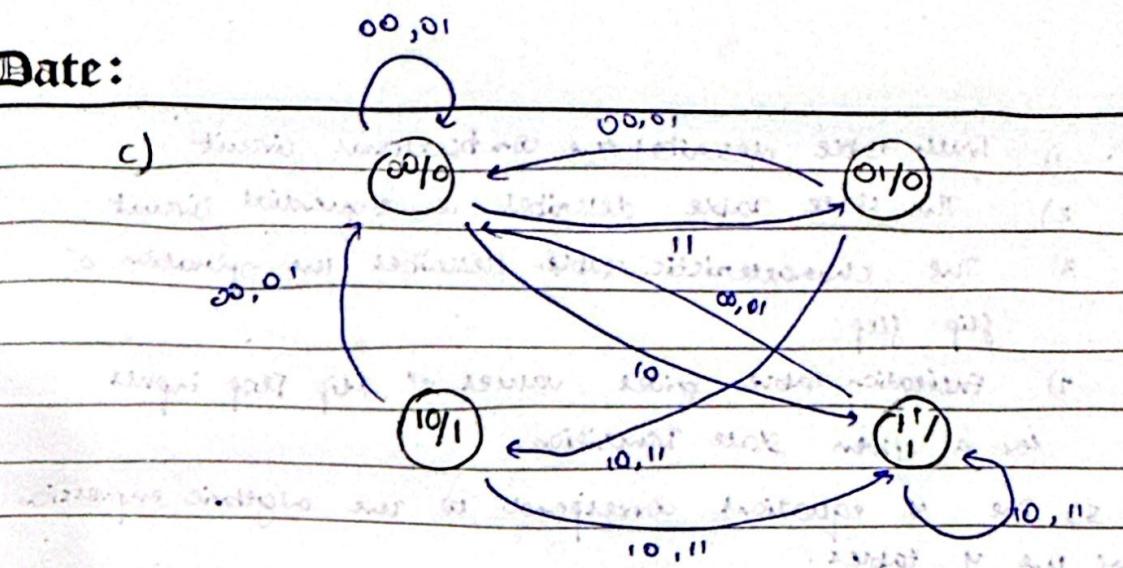
$$z = A$$

	Present		Next		Z
	A	B	$A' + B'$	x	
	0	0	0 0	0	0
	0	0	0 0	0	1
	0	0	1 1	1	0
	0	0	0 1	1	0
	0	1	0 0	0	0
	0	1	0 0	0	1
	0	1	1 0	1	0
	0	1	1 0	1	1
	1	0	0 0	0	0
	1	0	0 0	0	1
	1	0	1 1	1	0
	1	0	1 1	1	1
	1	1	0 0	0	0
	1	1	0 0	0	1
	1	1	1 1	1	1

Dalmatian

Date:

c)



5.7.

Present

inputs

Next

output

Q

x, y

Q⁺

S.

0

0, 0

0

0

0

1, 0

0

1

1

1, 1

1

0

1

0, 1

1

1

1

1, 0

1

0

1

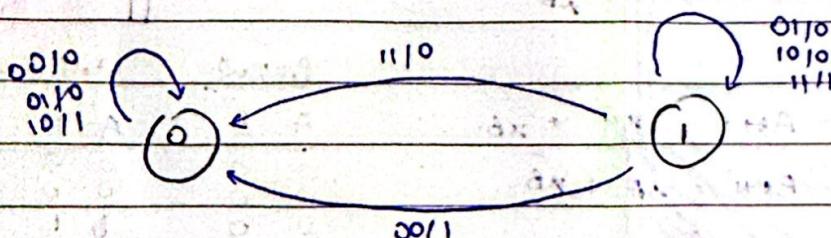
1, 1

1

1

$$S = x \oplus y \oplus Q$$

$$Q^{+} = xy + xQ + yQ$$



Present

Next

FF inputs.

5.8

A

B

A⁺

B⁺

T_A

T_B

Q_t Q_{t+1}

$$T_A = A + B$$

0

0

0

1

0 0

$$T_B = \bar{A} + B$$

0

1

1

1

0 1

:

1

0

1

0

1 1

:

1

0

1

1

1 1

Look at T_B
T_A = A + B

DALMATIAN

Date:

$$T_A = A + B.$$

$$T_B = A^T + B = \bar{A}$$

$$\bar{A} + A = 0$$

$$AB = BA$$

00

01

11

10

5.9.

$$JA = xAT \quad KA = B$$

$$JB = xP \quad KB = \bar{A}$$

a)

$$Q_{t+1} = J\bar{A} + \bar{K}Q_t$$

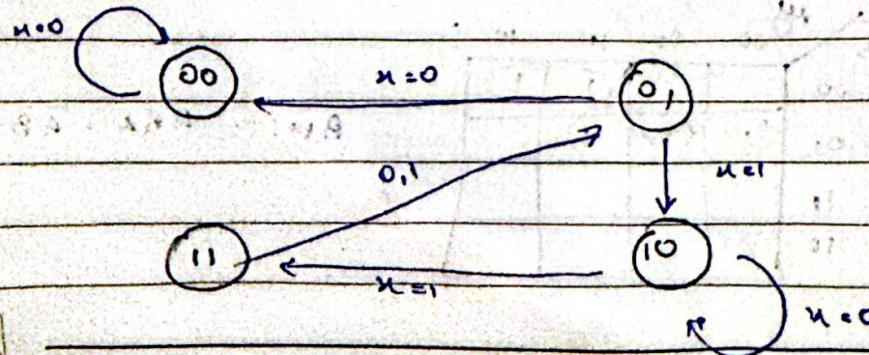
$$A_{t+1} = JA\bar{A} + \bar{KA}A$$

$$\rightarrow A_{t+1} = xA\bar{A} + \bar{B}A$$

$$\rightarrow B_{t+1} = JB\bar{B} + \bar{K}B = u\bar{B} + AB.$$

b)

		Present	Next	JA	KA	JB	KB
		A	B	A ⁺	B ⁺		
Q	Q _{t+1}	J K 0	0 0 0	0 0 0	0 0 0	0 0 1	1
0	0	x 0	0 1	0 0	0 1	0 0	1
0	1	x 0	1 0	1 0	0 0	0 0	0 0
1	1	x 1	0 1	0 1	0 1	1 0	0 0
1	1	x 0 1	0 0 1	1 0 1	1 0 1	1 0	1 1
1	1	0 1	1 0	1 0 1	1 0 1	1 1	1 1
1	1	1 0	1 1	1 1 1	1 0 1	1 0	1 0
1	1	1 1	0 1	1 1 0	1 1 1	1 1	0



DALMATIAN

Q	Q _{t+1}	J	K
0	0	0	x
0	1	1	x
1	0	x	1
1	1	x	0

Date:

5-10.

$$a) JA = \bar{B}x + \bar{B}y$$

$$KA = \bar{B}x\bar{y}$$

$$JB = \bar{A}x$$

$$KB = A + \bar{x}\bar{y}$$

$$z = \bar{A}\bar{x}\bar{y} + \bar{B}\bar{x}\bar{y}$$

b)

using excitation table

Present	Input	Next		Output		FF inputs				
A	B	x	y	A ⁺	B ⁺	z	JA	KA	JB	KB
0	0	0	0	1	0	0	1	0	0	0
0	0	0	1	0	0	0	0	0	0	0
0	0	1	0	1	1	0	1	1	1	1
0	0	1	1	0	1	1	0	0	1	0
0	1	0	0	0	1	1	0	0	0	0
0	1	0	1	0	1	0	0	0	0	0
0	1	1	0	1	0	0	1	0	1	0
0	1	1	1	1	1	0	1	0	0	0
1	0	0	0	1	0	0	0	0	0	0
1	0	0	1	0	1	0	0	0	0	0
1	0	1	0	1	0	0	0	0	0	0
1	0	1	1	0	1	0	0	0	0	0
1	1	0	0	1	0	0	1	0	0	0
1	1	0	1	0	1	0	0	0	0	0
1	1	1	0	0	1	0	0	0	0	0
1	1	1	1	0	0	1	0	0	0	0

c)

AB	xy	00	01	11	10
00		1	0	0	1
01			1	1	1
11		1	1	1	1
10		1	1	1	1

$$A^{++} = A\bar{x} + Bx + Ay + \bar{A}\bar{B}\bar{y}$$

AB	xy	00	01	11	10
00				1	1
01		1	1	1	1
11				1	1
10				1	1

$$B^{++} = \bar{A}\bar{B}x + \bar{A}\bar{B}(x+y)$$

DALMATIAN

Date:



S.11. Present : 00 00 01 00 01 11 00 01 11 10 00 01 11 10 10

a) Input : 0 1, 0 1, 1 0 1 1 1 0 1 1 1 0

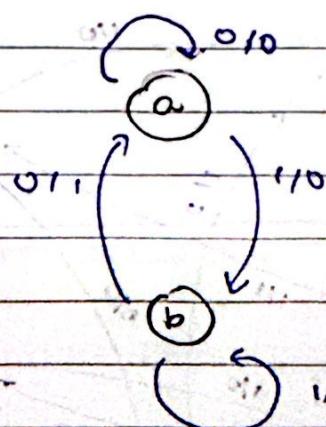
Output : 0 0 1 0 0 1 0 0 0 1 0 0 0 0 1

Next : 00 01 00 01 11 00 01 11 10 00 01 11 10 10 00

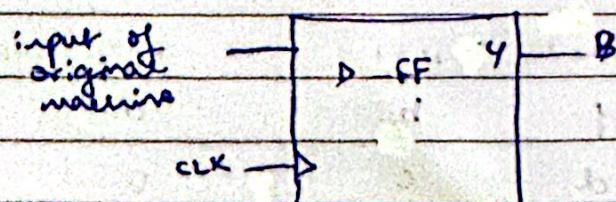
b). State labels : a: 00, b: 10, c: 11, d: 01

c is equal to b.

d is equal to c.



input	state	next-state	output
0	0	0	0
0	1	1	0
1	0	0	0
1	1	1	1

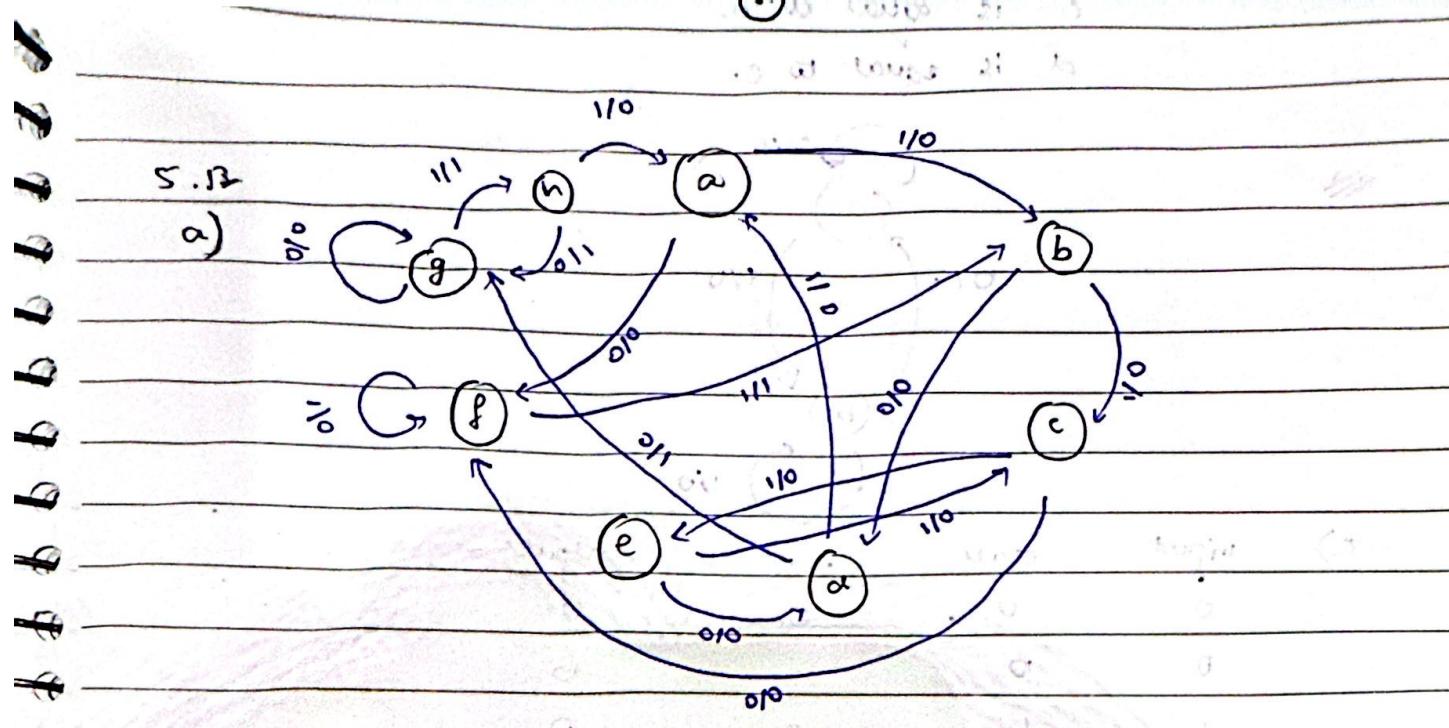


• Direct input of input to original machine

• output : $y = (\text{not equal to input})$

start : B.

DALMATIAN



b) $d = h$

	b = e	Next	Output
Present	$n = 0, 1, \dots, n+1$	$n = 0, 1, \dots, n+1$	$n = 0, 1, \dots, n+1$
same	a b c d e f g	f d g b a c h	0 0 0 0 1 0 0
at begin	0 0 0 0 0 0 0	1 1 1 1 0 0 0	0 0 0 0 0 0 0
at begin	0 0 0 0 0 0 0	1 1 1 1 0 0 0	0 0 0 0 0 0 0

DALMATIAN

Date:

Present	Next	Output
	0 1	0 1
a	f b	0 0
b	d a	0 0
d	g a	0 1 0 0
f	g b	0 1 1 0
g	d t	0 1 0

5.13.

a) State: a f b c e d g h g g + initial

Input: 0 1 0 1 1 0 0 1 0 0 0 1 1 0

Output: 0 1 0 0 0 1 1 0 1 0 1 0 1 0

b)

$$a = c$$

$$d = h$$

$$b = e$$

State: a f b a b d g a g g + initial

Input: 0 1 0 1 1 0 0 1 0 0 0 1 1 0

Output: 0 1 0 0 0 1 1 0 1 1 0 1 0

5.14.

Table 5.9	state	ASS. 1
		.000
a	1	.000
b	0	.001
c	1	.010
d	0	.011
e		100

DALMATIAN

Date: 15/06/2023

S-B Reduced Table.

Previous Next Output

$n=0$ $n=1$

a a b 0 0

b c d 0 0

c a d 0 0

d e d 0 1

e a d 0 1

Solution: P.C , binary

		$n=0$	$n=1$
a		000	000
b		001	010
c		010	000
d		011	100
e		100	000

$$S-15 \quad Q_{t+1} = \bar{Q}J + Q\bar{K}$$

P.S	Inputs	N.S	Q	Q _{t+1}	J	K
0	0 0	0	1	0	x	1
0	0 1	0	1	1	x	0
0	1 0	1	1	0	1	0
0	1 1	1	0	1	0	1
1	0 0	1	Q	00 01 11 10	J	K
1	0 1	0	0	1	1	1
1	1 0	1	1	1	1	1
1	1 1	0	Q _{t+1}	00 01 11 10	J	K

DALMATIAN

Date:

