

AXI4-Lite UART 16550 (Beta Release)

Version 0.1



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IP Summary

Introduction

The UART (Universal Asynchronous Receiver/Transmitter) core offers the ability to communicate serially, enabling interaction with external devices such as modems or other computers using an RS232 protocol and a serial cable. The core has been developed to be highly compatible with the National Semiconductors' 16550A device, which is an industry standard. This is an AXI-Lite compliant UART IP for easy integration with other AXI based systems.

Features

- · FIFO only operation.
- · Register level and functionality compatibility with NS16550A.
- Debug Interface in 32-bit data bus mode.
- AXI4-Lite interface in 32-bit or 8-bit data bus modes.



Overview

AXIL UART

The UART 16550 is a device that provides asynchronous serial communication capabilities for interacting with external devices, such as modems, printers, and other computers. It is a widely used standard in the industry for serial communication and has been around since the early 1980s.

The Universal Asynchronous Receiver/Transmitter (UART) is a component within the device that provides the ability to transmit and receive data over a serial connection. It is a soft IP core that converts parallel data into a serial stream of bits that can be transmitted over a single communication line, and then reconverts the received serial data back into parallel data. The UART 16550 is designed to be compatible with the National Semiconductors' 16550A device, which is an industry standard. This compatibility allows for easy integration of the device into existing systems and makes it a popular choice for many applications. Overall, the UART 16550 is a reliable and efficient device that provides serial communication capabilities for a variety of applications. Its features and compatibility with industry standards make it a popular choice in many different industries, including telecommunications, industrial control, and computing. A block diagram for the AXI-Lite UART IP is shown in Figure 1.

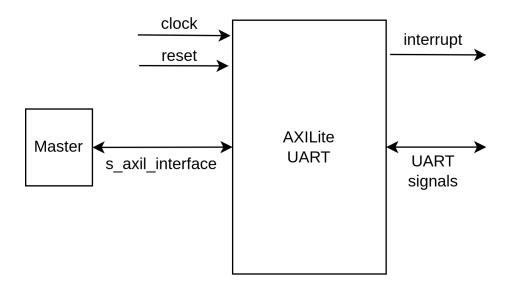


Figure 1: AXIL UART Block Diagram



IP Specification

AXI Lite UART is a type of Universal Asynchronous Receiver-Transmitter (UART) that uses the AXI Lite protocol to interface with other devices in an embedded system. UARTs are commonly used to transmit and receive data between a microcontroller or processor and other devices, such as sensors, actuators, or other microcontrollers. The AXI Lite UART provides a standard UART interface using the AXI Lite protocol, which allows it to easily integrate with other AXI Lite devices in a system. This can help simplify the overall system design and reduce the number of components required. The operation of UART can be defined by utilizing the various registers in its address space, the details of which are given below. The internal block diagram can be seen in Figure 2.

Standards

The AXI4-Lite interface is compliant with the AMBA® AXI Protocol Specification.

IP Support Details

The Table 1 gives the support details for AXIL UART.

| Com | pliance | | IP Res | ources | | Too | l Flow | |
|--------|-----------|--------------|------------------|-----------|------------------|-------------------------|-----------------|-----------|
| Device | Interface | Source Files | Constraint Files | Testbench | Simulation Model | Analyze and Elaboration | Simualtion | Synthesis |
| Gemini | AXI4-Lite | Verilog | - | - | - | Surelog (Raptor) | Icarus (Raptor) | Raptor |

Table 1: IP Details

Parameters

Table 2 lists the parameters of the AXIL UART.

| Parameter | Values | Default Value | Description |
|---------------|-----------|---------------------------------|---|
| ADDRESS WIDTH | 8, 16, 32 | 16 | AXIL Read/Write Address Width for UART |
| DATA WIDTH | 32 / 64 | 32 | AXIL Read/Write Data Width for UART |
| IP TYPE | - | AXIL_URT | Type of Peripheral |
| IP VERSION | - | <ip_version></ip_version> | Version of Peripheral |
| IP ID | - | <date_and_time></date_and_time> | Date and Time of the generated Peripheral |

Table 2: Parameters

Note: Data Width for the UART registers is 8 bit but due to AXI-Lite limitation, the data
width for the top level interface is either kept 32 or 64 bits. Keeping in mind that the
above MSBs out of the remaining 8 LSBs will be truncated or ignored when in use
because of the internal 8 bit registers of UART.



Port List

Table 3 lists the top interface ports of the AXIL UART.

| Signal Name | I/O | Description |
|----------------------|-----|---|
| AXI Clock and Reset | | |
| s_axi_aclk | I | System Clock |
| s_axi_aresetn | I | Active Low Reset |
| Write Address Channe | el | |
| s_axi_awvalid | I | AXI4-Lite Write Address Valid |
| s_axi_awaddr | I | AXI4-Lite Write Address |
| s_axi_awprot | I | AXI4-Lite Write Address Protection type |
| s_axi_awready | 0 | AXI4-Lite Write Address Ready |
| Write Data Channel | | |
| s_axi_wvalid | I | AXI4-Lite Write Data Valid |
| s_axi_wdata | I | AXI4-Lite Write Data |
| s_axi_wstrb | I | AXI4-Lite Write Data Strobe |
| s_axi_wready | 0 | AXI4-Lite Write Data Ready |
| Write Response Chani | nel | |
| s_axi_bvalid | 0 | AXI4-Lite Write Response Valid |
| s_axi_bresp | 0 | AXI4-Lite Write Response |
| s_axi_bready | I | AXI4-Lite Write Response Ready |
| Read Address Channe | | |
| s_axi_arravlid | I | AXI4-Lite Read Address Valid |
| s_axi_araddr | I | AXI4-Lite Read Address |
| s_axi_arprot | I | AXI4-Lite Read Address Protection type |
| s_axi_arready | 0 | AXI4-Lite Read Address Ready |
| Read Data Channel | | |
| s_axi_rvalid | 0 | AXI4-Lite Read Data Valid |
| s_axi_rdata | 0 | AXI4-Lite Data |
| s_axi_rresp | 0 | AXI4-Lite Read Data Response |
| s_axi_rready | I | AXI4-Lite Read Data Ready |
| UART Signals | | |
| int_o | 0 | Interrupt output |
| srx_pad_i | I | Serial RX input signal |
| stx_pad_o | 0 | Serial TX output signal |
| rts_pad_o | 0 | Request To Send |
| cts_pad_i | I | Clear To Send |
| dtr_pad_o | 0 | Data Terminal Ready |
| dsr_pad_i | I | Data Set Ready |
| ri_pad_i | I | Ring Indicator |
| dcd_pad_i | I | Data Carrier Detect |

Table 3: AXIL UART Interface

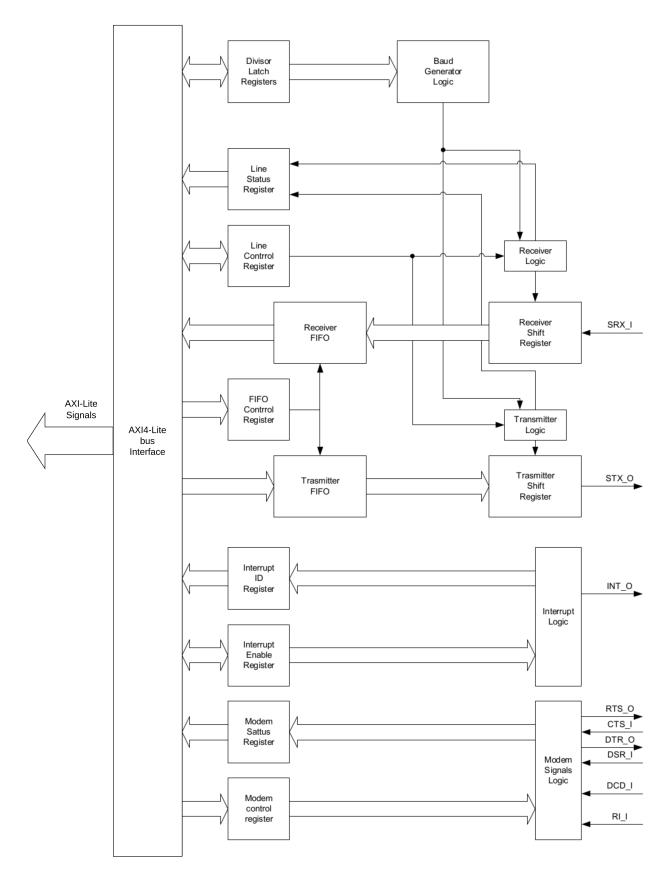


Figure 2: AXIL UART Internal Diagram



Resource Utilization

The parameters for computing the maximum and minimum resource utilization are given in Table 4, remaining parameters have been kept at their default values.

| Tool | Raptor Design Suite | | | | | |
|------------------|---------------------|----------------------------------|-----------|----------|--|--|
| FPGA Device | | GEMINI | | | | |
| Co | onfiguration | nfiguration Resource Utilization | | | | |
| | Options | Configuration | Resource | Utilized | | |
| Minumum Resource | ADDR WIDTH | 8 | LUTs | 677 | | |
| | DATA WIDTH | 8 | Registers | 557 | | |
| | Options | Configuration | Resource | Utilized | | |
| Maximum Resource | ADDR WIDTH | 32 | LUTs | 814 | | |
| | DATA WIDTH | 64 | Registers | 636 | | |

Table 4: Resource Utilization

Registers and Address Space

The Table 5 shows the address space of this UART IP that can be accessed and modified according to the user requirement.

| Name | Address Offset | Width | Access | Description |
|--------------------------|----------------|-------|--------|----------------------------------|
| IP TYPE | 0x00 | 32 | R | Holds IP Type information |
| IP VERSION | 0x04 | 32 | R | Holds IP Version information |
| IP ID | 0x08 | 32 | R | Holds IP ID information |
| Reserved1 | 0x0C | 32 | R | Reserved |
| Reserved2 | 0x10 | 32 | R | Reserved |
| Receiver Buffer | 0x14 | 8 | R | Receiver FIFO output |
| Transmitter Holding | 0x14 | 8 | W | Transmit FIFO input |
| Register (THR) | 0.814 | 0 | VV | Halishiit FiFO iliput |
| Interrupt Enable | 0x15 | 8 | RW | Enable/Mask interrupts generated |
| interrupt Enable | UXIS | 0 | KVV | by UART |
| Interrupt Identification | 0x16 | 8 | R | Get interrupt information |
| FIFO Control | 0x16 | 8 | W | Control FIFO options |
| Line Control Register | 0x17 | 8 | RW | Control connection |
| Modem Control | 0x18 | 8 | W | Controls Modem |
| Line Status | 0x19 | 8 | R | Status information |
| Modem Status | 0x1A | 8 | R | Modem Status |

Table 5: Register Address Space

In addition, there are 2 Clock Divisor registers that together form one 16-bit. The registers can be accessed when the 7th (DLAB) bit of the Line Control Register is set to '1'. At this time the above registers at addresses 0-1 can't be accessed as detailed in Table 6. The list of abbreviations may be seen in Table 15 at the end of this document.

When using 32-bit data bus interface, additional read-only registers are available for debug purposes as detailed in Table 7:



| Name | Address | Width | Access | Description |
|----------------------------|---------|-------|--------|------------------------------|
| Divisor Latch Byte 1 (LSB) | 0 | 8 | RW | The LSB of the divisor latch |
| Divisor Latch Byte 2 | 1 | 8 | RW | The MSB of the divisor latch |

Table 6: Divisor Latches

| Name | Address | Width | Access | Description |
|---------|---------|-------|--------|-----------------------|
| Debug 1 | 8 | 32 | R | First debug register |
| Debug 2 | 12 | 32 | R | Second debug register |

Table 7: Debug Registers

Interrupt Enable Register (IER)

This register allows enabling and disabling interrupt generation by the UART detailed in Table 8.

| Bit | Access | Description |
|-------|--------|--|
| | | Received Data available interrupt |
| 0 | RW | '0' – disabled |
| | | '1' – enabled |
| | | Transmitter Holding Register empty interrupt |
| 1 | RW | '0' – disabled |
| | | '1' – enabled |
| | | Receiver Line Status Interrupt |
| 2 | RW | '0' – disabled |
| | | '1' – enabled |
| | | Modem Status Interrupt |
| 3 | RW | '0' – disabled |
| | | '1' – enabled |
| 7 - 4 | RW | Reserved. Should be logic '0'. |

Table 8: IER Register

Reset Value: 00h

Interrupt Identification Register (IIR)

The IIR enables the programmer to retrieve what is the current highest priority pending interrupt. Bit 0 indicates that an interrupt is pending when it's logic '0'. When it's '1' – no interrupt is pending. The Table 9 displays the list of possible interrupts along with the bits they enable, priority, and their source and reset control.

| Bit 3 | Bit 2 | Bit 1 | Bit 2 Bit 1 Priority | Interrupt Type | Interrupt Source | Interrupt Reset Control |
|----------|-------|-------|----------------------|----------------------------|--------------------------------|-------------------------|
| _ | - | - | ر ب | Pacaivar Lina Status | Parity, Overrun or Framing | Reading the Line |
| > | _ | - | <u>10</u> | ויפכפועפו דווופ סומותא | errors or Break Interrupt | Status Register |
| 0 | , | 0 | 2nd | Receiver Data Available | FIFO trigger level reached | FIFO drops below |
|) | - |) | 5 | | | trigger level |
| | | | | | There's at least 1 character | |
| | | | | | in the FIFO but no character | Reading from the |
| _ | _ | 0 | 2nd | Timeout Indication | has been input to the FIFO | FIFO (Receiver |
| | | | | | or read from it for the last 4 | Buffer Register) |
| | | | | | Char times. | |
| | | | | | | Writing to the |
| c | c | 7 | 7.7 | Transmitter Holding | Transmitter Holding | Transmitter Holding |
| > |) | _ | 5 | Register Empty | Register Empty | Register or reading |
| | | | | | | IIR. |
| C | c | _ | 7+h | Modem Ctatus | CTC DSD DISCORD | Reading the Modem |
|) | > | > | - | ואוסמפוון סנמנתס | | status register. |

Table 9: IIR Register



Bits 4 and 5: Logic '0'.

Bits 6 and 7: Logic '1' for compatibility reason.

Reset Value: C1h

FIFO Control Register (FCR)

The FCR allows selection of the FIFO trigger level (the number of bytes in FIFO required to enable the Received Data Available interrupt). In addition, the FIFOs can be cleared using this register as detailed in Table 10.

| Bit | Access | Description |
|-------|--------|--|
| 0 \ | W | Ignored (Used to enable FIFOs in NS16550D). Since this UART |
| U VV | | only supports FIFO mode, this bit is ignored. |
| | | Writing a '1' to bit 1 clears the Receiver FIFO and resets its logic. |
| 1 | W | But it doesn't clear the shift register, i.e. receiving of the current |
| | | character continues. |
| | | Writing a '1' to bit 2 clears the Transmitter FIFO and resets its |
| 2 | W | logic. The shift register is not cleared, i.e. transmitting of the |
| | | current character continues. |
| 5 - 3 | W | Ignored |
| | | Define the Receiver FIFO Interrupt trigger level |
| | W | '00' – 1 byte |
| 7 - 6 | | '01' - 4 bytes |
| | | '10' - 8 bytes |
| | | '11' - 14 bytes |

Table 10: FCR Register

Reset Value: 11000000b

· Line Control Register (LCR)

The line control register allows the specification of the format of the asynchronous data communication used. A bit in the register also allows access to the Divisor Latches, which define the baud rate. Reading from the register is allowed to check the current settings of the communication as detailed in Table 11.

| Bit | Access | Description |
|-------|--------|---|
| | | Select number of bits in each character |
| | | '00' – 5 bits |
| 1 - 0 | RW | '01' – 6 bits |
| | | '10' – 7 bits |
| | | '11' – 8 bits |



| 2 | RW | Specify the number of generated stop bits '0' – 1 stop bit '1' – 1.5 stop bits when 5-bit character length selected and 2 bits otherwise Note that the receiver always checks the first stop bit only. | |
|---|----|--|--|
| 3 | RW | Parity Enable '0'- No parity '1'- Parity bit is generated on each outgoing character and is checked on each incoming one. | |
| 4 | RW | Even Parity select '0' – Odd number of '1' is transmitted and checked in each word (data and parity combined). In other words, if the data has an even number of '1' in it, then the parity bit is '1'. '1' – Even number of '1' is transmitted in each word. | |
| 5 | RW | Stick Parity bit. '0' – Stick Parity disabled '1' – If bits 3 and 4 are logic '1', the parity bit is transmitted and checked as logic '0'. If bit 3 is '1' and bit 4 is '0' then the parity bit is transmitted and checked as '1'. | |
| 6 | RW | Break Control bit '1' – the serial out is forced into logic '0' (break state). '0' – break is disabled | |
| 7 | RW | Divisor Latch Access bit. '1'- The divisor latches can be accessed '0'- The normal registers are accessed | |

Table 11: LCR Register

Reset Value: 00000011b

Modem Control Register (MCR)

The modem control register allows transferring control signals to a modem connected to the UART detailed in Table 12.

| Bit | Access | Description | |
|-----|--------------------------------------|--|--|
| | | Data Terminal Ready (DTR) signal control | |
| 0 | W | '0' – DTR is '1' | |
| | | '1' - DTR is '0' | |
| | Request To Send (RTS) signal control | | |
| 1 | W | '0' - RTS is '1' | |
| | | '1' - RTS is '0' | |
| 2 | W | Out1. In loopback mode, connected Ring Indicator (RI) signal input | |



| 3 | W | Out2. In loopback mode, connected to Data Carrier Detect (DCD) |
|-------|----|---|
| 3 | VV | input. |
| | W | Loopback mode |
| | | '0' – normal operation |
| | | '1' – loopback mode. When in loopback mode, the Serial |
| | | Output Signal (STX _P AD ₀)issettologic'1′.Thesignalofthe |
| | | transmitter shift register is internally connected to the input of the |
| 4 | | receiver shift register. |
| | | The followingconnections are made: |
| | | DTR -> DSR |
| | | RTS -> CTS |
| | | Out1 -> RI |
| | | Out2 -> DCD |
| 7 - 5 | W | Ignored |

Table 12: MCR Register

Reset Value: 0

• Line Status Register (LSR)

Table 13 details the usage of Line Status Register.

| Bit | Access | Description | | |
|-----|--------|--|--|--|
| 0 | R | Data Ready (DR) indicator. '0' – No characters in the FIFO '1' – At least one character has been received and is in the | | |
| | | FIFO. | | |
| 1 | R | Overrun Error (OE) indicator '1'- If the FIFO is full and another character has been received in the receiver shift register. If another character is starting to arrive, it will overwrite the data in the shift register but the FIFO will remain intact. The bit is cleared upon reading from the register. Generates Receiver Line Status interrupt. '0'- No overrun state | | |
| 2 | R | Parity Error (PE) indicator '1'– The character that is currently at the top of the FIFO has been received with parity error. The bit is cleared upon reading from the register. Generates Receiver Line Status interrupt. '0'– No parity error in the current character | | |



| 3 | R | Framing Error (FE) indicator '1'- The received character at the top of the FIFO did not have a valid stop bit. Of course, generally, it might be that all the Following data is corrupt. The bit is cleared upon reading from the register. Generates Receiver Line Status interrupt. '0' - No framing error in the current character | | |
|---|---|--|--|--|
| 4 | R | Break Interrupt (BI) indicator '1'—A break condition has been reached in the current character. The break occurs when the line is held in logic 0 for a time of one character (start bit + data + parity + stop bit). In that case, one zero character enters the FIFO and the UART waits for a valid start bit to receive next character. The bit is cleared upon Reading from the register. Generates Receiver Line Status interrupt. '0'— No break condition in the current character | | |
| 5 | R | Transmit FIFO is empty. '1'— The transmitter FIFO is empty. Generates Transmitter Holding Register Empty interrupt. The bit is cleared when data is being been written to the transmitter FIFO. '0'— Otherwise | | |
| 6 | Transmitter Empty indicator. '1' – Both the transmitter FIFO and transmitter shift register R are empty. The bit is cleared when data is being been written to transmitter FIFO. '0' – Otherwise | | | |
| 7 | R | '1'- At least one parity error, framing error or break indications have been received and are inside the FIFO. The bit is cleared upon reading from the register. '0' - Otherwise. | | |

Table 13: LSR Register

Modem Status Register

The register displays the current state of the modem control lines. Also, four bits also provide an indication in the state of one of the modem status lines. These bits are set to '1' when a change in corresponding line has been detected and they are reset when the register is being read as detailed in Table 14.

| Bit | Access | Description | |
|-----|--------|---|--|
| 0 | R | Delta Clear To Send (DCTS) indicator | |
| U | | '1' – The CTS line has changed its state. | |
| 1 | R | Delta Data Set Ready (DDSR) indicator | |
| I | | '1'- The DSR line has changed its state. | |



| 2 | R Trailing Edge of Ring Indicator (TERI) detector. The RI line has changed its state from low to high state. | |
|---|--|---|
| 3 | R | Delta Data Carrier Detect (DDCD) indicator |
| 3 | I T | '1'- The DCD line has changed its state. |
| 4 | R Complement of the CTS input or equals to RTS in loopback mod | |
| 5 | R Complement of the DSR input or equals to DTR in loopback mod | |
| 6 | R Complement of the RI input or equals to Out1 in loopback mode. | |
| 7 | R | Complement of the DCD input or equals to Out2 in loopback mode. |

Table 14: MSR Register

Divisor Latches

The divisor latches can be accessed by setting the 7th bit of LCR to '1'. You should restore this bit to '0' after setting the divisor latches in order to restore access to the other registers that occupy the same addresses. The 2 bytes form one 16-bit register, which is internally accessed as a single number. You should therefore set all 2 bytes of the register to ensure normal operation. The register is set to the default value of 0 on reset, which disables all serial I/O operations in order to ensure explicit setup of the register in the software. The value set should be equal to (system clock speed) / (16 x desired baud rate). The internal counter starts to work when the LSB of DL is written, so when setting the divisor, write the MSB first and the LSB last.

More details on the UART 16550 IP may be accessed from here.

Operation

Upon reset the core performs the following tasks:

- The receiver and transmitter FIFOs are cleared.
- The receiver and transmitter shift registers are cleared.
- The Divisor Latch register is set to 0.
- The Line Control Register is set to communication of 8 bits of data, no parity, 1 stop bit.
- All interrupts are disabled in the Interrupt Enable Register.

For proper operation, perform the following:

- Set the Line Control Register to the desired line control parameters. Set bit 7 to '1' to allow access to the Divisor Latches.
- Set the Divisor Latches, MSB first, LSB next.
- Set bit 7 of LCR to '0' to disable access to Divisor Latches. At this time the transmission engine starts working and data can be sent and received.



- Set the FIFO trigger level. Generally, higher trigger level values produce less interrupt to the system, so setting it to 14 bytes is recommended if the system responds fast enough.
- Enable desired interrupts by setting appropriate bits in the Interrupt Enable register.



Design Flow

IP Customization and Generation

AXIL UART IP core is a part of the Raptor Design Suite Software. A customized AXIL UART can be generated from the Raptor's IP configurator window as shown in Figure 3.

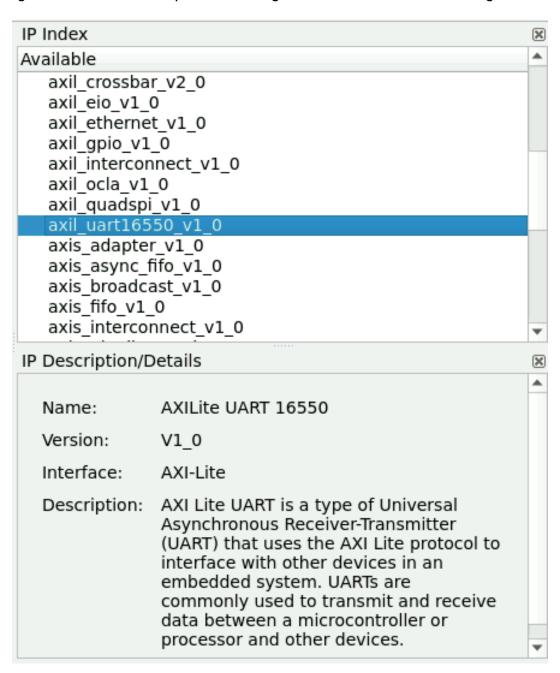


Figure 3: IP list



Parameters Customization

From the IP configuration window, the parameters of the UART can be configured and UART features can be enabled for generating a customized UART IP core that suits the user application requirement as shown in Figure 4. After IP Customization, all the source files are made available to the user with a top wrapper that instantiates a parameterized instance of the AXIL UART.

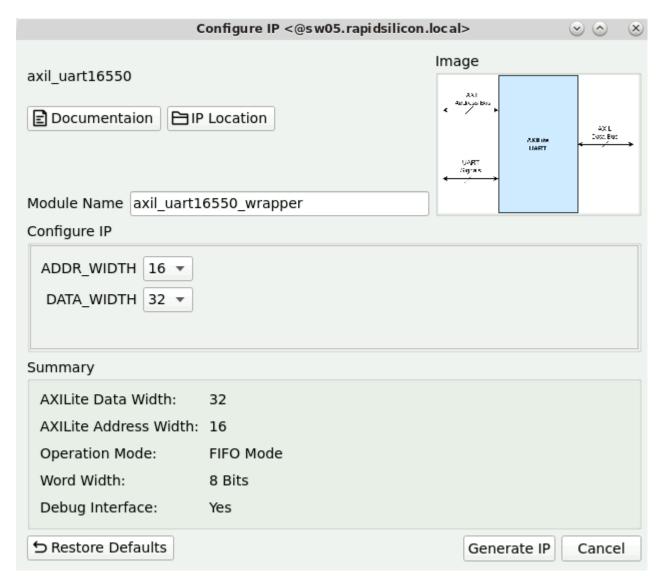


Figure 4: IP Configuration



Example Design

Overview

This AXIL UART IP can be utilized in a system that requires sequential transmission and reception of data from the outside world. UART is a crucial component in many electronic systems, enabling communication between the system and external devices through a serial interface. It can be embedded inside SoCs to enable two-way communication via the SoC. One such example design of this AXIL UART can be visualized in Figure 5.

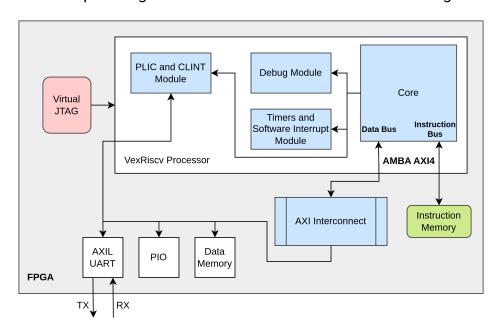


Figure 5: AXIL UART inside and SoC

Simulating the Example Design

The IP being Verilog HDL, can be simulated via a bunch of industry standard stimulus. For instance, it could be simulated via writing a Verilog Test-bench, or incorporating a soft processor that can stimulate this UART. The bundled example design is stimulated via an SoC based design as pictured above via any simulator of choice. The testplan is written in C or Assembly and fed to the SoC in a hex format, which then stimulates the UART IP connected within the SoC in a loopback fashion so both the RX and TX streams can be compared and verified based on the generated interrupts that are handled by the PLIC controller on the CPU tile. In this way, most of the UART IP is covered in testing.

Synthesis and PR

Raptor Suite is armed with tools for Synthesis along with Post and Route capabilities and the generated post-synthesis and post-route and place net-lists can be viewed and analyzed from within the Raptor. The generated bit-stream can then be uploaded on an FPGA device to be utilized in hardware applications.



Test Bench

The AXIL UART is integrated into an SoC and tested using a bare-metal firmware written in C/Assembly. The testbench, part of the firmware, operates in a loopback fashion to validate data consistency between transmission and reception. The UART, generating various interrupts, is supported by an ISR in Assembly. This firmware, loaded onto the SoC, initiates UART operations with externally provided clock and reset signals in a Verilog testbench. The testbench can be extended to cover diverse UART operations, ensuring thorough testing of all UART registers for complete integration with other AXI-based systems and peripherals. This testbench is provided as a part of the Example Designs in Raptor Design Suite and can be simulated by clicking the "Simulate IP" button as shown in the figure 6.

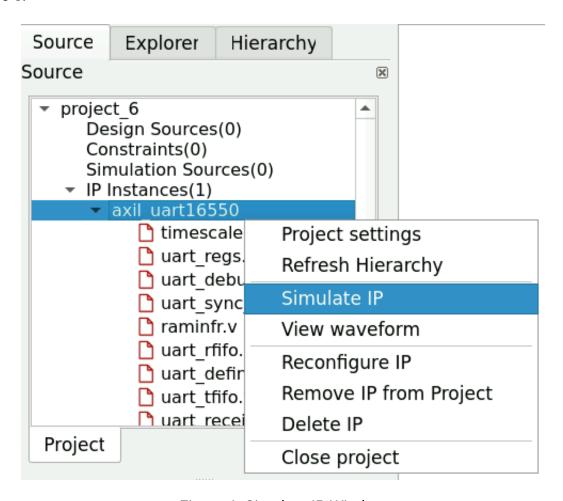


Figure 6: Simulate IP Window



Release

Release History

| Date | Version | Revisions |
|----------------------|---------|--|
| February 14, 2024 | 0.1 | Initial version AXI4-Lite UART User Guide Document |

List of Abbreviations

| Abbreviation | Definition |
|--------------|---|
| R | Read Only |
| W | Write Only |
| RW | Read and Write |
| UART | Universal Asynchronous Receiver / Transmitter |

Table 15: List of Abbreviations